

Introduction to the tetrahedron equation

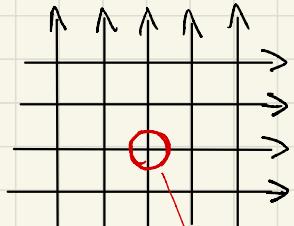
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§ 1 2D integrable lattice model and Yang-Baxter equation L1



2-dim. (square) lattice

To each edge we assign a "spin"

$$i \in \{1, 2, \dots, N\} \quad \dim V = N$$

$$E_{ij}^{kl}(u_a, u_b) = \begin{array}{c} u_b \\ \uparrow l \\ i \end{array} \begin{array}{c} k \rightarrow u_a \\ j \end{array}$$

$R_{ab}(u_a, u_b) \in \text{End}(V_a(u_a) \otimes V_b(u_b))$

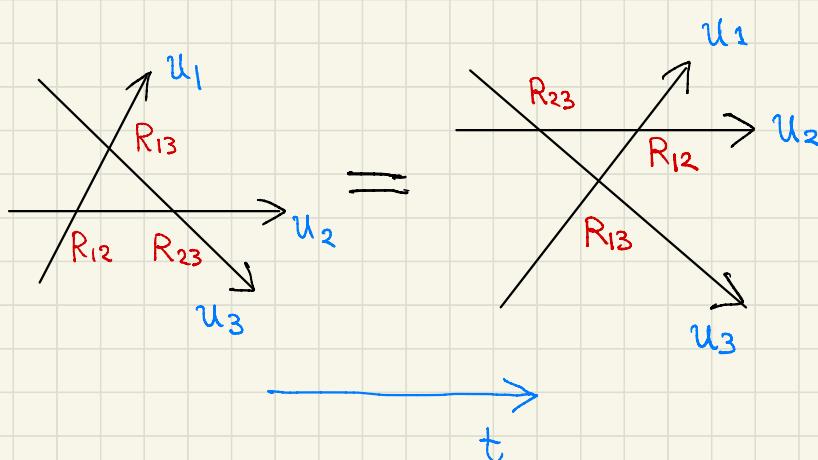
$$(R_{ab})_{ij}^{kl} := e^{-\beta E_{ij}^{kl}(u_a, u_b)}$$

R-matrix = the Boltzmann weight

"vertex model"

If the R-matrix satisfies the Yang-Baxter equation L^2

$$R_{23} R_{13} R_{12} = R_{12} R_{13} R_{23} \in \text{End}(V_1 \otimes V_2 \otimes V_3),$$



$$\begin{aligned} & R_{23} (R_{13} R_{12}) R_{23} \\ & " = " \quad \text{X} \\ & " = " \quad R_{12} R_{13} \end{aligned}$$

By the adjoint action of R_{23}
we can exchange R_{12} and R_{13} .

the vertex model is integrable.

∴

Infinite number of mutually commuting Hamiltonians H_n

$$n = 0, 1, 2, \dots$$

The symmetry underlying the art of the vertex model

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is the quantum affine algebra $A = U_q(\widehat{\mathfrak{sl}_n})$.

Coproduct $\Delta : A \longrightarrow A \otimes A$

$$P(x \otimes y) = y \otimes x$$

$$R \Delta = \Delta' R$$

R-matrix as the intertwiner of

$$\Delta \text{ and } \Delta' = P\Delta$$

§ 2 3 D generalization (Tetrahedron equation)

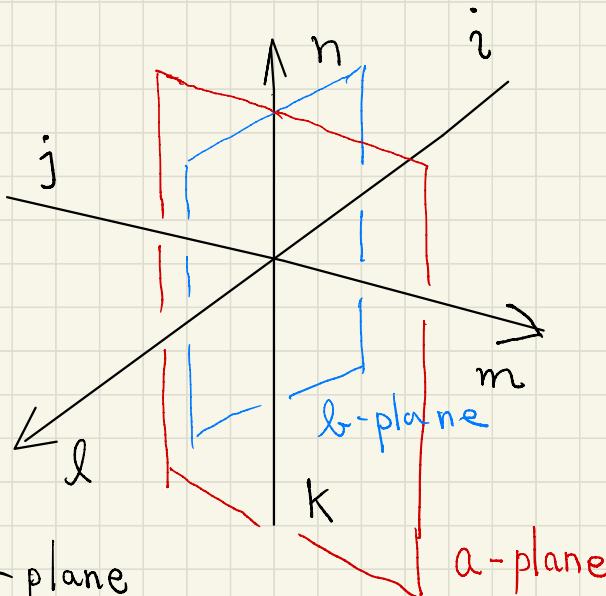
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2D (square) lattice \longrightarrow 3D (cubic) lattice

