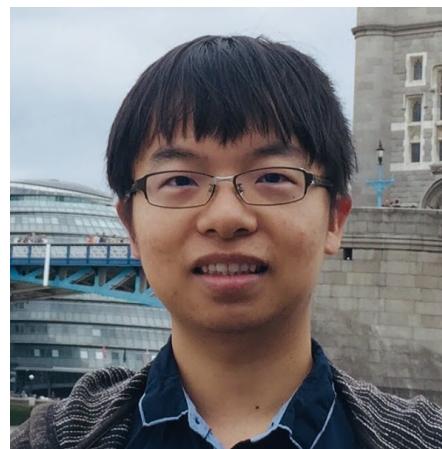
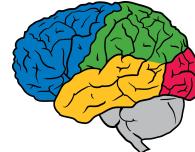


Energy-Based Processes for Exchangeable Data

Mengjiao Yang*, Bo Dai*, Hanjun Dai, Dale Schuurmans

Google Brain

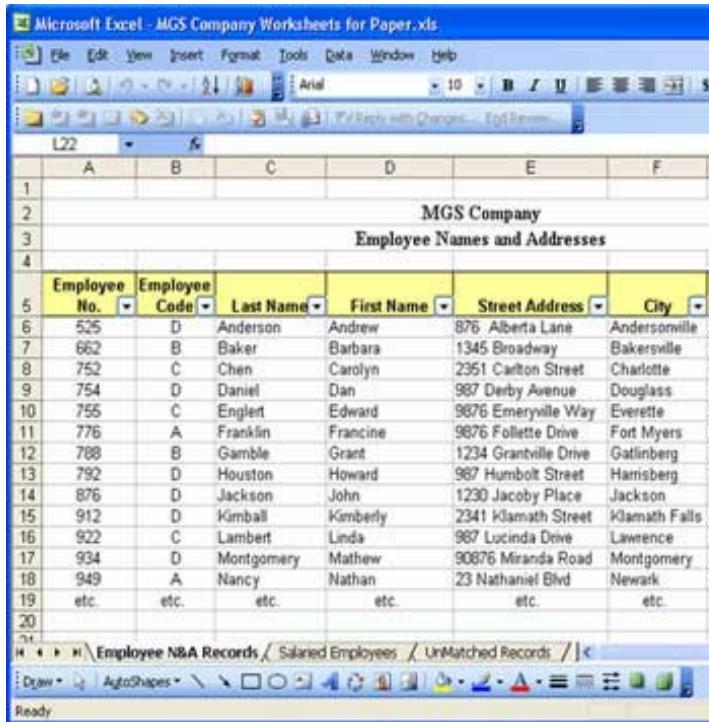


Paper: <https://arxiv.org/abs/2003.07521>

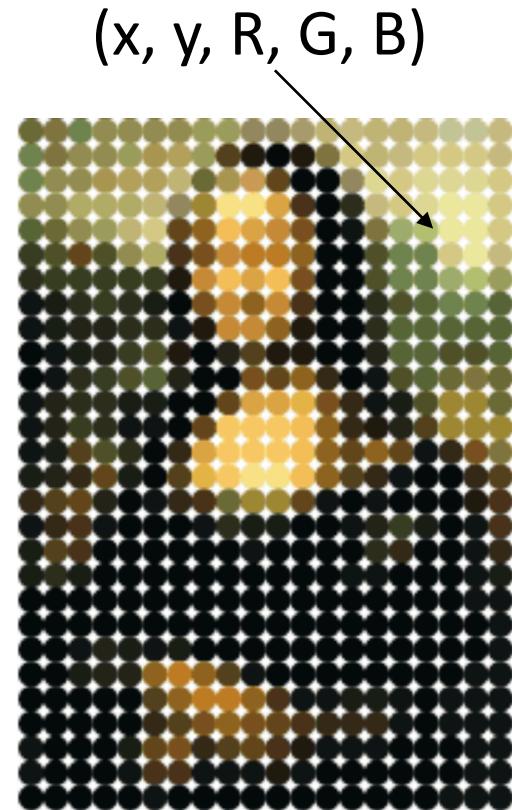
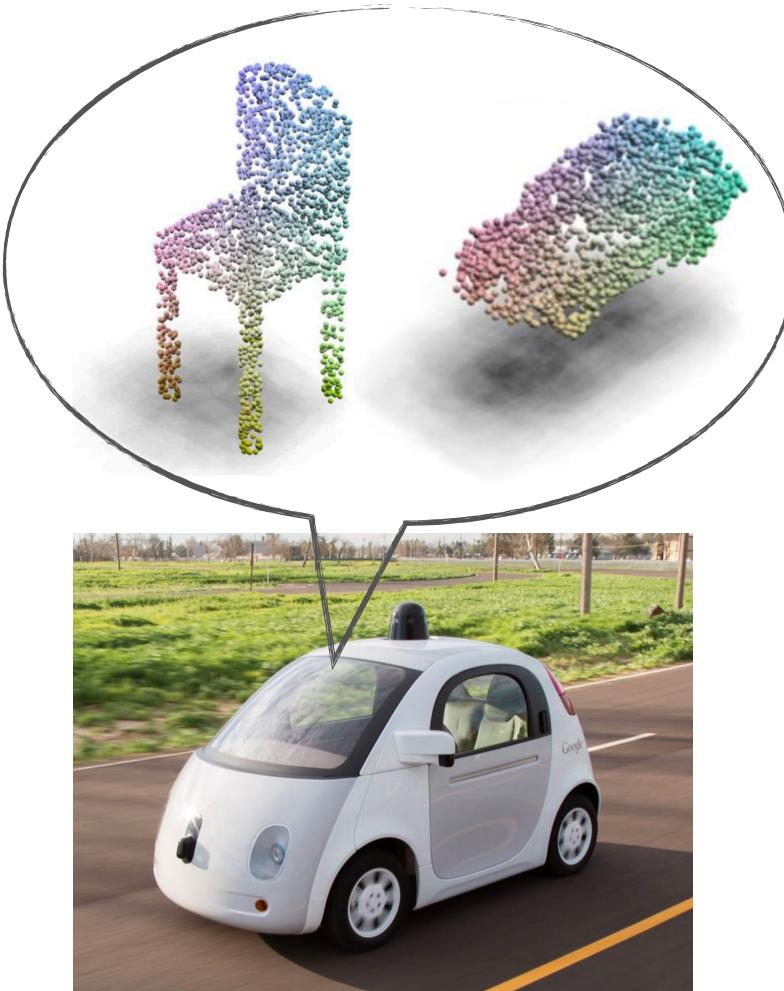
Code: <https://github.com/google-research/google-research/tree/master/ebp>

