Research on Design and Analysis of Experiments

- Surrogates (Athey, Chetty, Imbens, Kang, 2016, update coming shortly)
- Heterogeneous treatment effects (Wager & Athey (JASA, 2018); Athey, Tibshirani, and Wager (AOS, 2019); Friedberg, Athey, Tibshirani, and Wager (2018)
- Offline policy estimation (Athey and Wager, 2017; Zhou, Athey, and Wager 2018)
- Improving estimation model used in contextual bandit algorithms (Dimakopoulou, Zhou, Athey and Imbens, AAAI, 2018)
- Survey Athey & Imbens, The Econometrics of Randomized Experiments (Handbook of Experimental Economics)

TODAY:

- Designing experiments with staggered rollouts (Xiong, Athey, Bayati, Imbens 2019)
- Testing hypotheses using adaptively collected data (Hadad, Hirschberg, Zhan, Wager, Athey, 2019)

Recent work on causal inference with panel data

Matrix factorization in Consumer Choice settings

- Donnelly, Ruiz, Blei, and Athey (2019), Ruiz, Athey and Blei (AOAS, 2019), Athey, Blei, Donnelly, Ruiz, and Schmidt (AEA P&P, 2018)
- Augment traditional mixed/nested logit models with matrix factorization for random coefficients
- Tune for causal effects, test with held-out experiments

Matrix Completion for Panel Data Models

- Athey, Bayati, Doudchenko, Imbens, Khosravi, 2017
- When evaluating staggered rollouts, use matrix completion to construct counterfactual outcomes

Synthetic Difference-in-Differences

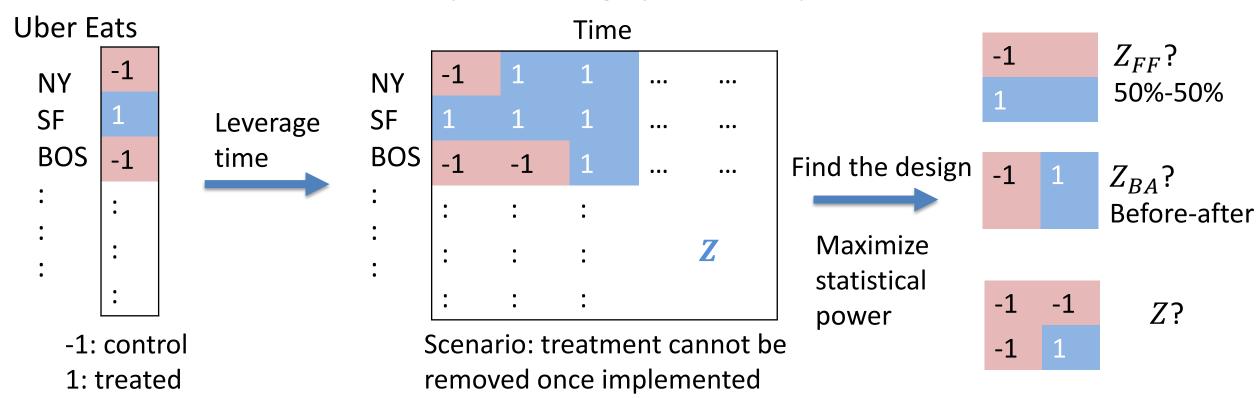
- Arkhangelsky, Athey, Hirschberg, Imbens, Wager, 2018
- Builds on ideas of double robustness in causal inference
- Combine outcome models (e.g. matrix completion) with weighting that focuses on similar units and time periods
- This paper: Design experiments anticipating future hypothesis testing
 - Take the matrix completion approach to outcome modeling for tractability

Optimal Experimental Design for Staggered Rollouts

Ruoxuan Xiong, Susan Athey, Mohsen Bayati, Guido Imbens Stanford University

Statistical Power: A Fundamental Challenge

- Randomized controlled experiments are the gold standard to draw inference about whether a product or an intervention is effective.
- Fundamental challenge: Low power due to small sample size:
 - Avoid contamination and network effects
 - Relevant units are market, product category, school, hospital...



