

Introduction to Computer Vision



Agenda

- Computer Vision Quiz
- Problems with ANNs for Images
- Convolutional Neural Networks (CNNs)
- Components of CNNs



Let's begin the discussion by answering a few questions on computer vision and convolutional neural networks (CNNs)



ANNs are not invariant to which of the following transformations?

A Translation

B Rotation

c Scaling

D Translation followed by Rotation



ANNs are not invariant to which of the following transformations?

- **A** Translation
- **B** Rotation

- **c** Scaling
- D Translation followed by Rotation

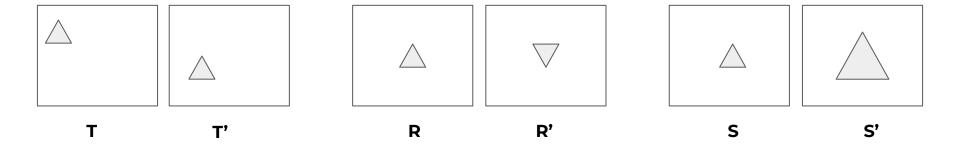
Problems with ANNs for Images



ANNs may struggle with recognizing objects that are translated, rotated, and/or scaled within an image

Each of the pairs below (T and T' for translation, R and R' for rotation, S and S' for scaling) are different sets of inputs to the ANN - the outputs will also be different

But if the task is to identify a triangle in an image, then each pair should give the same output.





How do CNNs address the problem of translation invariance?

- By moving filters across the entire image to detect patterns at different locations.
- By randomly selecting regions of the image for feature extraction.
- By resizing the image.
- **D** By adding brightness to the image.



How do CNNs address the problem of translation invariance?

- By moving filters across the entire image to detect patterns at different locations.
- By randomly selecting regions of the image for feature extraction.
- By resizing the image.
- **D** By adding brightness to the image.

CNN Filters

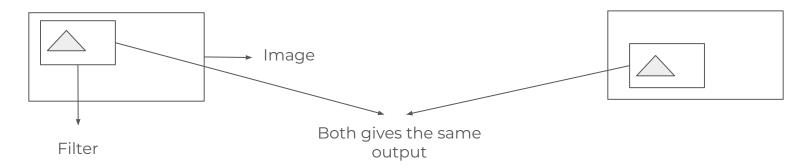


A CNN filter scans an image to find features like edges or textures

Adapts its parameters to recognize particular patterns during training

CNNs address the problem of translation invariance by moving filters across the entire image through a sliding mechanism

Allows the network to detect patterns or features at different spatial locations





What is the output of convolving a 2x2 filter of all ones with any 2x2 input matrix of real values?

- A The product of all elements in the input matrix.
- B The mean of all elements in the input matrix

C The sum of all elements in the input matrix.

The maximum value of all elements in the input matrix.



What is the output of convolving a 2x2 filter of all ones with any 2x2 input matrix of real values?

- A The product of all elements in the input matrix.
- B The mean of all elements in the input matrix

The sum of all elements in the input matrix.

The maximum value of all elements in the input matrix.

Convolution Operation



Refers to the process of applying a filter to the input data by computing the dot product between the filter and the local regions of the input

а	b	<u></u>	1	1
С	d	*	1	1

$$= a + b + c + d$$

Thus, we get the sum of all elements of the input matrix



Which operation applied to an image helps in preserving its dimensionality after convolution?

- **A** Translation
- **B** Rotation

- c Increasing the brightness
- **D** Padding



Which operation applied to an image helps in preserving its dimensionality after convolution?

- **A** Translation
- **B** Rotation

- c Increasing the brightness
- **D** Padding

Padding



Refers to adding extra border pixels around the input data before applying the convolution operation

Helps preserve spatial dimensions and information at the edges of the input, ensuring that the output feature map has the desired size

				0	0	0	0	0								
1	1	-1	Padding	0	1	1	-1	0	Convolution	1	1	1	Output	1	1	-1
1	-1	-1		0	1	-1	-1	0						1	-1	-1
-1	0	1		0	-1	0	1	0		1	1			-1	0	1
				0	0	0	0	0	'		Filte	r				

Convolution with a padding of 1



In convolutional neural networks (CNNs), what effect does increasing the stride value have on the output feature map size?

- A It increases the size of the output feature map.
- It has no effect on the size of the output feature map.

- c It reduces the number of channels in the output feature map.
- It decreases the size of the output feature map.



In convolutional neural networks (CNNs), what effect does increasing the stride value have on the output feature map size?

- A It increases the size of the output feature map.
- It has no effect on the size of the output feature map.