Sets

- Record data
- 3D point clouds
- Images

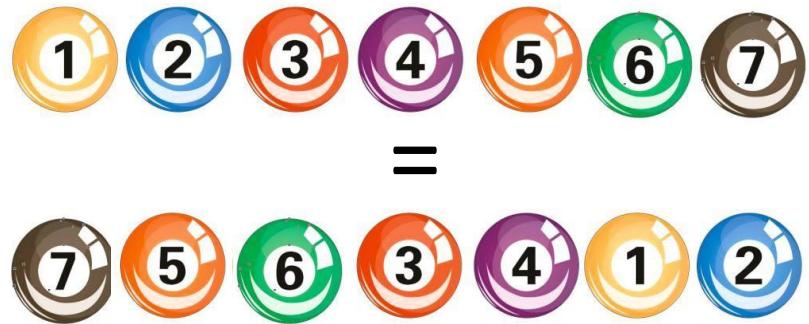


Employee No.	Employee Code	Last Name	First Name	Street Address	City
525	D	Anderson	Andrew	876 Alberta Lane	Andersonville
662	B	Baker	Barbara	1345 Broadway	Bakersville
752	C	Chen	Carolyn	2351 Carlton Street	Charlotte
754	D	Daniel	Dan	987 Derby Avenue	Douglass
755	C	Englert	Edward	9876 Emeryville Way	Everette
776	A	Franklin	Francine	9876 Follette Drive	Fort Myers
788	B	Gamble	Grant	1234 Granville Drive	Gatlinberg
792	D	Houston	Howard	987 Humboldt Street	Harrisberg
876	D	Jackson	John	1230 Jacoby Place	Jackson
912	D	Kimball	Kimberly	2341 Klamath Street	Klamath Falls
922	C	Lambert	Linda	987 Lucinda Drive	Lawrence
934	D	Montgomery	Mathew	90876 Miranda Road	Montgomery
949	A	Nancy	Nathan	23 Nathaniel Blvd	Newark
etc.	etc.	etc.	etc.	etc.	etc.



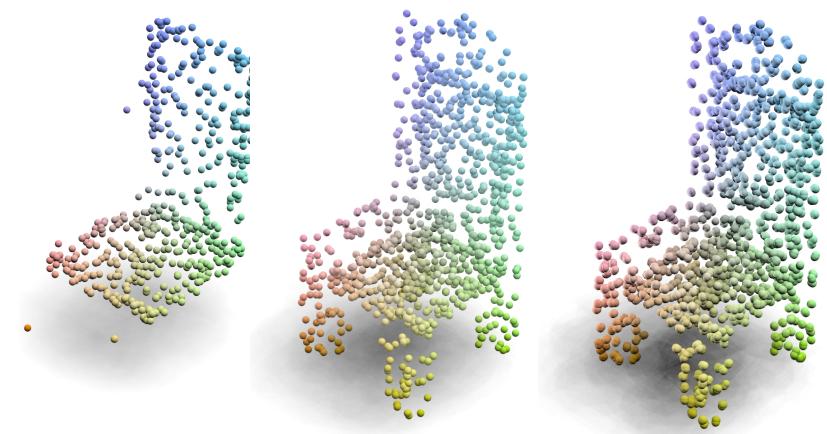
Sets Properties

- Exchangeability



Same set

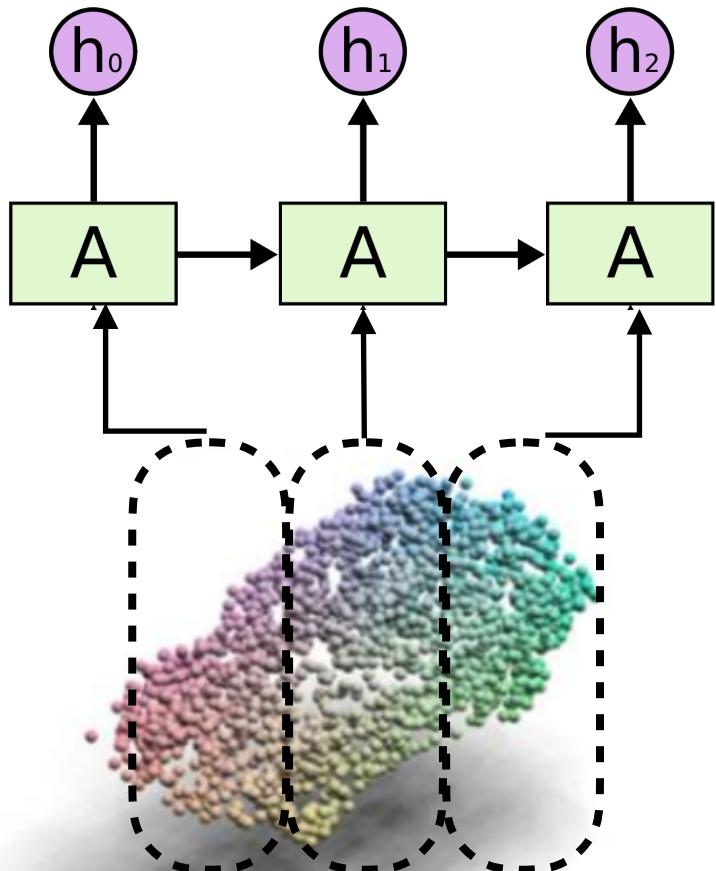
- Varying cardinality



Same chair

Modeling Sets (Unconditional)