Related Literature

- Related work: optimal allocation of clusters for a multi-period design
 - Hussey and Hughes 2007, Hemming et al. 2015, Li et al. 2018
- Contribution of this paper
 - 1. Study the optimal multi-period design under a general class of linear models
 - 2. Allow to use historical control data to find a better design

Problem Formulation: Optimization

- Model, for all $(i, t) \in \{1, ..., N\} \times \{1, ..., T\}$ $Y_{it} = \alpha_i + \beta_t + u_i^T v_t + \tau z_{it} + \varepsilon_{it}$
- Optimization problem: given $\hat{\tau}$, solve $Z = [z_{it}]$

min $Var(\hat{\tau})$ Maximize statistical power Z_{it}

s.t. $z_{it} \le z_{it+1}$ Treatment cannot be removed once implemented $z_{it} \in \{-1,1\}$ -1: control, 1: treated

- Integer programming
- Estimation: Best Linear Unbiased Estimator (BLUE) to estimate τ
 - Explicit formula for $Var(\hat{\tau})$ in terms of Z

Observed : Y_{it} , z_{it}

Unknown: $\alpha_i, \beta_t, \overline{\mathbf{\tau}}, \varepsilon_{it}, u_i, v_t$

 α_i , β_t : unit, time fixed effects

 u_i : latent covariates

 z_{it} : treatment status

\tau: treatment effect

NY	-1	1	1		
SF α_i BOS	1	1	1		
$_{lpha_i}$ BOS	-1	-1	1		•••
	:	•	•		
:	:	:	:	Z	
:	:	•	•		

Time

 β_t

Main Result

• N units, T periods, and $Y_{it} = \alpha_i + \beta_t + u_i^T v_t + \tau z_{it} + \varepsilon_{it}$ with $z_{it} \in \{-1,1\}$

Theorem. If u_i takes finitely many values, then any design that has **staggered rollouts** with $\frac{2t-2}{2T}$ 100% treated for each **strata** at time t is an **optimal** solution to $\min_{\substack{[z_{it}] \in [-1,1]^{N \times T} \\ z_{it} \leq z_{it+1}}} Var(\hat{\tau})$

Some intuition why?

-1	-1
-1	-1
1	1
1	1

Only time effect β_t Z_{FF} : 50%-50%

-1	1
-1	1
-1	1
-1	1

Only unit effect α_i Z_{BA} :Before-after

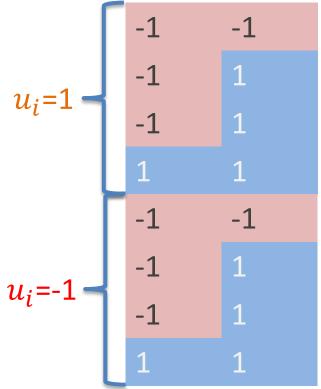
Both effects: $\frac{2t-2}{2T}$

Main Result

• *N* units, *T* periods, and $Y_{it} = \alpha_i + \beta_t + u_i^T v_t + \tau z_{it} + \varepsilon_{it}$ with $z_{it} \in \{-1,1\}$

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Strata: units with the same covariate values



Uber Eats

 u_i : quality of restaurants

 u_i =1: good

 u_i =-1: bad

Main Result

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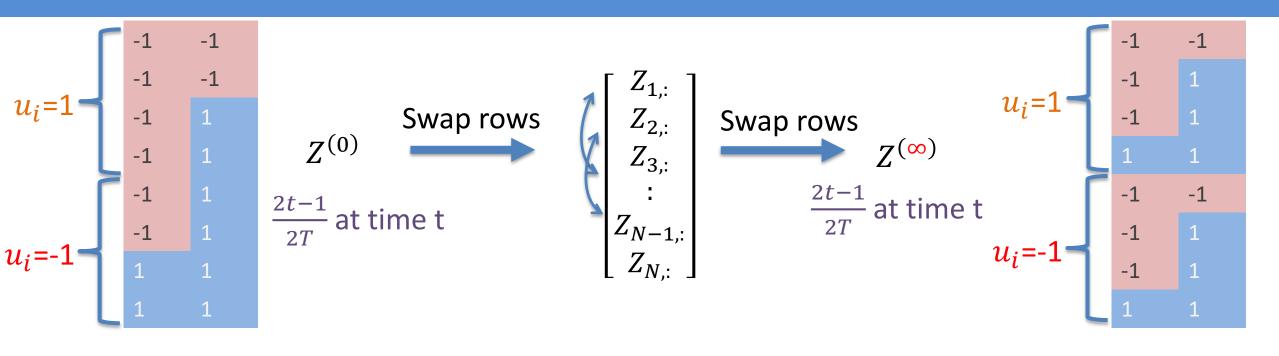
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Remark 1: This result holds regardless of whether u_i is known or latent

