

Geometry

Elijah Sheridan

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Chapter 1

Introduction

What follows endeavors to encapsulate the author's knowledge of geometry (and the notions upon which it depends, which decidedly extend well beyond the boundaries of geometry itself) as he studies theoretical particle physics and string theory.

Chapter 2

Manifolds

2.1 Construction

Let M be a second-countable¹, Hausdorff², locally Euclidean topological space of dimension n . We define an equivalence relation on the set of homeomorphisms between open subsets of M and \mathbb{R}^n given by $\phi \sim \psi$ when $\psi \circ \phi^{-1}$ is smooth. We then choose a $\mathcal{U} = \{(U_\alpha, \phi_\alpha)\}$ (i.e., $\phi_\alpha : U_\alpha \rightarrow \mathbb{R}^n$) such that the $\{U_\alpha\}$ cover M and the $\{\phi_\alpha\}$ are an equivalence class: this is denoted a maximal atlas³. We then say that M is an n -dimensional smooth manifold⁴ (or manifold). Let $(\phi, U) \in \mathcal{U}$: ϕ is a coordinate chart (or chart) and the components of ϕ , x^i

¹Arguably, the truly important property here is paracompactness, which is slightly stronger and enables partitions of unity (enabling local-to-global promotions). However, it is a result that Hausdorff, second countable, locally compact space is paracompact (and we get local compactness follows from locally Euclidean). Second countability also contributes to the feasibility of Euclidean embeddings and other nice, preferable behavior.

References: Second countability and manifolds

²Hausdorff topological spaces feature points which are sufficiently disjoint: in particular, calculus depends upon limits, and Hausdorff \implies unique limits as desired (note, though, that the converse isn't true).

³Definitions vary here (indeed, it is more conventional to merely require "maximal" atlases) but the general motivation is as follows: given a chart ϕ on a manifold M , there are likely uncountably many collections of charts covering M containing ϕ , but there is a *unique* (i.e., canonical) choice of equivalence class of charts containing ϕ .

References: Axiom of choice and maximal atlases

⁴Our consideration of differential topology/geometry is motivated by physics, which interests itself in the dynamics (or change) of our universe. Calculus, in a word, is the mathematics of change: hence, we are interested in studying the *least structured* space that permits the calculus. This is not Euclidean space itself but rather a smooth manifold, a space that need only resemble Euclidean space *locally*.

(i.e., $\phi_\alpha(m) = (x^1(m), \dots, x^n(m))$), are extcolor{blue}{coordinates}. We say real-valued maps are extcolor{blue}{functions} (e.g., the x^i are functions).

2.2 Smooth Maps

Given another manifold N , we say $f : V \rightarrow N$ is a extcolor{blue}{smooth map} (or smooth) for an open set $V \subseteq M$ when for all $m \in U$, there exist charts ϕ and ψ defined around m and $f(m)$ such that $\psi \circ f \circ \phi^{-1}$ is smooth. Given $f : U \rightarrow N$ for arbitrary $U \subset M$, we say the same when f is the restriction of a smooth map on some open $W \supseteq V$. We call smooth maps with smooth inverse extcolor{blue}{diffeomorphisms}. We use $C^\infty(M)$, $\text{Diff}(M, N)$, and $\text{Diff}(M)$ to denote the spaces of smooth functions on M , diffeomorphisms $M \rightarrow N$, and diffeomorphisms $M \rightarrow M$, respectively. From this point forward, all maps are smooth unless otherwise specified.

2.3 Tangent Spaces

Let $T_m M$ denote the extcolor{magenta}{vector space} of extcolor{magenta}{linear derivations} on the (vector) space of extcolor{magenta}{germs} of functions defined around m , F_m . Equivalently, let $T_m M$ be the extcolor{magenta}{quotient ring} $(F_m/F_m^2)^*$, where $*$ denotes the extcolor{magenta}{dual space}⁵. $T_m M$ has dimension n , and we call it the extcolor{blue}{tangent space} to M at m and elements of $T_m M$ extcolor{blue}{vectors}. There is a natural map $f \mapsto f_*$ from the set of smooth functions $M \rightarrow N$, denoted $C^\infty(M, N)$, to the set of extcolor{magenta}{endomorphisms} $T_m M \rightarrow T_{f(m)} N$ given by $f_* X(g) \mapsto X(g \circ f)$ (where $X \in T_m M$ and $g \in C^\infty(M)$, the extcolor{magenta}{ring} of smooth functions on M). We call f_* the extcolor{blue}{pushforward} of f . We define $T_m^* M$ to be the extcolor{blue}{cotangent space} to M at m , and we have the dual map $f \mapsto f^*$, the extcolor{blue}{pullback}, acting as $T_{f(m)}^* N \rightarrow T_m^* M$ by $f^* A(X) = A(f_* X)$. There is additionally a natural map $d : C^\infty(M) \rightarrow T_m^* M$ given by $f \mapsto df(m) = v \mapsto v(f)$, which we call the extcolor{blue}{differential}. Given a chart ϕ around M , a basis for $T_m M$ is given by $\frac{\partial}{\partial x^i}$ or ∂_i , given by

