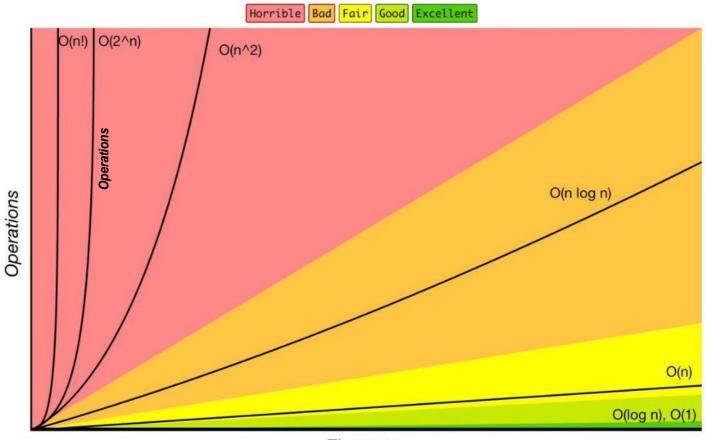
**Big-O Complexity Chart** 



Elements

## **Common Data Structure Operations**

Data Structure	Time Complexity						Space Complexity		
	Average			Worst				Worst	
	Access	Search	Insertion	Deletion	Access	Search	Insertion	Deletion	
Array	O(1)	O(n)	O(n)	O(n)	O(1)	O(n)	O(n)	O(n)	O(n)
Stack	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Queue	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Singly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Doubly-Linked List	O(n)	O(n)	O(1)	O(1)	O(n)	O(n)	O(1)	O(1)	O(n)
Skip List	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n log(n))
Hash Table	N/A	O(1)	O(1)	O(1)	N/A	O(n)	O(n)	O(n)	O(n)
<b>Binary Search Tree</b>	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n)
Cartesian Tree	N/A	O(log(n))	O(log(n))	O(log(n))	N/A	O(n)	O(n)	O(n)	O(n)
B-Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)
Red-Black Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)
Splay Tree	N/A	O(log(n))	O(log(n))	O(log(n))	N/A	O(log(n))	O(log(n))	O(log(n))	O(n)
AVL Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)
KD Tree	O(log(n))	O(log(n))	O(log(n))	O(log(n))	O(n)	O(n)	O(n)	O(n)	O(n)

## **Array Sorting Algorithms**

Algorithm	Time Complex	<b>Space Complexity</b>			
	Best	Average	Worst	Worst	
Quicksort	O(n log(n))	O(n log(n))	O(n^2)	O(log(n))	
Mergesort	O(n log(n))	O(n log(n))	O(n log(n))	O(n)	
Timsort	O(n)	O(n log(n))	O(n log(n))	O(n)	
Heapsort	O(n log(n))	O(n log(n))	O(n log(n))	O(1)	
<b>Bubble Sort</b>	O(n)	O(n^2)	O(n^2)	O(1)	
Insertion Sort	O(n)	O(n^2)	O(n^2)	O(1)	
Selection Sort	O(n^2)	O(n^2)	O(n^2)	O(1)	
Tree Sort	O(n log(n))	O(n log(n))	O(n^2)	O(n)	
Shell Sort	O(n log(n))	O(n(log(n))^2)	O(n(log(n))^2)	O(1)	
Bucket Sort	O(n+k)	O(n+k)	O(n^2)	O(n)	
Radix Sort	O(nk)	O(nk)	O(nk)	O(n+k)	
Counting Sort	O(n+k)	O(n+k)	O(n+k)	O(k)	
Cubesort	O(n)	O(n log(n))	O(n log(n))	O(n)	

## **Graph Data Structure Operations**

<b>Data Structure</b>	Time Complexity						
	Storage	Add Vertex	Add Edge	Remove Vertex	Remove Edge	Query	
Adjacency list	O( V + E )	O(1)	O(1)	O( V  +  E )	O( E )	O( V )	
Incidence list	O( V + E )	O(1)	O(1)	O( E )	O( E )	O( E )	
Adjacency matrix	O( V ^2)	O( V ^2)	O(1)	O( V ^2)	O(1)	O(1)	
Incidence matrix	O( V  ·  E )	O( V  ·  E )	O( V  ·  E )	O( V  ·  E )	O( V  ·  E )	O( E )	

## **Graph Algorithms**

Algorithm	Time Complex	<b>Space Complexity</b>		
	Average	Worst	Worst	
Dijkstra's algorithm	O( E  log  V )	O( V ^2)	O( V  +  E )	
A* search algorithm	O( E )	O(b^d)	O(b^d)	
Prim's algorithm	O( E  log  V )	O( V ^2)	O( V  +  E )	
Bellman-Ford algorithm	O( E  ·  V )	O( E  ·  V )	O( V )	
Floyd-Warshall algorithm	O( V ^3)	O( V ^3)	O( V ^2)	
Topological sort	O( V  +  E )	O( V  +  E )	O( V  +  E )	