Sachin Fernando

Systems Integration Engineering shfernan@uwaterloo.ca LinkedIn

TECHNICAL COMPETENCIES

Software

programming (C++, Python, MATLAB), ROS, software testing (GoogleTest, pytest), OS (Windows, Linux), CI/CD, Docker, simulation (CARLA, Driving Scenario Designer), libraries (scikit-learn, PyTorch, OpenCV)

Hardware

vehicle testing and CAN interfacing (dSPACE ControlDesk, Vector CANalyzer), sensor calibration (radar, lidar, camera), HV and LV electrical testing/debugging

RESEARCH GROUP

University of Waterloo EcoCAR Team (Mobility Challenge and EV Challenge)

Jan. 2021 – Aug. 2023

Connected and Automated Vehicle Software Development

Waterloo, ON

- Converted stock SUVs from manual control to level 2/3 autonomy by leading perception, controls and V2X algorithm development using ROS based architecture in Python and C++.
- Achieved near 25% increase in tracking accuracy from previous year through alternative sensor fusion techniques. Preliminary validation conducted using CARLA simulator.

Hardware Testing and Integration

- Ensured vehicle performance met engineering standards through hardware-in-the-loop (**HIL**) and vehicle-in-the-loop (**VIL**) tests on local track. Gained proficiency with **CAN** interfacing with Vector CANalyzer.
- Calibrated radar and camera sensors for dynamic driving using CAPL scripts.
- Resolved all major software and hardware issues relating to in-vehicle Electronic Control Units (**ECUs**) using **dSPACE ControlDesk** and HV/LV electronic test equipment.

INTERNSHIPS

Stacktronic

May 2020 – Aug. 2020

Kitchener, ON

Battery Systems Engineering

- Developed model and charging simulations for custom battery pack to determine energy efficiency under various pack configurations using MATLAB's Simscape Electrical toolbox.
- Reduced pack frame's form factor by 15% by re-designing mounting geometry using **Onshape CAD** platform.

Dematic Ltd.

May – Aug. 2018, Jan. – Apr. 2019

Controls and Simulation Engineering

Mississauga, ON

- Supported senior engineer in controls development and commissioning of 100+ conveyor unit system.
- Validated PLC logic for merge and sortation system using RSLogix with Emulate 3D.

EDUCATION

University of Waterloo

Candidate for MASc, Mechatronics Engineering

Aug. 2023

- Thesis: "A Structured Testing Framework for ADAS Software Development"
 - o **Publication**: IEEE International Automated and Vehicle Validation Conference (IAVVC), 2023

BASc, Systems Design Engineering

June 2021

Presidents Scholarship of Distinction (95%+ admission average)

Relevant Coursework

- EV and HEV Design Fundamentals
- Algorithm Design and Analysis
- Autonomous Mobile Robots

- Computational Intelligence
- Multi-sensor Data Fusion
- Control Systems