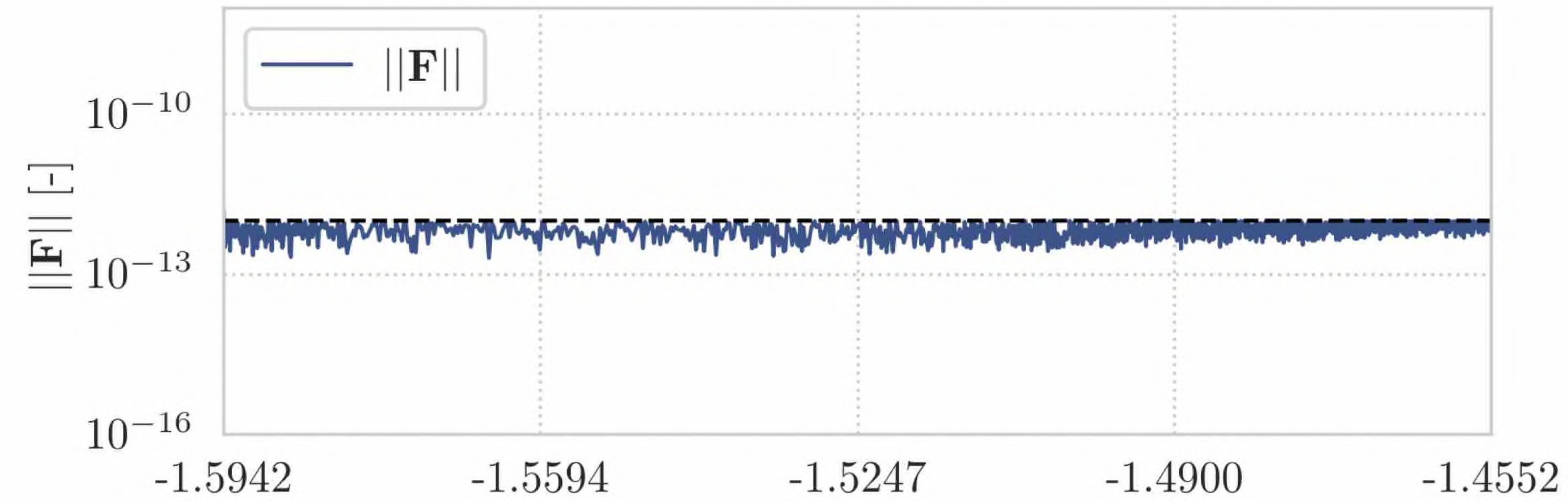
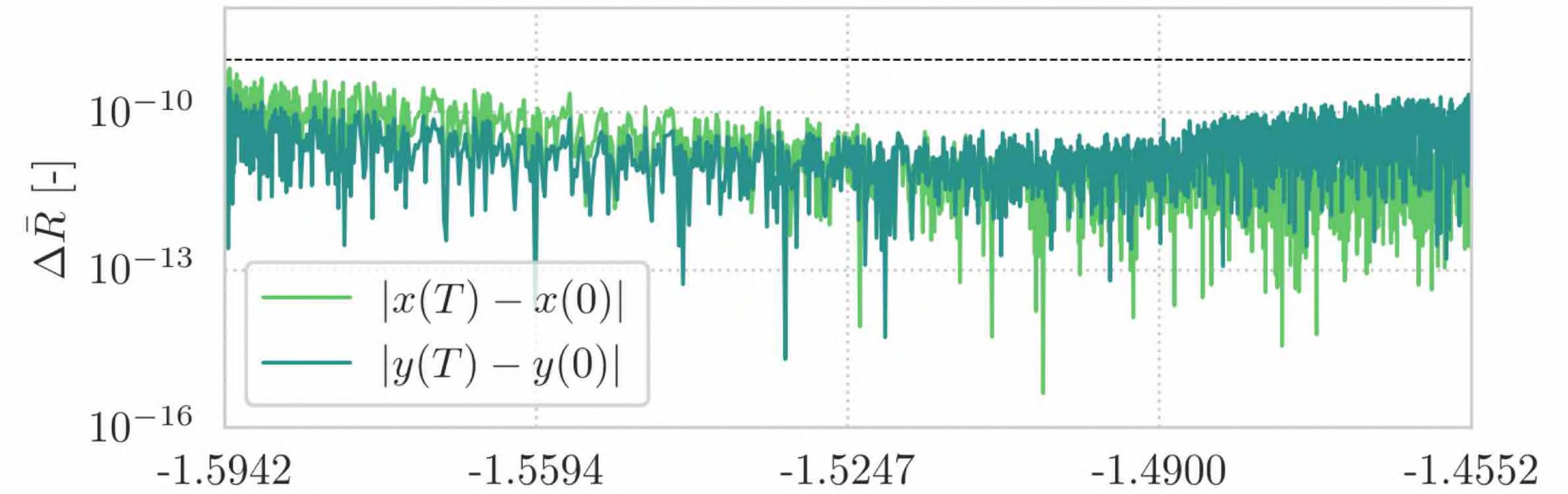