$$R_{abc} \in \text{End}(V_{bc} \otimes V_{ca} \otimes V_{ab})$$

$$(R_{abc})_{ijk}^{lmn} =$$

$V_{abc} \Leftrightarrow$ intersection
of a -plane and b -plane



$\mathcal{F} = \bigoplus \mathbb{C} |m\rangle$ a vector space with a basis $\{|m\rangle\}_{m \in \mathbb{Z}}^{\leq 5}$

$$R \in \text{End}(\mathcal{F}^{\otimes 3})$$

$$R(|i\rangle \otimes |j\rangle \otimes |k\rangle) = \sum_{l, m, n} R_{ijk}^{lmn} (|l\rangle \otimes |m\rangle \otimes |n\rangle)$$

$$\Rightarrow \sum_{l, m} |l\rangle \otimes |m\rangle \otimes R_{ij}^{lm} |k\rangle$$

$$R_{ij}^{lm} \in \text{End}(\mathcal{F})$$

$$R_{ij}^{lm} |k\rangle = \sum_n R_{ijk}^{lmn} |n\rangle$$

~~~~~ A vertex model with an  $\text{End}(\mathcal{F})$ -valued  
 Boltzmann weight  $R_{ij}^{lm}$

the tetrahedron equation

A.B. Zamolodchikov (1980)

$$R_{124} R_{135} R_{236} R_{456} = R_{456} R_{236} R_{135} R_{124}$$

$$\in \text{End } (\mathcal{F}_1 \otimes \mathcal{F}_2 \otimes \mathcal{F}_3 \otimes \mathcal{F}_4 \otimes \mathcal{F}_5 \otimes \mathcal{F}_6)$$

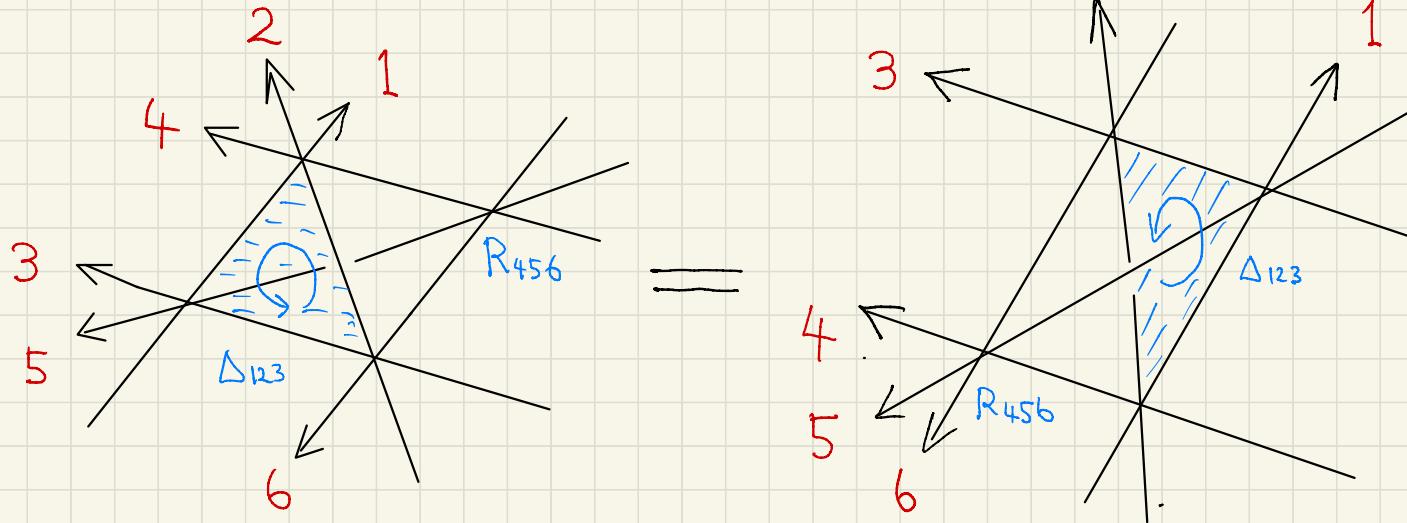
$$R_{124} \xrightarrow{\wedge} \hat{R}_{12} \quad R_{135} \xrightarrow{\wedge} \hat{R}_{13} \quad R_{236} \xrightarrow{\wedge} \hat{R}_{23}$$

$$\hat{R}_{12} \quad \hat{R}_{13} \quad \hat{R}_{23} \cong \hat{R}_{23} \quad \hat{R}_{13} \quad \hat{R}_{12} \quad \text{up to the conjugation by } R_{456}$$

This may be regarded as a quantization of Yang-Baxter eq.

along the direction of the auxiliary sp.  $\mathcal{F}_4 \otimes \mathcal{F}_5 \otimes \mathcal{F}_6$

## Graphical representation



$$R_{124} R_{135} R_{236} R_{456} = R_{456} R_{236} R_{135} R_{124}$$

Dual description : assign  $R_{abc}$  to each face  
 vertex formalism v.s. face formalism

### § 3 Solution to the tetrahedron eq.

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The tetrahedron eq. is a highly overdetermined system

$\dim \mathcal{F} = N \Rightarrow N^{12}$  conditions for  $N^6$ -components