Remark 2: For general u_i use a clustering algorithm (e.g., K-means) to stratify

Next: A data-driven heuristic to stratify, when u_i 's are latent

A Local Search Heuristic to Stratify



- Step 1. Preprocess historical data: split historical data into several matrices
- Step 2. Minimax decision rule: synthetic experiment τ on each matrix with estimator $\hat{\tau}^{(j)}$
- Find the Z to minimize $\max_{j} |\hat{\tau}^{(j)} \tau|$. (Robust measure)
- Step 3. Local Search Z (simulated annealing)

Empirical Application

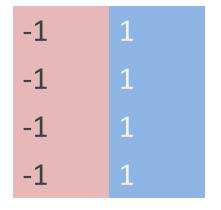
- Purchases from a large grocery store
 - 17,880,248 transactions between May 2005 and May 2007
 - Aggregated weekly net expenditure by household
 - 63,375 households over 97 weeks
 - 85.4% entries to be 0
- Hypothetical experiments:
 - Promotions, coupons, ads, etc.

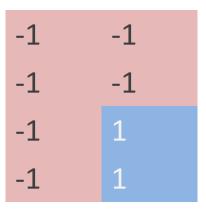
— ...

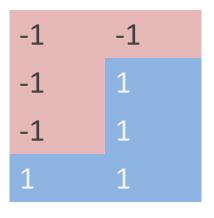
Empirical Application: Comparison

Design matrices

-1	-1
-1	-1
1	1
1	1







 Z_{FF} 50% control 50% treated at every time period

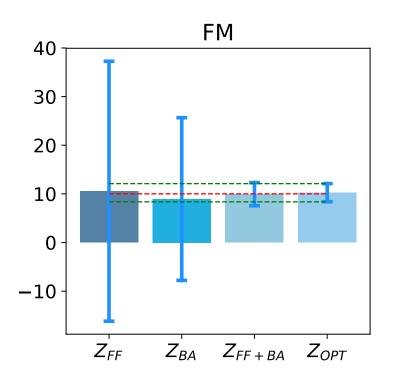
 Z_{BA} First half all control second half all treated

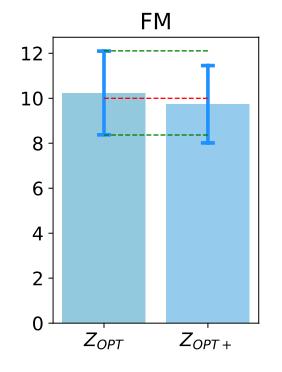
 Z_{FF+BA} First half all control second half half treated

 Z_{OPT} Staggered rollouts % treated: $\frac{2t-1}{2T}$

Results

- Z_{OPT} outperforms benchmark matrices Z_{FF} , Z_{BA} , Z_{FF+BA} for all estimation methods
- Factor model has RMSE about half of linear fixed effect model
- Using historical data, local search heuristic with minimax decision rule provides a better matrix Z_{OPT+} than Z_{OPT} for all estimation methods





Red dash line: true value

Bar height: average estimated value

Error bar: variance

RMSE: 26.73 16.76 2.37 **1.88**

1.88

1.74

Conclusion

- Optimal multi-period design
 - Linear treated portion in time with stratification (randomize the treatment allocation within each strata, the units with the same covariates' value)
- A data driven data-driven heuristic to stratify
 - Based on local search with minimax decision rule using historical control data
- Extension: Treatment effect varies over time
 - Optimal design starts with lower % treated, increases faster, in order to learn time-dependent treatment effects
- Empirics: synthetic experiments on several real world data sets
 - Various domains, including retail and health care
 - Superior performance of the analytical solution and our algorithm compared with the benchmark designs

Confidence Intervals for Policy Evaluation in Adaptive Experiments

Vitor Hadad David A. Hirshberg Ruohan Zhan Stefan Wager Susan Athey

> Graduate School of Business Stanford University vitorh@stanford.edu

> > November, 2019

Adaptive Experimentation

The promise

Multi-armed bandit experiments can be a substantially more efficient optimization method than traditional experiments. ¹

¹ Scott, S. L. (2015). Multi-armed bandit experiments in the online service economy. Applied Stochastic Models in Business and Industry, 31(1), 37-45.

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What do we want to *optimize*?

Standard for bandits: Low regret during the experiment

But for innovation, understanding, scientific discovery, also want:

- Statistical accuracy
- ► Valid confidence intervals
- ► *Power* for the hypothesis test

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These goals can be at odds with each other.

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You are given data $\{(W_t, Y_t)\}_{t=1}^T$ coming from an adaptive experiment. How would you estimate the value of arm w?

