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<u>How to generate 2d map in rviz:</u>
1). start roscore
2). start kinect+rgbdslam
3). drive around and generate map of room.
4). Start octomap-server
5). send data from kinect+rgbdslam to octomap-server (Ctrl-M)
6). start rviz
7). add /projected_map topic
8). use move_base navigation using map