We can construct a solution based on q-Weyl algebra

Inoue - Kuniba - Sun - Terashima - Yagi (2024)

$$[u_i, w_j] = \hbar s_{ij}, \quad [u_i, u_j] = [w_i, w_j] = 0$$
$$q = e^\hbar \quad i, j = 1, 2, 3$$

$$\mathcal{F} = \bigoplus_{n_1 \in \mathbb{Z}} \mathbb{C} \langle n_1, n_2, n_3 \rangle, \quad \mathcal{F}^* = \bigoplus_{n_1 \in \mathbb{Z}} \mathbb{C} \langle n_1, n_2, n_3 \rangle$$

$$e^{u_k} |n\rangle = q^{n_k} |n\rangle \quad e^{u_k} \langle n| = q^{n_k} \langle n| \quad 9$$

$$e^{w_k} |n\rangle = |n + e_k\rangle \quad e^{w_k} \langle n| = \langle n - e_k| \quad ,$$

$$R \in \text{End } (\mathcal{F})$$

$$R = \mathbb{I}_q (e^{u_1 + u_3 + w_1 - w_2 + w_3})^{-1} \mathbb{I}_q (e^{u_1 - u_3 + w_1 - w_2 + w_3})$$

$$P \mathbb{I}_q (e^{u_1 - u_3 + w_1 - w_2 + w_3}) \mathbb{I}_q (e^{u_1 + u_3 + w_1 - w_2 + w_3})$$

$$\mathbb{I}_q(Y) = \frac{1}{(-qY; q^2)_\infty} = \sum_{n=0}^{\infty} \frac{(-qY)^n}{(q^2; q^2)_n}$$

quantum dilog. =  $q$ -exponential

$$P = e^{\frac{t}{h}^{-1} (u_3 - u_2) w_1} \quad \text{S}_{23} \leftarrow \text{transposition}$$

Prop [IKSTY (2024)]

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The matrix elements

$$R_{n'_1 n'_2 n'_3}^{n_1 n_2 n_3} = \langle n | R | n' \rangle \text{ are}$$

$$R_{n'_1 n'_2 n'_3}^{n_1 n_2 n_3} = \delta_{n'_1 + n'_2}^{n_1 + n_2} \delta_{n'_2 + n'_3}^{n_2 + n_3} \frac{g^{n_1 n_3 + n'_2}}{2\pi i} \oint \frac{d\bar{z}}{\bar{z}^{n'_2 + 1}} \frac{(-\bar{z} g^{2+n_1+n_3}; g^2)_{\infty} (-\bar{z} g^{-n_1-n_3}; g^2)_{\infty}}{(-\bar{z} g^{n'_1-n'_3}; g^2)_{\infty} (-\bar{z} g^{n'_3-n'_1}; g^2)_{\infty}}$$

$$= \delta_{n'_1 + n'_2}^{n_1 + n_2} \delta_{n'_1 + n'_3}^{n_2 + n_3} (-1)^{n'_2} g^{n_1 n_3 + n_2 (n'_3 - n'_1)} \begin{pmatrix} n'_1 + n'_2 \\ n'_1 \end{pmatrix}_{g^2} {}_2\phi_1 \left( \begin{matrix} -2n'_2, & -2n_1 \\ g^{-2(n'_1 + n'_2)} & ; g^2, g^2 \end{matrix} \right)$$

