# Network Computing & Programming Lecture 4 Key Problems of Client & Server Design

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# Issues in C/S Programming

- 1 Identifying the Server.
- 2 Looking up an IP address.
- 3 Looking up a well known port name.
- 4 Specifying a local IP address.
- 5 UDP/TCP client design.

# Identifying the Server

#### □ Options:

- 1 Hard-coded into the client program.
- 2 Require that the user identify the server.
- 3 Read from a configuration file.
- 4 Use a separate protocol/network service to lookup the identity of the server.

# Identifying a TCP/IP server

- □ Need an IP address, protocol and port.
  - Usually use <u>host names</u> instead of IP addresses
    - Two parameter: ostec.uestc.edu.cn http
    - · One parameter: ostec.uestc.edu.cn:http

# Converting an IP address

```
    in_addr_t inet_addr(const char *strptr);
    Convert ASCII dotted-decimal IP address to
        Network byte ordered 32-bit (IPv4) value. Just like inet_aton() learned before.

    Returns a 32-bit binary network byte ordered IPv4 address and INADDR_NONE on error
```

```
(...)
    struct sockaddr_in dest;
    memset(&dest, '\0', sizeof(dest));
    dest.sin_addr.s_addr = inet_addr("202.115.16.62");
(...)
```

# Looking up an IP address

```
struct hostent *gethostbyname(const char
  *hostname); (but obsolete, use getaddrinfo() now)
   struct hostent{
      Char *h name;
      Char ** h aliases;
      Short h addrtype;
      Short h length;
      Char ** h addr list;};
(...)
struct hostent *remoteHost;
remoteHost = gethostbyname(hostname)
(\ldots)
```

# Looking up a well known port name

```
struct servent *getservbyname(const char * name,
  const char *proto);
   struct servent{
    char
           *s name;
    char **s aliases;
    int s_port;
    char
        *s proto;};
(...)
struct servent *remoteSvr;
remoteSvr = getservbyname("domain", "udp")
(\ldots)
```

# Looking up a protocal

```
struct protoent *getprotobynumber(int proto)
   Look up /etc/protocols to get result.
   struct protoent {
    char
         *p_name;
    char *p_aliases;
    short *p proto;};
(\ldots)
struct protoent *pptr;
pptr = getprotobyname("udp")
(...)
```

# Specifying a Local Address

■ When a client creates and binds a socket, it must specify a local port and IP address

Typically a client doesn't care what port it is working on:

```
haddr->port = htons(0);

Give me any available port!
```

# Local IP address

 A client can also ask the operating system to take care of specifying the local IP address:

```
haddr->sin_addr.s_addr=
htonl(INADDR_ANY);

Give me the appropriate address
```

# UDP Client Design

- □ Establish server address (IP and port).
- Allocate a socket.
- Specify that any valid local port and IP address can be used.
- Communicate with server (send, recv)
- Close the socket.

# Connected mode UDP

- A UDP client can call connect() to <u>establish</u> the address of the server
- □ The UDP client can then use read() and write() or send() and recv()
- □ A UDP client using a connected mode socket can only talk to one server
  - using the connected-mode socket

# TCP Client Design

- □ Establish server address (IP and port).
- Allocate a socket.
- Specify that any valid local port and IP address can be used.
- □ Call connect()
- □ Communicate with server (read, write).
- Close the connection.

# Closing a TCP socket

- Many TCP based application protocols support
  - multiple requests and/or
  - variable length requests over a single TCP connection.

- □ How does the server known when the client is done?
  - and it is OK to close the socket?

# Partial Close

- One solution is for the client to shut down only it's writing end of the socket.
- □ Shutdown() provides this function.
  shutdown(int s, int direction);
  - direction can be 0 to close the reading end or 1 to close the writing end.
  - shutdown sends info to the other process!

# TCP sockets programming

- □ Common problem areas:
  - null termination of strings.
  - reads don't correspond to writes.
  - synchronization (including close()).
  - \* ambiguous protocol.

# TCP Reads

- □ Each call to read() on a TCP socket returns any available data
  - up to a maximum
- □ TCP buffers data at both ends of the connection.
- You must be prepared to accept data 1 byte at a time from a TCP socket!

# Server Design

Iterative Connectionless

Iterative Connection-Oriented

Concurrent Connectionless Concurrent Connection-Oriented

## Concurrent vs. Iterative

#### Concurrent

Large or variable size requests
Harder to program
Typically uses more system resources

#### **Iterative**

Small, fixed size requests Easy to program

# Connectionless vs. Connection-Oriented

#### Connection-Oriented

EASY TO PROGRAM transport protocol handles the tough stuff. requires separate socket for each connection.

#### Connectionless

less overhead no limitation on number of clients

# Statelessness

■ State: Information that a server maintains about the status of ongoing client interactions.

Connectionless servers that keep state information must be designed carefully!

Messages can be duplicated!

# The Dangers of Statelessness

- Clients can go down at any time.
- Client hosts can reboot many times.
- □ The network can lose messages.
- □ The network can duplicate messages.

# Concurrent Server Design Alternatives

- One child per client
- Spawn one thread per client
- Preforking multiple processes
- Prethreaded Server

# One child per client

- □ Traditional Unix server:
  - \* TCP: after call to accept(), call fork().
  - \* UDP: after recvfrom(), call fork().
  - \* Each process needs only a few sockets.
  - Small requests can be serviced in a small amount of time.
- □ Parent process needs to clean up after children!!!!
  - call wait()

# One thread per client

- Almost like using fork
  - call pthread\_create instead
- Using threads makes it easier to have sibling processes share information
  - \* less overhead
- Sharing information must be done carefully
  - use pthread\_mutex

## Prefork () 'd TCP Server

- □ Initial process creates socket and binds to well known address.
- Process now calls fork() a bunch of times.
- □ All children call accept().
- □ The next incoming connection will be handed to one child.

# Preforking

Having too many preforked children can be bad.

- Using dynamic process allocation instead of a hard-coded number of children can avoid problems.
- Parent process just manages the children
  - doesn't worry about clients

# Sockets library vs. system call

- A preforked TCP server won't usually work the way we want if sockets is not part of the kernel:
  - calling accept() is a library call, not an atomic operation.
- We can get around this by making sure only one child calls accept() at a time using some locking scheme.

## Prethreaded Server

- Same benefits as preforking.
- □ Can also have the main thread do all the calls to accept()
  - \* and hand off each client to an existing thread

# What's the best server design for my application?

- Many factors:
  - \* expected number of simultaneous clients
  - Transaction size
    - time to compute or lookup the answer
  - Variability in transaction size
  - Available system resources
    - perhaps what resources can be required in order to run the service

# Server Design

■ It is important to understand the issues and options.

Knowledge of queuing theory can be a big help.

■ You might need to test a few alternatives to determine the best design.