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Sample average

$$\widehat{Q}^{Sample}(w) = \frac{1}{n_w} \sum_{t:W_t = w} Y_t$$

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- In a randomized control trial: unbiased, consistent
- ▶ In a sequential experiment: possibly biased and inconsistent ¹

¹[Xu et al., 2013, Bowden and Trippa, 2017, Nie et al., 2018, Shin et al., 2019]

An *unbiased* estimator

Inverse Propensity Weighted Estimator

$$\widehat{Q}^{IPW}(w) = \frac{1}{T} \sum_{t=1}^{T} \frac{\mathbb{I}\left\{W_{t} = w\right\}}{e_{t}(w)} Y_{t}$$

Notation: $e_t(w)$ is probability of selecting arm w at t

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- ► Intuition:
 - Adaptive data collection introduces sample bias
 - ► Up/down weight observations to counter bias

An *unbiased* estimator

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- **Notation:** $e_t(w)$ is probability of selecting arm w at t
- ► Intuition:
 - Adaptive data collection introduces sample bias
 - ► Up/down weight observations to counter bias
- **Problem:** High variance if $e_t(w)$ small

A lower variance and unbiased estimator

Augmented Inverse Propensity Weighted Estimator

$$\widehat{Q}^{AIPW}(w) = \frac{1}{T} \sum_{t=1}^{T} \frac{\mathbb{I}\left\{W_{t} = w\right\}}{e_{t}(w)} Y_{t} + \left(1 - \frac{\mathbb{I}\left\{W_{t} = w\right\}}{e_{t}(w)}\right) \widehat{\mu}_{t}$$

- **Notation:** $\hat{\mu}_t$ is any other estimator (including sample mean)
- ► Additional term helps decrease variance...
- ▶ ...but in bandit experiments, variance is still too high

(Remainder of the talk: IPW only)

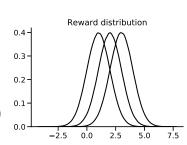
A simple example with three treatments (arms).

True distribution (unknown)

$$Y_t(1) \sim \mathcal{N}(3,1)$$
 High reward

$$Y_t(2) \sim \mathcal{N}(2,1)$$

$$Y_t(3) \sim \mathcal{N}(1,1)$$
 Low reward (Control)



Let's compare

Adaptive vs random estimates of Q(w).

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Random

 Assign arms at random, with equal probability

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Adaptive

 As we learn which arms are better, increase assignment probabilities to them (Thompson Sampling)

Let's compare

Adaptive vs random estimates of Q(w).

Random

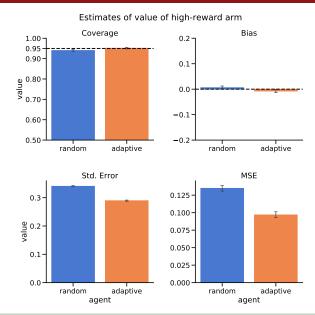
 Assign arms at random, with equal probability

Adaptive

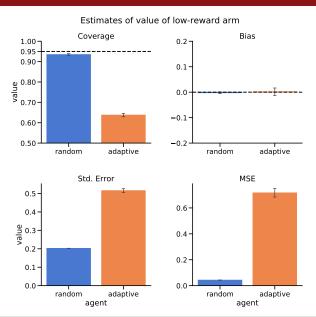
 As we learn which arms are better, increase assignment probabilities to them (Thompson Sampling)

Which data-collection algorithm yields better *coverage*, *power*, and *mse*?

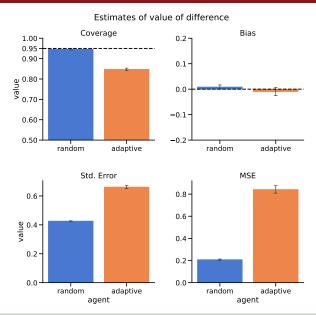
High-reward arm is estimated well



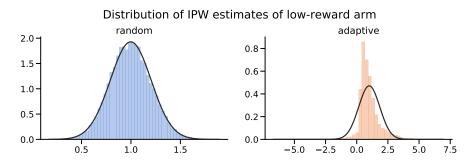
Low-reward arm is estimated poorly



Difference (High-Low) is estimated poorly too



Adaptivity hurts normality



central limit theorem may not hold

Wrong confidence intervals!

Our contribution

Introduce evaluation weights $h_t(w)$.

Adaptively-Weighted Augmented Inverse Propensity Score Estimator

$$\widehat{Q}_{T}^{AW}(w) := \sum_{t=1}^{T} \frac{h_{t}(w)}{\sum_{s=1}^{T} h_{s}(w)} \left\{ \frac{\mathbb{I}\left\{W_{t} = w\right\}}{e_{t}(w)} Y_{t} + \left(1 - \frac{\mathbb{I}\left\{W_{t} = w\right\}}{e_{t}(w)}\right) \widehat{\mu}_{t} \right\}$$

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Introduce *evaluation weights* $h_t(w)$.

