SHERWIN BAHMANI

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EDUCATION Ph.D. Computer Science, University of Toronto Sep 2023 - Aug 2027 • Focus: Computer Vision, Computer Graphics, Machine Learning • Advisors: David Lindell, Andrea Tagliasacchi M.Sc. Computational Engineering, Technical University of Darmstadt Apr 2018 - Sep 2021 • Focus: Computer Vision, Machine Learning • Advisor: Stefan Roth B.Sc. Mechanical and Process Engineering, Technical University of Darmstadt Oct 2014 - Apr 2018 • Focus: Mechatronics RESEARCH EXPERIENCE Feb 2024 - Dec 2024 Research Intern: Snap Inc. • Creative Vision Group: 3D camera control in video diffusion transformers • Advisors: Sergey Tulyakov, Aliaksandr Siarohin, Ivan Skorokhodov Research Intern: Simon Fraser University Jun 2023 - Aug 2023 • GrUVi Lab: Text-to-4D generation • Advisor: Andrea Tagliasacchi • Collaborators: Ivan Skorokhodov, Sergey Tulyakov, Jeong Joon Park, David Lindell Research Intern: Stanford University Jul 2022 - Nov 2022 • Geometric Computation Group: Compositional and controllable generation of 3D scenes • Advisors: Jeong Joon Park, Despoina Paschalidou, Gordon Wetzstein, Leonidas Guibas • Collaborator: Andrea Tagliasacchi Research Intern: ETH Zurich Jan 2022 - Jun 2022 • Computer Vision Lab: 4D generative adversarial networks • Advisors: Hao Tang, Radu Timofte, Luc Van Gool • Collaborators: Jeong Joon Park, Despoina Paschalidou, Gordon Wetzstein, Leonidas Guibas Research Intern: École Polytechnique Fédérale de Lausanne (EPFL) Oct 2021 - Nov 2021 • Visual Intelligence for Transportation Lab: Causal motion forecasting for out-of-distribution robustness • Advisors: Yuejiang Liu, Alexandre Alahi Student Research Assistant: Technical University of Darmstadt Apr 2021 - Oct 2021 • Visual Inference Lab: Video frame interpolation and optical flow estimation • Advisors: Simone Schaub-Meyer, Stefan Roth Master Thesis: Mercedes-Benz AG / Technical University of Darmstadt Sep 2020 - Mar 2021 • Image Understanding Group: Multi-scale value iteration networks for panoptic segmentation Advisors: Jonas Uhrig, Marius Cordts, Stefan Roth Working Student: Mercedes-Benz AG Mar 2020 - Sep 2020 • Image Understanding Group: Instance and panoptic segmentation • Advisors: Jonas Uhrig, Uwe Franke

Nov 2017 - Apr 2018

• Reliability of Electric Vehicles: Battery aging forecasting using nonlinear regression

• Advisors: Alexander Dautfest, Tobias Melz

Bachelor Thesis: Fraunhofer LBF

WORK EXPERIENCE

Intern: Daimler AG Aug 2019 - Feb 2020

• Electric Powertrain Development: Software engineering for automated hybrid powertrain designs

Intern: Porsche AG Apr 2017 - Sep 2017

• Digital Powertrain Development: Software engineering for damage calculation in electric powertrains

ACADEMIC SERVICE

Reviewer: CVPR, ICCV, ECCV, SIGGRAPH, SIGGRAPH Asia, NeurIPS, ICLR, TPAMI, TVCG

PUBLICATIONS / PREPRINTS

- [1] S.Bahmani, I. Skorokhodov, A. Siarohin, W. Menapace, G. Qian, M. Vasilkovsky, H.-Y. Lee, C. Wang, J. Zou, A. Tagliasacchi, D. B. Lindell, and S. Tulyakov, "VD3D: Taming large video diffusion transformers for 3d camera control", arXiv, 2024.
- [2] S. Bahmani*, X. Liu*, W. Yifan*, I. Skorokhodov, V. Rong, Z. Liu, X. Liu, J. J. Park, S. Tulyakov, G. Wetzstein, A. Tagliasacchi, and D. B. Lindell, "TC4D: Trajectory-conditioned text-to-4d generation", ECCV, 2024.
- [3] S. Bahmani, I. Skorokhodov, V. Rong, G. Wetzstein, L. Guibas, P. Wonka, S. Tulyakov, J. J. Park, A. Tagliasacchi, and D. B. Lindell, "4D-fy: Text-to-4d generation using hybrid score distillation sampling", CVPR, 2024.
- [4] S. Bahmani, J. J. Park, D. Paschalidou, X. Yan, G. Wetzstein, L. Guibas, and A. Tagliasacchi, "CC3D: Layout-conditioned generation of compositional 3d scenes", *ICCV*, 2023.
- [5] S. Bahmani, J. J. Park, D. Paschalidou, H. Tang, G. Wetzstein, L. Guibas, L. Van Gool, and R. Timofte, "3D-aware video generation", TMLR, 2023.
- [6] S. Bahmani*, O. Hahn*, E. Zamfir*, N. Araslanov, D. Cremers, and S. Roth, "Semantic self-adaptation: Enhancing generalization with a single sample", *TMLR*, 2023.
- [7] Y. Liu, R. Cadei*, J. Schweizer*, S. Bahmani, and A. Alahi, "Towards robust and adaptive motion forecasting: A causal representation perspective", CVPR, 2022.