L_1 Horizontal Lyapunov ($a_{lt} = 0.00$, $\alpha = 0$ rad) - Periodicity constraints verification

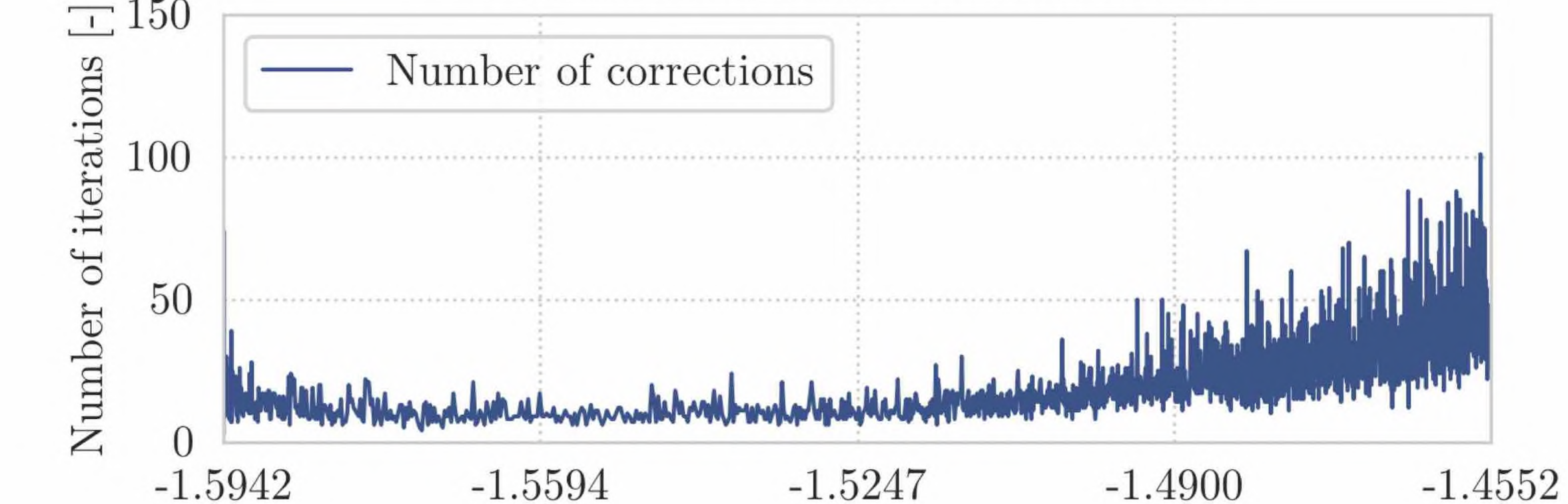
Defect vector magnitude after convergence