Adaptively-Weighted Augmented Inverse Propensity Score Estimator

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- ▶ **Intuition:** $h_t(w)$ controls *flow of information*
- ► Main result: Conditions for CLT

Assumptions

A1: Bounded moments

Rewards have bounded fourth moments.

A2: Bounded $\hat{\mu}_t$

Estimate $\hat{\mu}_t$ is uniformly bounded, depends only on past data.

Assumptions

A3: Assignments

Assignment probabilities $e_t(w)$ depend on past data and converge in a.s. to a constant.

$$e_t(w) \xrightarrow[T \to \infty]{a.s.} e_{\infty}$$

A4: Evaluation weights

Weights $h_t(w)$ are non-negative, depend on past data.

Main result

A5: Growth and decay conditions (Main assumption)

Unnormalized weights $h_t(w)$ and assignment probabilities $e_t(w)$ jointly satisfy

$$\frac{\sum_{t=1}^{T} \frac{h_t(w)^p}{e_t(w)^{p-1}}}{\left(\sum_{t=1}^{T} \mathbb{E}\left[\frac{h_t(w)^2}{e_t(w)}\right]\right)^{p/2}} \xrightarrow[T \to \infty]{p} \begin{cases} \infty & \text{if } p = 1\\ 1 & \text{if } p = 2\\ 0 & \text{if } p \in \{3, 4\} \end{cases}$$

In addition, for $p \in \{2, 3, 4\}$ this is bounded.

Joint constraint:

- ▶ Data-collection algorithm: $e_t(w)$ must decay slowly
- ightharpoonup Evaluation weights: $h_t(w)$ chosen appropriately

Main result: Consistency and Asymptotic Normality

Theorem

If Assumption 1-5 are satisfied, then \widehat{Q}_T^{AW} is a consistent estimator of the true arm value Q, and the following statistic is asymptotically normal.

$$rac{\widehat{Q}_{\mathcal{T}}(w)^{AW}-Q(w)}{\widehat{V}^{rac{1}{2}}}\stackrel{d}{\longrightarrow} \mathcal{N}(0,1)$$

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Notation: \hat{V}_T is estimate of variance

Weighting schemes

Propensity-score based (ps)

Seeks minimum variance. When applied to IPW, gets us back approximately to simple averaging. Does not always satisfy A5.

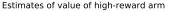
$$h_t = e_t(w)$$

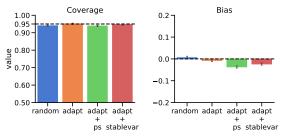
Variance-stabilizing stablevar

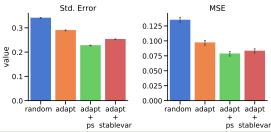
Ensures assumption A5(2) is satisfied.

$$h_t^2 = \left(1 - \sum_{s=1}^{t-1} h_s^2 e_s^{-1}\right) \mathbb{E}\left[\frac{e_t(w)}{\sum_{s=t}^T e_s} \,\middle|\, \mathcal{F}_{t-1}\right] e_t(w)$$

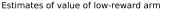
High-reward arms are (still) estimated well

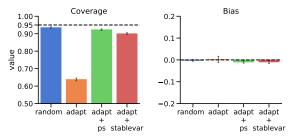


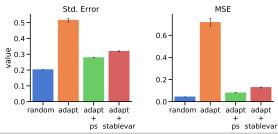




Low-reward arms are estimated well too

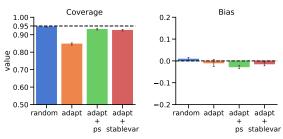


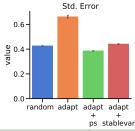


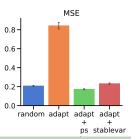


Difference is estimated well too

Estimates of value of difference

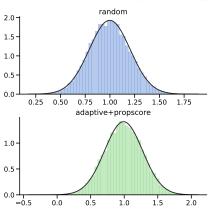


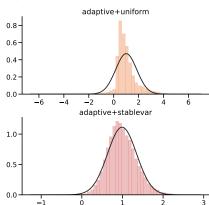




Normality is restored







Concluding thoughts

Appropriately chosen adaptive evaluation weights:

- Yield valid confidence intervals
- Produce estimates with smaller MSE
- Still allow for adaptive data collection

However: For hypothesis testing, beware of too-aggressive algorithms!