- RNNs



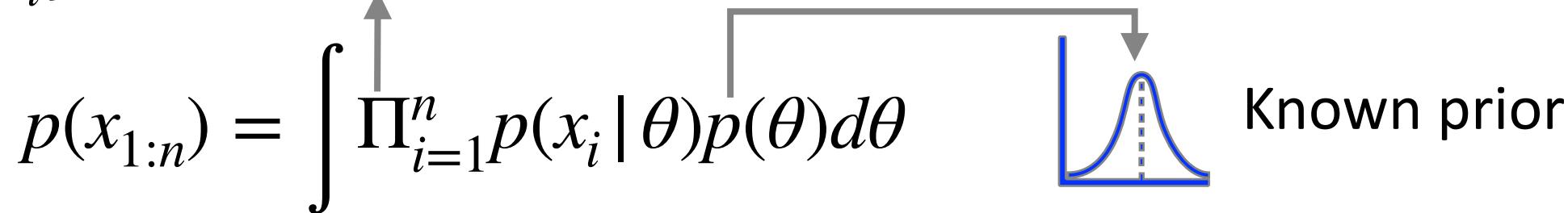
$$p(x_{1:n}) = \prod_{i=1}^n p(x_i | x_{1:i-1})$$

✓ Varying Cardinality
✗ Exchangeability

Modeling Sets (Unconditional)

- Latent variable models

$\{x_i\}$ conditionally i.i.d.

$$p(x_{1:n}) = \int \prod_{i=1}^n p(x_i | \theta) p(\theta) d\theta$$


Known prior

- ✓ Varying Cardinality
- ✓ Exchangeability

Modeling Sets (Unconditional)

- Latent variable models

$\{x_i\}$ conditionally i.i.d.

$$p(x_{1:n}) = \int \prod_{i=1}^n p(x_i | \theta) p(\theta) d\theta$$

The diagram illustrates the decomposition of the joint probability of data points $x_{1:n}$ into a product of conditional probabilities $p(x_i | \theta)$ and a prior distribution $p(\theta)$. This decomposition leads to two graphical representations: a 'Known prior' where the posterior distribution is a tractable form (a blue curve over a red density function), and a 'Tractable' section where the posterior distribution is also a tractable form (a blue curve over a red density function).

- ✓ Varying Cardinality
- ✓ Exchangeability
- ? Flexibility

Modeling Sets (Conditional)

- Stochastic processes

A set of random variables: $\{X_t; t \in \mathcal{T}\}$

with finite-dimensional marginal distribution: $p(x_{t_1:t_n} | \{t_i\}_{i=1}^n)$

Modeling Sets (Conditional)

- Stochastic processes

A set of random variables: $\{X_t; t \in \mathcal{T}\}$

with finite-dimensional marginal distribution: $p(x_{t_1:t_n} | \{t_i\}_{i=1}^n)$

- ✓ Consistency: $p(x_{t_1:t_m}) = \int p(x_{t_1:t_n}) dx_{t_{m+1}:t_n}$
- ✓ Exchangeability: $p(x_{t_1:t_n}) = p(\pi(x_{t_1:t_n}))$

Modeling Sets (Conditional)

- Stochastic processes

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✓ Consistency: $p(x_{t_1:t_m}) = \int p(x_{t_1:t_n}) dx_{t_{m+1}:t_n}$

✓ Exchangeability: $p(x_{t_1:t_n}) = p(\pi(x_{t_1:t_n}))$

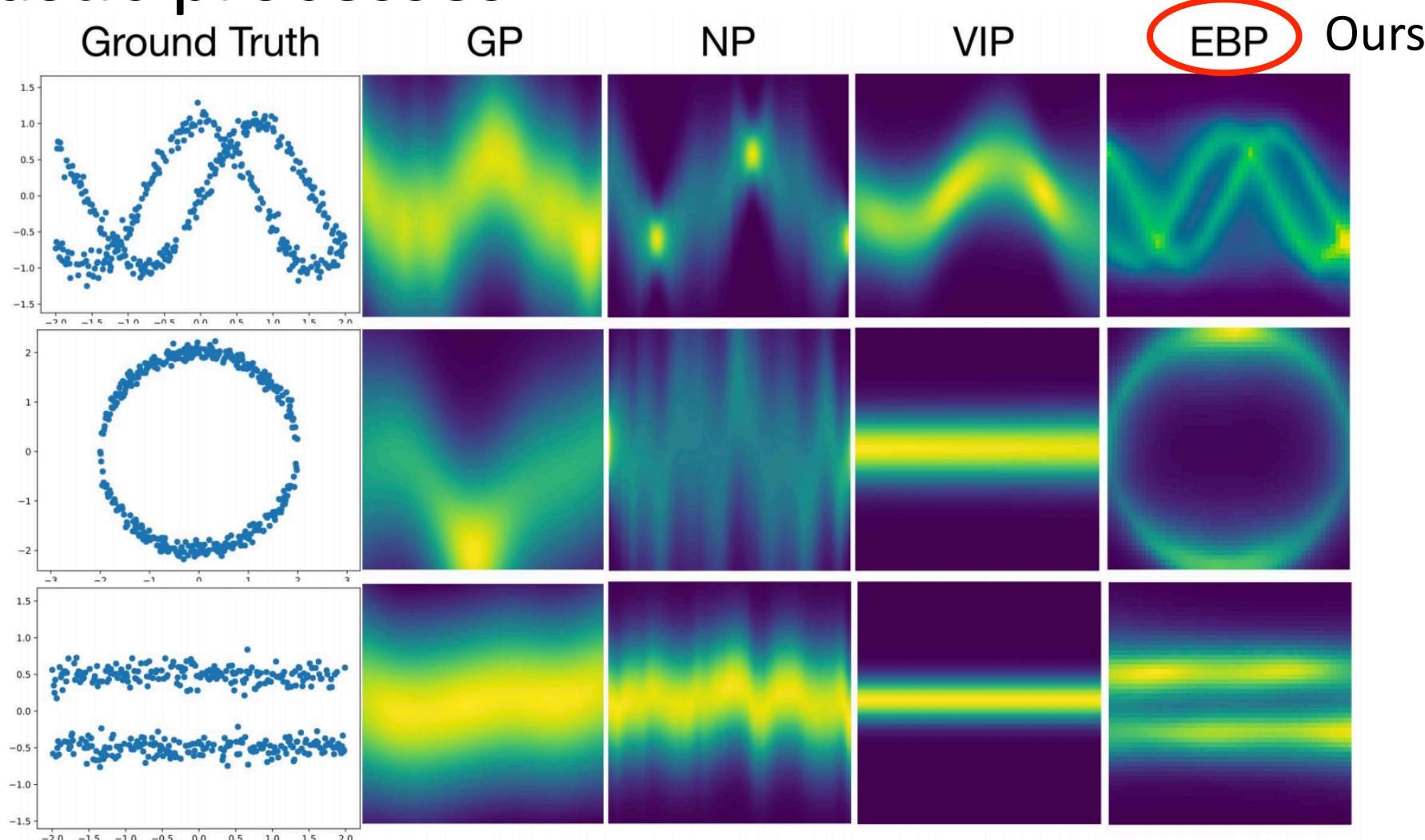
? Flexibility:

- Gaussian processes: $p(x_{t_1:t_n}) = \mathcal{N}(0, K(t_{1:n}) + \sigma^2 I_n)$

- Student-t processes: $p(x_{t_1:t_n}) = \mathcal{N}(\nu, 0, K(t_{1:n}) + \sigma^2 I_n)$

Modeling Sets (Conditional)

- Stochastic processes



Rasmussen, C. E. and Williams, C. K. I. Gaussian Processes for Machine Learning. MIT Press, Cambridge, MA, 2006.

Garnelo, M., Schwarz, J., Rosenbaum, D., Viola, F., Rezende, D. J., Eslami, S., and Teh, Y. W. Neural processes. arXiv preprint arXiv:1807.01622, 2018b.

Ma, C., Li, Y., and Hernández-Lobato, J. M. Variational implicit processes. arXiv preprint arXiv:1806.02390, 2018.

Energy-Based Processes

- Stochastic processes as latent variable models

$$p(x_{t_1:t_n}) = \int \prod_{i=1}^n p(x_i | \theta, t_i) p(\theta) d\theta$$

✓ Varying Cardinality

✓ Exchangeability

Energy-Based Processes

- Stochastic processes as latent variable models

$$p(x_{t_1:t_n}) = \int \prod_{i=1}^n p(x | \theta, t_i) p(\theta) d\theta$$


$$\frac{\exp(f_w(x, t; \theta))}{\int \exp(f_w(x, t; \theta)) dx}$$

Deep EBMs

- Deep energy-based models for likelihood
 - ✓ Varying Cardinality
 - ✓ Exchangeability
 - ✓ Flexibility

Energy-Based Processes

- Stochastic processes as latent variable models

$$p(x_{t_1:t_n}) = \int \prod_{i=1}^n p(x | \theta, t_i) p(\theta) d\theta$$

- ✓ Varying Cardinality
- ✓ Exchangeability


$$\frac{\exp(f_w(x, t; \theta))}{\int \exp(f_w(x, t; \theta)) dx}$$

Deep EBMs

- Deep energy-based models for likelihood
 - ✓ Flexibility
- Neural collapsed inference => unconditional EBPs

$$p(x_{1:n}) = \int p(x_{1:n} | \theta) p(\theta) d\theta$$

Energy-Based Processes

- Learning EBPs: $\max_w \mathbb{E}_{x_{1:n} \sim \mathcal{D}} [\log p_w(x_{1:n})]$

Energy-Based Processes

- Learning EBPs: $\max_w \mathbb{E}_{x_{1:n} \sim \mathcal{D}}[\log p_w(x_{1:n})]$

? Intractable integration over θ

$$\log \int p_w(x_{1:n} | \theta) p(\theta) d\theta$$

Energy-Based Processes

- Learning EBPs: $\max_w \mathbb{E}_{x_{1:n} \sim \mathcal{D}}[\log p_w(x_{1:n})]$

? Intractable integration over θ

$$\log \int p_w(x_{1:n} | \theta) p(\theta) d\theta = \max_{q(\theta|x_{1:n})} \mathbb{E}_q[\log p_w(x_{1:n} | \theta)] - KL(q || p)$$

✓ ELBO

Energy-Based Processes

- Learning EBPs: $\max_w \mathbb{E}_{x_{1:n} \sim \mathcal{D}}[\log p_w(x_{1:n})]$

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✓ ELBO

? Intractable partition function

$$\log p_w(x_{1:n} | \theta) = f_w(x_{1:n}; \theta) - \log Z(f_w, \theta)$$

Energy-Based Processes

- Learning EBPs: $\max_w \mathbb{E}_{x_{1:n} \sim \mathcal{D}}[\log p_w(x_{1:n})]$

? Intractable integration over θ

$$\log \int p_w(x_{1:n} | \theta) p(\theta) d\theta = \max_{q(\theta|x_{1:n})} \mathbb{E}_q[\log p_w(x_{1:n} | \theta)] - KL(q || p)$$

