

# Лекция 3.3 Кросс сборка для модуля для Beagle bone

Разработал: Максимов А.Н.

# Кросс компиляция

- Установка необходимого ПО
- Сборка ядра
- Сборка модуля

# Кросс компиляция - установка

- `sudo apt-get install gcc-arm-linux-gnueab`
- `sudo apt-get install flex yacc bison u-boot-tools`

# Кросс компиляция

- `export ARCH=arm`
- `export CROSS_COMPILE=arm-linux-gnueabi-`
- `export CC=/usr/bin/arm-linux-gnueabi-gcc`
  
- `make omap2plus_defconfig`
- `make LOADADDR=0x80008000 ulmage dtbs -j4`
- `make modules -j4`
- `make`

# Кросс компиляция

obj-m += hello.o

KDIR := /work/2025\_02/linux-6.6.68

all:

make -C \$(KDIR) M=\$(PWD) modules

clean:

make -C \$(KDIR) M=\$(PWD) clean

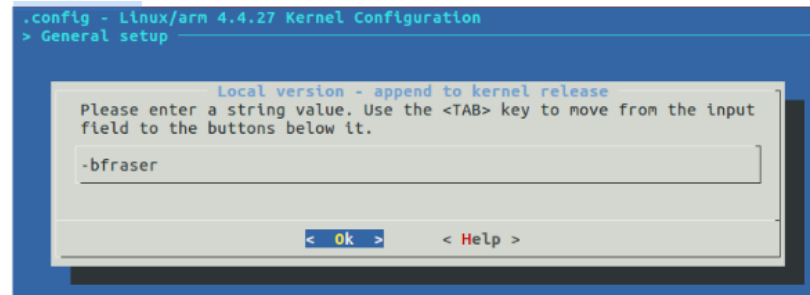
# Установка версии

When the blue kernel configuration menu appears, change the Local Version to be your user ID:

- Select General Setup --> , and press Enter.
- Select Local version - append to kernel release and press Enter.
- Type in a dash and your SFU ID (your login) and press Enter, such as, and shown below in the screen shot:

-bfraser

Screen shot



<https://opencoursehub.cs.sfu.ca/bfraser/grav-cms/cmpt433/guides/files/DriverCreationGuide-FullKernelDownload.pdf>

# Configure

Install compiler:

```
apt-get install gcc-arm-linux-gnueabi  
sudo apt-get install liblz4-tool  
sudo apt-get install u-boot-tools
```

Compile

```
make ARCH=arm bb.org_defconfig
```

```
export CC=/usr/bin/arm-linux-gnueabi
```

```
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- menuconfig
```

```
sudo make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- ulmage dtbs  
LOADADDR=0x80008000 -j4
```

# Копирование результатов

Copy “ulmage” file from “arch/arm/boot directory to the BOOT partition.

Copy “am335x-boneblack.dtb” file from “arch/arm/boot/dts/” directory to the BOOT partition directory 2024\_06.

```
/extlinux/extlinux.conf
```

```
label buildroot
```

```
kernel /2024_06/ulmage
```

```
devicetree /2024_06/am335x-boneblack.dtb
```

```
append console=ttyO0,115200 root=/dev/mmcblk0p2 rootwait
```

<https://opencoursehub.cs.sfu.ca/bfraser/grav-cms/cmpt433/guides/files/DriverCreationGuide-FullKernelDownload.pdf>



# Модификация am325x-bonefoo.dts

```
/dts-v1/;
/plugin/;
/ {
    compatible = "ti,am335x-bone-black";
    fragment@0 {
        target-path = "/";
        __overlay__ {
            my_device {
                compatible = "brightlight,mydev";
                status = "okay";
                label = "Test";
                my_value = <12>;
            };
        };
    };
};
```

# Модификация dts

Модифицировать arch/arm/dts/ti/omap/Makefile

```
make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- dtbs
```

# Пример

```
#include <linux/module.h>
#include <linux/init.h>
#include <linux/mod_devicetable.h>
#include <linux/property.h>
#include <linux/platform_device.h>
#include <linux/of_device.h>

static int dt_probe(struct platform_device *pdev);
static int dt_remove(struct platform_device *pdev);

static struct of_device_id my_driver_ids[] = {
    {
        .compatible = "brightlight,mydev",
    }, { /* sentinel */ }
};

MODULE_DEVICE_TABLE(of, my_driver_ids);

static struct platform_driver my_driver = {
    .probe = dt_probe,
    .remove = dt_remove,
    .driver = {
        .name = "my_device_driver",
        .of_match_table = my_driver_ids,
    },
};
```

Перед сборкой модуля для ядра  
должны быть собраны модули

make ARCH=arm  
CROSS\_COMPILE=arm-linux-  
gnueabi- modules

# Пример overlay

```
static int dt_probe(struct platform_device *pdev) {
    struct device *dev = &pdev->dev;
    const char *label;
    int my_value, ret;
    printk("dt_probe - Now I am in the probe function!\n");
    if(!device_property_present(dev, "label")) {
        printk("dt_probe - Error! Device property 'label' not found!\n");
        return -1;
    }
    if(!device_property_present(dev, "my_value")) {
        printk("dt_probe - Error! Device property 'my_value' not found!\n");
        return -1;
    }
    ret = device_property_read_string(dev, "label", &label);
    if(ret) {
        printk("dt_probe - Error! Could not read 'label'\n");
        return -1;
    }
    printk("dt_probe - label: %s\n", label);
    ret = device_property_read_u32(dev, "my_value", &my_value);
    if(ret) {
        printk("dt_probe - Error! Could not read 'my_value'\n");
        return -1;
    }
    printk("dt_probe - my_value: %d\n", my_value);
    return 0;
}
```

# Пример overlay

```
static int dt_remove(struct platform_device *pdev) {
    printk("dt_probe - Now I am in the remove function\n");
    return 0;
}

/**
 * @brief This function is called, when the module is loaded into the kernel
 */
static int __init my_init(void) {
    printk("dt_probe - Loading the driver...\n");
    if(platform_driver_register(&my_driver)) {
        printk("dt_probe - Error! Could not load driver\n");
        return -1;
    }
    return 0;
}

/**
 * @brief This function is called, when the module is removed from the kernel
 */
static void __exit my_exit(void) {
    printk("dt_probe - Unload driver");
    platform_driver_unregister(&my_driver);
}

module_init(my_init);
module_exit(my_exit);
```