APPENDIX A ERROR BOUND FOR REDUCTION

Given a vector $\mathbf{x} \in \mathbb{R}^{1 \times n}$, let $\mathbf{x}' \in \mathbb{R}^{1 \times n}$ be its perturbed version. Define $\mathbf{y} = \mathbf{x}\mathbf{A}$ and $\mathbf{y}' = \mathbf{x}'\mathbf{A}$. The condition number $\kappa(\mathbf{A})$ provides an upper bound on the amplification induced by linear transformation:

$$\frac{\|\mathbf{y}' - \mathbf{y}\|}{\|\mathbf{y}\|} \le \kappa(\mathbf{A}) \cdot \frac{\|\mathbf{x}' - \mathbf{x}\|}{\|\mathbf{x}\|}.$$
 (14)

Recall that the transmitted message of node $t \in \mathcal{T}$ on its outgoing links is given by

$$\mathbf{s}_t = \mathbf{x}_t((\overline{\mathbf{F}}_t^{-1})^T + \mathbf{E}_t^{(1)}),$$

where

$$\mathbf{E}_t^{(1)} = (\mathbf{E}_t^{(rep)})^T + \mathbf{E}_t^{(mul)}.$$

After transmitted by t, \mathbf{s}_t is recoded by the intermediate nodes and finally decoded at ρ . The whole process can be ideally modeled as $\mathbf{s}_t \overline{\mathbf{F}}_t^T$. The decoded message then becomes

$$\mathbf{x}_{t}^{(0)} = \mathbf{s}_{t} \overline{\mathbf{F}}_{t}^{T}$$

The inequality (14) suggests that the error between $\mathbf{x}_t^{(0)}$ and the original message $\mathbf{x}_t = [\mathbf{x}_t(\overline{\mathbf{F}}_t^{-1})^T](\overline{\mathbf{F}}_t^T)$ is lower bounded by:

$$\frac{\|\mathbf{x}_{t}^{(0)} - \mathbf{x}_{t}\|}{\|\mathbf{x}_{t}\|} \leq \kappa(\overline{\mathbf{F}}_{t}) \cdot \frac{\|\mathbf{s}_{t} - \mathbf{x}_{t}(\overline{\mathbf{F}}_{t}^{-1})^{T}\|}{\|\mathbf{x}_{t}(\overline{\mathbf{F}}_{t}^{-1})^{T}\|}$$

$$\leq \kappa^{2}(\overline{\mathbf{F}}_{t}) \cdot \frac{\|\mathbf{E}_{t}^{(1)}\|_{op}}{\|\overline{\mathbf{F}}_{t}^{-1}\|_{op}}.$$
(15)

Additionally, the following inequality holds:

$$\frac{\|\mathbf{x}_{t}^{(0)}\|}{\|\mathbf{x}_{t}\|} \leq \frac{\|\mathbf{x}_{t}^{(0)} - \mathbf{x}_{t}\| + \|\mathbf{x}_{t}\|}{\|\mathbf{x}_{t}\|}
\leq 1 + \kappa^{2}(\overline{\mathbf{F}}_{t}) \cdot \frac{\|\mathbf{E}_{t}^{(1)}\|_{op}}{\|\overline{\mathbf{F}}_{t}^{-1}\|_{op}}.$$
(16)

Fig. 5 illustrates the reduction process in a butterfly network.

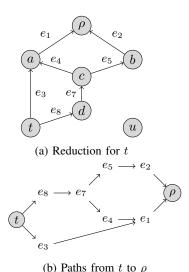


Fig. 5: Reduction process

In the butterfly network, three paths connect t to ρ , which are not mutually disjoint. Some paths may bifurcate into multiple distinct routes midway, while in other instances multiple paths may converge into a single route. We can use vector-matrix multiplication to represent the process of coding and decoding:

$$\begin{bmatrix} \mathbf{x}_{t,1}^{(0)} & \mathbf{x}_{t,2}^{(0)} \end{bmatrix} = \begin{bmatrix} \mathbf{s}_{t,1} & \mathbf{s}_{t,2} \end{bmatrix} \begin{bmatrix} \beta_{e_7,e_5} & \beta_{e_7,e_4} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix}, (17)$$

where $\begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix}$ is a transpose of **A**.