## § 4 Relation to supersymmetric gauge theory

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Awata - Hasegawa - K - Ohkawa - Shakirov - Shiraishi - Yamada

(2023 + work in progress)

Non stationary difference equation

for the instanton counting partition function

on  $\mathbb{R}^4 \times S_g^1$   $q_b \sim e^{\hbar R}$   $R$ : radius of  $S^1$

$$\mathbb{I}(\Delta, x) = \sum_{k, l \geq 0} C_{k, l} x^k \left(\frac{\Delta}{x}\right)^l$$

$$C_{k, l} = C_{k, l}(q, d_1, \dots, d_4; q_b, t)$$

$$T_{gtQ, x} T_{t, \Lambda} \Psi(\Lambda, x) = \mathcal{Y}_S(d_1, \dots d_4; g) \Psi(\Lambda, x)$$

$T_{t, \Lambda} : \Lambda \rightarrow t\Lambda$  "time" shift

When  $d_2 = g^{-n}$ ,  $d_4 = g^{-m}$   $n, m \in \mathbb{Z}_{\geq 0}$

$\Psi(\Lambda, x) \Rightarrow \sum_{i=-n}^m \tilde{c}_i(\Lambda) x^i$  consistent truncation  
to a finite series in  $x$ .

$$\mathcal{Y}_S x^i = \sum_{j=-n}^m \underline{r_{i,j}(\Lambda, d_1, d_3; g) x^j}$$

↑  
R-matrix of  $\hat{U}_g(\mathfrak{sl}_2)$

with spin  $N = n+m$

Observation  $r_{i,j}(\Lambda; d_1, d_3; g)$  is given by 13

the trace of the product of 3D R-matrix

(up to a similarity transformation or a base change.)

$$B_N = \{ i = (i_1, i_2) \in \mathbb{Z}_{\geq 0} ; i_1 + i_2 = N \}$$

$$|B_N| = N+1$$

$R_{i,j,k}^{a,b,c}$  : matrix elements of 3D R matrix

$$R_{i,j}^{tr_3(\bar{x})}{}^{a,b} = \sum_{c_1, c_2} \bar{x}^{c_1} R_{i_1, j_1, c_2}^{a_1, b_1, c_1} R_{i_2, j_2, c_1}^{a_2, b_2, c_2}$$

$$a, b, i, j \in B_N$$

By the conservation law  $i+j = a+lb \Rightarrow M$  [14]

$$(R^{tr_3}(z)_{ij}^{ab}) \sim \delta_{i+i_2}^{a_1+b_1} \delta_{j+j_2}^{a_2+b_2}$$

$$R^{tr_3}(z)_{ij}^{ab} = R^{tr_3}(z; M)_i^a \quad (N+1) \times (N+1)$$

matrix.

$$\sim r_{i,j}(\Lambda, d_1, d_3; g)$$

$$(\Lambda \Rightarrow z \quad d_1 = g^{-\mu_1}, \quad d_3 = g^{-\mu_2})$$

A formal analytic continuation to complex parameters  $d_1 \dots d_4$  //

Continuous or unbounded spin variables imply  
a third direction of space ??