优化实用算法: 第二次作业

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Problem 1

1.Implement CG algorithm to solve linear systems in which A is the Hilbert matrix, whose elements are $A(i,j) = \frac{1}{i+j-1}$. Set the right-hand-side to $b = (1,1,\cdots,1)^T$ and the initial point to $x_0 = 0$. Try dimensions n = 5, 8, 12, 20 and show the performance of residual with respect to iteration numbers to reduce the residual below 10^{-6} .

解: 首先利用 Python 写出共轭梯度法的函数,代码如下:

```
def CGmethod(A, b, n, x0, max, epsilon):
   #求解Ax=b的共轭梯度法, n为维数, x0为初值, max为最大迭代次数, epsilon为精度
2
3
           k = 0
           x = x0
4
5
           r = np.dot(A, x)-b
6
           p = -r
7
           while k \le max:
8
                   if np.sqrt(np.dot(r.T, r)) <= epsilon:</pre>
9
                   alpha = np.dot(-r.T, p)/np.dot(p.T, np.dot(A, p))
10
11
                   x = x+np.array(alpha)[0][0]*p
12
                   r0 = r
13
                   r = r+np.dot(np.array(alpha)[0][0]*A, p)
14
                   beta = np.dot(r.T, r)/np.dot(r0.T, r0)
15
                   p = -r + np. array(beta)[0][0]*p
16
                   k = k+1
17
           return x, k
```

下面利用该函数求解题目指定的 Hilbert 矩阵, 代码如下:

```
dimension=np.array([5,8,12,20])#四种维数情况
2
  m=1
3
   epsilon=1e-6
   for index in range(4):
5
           n = dimension[index]
           A = [[random.random() for col in range(n)] for row in range(n)]
6
7
           x0 = [[random.random() for col in range(m)] for row in range(n)]
8
           b = [[random.random() for col in range(m)] for row in range(n)]
9
           for i in range(n):
10
                   for j in range(n):
11
                           A[i][j] = 1/(i+j+1)
           #A为n阶 Hilbert 矩阵, 初始化矩阵并赋值
12
13
           for i in range(n):
                   for j in range (m):
14
15
                           x0[i][j] = 0
16
                           b[i][j] = 1
           #初始化 x0和 b
17
18
           A = np.mat(A)
19
           b = np.mat(b)
```

```
      20
      x0 = np.mat(x0)

      21
      #将A,b,x0转化为矩阵类型

      22
      (x, k) = CGmethod(A, b, n, x0, 10000, epsilon)

      23
      print(x)

      24
      print(k)
```

5 阶 Hilbert 矩阵使用 CG 法, 迭代次数为 6, 解如下:

```
1 [[ 4.9999996]
2 [ -119.9999998]
3 [ 630.00000003]
4 [-1119.9999997]
5 [ 630.00000003]]
```

8 阶 Hilbert 矩阵使用 CG 法, 迭代次数为 20, 解如下:

```
1  [[-8.00001170e+00]
2  [ 5.04000300e+02]
3  [-7.56000196e+03]
4  [ 4.62000058e+04]
5  [-1.38600011e+05]
6  [ 2.16216014e+05]
7  [-1.68168011e+05]
8  [ 5.14800039e+04]]
```

12 阶 Hilbert 矩阵使用 CG 法, 迭代次数为 44, 解如下:

```
1  [[-9.60760022e+00]
2  [ 8.15348107e+02]
3  [-1.64961591e+04]
4  [ 1.35509221e+05]
5  [-5.36480720e+05]
6  [ 1.02540139e+06]
7  [-6.42580101e+05]
8  [-6.57592000e+05]
9  [ 8.04244085e+05]
10  [ 6.63073788e+05]
11  [-1.24127915e+06]
12  [ 4.65505726e+05]]
```

20 阶 Hilbert 矩阵使用 CG 法, 迭代次数为 85, 解如下:

```
1  [[-1.09717066e+01]
2  [ 1.05074723e+03]
3  [-2.39540259e+04]
4  [ 2.20415205e+05]
5  [-9.65326279e+05]
6  [ 1.99009026e+06]
```

```
[-1.25270412e+06]
   [-1.34347342e+06]
9
   [ 8.83234198e+05]
  [ 1.68796915e+06]
10
   [ 3.88214600e+05]
11
12
  [-1.30552508e+06]
   [-1.71054478e+06]
13
   [-5.28252009e+05]
14
15
  [ 1.20867559e+06]
  [ 2.00288477e+06]
16
17
  [ 9.44593867e+05]
  [-1.43403647e+06]
18
  [-2.65094537e+06]
   [ 1.88784341e+06]]
20
```

我们发现,本题中 n 阶的 Hilbert 矩阵在求解时迭代次数均大于 n,且随着维数的上升迭代次数增长非常迅速,这与一般对 n 阶矩阵应用共轭梯度法求解时迭代次数不超过 n 的结论不符,我们推测这一点可能与 Hilbert 矩阵的条件数有关。

经过计算发现,5 阶矩阵的条件数为 4.77×10^5 ,8 阶矩阵的条件数为 1.53×10^{10} ,12 阶矩阵的条件数为 1.62×10^{16} ,20 阶矩阵的条件数为 2.11×10^{18} 。Hilbert 矩阵的条件数较大,因此共轭梯度法迭代时无法达到预想的准确程度,则 CG 法的收敛速度无法达到理论预期。

Problem 2

2. Derive Preconditioned CG Algorithm by applying the standard CG method in the variables \hat{x} and transforming back into the original variables x to see the expression of preconditioner M.