In practice, the round-off error introduced by this sequence of vector-matrix multiplication can't be avoided. The real decoded message $\mathbf{x}_{t}^{(1)}$ is modeled as:

$$\mathbf{x}_{t}^{(1)} = \mathbf{s}_{t}(\overline{\mathbf{F}}_{t}^{T} + \mathbf{E}_{t}^{(2)}).$$

In this model, we define an error matrix $\mathbf{E}_t^{(2)} = (e_{ij} : 1 \le i \le r, 1 \le j \le r)$ to represent error introduced by floating-point number arithmetic operations. $\mathbf{E}_t^{(2)}$ is a random matrix depending on the input \mathbf{s}_t and the subsequent vector-matrix multiplication. It can be derived that:

$$\frac{\left\|\mathbf{x}_{t}^{(1)} - \mathbf{x}_{t}^{(0)}\right\|}{\left\|\mathbf{x}_{t}^{(0)}\right\|} \leq \kappa(\overline{\mathbf{F}}_{t}) \cdot \frac{\left\|\mathbf{E}_{t}^{(2)}\right\|_{op}}{\left\|\overline{\mathbf{F}}_{t}\right\|_{op}}.$$
(18)

By combining inequalities (18) and (16), we derive the upper bound for the distortion rate $\frac{\left\|\mathbf{x}_{t}^{(1)}-\mathbf{x}_{t}\right\|}{\left\|\mathbf{x}_{t}\right\|}$ as follows:

$$\frac{\left\|\mathbf{x}_{t}^{(1)} - \mathbf{x}_{t}\right\|}{\left\|\mathbf{x}_{t}\right\|} \leq \frac{\left\|\mathbf{x}_{t}^{(1)} - \mathbf{x}_{t}^{(0)}\right\| + \left\|\mathbf{x}_{t}^{(0)} - \mathbf{x}_{t}\right\|}{\left\|\mathbf{x}_{t}^{(1)} - \mathbf{x}_{t}^{(0)}\right\|} \\
\leq \frac{\left\|\mathbf{x}_{t}^{(1)} - \mathbf{x}_{t}^{(0)}\right\|}{\left\|\mathbf{x}_{t}^{(0)}\right\|} \cdot \frac{\left\|\mathbf{x}_{t}^{(0)}\right\|}{\left\|\mathbf{x}_{t}\right\|} + \frac{\left\|\mathbf{x}_{t}^{(0)} - \mathbf{x}_{t}\right\|}{\left\|\mathbf{x}_{t}\right\|} \\
\leq \kappa(\overline{\mathbf{F}}_{t}) \cdot \frac{\left\|\mathbf{E}_{t}^{(2)}\right\|_{op}}{\left\|\overline{\mathbf{F}}_{t}^{(1)}\right\|_{op}} \cdot (1 + \kappa^{2}(\overline{\mathbf{F}}_{t}) \cdot \frac{\left\|\mathbf{E}_{t}^{(1)}\right\|_{op}}{\left\|\overline{\mathbf{F}}_{t}^{-1}\right\|_{op}} \\
+ \kappa^{2}(\overline{\mathbf{F}}_{t}) \cdot \frac{\left\|\mathbf{E}_{t}^{(1)}\right\|_{op} \cdot \left\|\mathbf{E}_{t}^{(2)}\right\|_{op}}{\left\|\overline{\mathbf{F}}_{t}^{-1}\right\|_{op}} \\
\leq \kappa^{3}(\overline{\mathbf{F}}_{t}) \cdot \frac{\left\|\mathbf{E}_{t}^{(1)}\right\|_{op} \cdot \left\|\mathbf{E}_{t}^{(2)}\right\|_{op}}{\left\|\overline{\mathbf{F}}_{t}^{-1}\right\|_{op}} \\
+ \kappa^{2}(\overline{\mathbf{F}}_{t}) \cdot \frac{\left\|\mathbf{E}_{t}^{(1)}\right\|_{op}}{\left\|\overline{\mathbf{F}}_{t}^{-1}\right\|_{op}} + \kappa(\overline{\mathbf{F}}_{t}) \cdot \frac{\left\|\mathbf{E}_{t}^{(2)}\right\|_{op}}{\left\|\overline{\mathbf{F}}_{t}\right\|_{op}}. \tag{19}$$

APPENDIX B

EXAMPLE OF NETWORK CODES CONSTRUCTION

APPENDIX C PROOF OF LEMMA 3

Note that $\phi(\alpha) = \prod_{i=1}^m (\alpha^T \alpha + \gamma_i^2)^{r/2} >= \prod_{i=1}^m \gamma_i^r$, $f(\alpha) = \prod_{i=1}^m |b_i^T \alpha|$ and usually r >= 2. We denote the

domain of $\frac{\phi(\alpha)}{f(\alpha)}$ as $D=\{\alpha: f(\alpha)\neq 0\}$, then randomly select a point $\alpha'\in D$. As $\|\alpha\|$ approaches 0, $f(\alpha)$ approaches 0 while $\phi(\alpha)>\prod_{i=1}^m\gamma_i^r$. Thus $\frac{\phi(\alpha)}{f(\alpha)}$ tends to positive infinity. There exists $l\in\mathbb{R}$ such that

APPENDIX D PROOF OF THEOREM 1

This section we verify that coding scheme based on floating-point number exists. Assume that $\widetilde{\mathbf{F}}_t^{i-1}$ is full rank. The updating in the *i*-th step of the algorithm should guarantee that $\widetilde{\mathbf{F}}_t^i$ is full rank in the *i*-th step.