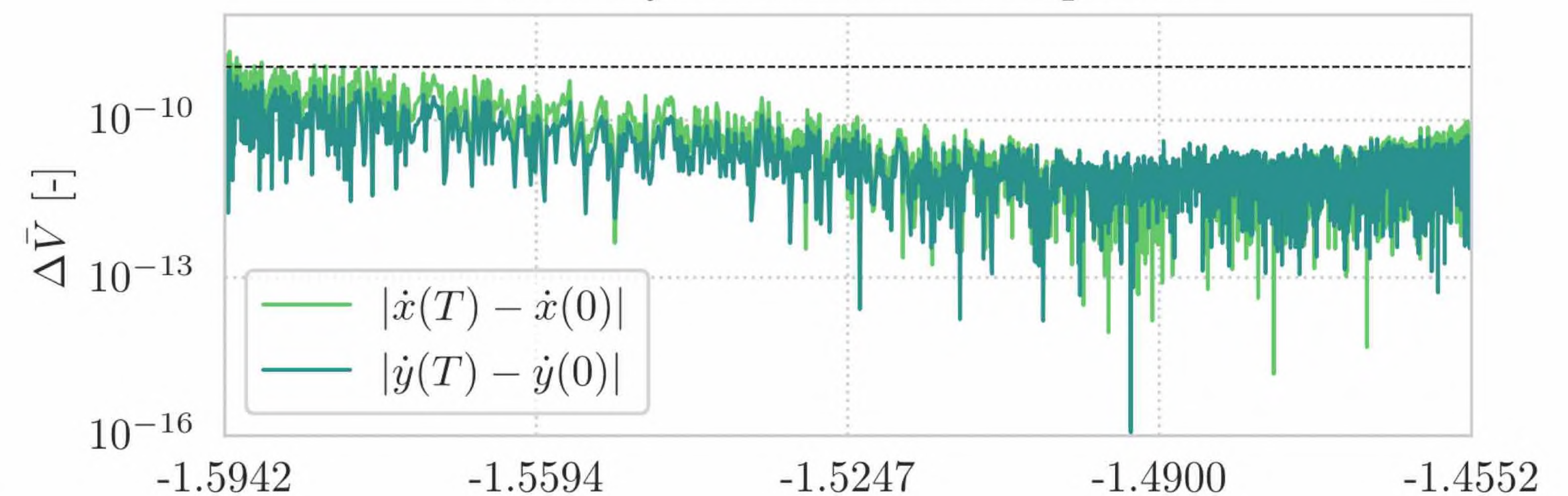
Position deviation at full period



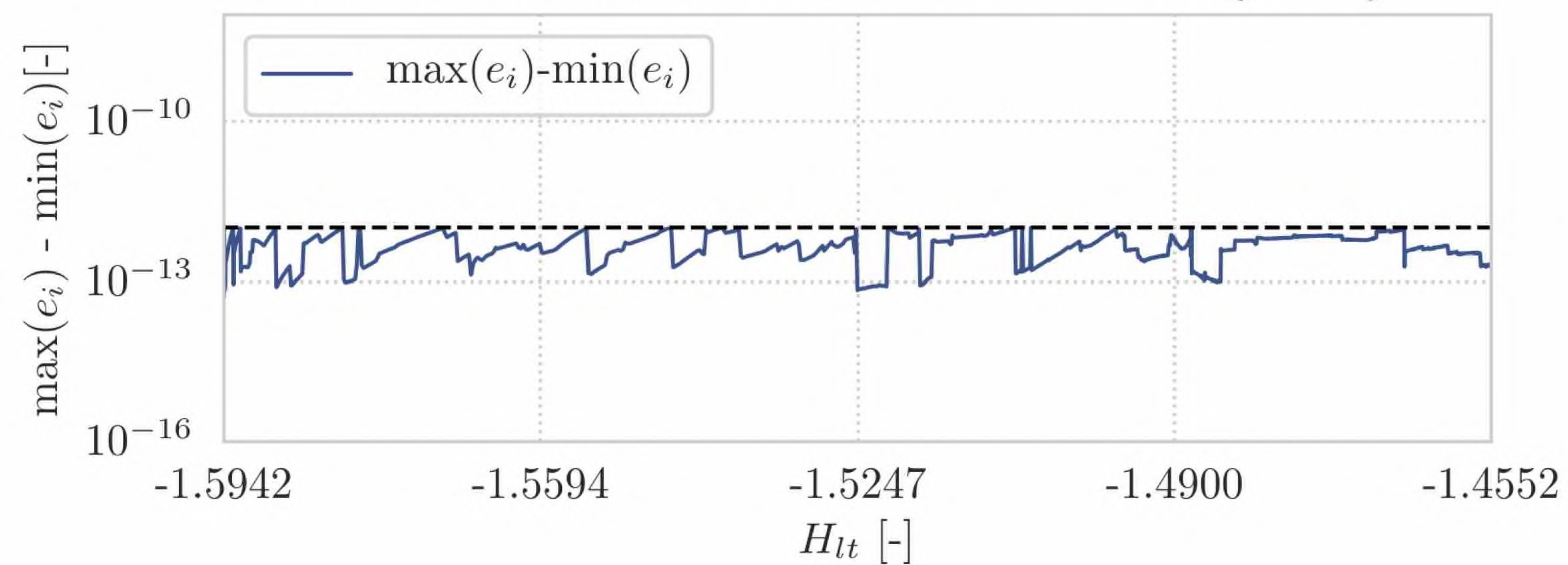
Maximum number of corrections



Velocity deviation at full period



Distribution of errors over collocated trajectory



Maximum collocation segment error