解:对变量 x 乘上非奇异矩阵 C 得到新变量 \hat{x} ,即 $\hat{x} = Cx$,此时目标函数表达式如下

$$\phi(\hat{x}) = \frac{1}{2}\hat{x}^T (C^{-T}AC^{-1})^{-1}\hat{x} - (C^{-1}b)^T\hat{x}$$

记 $\hat{A} = C^{-T}AC^{-1}$, $\hat{b} = C^{-T}b$,首先写出对于 \hat{x} 的 CG 算法。

Algorithm 1 CG

```
Require: \hat{x_0} = Cx_0;

\hat{r_0} \leftarrow C^{-T}(Ax_0 - b), \, \hat{p_0} \leftarrow -\hat{r_0}, \, k \leftarrow 0;

while r_k \neq 0 do

\hat{\alpha_k} \leftarrow -\frac{\hat{r_k}^T \hat{p_k}}{\hat{p_k}^T \hat{A} \hat{p_k}};

\hat{x}_{k+1} \leftarrow \hat{x_k} + \hat{\alpha_k} \hat{p_k};

\hat{r}_{k+1} \leftarrow \hat{r_k} + \hat{\alpha_k} \hat{A} \hat{p_k};

\hat{\beta}_{k+1} \leftarrow \frac{\hat{r}_{k+1}^T \hat{r_k} + 1}{\hat{r_k}^T \hat{r_k}};

\hat{p}_{k+1} \leftarrow -\hat{r}_{k+1} + \hat{\beta}_{k+1} \hat{p_k};

k \leftarrow k + 1;

end while
```

以上就是对 \hat{x} 应用标准 CG 算法的流程,下面我们对上述算法的每一步进行分析,改为对 x 进行过预处理后的形式。

• 首先由 $\hat{x_0} = Cx_0$ 合理推测每一步均有 $\hat{x_k} = Cx_k$,同理由 $\hat{r_0} = C^{-T}(Ax_0 - b) = C^{-T}r_0$ 可知每一步也均有 $\hat{r_k} = C^{-T}r_k$ 。

- 对于 $\hat{x}_{k+1} \leftarrow \hat{x}_k + \hat{\alpha}_k \hat{p}_k$,代入后可以得到 $x_{k+1} \leftarrow x_k + C^{-1} \hat{\alpha}_k \hat{p}_k$,为了保证算法的形式不变,新算法的形式也应为 $x_{k+1} \leftarrow x_k + \alpha_k p_k$,因此有 $\alpha_k = \hat{\alpha}_k$, $p_k = C^{-1} \hat{p}_k$ 。
- 对于 $\alpha_k = \hat{\alpha_k}$,代入化简 $\hat{\alpha_k} = -\frac{\hat{r_k}^T \hat{p_k}}{\hat{p_k}^T \hat{A} \hat{p_k}}$ 后,得到 $\alpha_k = -\frac{r_k^T C^{-1} C p_k}{p_k^T C^T C^{-1} A C^{-1} C p_k} = -\frac{r_k^T p_k}{p_k^T A p_k}$
- 对于 $\hat{r}_{k+1} \leftarrow \hat{r}_k + \hat{\alpha}_k \hat{A} \hat{p}_k$,代入得到 $C^{-T} r_{k+1} = C^{-T} r_k + \alpha_k C^{-T} A C^{-1} C p_k$,化简得到 $r_{k+1} = r_k + \alpha_k A p_k$ 。
- 对于 $\hat{p_0} = -\hat{r_0}$,代入得到 $Cp_0 = -C^{-T}r_0$,化简得到 $p_0 = -(C^TC)^{-1}r_0$,引入新变量 $y_0 = (C^TC)^{-1}r_0$ 。设预处理器 $M = C^TC$,则有 $y_0 = M^{-1}r_0$, $p_0 = -y_0$ 。
- 对于 $\hat{\beta}_{k+1} \leftarrow \frac{\hat{r}_{k+1}^T \hat{r}_{k+1}}{\hat{r}_k^2 T \hat{r}_k}$,保持 $\beta_{k+1} = \hat{\beta}_{k+1}$,则有 $\beta_{k+1} = \frac{r_{k+1}^T C^{-1} C^{-T} r_{k+1}}{r_k^T C^{-1} C^{-T} r_k} = \frac{r_{k+1}^T M^{-1} r_{k+1}}{r_k^T M^{-1} r_k} = \frac{r_{k+1}^T y_{k+1}}{r_k^T y_k}$ 。
- 对于 $\hat{p}_{k+1} \leftarrow -\hat{r}_{k+1} + \hat{\beta}_{k+1}\hat{p}_k$,代入得到 $Cp_{k+1} = -C^{-T}r_{k+1} + \beta_{k+1}Cp_k$,化简得到 $p_{k+1} = -M^{-1}r_{k+1} + \beta_{k+1}p_k = -y_{k+1} + \beta_{k+1}p_k$ 。

Algorithm 2 Preconditioned CG

```
Require: x_0, preconditioner M;

r_0 \leftarrow Ax_0 - b;

Solve My_0 = r_0, p_0 \leftarrow -y_0, k \leftarrow 0;

while r_k \neq 0 do

\alpha_k \leftarrow -\frac{r_k^T p_k}{p_k^T A p_k};
x_{k+1} \leftarrow x_k + \alpha_k p_k;
r_{k+1} \leftarrow r_k + \alpha_k A p_k;
Solve My_{k+1} = r_{k+1};
\beta_{k+1} \leftarrow \frac{r_{k+1}^T y_{k+1}}{r_k^T y_k};
p_{k+1} \leftarrow -y_{k+1} + \beta_{k+1} p_k;
k \leftarrow k + 1;
end while
```

上面算法中的 M 为预处理器, $M = C^T C$,是一个对称正定矩阵,以上就是求解 x 的经过 M 预处理 的 CG 算法的流程。