✓ ELBO

? Intractable partition function

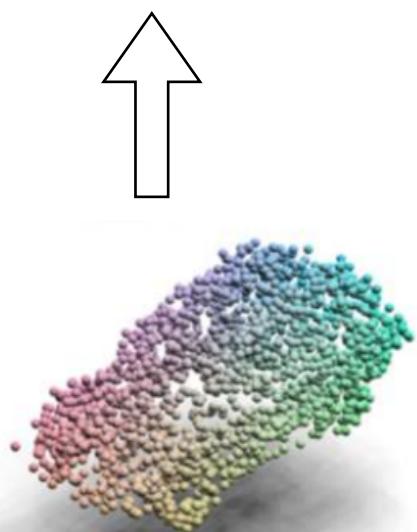
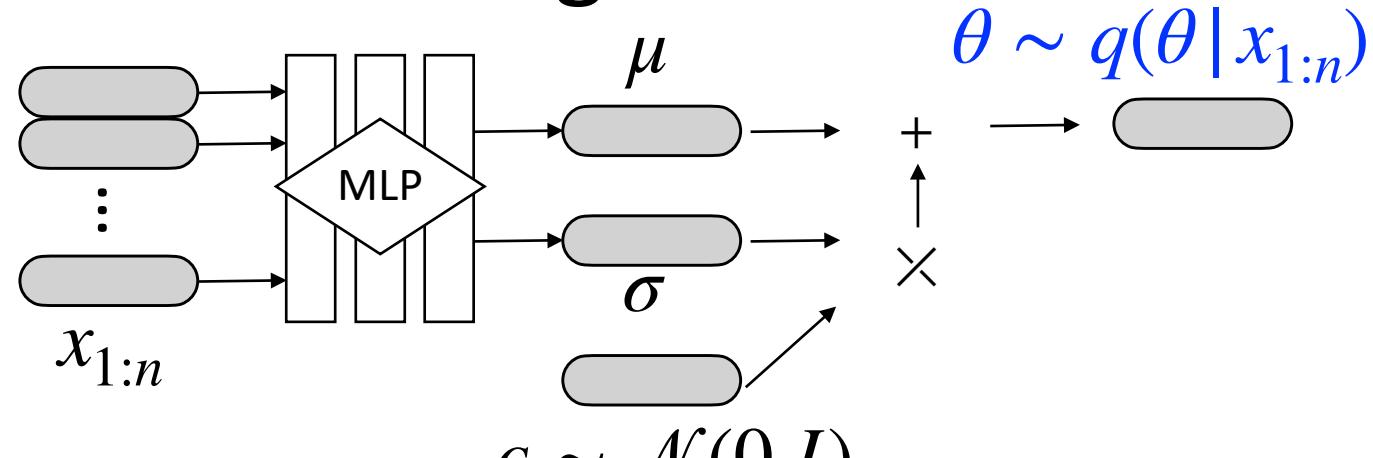
$$\log p_w(x_{1:n} | \theta) = f_w(x_{1:n}; \theta) - \log Z(f_w, \theta)$$

$$\propto \min_{q(x_{1:n}, \nu | \theta)} f_w(x_{1:n}; \theta) - \mathbb{E}_q[f_w(x_{1:n}; \theta)] - \frac{\lambda}{2} \nu^\top \nu - H(q)$$

✓ Adversarial dynamic embeddings

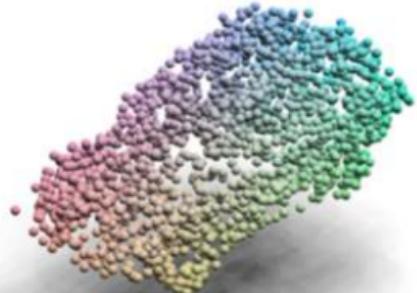
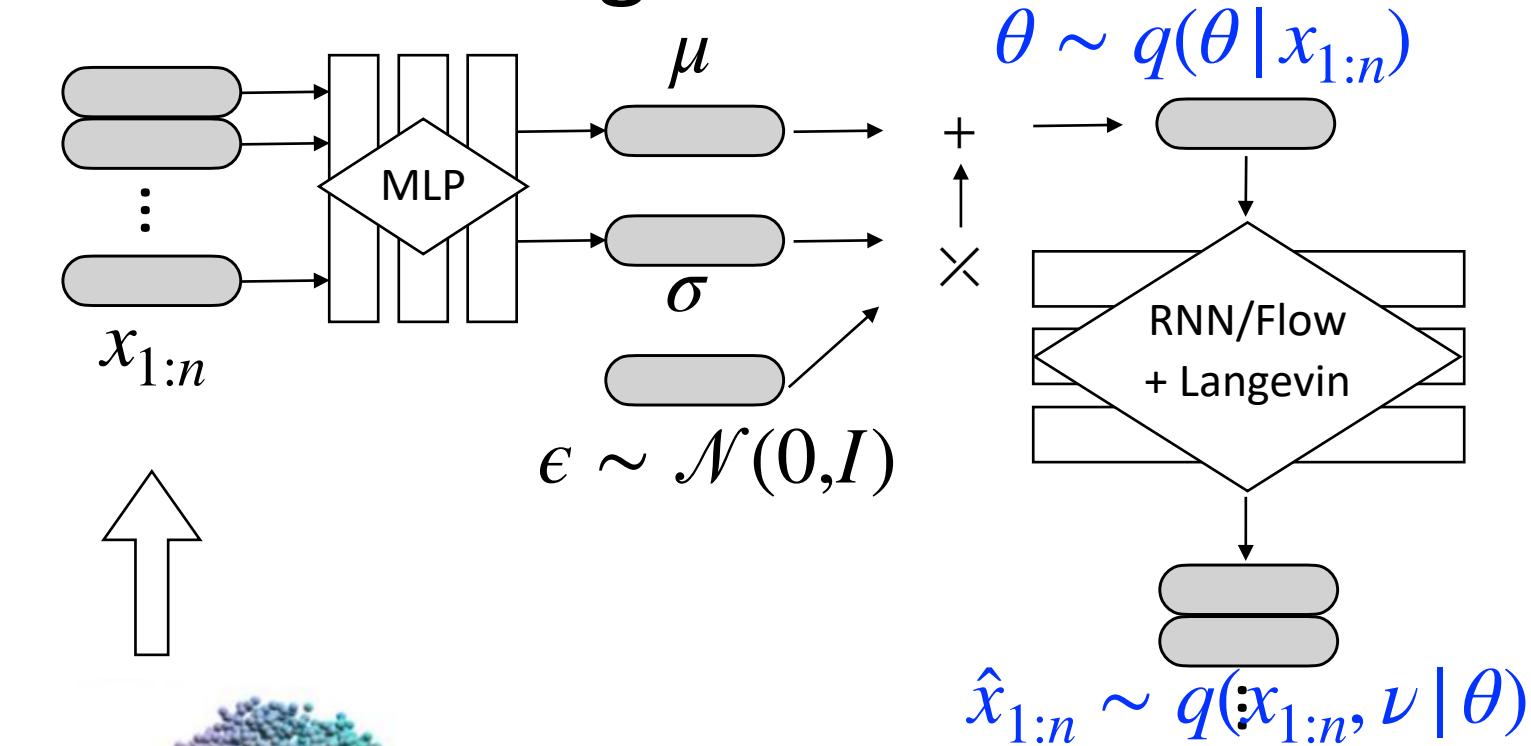
Energy-Based Processes