Let $U := \langle \mathbf{c}_{e'} : e' \in \operatorname{In}(v) \rangle$ and $V_t := \langle \widetilde{\mathbf{c}}_{t,k}^{i-1}, 0 \leq k < r, k \neq j \rangle$. Then \mathbf{c}_e must satisfy $\mathbf{c}_e \in U \setminus \bigcup_{t \in \mathcal{T}_e} (U \cap V_t)$, where \mathcal{T}_e is the set of sink nodes with e on one of its paths from the source node.

Let's view this problem from the perspective of linear subspaces. For any $t \in \mathcal{T}$ with e on its path, there exists $\dim(U \cap V_t) \leq \dim(U) - 1$. Since $|\mathcal{T}_e|$ is finite, nearly all of the points in linear space U lie in the set $U \setminus \bigcup_{t \in \mathcal{T}_e} (U \cap V_t)$, which implies that, when based on floating-point number, randomly choosing the $\beta_{e',e}$ for each $e' \in \operatorname{In}(v)$ is sufficient to derive a full-rank matrix $\widetilde{\mathbf{F}}_t^i$. Similar randomized approach can be utilized to construct the matrix \mathbf{A} .

As the algorithm stops, we see that $\widetilde{\mathbf{F}}_t = \overline{\mathbf{F}}_t$ since, in each step i of the algorithm, $\widetilde{\mathbf{F}}_{t,j}$ always takes the value of \mathbf{c}_e where e is the most downstream edge in the truncation in G^i of the j-th edge-disjoint path from the source node ρ to sink node t in \mathcal{T} .

APPENDIX E PROOF OF THEOREM 2

Assume that point α_1 minimizes function $\frac{\phi}{f}$ globally and α_0 is the maximizer for f as it constrained on the unit sphere, then the point $\frac{\alpha_1}{\|\alpha_1\|} \in \{x : \alpha^T \alpha = 1\}$ satisfying $f(\frac{\alpha_1}{\|\alpha_1\|}) \leq f(\alpha_0)$. Since $f(\alpha_1) = \|\alpha_1\|^m \cdot f(\frac{\alpha_1}{\|\alpha_1\|})$ and $f(\|\alpha_1\| \cdot \alpha_0) = \|\alpha_1\|^m \cdot f(\alpha_0)$ there exists $f(\alpha_1) \leq f(\|\alpha_1\| \cdot \alpha_0)$. Simultaneously, $\phi(\alpha_1^T \alpha_1) = \phi((\|\alpha_1\| \cdot \alpha_0^T)(\|\alpha_1\| \cdot \alpha_0))$ because $\alpha_0^T \alpha_0 = 1$. Thus $\|\alpha_1\| \cdot \alpha_0$ minimizes our objective function.

APPENDIX F CONSTRUCTION OF GENERATOR MATRIX

To optimize the initial generator matrix \mathbf{A} , we propose a heuristic algorithm to reduce $\prod_{t \in \mathcal{T}} \kappa(\widetilde{\mathbf{F}}_t^0)$.

First, initialize \mathbf{A} by sampling each entry uniformly from [0,2]. Note that each column in \mathbf{A} corresponds to a coefficient vector \mathbf{c}_e such that $e \in \mathrm{Out}(\rho)$. And each transfer matrix $\widetilde{\mathbf{F}}_t^0$ consists of a subset of $\{\mathbf{c}_e: e \in \mathrm{Out}(\rho)\}$. We replace the columns of \mathbf{A} appearing in only one transfer matrix $\widetilde{\mathbf{F}}_t^0$ with standard basis vectors $\{\hat{\mathbf{e}}_i: i=1,\dots r\}$ while preserving the full-rank property of $\widetilde{\mathbf{F}}_t^0$.

Next, shared columns are optimized. For a column $\mathbf{c_e}$, let $\mathcal{T}_e \subset \mathcal{T}$ denote the set of sink nodes where \mathbf{c}_e appears in their transfer matrices. Using our optimization framework, we compute coefficients $\{\beta_i\}_{i=1}^r$ to reconstruct $\mathbf{c}_e = \sum_{i=1}^r \beta_i \hat{\mathbf{e}}_i$.

This process is iterated for all shared columns, with multiple refinement cycles possible to improve results.