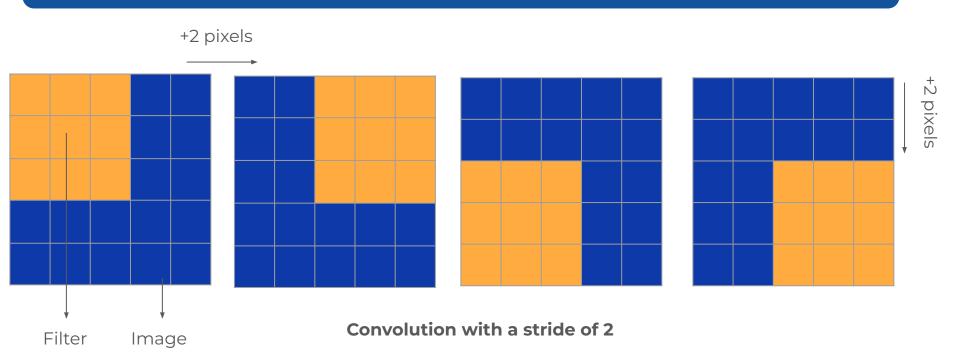
c It reduces the number of channels in the output feature map.

It decreases the size of the output feature map.

Stride



Refers to the number of pixels by which the filter is moved across the input data during the convolution operation





Why do we need a pooling layer in Convolutional Neural Networks (CNNs)?

- To increase the number of parameters.
- To reduce the spatial dimensions of the feature maps, reducing computational complexity.
- To increase the spatial dimensions of the feature maps, reducing computational complexity.
- To scale the input.



Why do we need a pooling layer in Convolutional Neural Networks (CNNs)?

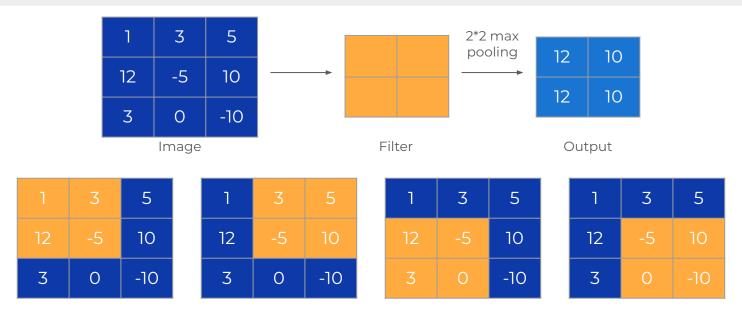
- A To increase the number of parameters.
- To reduce the spatial dimensions of the feature maps, reducing computational complexity.
- To increase the spatial dimensions of the feature maps, reducing computational complexity.
- To scale the input.

Pooling



Decreases the spatial dimensions of feature maps

Reduction in size aids in managing computational complexity, facilitating faster training



Taking the maximum value in each of the regions.



What is the total number of learnable parameters in a Max Pooling layer?

A Depends on the kernel size.

В 1

C Depends on the size of the input feature map

D



What is the total number of learnable parameters in a Max Pooling layer?

A Depends on the kernel size.

В 1

C Depends on the size of the input feature map

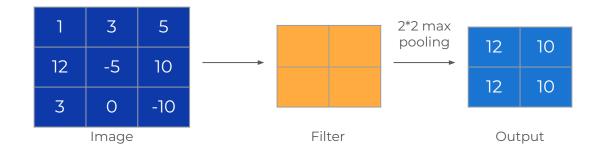
D

Max Pooling



Operates by selecting the maximum value within each pooling region, without any trainable weights or biases.

As we are performing an operation to find the maximum value, there are **no learnable parameters**





Consider the following code snippet for defining a CNN:

```
model = Sequential()
model.add(Conv2D(filters=1, kernel_size=(2, 2), input_shape=(3, 3, 1)))
model.add(Flatten())
model.add(Dense(units=1))
```

Given this model architecture with a 3x3 input image, how many learnable parameters are there in the entire model?

A 10 B 8 C 9 D 5



Consider the following code snippet for defining a CNN:

```
model = Sequential()
model.add(Conv2D(filters=1, kernel_size=(2, 2), input_shape=(3, 3, 1)))
model.add(Flatten())
model.add(Dense(units=1))
```

Given this model architecture with a 3x3 input image, how many learnable parameters are there in the entire model?

A 10 B 8 C 9 D 5

CNN Parameters



w21 w22	wll	w12
	w21	w22

b_w

الم	
dl	

d2

d3

d4



Parameter	Parameter Description	Count
wij	Weights of the CNN layer	4
b_w	Bias of the CNN layer	1
d_i	Weights of the Dense layer	4
b_d	b_d Bias of the Dense layer	

Thus, we have 10 learnable parameters in this neural network



Happy Learning!

