

# Trevor Sherrard

## CONTACT ME

---

📍 3474 Nathaniel Rochester Hall  
Rochester, NY 14623  
☎ +1 (440) 799-2705  
✉ tws4129@rit.edu  
🌐 [www.trevorsherrard.com](http://www.trevorsherrard.com)

## SUMMARY

---

I am a roboticist, and machine vision enthusiast. I am a fourth year college student with a passion for seeing my software come alive in robotics and machine vision projects. I am currently seeking a Spring-Summer 2017 Co-Op.

## WORK EXPERIENCE

---

SEPTEMBER 2016 – PRESENT

RIT Research Computing

### *Assistant Systems Administrator*

Responsible for assisting in the upkeep of RIT research computing infrastructure. Helped design workflow for faculty and graduate research students using Torch, Caffe and Cuda.

NOVEMBER 2014 – JULY 2015

Cuyahoga Community College

### *Physics Student Lab Assistant*

Responsibilities included taking down and setting up laboratory experiments for earth science and physics classes. Also assisted professors during the lab with answering students' questions about the material at hand.

JUNE 2012 – JULY 2015

Saint Edward High School

### *Engineering Camp Instructor*

Worked the summers of 2012, 2013, 2014 and 2015. Helped promote interest in STEM related fields, specifically robotics and computer science, to middle school students. Duties included material procurement and classroom instruction.

## EDUCATION

---

2015 – PRESENT **Rochester Institute of Technology**  
B.S ELECTRICAL ENGINEERING; ROBOTICS  
*Computer Science House*

2014 – 2015 **Cuyahoga Community College**  
COMMUNITY COLLEGE  
*Physics Club*

## ROBOTICS PROJECTS

---

- 2014 **SortME** (<http://www.trevorsherrard.com/SortME.html>)  
*My Computer Vision Robot Platform*
- 2015 **RoveME** (<http://www.trevorsherrard.com/RoveME.html>)  
*My Large scale, built from scratch ROS robot. Built from a basic andymark differential drive robot chasis, RoveME is my personal robotics testbed.*
- 2015 **ToolID** (<http://www.trevorsherrard.com/ToolID.html>)  
*Automatic tool identification for the computer science house project room. Allows user to query the type of tool using computer vision and HAAR classifiers. A laser diode on a two axis stepper motor gimbal will then point to where that tools resting location is.*

## COMPUTER VISION PROJECTS

---

- 2014 **HAAR Training Tutorial Web Page** ([http://www.trevorsherrard.com/Haar\\_training.html](http://www.trevorsherrard.com/Haar_training.html))  
*A tutorial I wrote on how to train HAAR classifiers using OpenCV. It covers everything from sample preparation to training itself.*
- 2015 **Mobile HAAR tester application** (<http://www.trevorsherrard.com/ComputerVision.html>)  
*An application that uses the OpenCV on the android platform to test mobile classifiers on the go. It allows for downloading of classifier on the go from a URL.*
- 2015 **CSH Augmented Reality Logo** (<https://youtu.be/dx1Ek2E-Dck>)  
*An Augmented Reality project for the Computer Science House at RIT.*

## PROFESSIONAL SKILLS

---

ADVANCED LEVEL C++, ROS, OpenCV,  
Robot Drive Kinematics

INTERMEDIATE LEVEL Python, Verilog, VHDL,  
PID, Linux, LiDAR

BASIC LEVEL Torch, Caffe,  $\LaTeX$