$$\partial_i f = \frac{\partial(f \circ \phi^{-1})}{\partial r^i} \Big|_m \quad (2.1)$$

where r^i is the i th Euclidean coordinate. A basis is also given for $T_m^* M$ by the dx^i . Finally, we define the extcolor{blue}{tangent bundle} $TM = \cup_{m \in M} T_m M$ and the extcolor{blue}{cotangent bundle} $T^* M = \cup_{m \in M} T_m^* M$; both are $2n$ -dimensional smooth manifolds equipped with natural projection maps onto M .

⁵TODO: prove equivalence of definitions.

Chapter 3

Fibre Bundles

3.1 Construction

Let M, F be manifolds and E be a extcolor{blue}{fibre bundle} with extcolor{blue}{base} M and extcolor{blue}{fibre} F , or a manifold endowed with a surjective projection $\pi : E \rightarrow M$ such that M admits an open covering $\{U_\alpha\}$ for which each U_α has a diffeomorphism $\phi_\alpha : \pi^{-1}(U_\alpha) \rightarrow U_\alpha \times F$ acting by $p \rightarrow (\pi(p), \xi_\alpha(p))$ for $p \in P$ and some $\xi_\alpha : U_\alpha \rightarrow \text{Diff}(F)$. This implies $\pi^{-1}(m)$ is diffeomorphic to F ; we say E is locally a product of M and F and that the (U_α, ϕ_α) is a extcolor{blue}{local trivialization}. On $U_\alpha \cap U_\beta$ we have functions $\phi_{\alpha\beta} = \phi_\alpha \circ \phi_\beta^{-1} : (U_\alpha \cap U_\beta) \times F \rightarrow (U_\alpha \cap U_\beta) \times F$ given by $(m, x) \mapsto (m, \xi_{\alpha\beta}(m)(x))$ for some $\xi_{\alpha\beta}(m) \in \text{Diff}(F)$ called extcolor{blue}{transition functions}. Sometimes we require $\xi_{\alpha\beta}(m) \in G$, a extcolor{blue}{topological group} acting on F on the left by diffeomorphisms (i.e., a subgroup of $\text{Diff}(F)$). If a fibre bundle's local trivializations satisfy this maximally, we say E is a extcolor{blue}{ G -bundle}, and that G is the extcolor{blue}{structure group}. We note that $\xi_{\alpha\alpha} = 1$, $\xi_{\alpha\beta} = \xi_{\beta\alpha}^{-1}$, and the extcolor{blue}{cocycle condition} $\xi_{\alpha\beta} \circ \xi_{\beta\delta} \circ \xi_{\delta\alpha} = 1$ holds on triple overlaps. Fibre bundles are uniquely determined by the base manifold and the transition functions. Given a manifold N and a map $g : N \rightarrow M$, the pullback bundle g^*E is the subset of $N \times E$ such that $g \circ \text{proj}_1 = \pi \circ \text{proj}_2$ with projection $\text{proj}_1 : g^*E \rightarrow N$. A extcolor{blue}{vector bundle} is a fibre bundle whose fibres are vector spaces and whose local trivializations are fibre-wise linear isomorphisms.

3.2 Lie Groups

A extcolor{blue}{Lie group} G is a smooth manifold with group structure such that the binary operation is smooth.¹ Elements $g \in G$ induce $R_g, L_g, A_g \in \text{Diff}(G)$ by $R_g : h \mapsto hg$, $L_g : h \mapsto gh$, and $A_g = L_g \circ R_{g^{-1}} : h \mapsto ghg^{-1}$.

3.3 Principal Bundles

Let G be a Lie group and P be a extcolor{blue}{principle G -bundle} with base M , or a G -bundle over M with fibre G and transition functions given by left multiplication. Because left and right multiplication commute, we have an invariant right action of G on P ². Equivalently, a principle G -bundle P is a fibre bundle with a extcolor{magenta}{regular} smooth right action by a Lie group G that preserves fibres and the ξ_α are G -equivariant. It follows that $P/G = M$ ³ and E admits a local trivialization with $M \times G$.

3.4 Associated Bundles

3.5 Sections

3.5.1 Vector Fields

3.5.2 Tensor Fields

3.5.3 Differential Forms

¹Some authors require the inverse map $g \mapsto g^{-1}$ to be smooth as well, but this follows from the smoothness of the binary operation.