- Parametrizing EBPs:



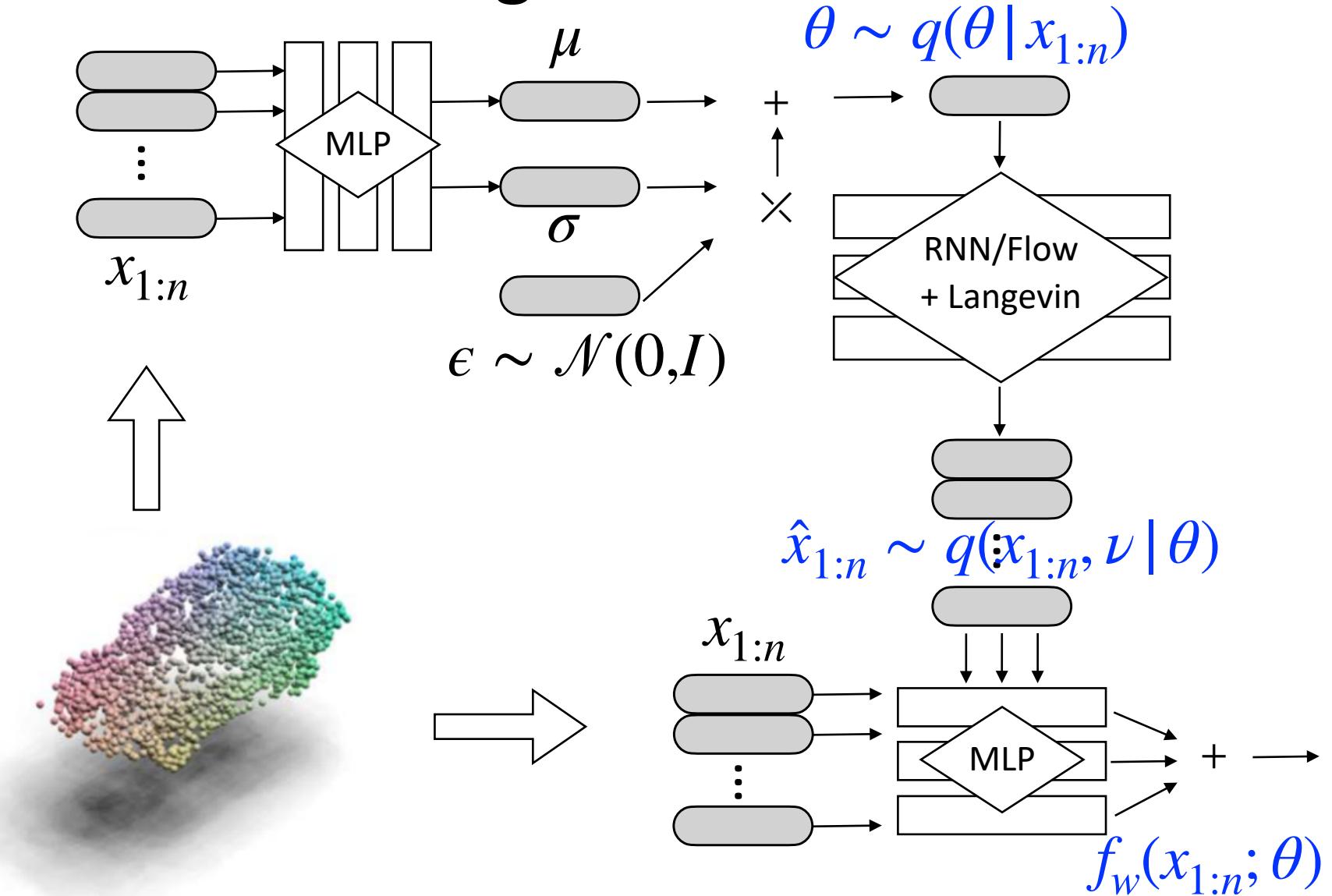
Energy-Based Processes

- Parametrizing EBPs:

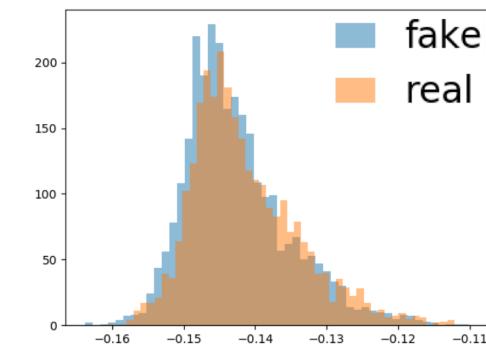


Energy-Based Processes

- Parametrizing EBPs:

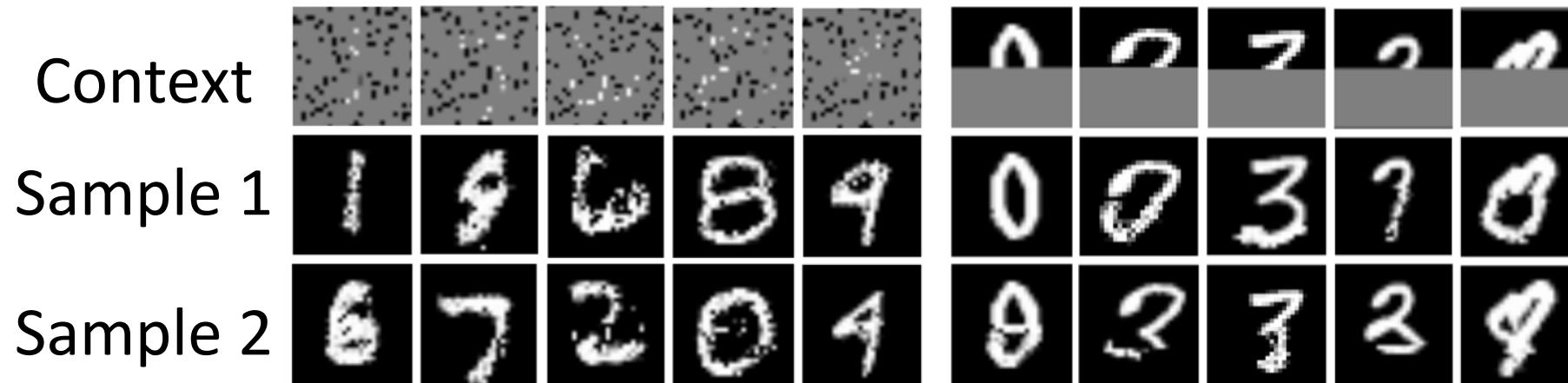


Energy



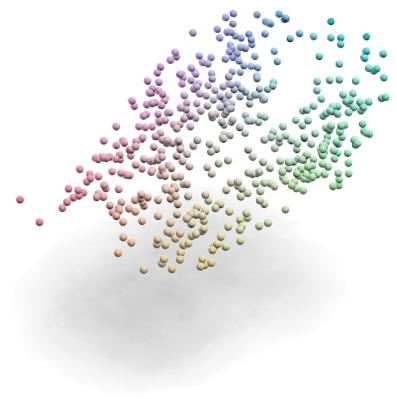
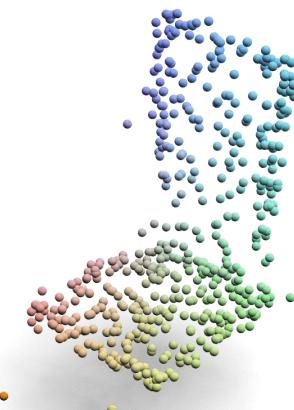
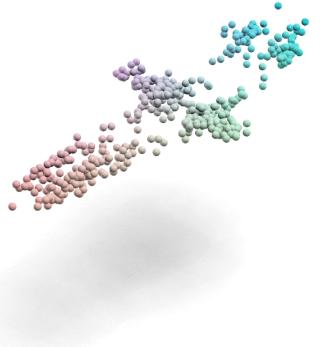
Applications

