

Sandy H. Huang

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Education

Ph.D. University of California, Berkeley
Computer Science Advisors: Anca Dragan, Pieter Abbeel
2013–present Expected graduation: June 2019 | GPA 3.96

B.S. with Honors Stanford University
Computer Science Thesis: *Computational Models for Predicting Diagnoses of Depression*
2009–2013 GPA 3.97

Research Experience

Research Assistant Department of Computer Science, UC Berkeley
2015–Present InterACT Lab (PI: Anca Dragan)
2013–Present Robot Learning Lab (PI: Pieter Abbeel)

Undergraduate RA Stanford
2012–2013 Shah Lab (PI: Nigam Shah), Department of Biomedical Informatics
2012 SNAP (PI: Jure Leskovec), Department of Computer Science

Honors and Awards

Rising Stars in EECS	2018
Best Paper Finalist , Human-Robot Interaction (HRI) “Expressing robot incapability”	2018
Chair’s Special Award , UC Berkeley EECS Department For services to the department during student admissions and recruitment	2015
National Science Foundation Graduate Research Fellowship	2014
National Defense Science and Engineering Graduate Fellowship , declined	2014
Berkeley Chancellor’s Fellowship Offered to top 4% of admitted doctoral students	2013
Stanford Terman Award Offered to graduating students with top 5% GPA in School of Engineering	2013
Google Anita Borg Scholar	2012
Other Scholarships Google Engineering Intern (2011), Microsoft Women’s (2010, 2011), Raytheon MathMovesU (2009, 2010)	
Presidential Scholar, National Merit Scholar	2009

Teaching Experience

Teaching Assistant UC Berkeley
Fall 2015 CS 287 Advanced Robotics
Spring 2015 CS 188 Introduction to Artificial Intelligence

Teaching Assistant Stanford
Spring 2013 CS 143 Compilers
Winter 2013 CS 106B Programming Abstractions
Fall 2011 CS 106A Programming Methodology

Industry Experience

DeepMind , Ph.D. Intern with Raia Hadsell	2018
Google , Software Engineering Intern, Display Ads Team	2013
Google , Engineering Practicum Intern, Maps Team	2011

Pre-Prints

Sandy H. Huang*, Isabella Huang*, Ravi Pandya*, and Anca D. Dragan. “Robot gaze as feedback for human teachers”. *Under review at RSS 2019*.

Sandy H. Huang*, Martina Zambelli*, Yuval Tassa, Jackie Kay, Murilo F. Martins, Patrick M. Pilarski, and Raia Hadsell. “Learning gentle object manipulation with curiosity-driven deep reinforcement learning”. *Under review at RSS 2019*.

Sherman Luo, **Sandy H. Huang**, and Anca D. Dragan. “Explainable plan corrections”. *Under review at IJCAI 2019*.

Peer-Reviewed Conference & Journal Papers

- [10] **Sandy H. Huang**, David Held, Pieter Abbeel, and Anca D. Dragan. “Enabling robots to communicate their objectives”. In: *Autonomous Robots (AURO)* 43.2 (2019), pp. 309–326.
- [9] Ravi Pandya, **Sandy H. Huang**, Dylan Hadfield-Menell, and Anca D. Dragan. “Human-AI learning performance in multi-armed bandits”. In: *Proceedings of the AAAI/ACM Conference on Artificial Intelligence, Ethics, and Society (AIES)*. 2019.
- [8] **Sandy H. Huang**, Kush Bhatia, Pieter Abbeel, and Anca D. Dragan. “Establishing appropriate trust via critical states”. In: *Proceedings of the Thirty-First Annual IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. 2018.
- [7] Minae Kwon, **Sandy H. Huang**, and Anca D. Dragan. “Expressing robot incapability”. In: *Proceedings of the Thirteenth Annual ACM/IEEE International Conference on Human Robot Interaction (HRI)*. 2018. **(best paper finalist)**.
- [6] **Sandy H. Huang**, David Held, Pieter Abbeel, and Anca D. Dragan. “Enabling robots to communicate their objectives”. In: *Proceedings of the Thirteenth Annual Robotics: Science and Systems (RSS)*. 2017. **(invited to special issue)**.
- [5] **Sandy H. Huang**, Jia Pan, George Mulcaire, and Pieter Abbeel. “Leveraging appearance priors in non-rigid registration, with application to manipulation of deformable objects”. In: *Proceedings of the Twenty-Eighth IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. 2015.
- [4] Dylan Hadfield-Menell, Alex X. Lee, Chelsea Finn, Eric Tzeng, **Sandy H. Huang**, and Pieter Abbeel. “Beyond lowest-warping cost action selection in trajectory transfer”. In: *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA)*. 2015.

- [3] Alex X. Lee, **Sandy H. Huang**, Dylan Hadfield-Menell, Eric Tzeng, and Pieter Abbeel. “Unifying scene registration and trajectory optimization for learning from demonstrations with application to manipulation of deformable objects”. In: *Proceedings of the Twenty-Seventh IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. 2014.
- [2] **Sandy H. Huang**, Paea LePendou, Srinivasan V. Iyer, Ming Tai-Seale, David Carrell, and Nigam H. Shah. “Toward personalizing treatment for depression: predicting diagnosis and severity”. In: *Journal of the American Medical Informatics Association (JAMIA)* 21.6 (2014), pp. 1069–1075.
- [1] Caroline Suen*, **Sandy H. Huang***, Chantat Eksombatchai*, Rok Sasic, and Jure Leskovec. “NIFTY: A system for large scale information flow tracking and clustering.” In: *Proceedings of the Twenty-Second International World Wide Web Conference (WWW)*. 2013.

Peer-Reviewed Workshop Papers

Sandy H. Huang, Kush Bhatia, Pieter Abbeel, and Anca D. Dragan. Establishing (appropriate) trust via critical states. *HRI Workshop on Explainable Robotic Systems*. 2018.

Sandy H. Huang, Nicolas Papernot, Ian Goodfellow, Yan Duan, and Pieter Abbeel. Adversarial attacks on neural network policies. *ICLR Workshop*. 2017.

Sandy H. Huang, David Held, Pieter Abbeel, and Anca D. Dragan. Enabling robots to communicate reward functions. *NIPS Workshop: Future of Interactive Learning Machines*. 2016. Oral.

Research Mentoring

Current, Ravi Pandya (undergraduate), Sherman Luo (undergraduate), Isabella Huang (Ph.D.)
Former, Minae Kwon (now Ph.D. at Stanford)

Outreach and Service

Women in Computer Science and Electrical Engineering , Social Chair	2015–2016
Held events with a total of several hundred attendees, to strengthen community of female EECS PhDs	
Robot Learning Lab , Outreach Coordinator	2013–2015
Tau Beta Pi , Service Chair	2012–2013
Led volunteers in teaching hands-on engineering lessons to fourth grade students	
Citizen Schools , Citizen Teacher	2011, 2013
Designed curriculum and taught Lego Mindstorm robotics and piano to middle school students	
Society of Women Engineers (SWE) , Middle School Outreach Officer	2010–2011

Professional Activities

Paper reviewing

ACM/IEEE International Conference on Human Robot Interaction (HRI) 2017, 2018, 2019
 IEEE International Conference on Robotics and Automation (ICRA) 2016, 2018, 2019
 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2017, 2019
 Robotics: Science and Systems (RSS) 2019
 International Conference on Machine Learning (ICML) 2019
 Conference on Robot Learning (CoRL) 2017, 2018