²If $p \in \pi^{-1}(U_\alpha)$ and $\phi_\alpha(p) = (m, h)$, then $pg = \phi_\alpha^{-1}(m, hg)$.

³The second definition admits an exchange between fibre-preservation and $P/G = M$

Chapter 4

Lie Theory

4.1 Lie Algebras

Let G be a Lie group. A vector field X on G satisfying $(L_g)_*X = X \circ L_g$ is called **left invariant**. The **Lie algebra** to G , \mathfrak{g} , is the set of all left-invariant vector fields on G ; the name is natural as the Lie bracket induces a Lie algebraic structure on this set. Note that \mathfrak{g} is naturally isomorphic to $T_e G$, where e is the identity element, as $Y \in T_e G$ induces a vector field X given by $X_g = (L_g)_*Y$; in particular, this means $\dim \mathfrak{g} = \dim G$. Given a basis X_1, \dots, X_n of \mathfrak{g} , we have that $[X_i, X_j] = c_{ij}^h X_h$ and we say the c_{ij}^h are the **structure constants** associated with the basis. Identifying $\mathfrak{g} \cong T_e G$ there is a natural \mathfrak{g} -valued one-form θ on G defined by $v \mapsto (L_{g^{-1}})_*(v)$ for $v \in T_g G$. We call this the **Maurer-Cartan one-form**. Noting that, if G is a matrix Lie group, $(L_g)_*$ coincides with the natural matrix multiplication action of the matrix g on TG , we have that $\theta(v) = g^{-1}v$ where the right hand side is matrix multiplication¹.

A **one-parameter subgroup** on G is a continuous group homomorphism $\mathbb{R} \rightarrow G$. For $X \in \mathfrak{g}$, let $\phi_{X,t} : G \rightarrow G$ be the associated flow, and let $g_X(t) = \phi_{X,t}(e) \in G$; then g_X is a one parameter subgroup on G (i.e., $g_X(t)g_X(s) = g_X(t+s)$). Moreover, we have the **exponential map** $\exp : \mathfrak{g} \rightarrow G$ given by $X \mapsto g_X(1)$. From this it follows that $g_X(t) = \exp(tX)$; indeed, this is the most general form for a one parameter group.

TODO: adjoint representation and Maurer-Cartan structure formula

¹If we let G be embedded in a matrix Lie group by a map ϕ , then the Maurer-Cartan form on $\phi(G)$ is $\theta = \phi(g^{-1})\phi_*$.

Chapter 5

Connections

To each $A \in \mathfrak{g}$ we can naturally associate a fundamental vector field A^* on P given by $(A^\#)(p) = (\sigma_p)_*(A)$, where $\sigma_p : G \rightarrow P$ is the map $g \mapsto pg$. Equivalently, $(A^\#)(p)$ is the tangent vector to the curve $(\sigma_p \circ \exp)(At)$ at $t = 0$. Define $V_p = T_p \pi^{-1}(p) = \ker(\pi_*) \cap T_p P$, the vertical subspace of $T_p P$; $A \mapsto (A^*)_p$ is an isomorphism $\mathfrak{g} \mapsto V_p$. Moreover, $A \mapsto A^\#$ is equivariant with respect to the adjoint and principal actions of G and preserves the respective Lie brackets. The vertical bundle $VP = TP$ is the vector subbundle of these vertical subspaces.

To a principal bundle we can associate an Atiyah sequence

where ι is the natural inclusion and $\bar{\pi}$ is the map $X \mapsto (\pi_{TP}(X), (\pi_P)_*(X))$. A connection on P is a choice of equivariant split for this sequence (direct sum, left, and right splits are equivalent). Explicitly, the G actions are the diagonal action (identifying $VP \cong P \times \mathfrak{g}$), the canonical action, and the induced action from $P \times TM$ leaving TM invariant, respectively.

In particular, a direct sum split φ is frequently identified with the vector subbundle $HP = \varphi^{-1}(0 \oplus \pi^*TM)$, which is complementary to VP and invariant under $(R_g)_*$ for $g \in G$ and referred to as an Ehresmann connection. Left splits can be understood as G -equivariant \mathfrak{g} -valued one-forms on P , commonly referred to as connection one-forms. Right splits are interpreted as maps sending a vector in $T_m M$ to one in any $T_p P$ for $p \in \pi^{-1}(m)$ and are known as horizontal lifts.

Chapter 6

Complex Manifolds

We have finished a nice book.

Chapter 7

Spin Geometry

References

Appendix A

Tensors

Appendix B

Algebraic Topology