- Image completion

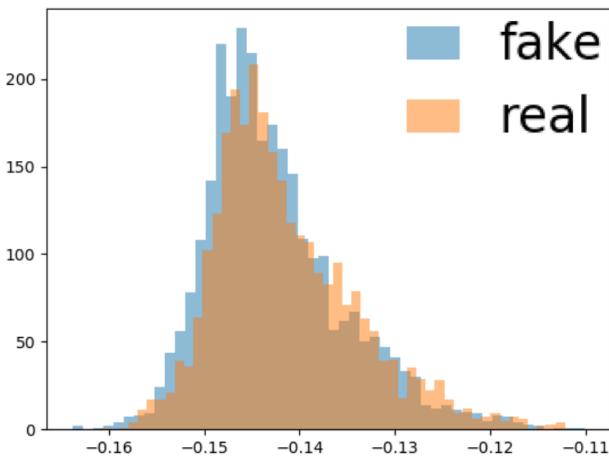


Applications

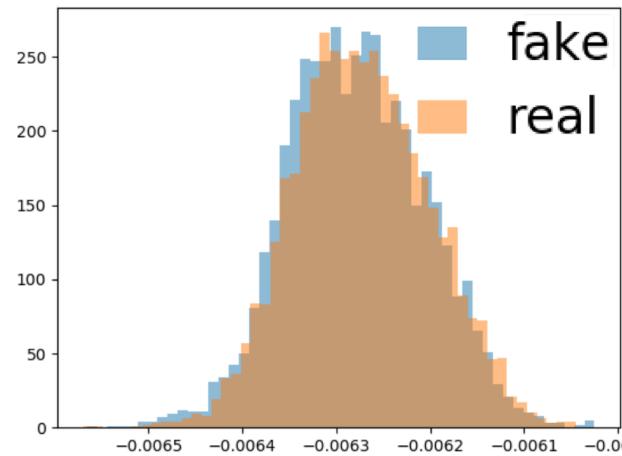
- Point-cloud generation



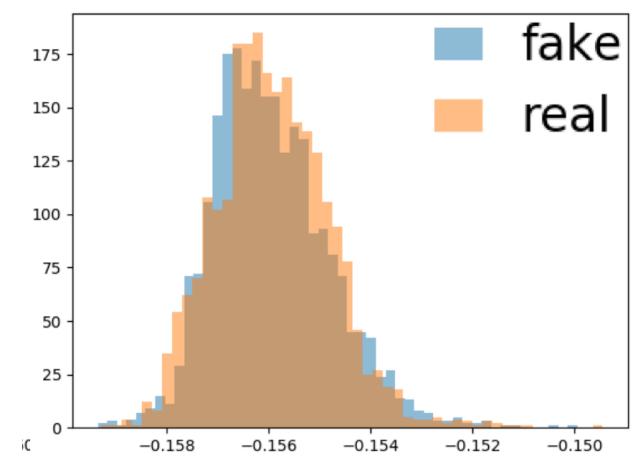
Airplane



Chair



Car



Applications

- Point-cloud generation

Category	Model	JSD (\downarrow)		MMD (\downarrow)		COV (%), \uparrow	
		CD	EMD	CD	EMD	CD	EMD
Airplane	l-GAN	3.61	0.239	3.29	47.90	50.62	
	PC-GAN	4.63	0.287	3.57	36.46	40.94	
	PointFlow	4.92	0.217	3.24	46.91	48.40	
	EBP (ours)	3.92	0.240	3.22	49.38	51.60	
Chair	l-GAN	2.27	2.46	7.85	41.39	41.69	
	PC-GAN	3.90	2.75	8.20	36.50	38.98	
	PointFlow	1.74	2.42	7.87	46.83	46.98	
	EBP (ours)	1.53	2.59	7.92	47.73	49.84	
Car	l-GAN	2.21	1.48	5.43	39.20	39.77	
	PC-GAN	5.85	1.12	5.83	23.56	30.29	
	PointFlow	0.87	0.91	5.22	44.03	46.59	
	EBP (ours)	0.78	0.95	5.24	51.99	51.70	

Achlioptas, P., Diamanti, O., Mitliagkas, I., and Guibas, L. Learning representations and generative models for 3d point clouds. arXiv preprint arXiv:1707.02392, 2017.

Li, C.-L., Zaheer, M., Zhang, Y., Poczos, B., and Salakhutdinov, R. Point cloud gan. arXiv preprint arXiv:1810.05795, 2018.

Yang, G., Huang, X., Hao, Z., Liu, M.-Y., Belongie, S., and Hariharan, B. Pointflow: 3d point cloud generation with continuous normalizing flows. arXiv preprint arXiv:1906.12320, 2019.

Applications

- Unsupervised representation learning

Model	Accuracy
VConv-DAE (Sharma et al., 2016)	75.5
3D-GAN (Wu et al., 2016)	83.3
l-GAN (EMD) (Achlioptas et al., 2017)	84.0
l-GAN (CD) (Achlioptas et al., 2017)	84.5
PointGrow (Sun et al., 2018)	85.7
MRTNet-VAE (Gadelha et al., 2018)	86.4
PointFlow (Yang et al., 2019)	86.8
PC-GAN (Li et al., 2018)	87.8
FoldingNet (Yang et al., 2018)	88.4
EBP (ours)	88.3

Sharma, A., Grau, O., and Fritz, M. Vconv-dae: Deep volumetric shape learning without object labels. In European Conference on Computer Vision, pp. 236–250. Springer, 2016.

Wu, J., Zhang, C., Xue, T., Freeman, B., and Tenenbaum, J. Learning a probabilistic latent space of object shapes via 3d generative-adversarial modeling. In Advances in neural information processing systems, pp. 82–90, 2016.

Achlioptas, P., Diamanti, O., Mitliagkas, I., and Guibas, L. Learning representations and generative models for 3d point clouds. arXiv preprint arXiv:1707.02392, 2017.

Sun, Y., Wang, Y., Liu, Z., Siegel, J. E., and Sarma, S. E. Pointgrow: Autoregressively learned point cloud generation with self-attention. arXiv preprint arXiv:1810.05591, 2018.

Gadelha, M., Wang, R., and Maji, S. Multiresolution tree networks for 3d point cloud processing. In Proceedings of the European Conference on Computer Vision (ECCV), pp. 103–118, 2018.

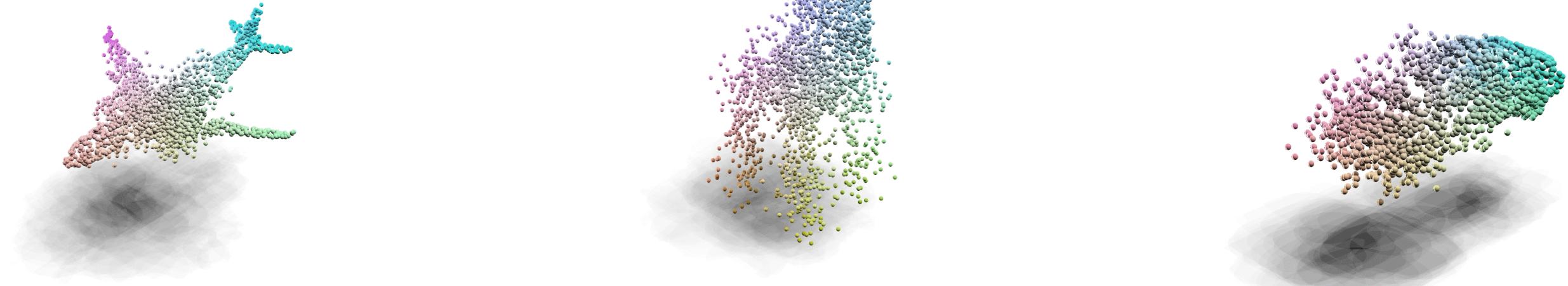
Yang, Y., Feng, C., Shen, Y., and Tian, D. Foldingnet: Point cloud auto-encoder via deep grid deformation. In Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition

Li, C.-L., Zaheer, M., Zhang, Y., Poczos, B., and Salakhutdinov, R. Point cloud gan. arXiv preprint arXiv:1810.05795, 2018.

Yang, G., Huang, X., Hao, Z., Liu, M.-Y., Belongie, S., and Hariharan, B. Pointflow: 3d point cloud generation with continuous normalizing flows. arXiv preprint arXiv:1906.12320, 2019.

Applications

- Point-cloud denoising



Summary

- Energy-based processes for flexibility set modeling
- Unifies stochastic process and latent variable perspectives
- Neural collapsed inference for learning
- State-of-the-art performance on a set of supervised and unsupervised tasks