Algorithm 1 Construction of a set \mathcal{A} with $H(\mathbf{c}_{\mathcal{A}}) < ML$ for a shift-XOR LRC

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1: Set A_0 = \emptyset and i = 1
      while H(\mathbf{c}_{A_{i-1}}) < ML do
              Pick j_i \notin \mathcal{A}_{i-1} s.t. |\Gamma(j_i) \setminus \mathcal{A}_{i-1}| \geq \delta - 1
  3:
              if H(\mathbf{c}_{A_{i-1}}, \mathbf{c}_{\Gamma(j_i)}) < ML then
  4:
                    set \mathcal{A}_i = \mathcal{A}_{i-1} \cup \Gamma(j_i)
  5:
              else if H(\mathbf{c}_{A_{i-1}}, \mathbf{c}_{\Gamma(j_i)}) \geq ML then
  6:
                             \operatorname*{arg\,max}_{\mathcal{T}' \subset \Gamma(j_i); H(\mathbf{c}_{\mathcal{A}_{i-1}}, \mathbf{c}_{\mathcal{T}'}) < ML} |\mathcal{T}'|
  7:
                    if \mathcal{T} = \emptyset then
  8:
  9:
                           break
10:
                    else
                           set A_i = A_{i-1} \cup T
11:
                           break
12:
                    end if
13:
              end if
14:
15:
             i = i + 1
16: end while
17: Output: A = A_{i-1}
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Proof of Theorem 1. Let file X consist of M sequences, where each sequence contains L bits that are independent and identically distributed (i.i.d.) uniform random variables over the binary field. The (binary) entropy of this file is

$$H(\mathbf{X}) = ML. \tag{3}$$

For a general shift-XOR code that encodes the file X into n code blocks $C = [c_1, c_2, \dots, c_n]$, where by the independence bound, each coded block has entropy

$$H(\mathbf{c}_i) < \alpha L + S. \tag{4}$$

By the defintion of (r, δ) locality, for any indices $j \in [n]$, there exists a set of indices $\Gamma(j) \subseteq [n]$, where $j \in \Gamma(j)$, $|\Gamma(j)| \le r + \delta - 1$ and any code block indexed by this group can be reconstructed from any other r blocks in the same group. Then, we can deduce that $H(\mathbf{c}_{\Gamma(j)}) \le r(\alpha L + S)$, where $\mathbf{c}_{\Gamma(j)} \triangleq \{\mathbf{c}_i : i \in \Gamma(j)\}$.

As the original file can be reconstructed from any k nodes, for any subset $\mathcal{A} \subseteq [n]$ with $|\mathcal{A}| \geq k$, we have $H(\mathbf{c}_{\mathcal{A}}) = ML$. Then we have

$$k \ge 1 + \max_{H(\mathbf{c}_{\mathcal{A}}) < ML} |\mathcal{A}|. \tag{5}$$

To establish a lower bound on k, we follow the approach in [1], [9], [21] to construct the largest possible subset $\mathcal{A}\subseteq [n]$ of indices that the corresponding blocks cannot reconstruct the original file. It is achieved by adapting an algorithm from [9], [21], as given in Algorithm 1. The algorithm starts with $\mathcal{A}_0=\emptyset$, and iteratively expands \mathcal{A}_{i-1} to \mathcal{A}_i by adding at most $r+\delta-1$ elements. For each iteration i, we define:

$$a_i = |\mathcal{A}_i| - |\mathcal{A}_{i-1}| \tag{6}$$

$$h_i = H(\mathbf{c}_{\mathcal{A}_i}) - H(\mathbf{c}_{\mathcal{A}_{i-1}}) \tag{7}$$

Let ℓ denote the number of iterations before termination, i.e., $\mathcal{A} = \mathcal{A}_{\ell}$. Then the final set size and entropy can be expressed as the sum of their increments:

$$|\mathcal{A}| = |\mathcal{A}_{\ell}| = \sum_{i=1}^{\ell} a_i \tag{8}$$

$$H(\mathbf{c}_{\mathcal{A}}) = H(\mathbf{c}_{\mathcal{A}_{\ell}}) = \sum_{i=1}^{\ell} h_i$$
 (9)

In step 3, such a j_i always exists, since otherwise, by the (r, δ) locality, $\mathbf{c}_{\mathcal{A}_{i-1}}$ can recover all other coded blocks not indexed in \mathcal{A}_{i-1} and hence $H(\mathbf{c}_{\mathcal{A}_{i-1}}) = ML$, which is a contradiction. Therefore, the algorithm can terminate at either step 9 or step 12, which are analyzed separately:

Case 1: Suppose that the algorithm terminates at step 9, i.e., after adding $\Gamma(j_{\ell})$ to $\mathcal{A}_{\ell-1}$ in the ℓ -th iteration. For each iteration $i \leq \ell$, we analyze the entropy increment h_i as follows:

$$h_{i} = H(\mathbf{c}_{\mathcal{A}_{i}}) - H(\mathbf{c}_{\mathcal{A}_{i-1}})$$

$$= H(\mathbf{c}_{\mathcal{A}_{i-1} \cup (\mathcal{A}_{i} \setminus \mathcal{A}_{i-1})}) - H(\mathbf{c}_{\mathcal{A}_{i-1}})$$

$$= H(\mathbf{c}_{\mathcal{A}_{i-1}}) + H(\mathbf{c}_{\mathcal{A}_{i} \setminus \mathcal{A}_{i-1}} | \mathbf{c}_{\mathcal{A}_{i-1}}) - H(\mathbf{c}_{\mathcal{A}_{i-1}})$$

$$= H(\mathbf{c}_{\mathcal{A}_{i} \setminus \mathcal{A}_{i-1}} | \mathbf{c}_{\mathcal{A}_{i-1}})$$

$$\leq (a_{i} - \delta + 1)(\alpha L + S). \tag{10}$$

The last inequality holds as follow: in iteration i, $a_i = |\Gamma(j_i) \setminus A_{i-1}| \ge \delta - 1$ new blocks are added to A_{i-1} . Among the a_i newly added blocks in iteration i, at least $\delta - 1$ blocks are deterministic functions of the other blocks indexed in $\Gamma(j_i)$. Therefore, these $\delta - 1$ blocks do not contribute to the entropy increment, leaving at most $(a_i - \delta + 1)$ blocks that can contribute at most $(\alpha L + S)$ each to the entropy.

From (10), we can derive a lower bound on the size increment:

$$a_i \ge \frac{h_i}{\alpha L + S} + \delta - 1. \tag{11}$$

Substituting this into (8), we obtain:

$$|\mathcal{A}| = |\mathcal{A}_{\ell}| = \sum_{i=1}^{\ell} a_{i}$$

$$\geq \sum_{i=1}^{\ell} \left(\frac{h_{i}}{\alpha L + S} + \delta - 1 \right)$$

$$= \frac{1}{\alpha L + S} \sum_{i=1}^{\ell} h_{i} + (\delta - 1)\ell \qquad (12)$$

$$= \frac{1}{\alpha L + S} H(\mathbf{c}_{\mathcal{A}}) + (\delta - 1)\ell \qquad (13)$$

We now give a lower bound on $H(\mathbf{c}_{\mathcal{A}})$ and ℓ . Since the algorithm is exiting, we know that no additional index $j \notin \mathcal{A}$ can be added to our current index set \mathcal{A} without violating $H(\mathbf{c}_{\mathcal{A}}) < ML$. This means that $H(\mathbf{c}_{\mathcal{A}})$ must be sufficiently close to ML. Specifically, we argue that

$$H(\mathbf{c}_{\mathcal{A}}) \ge ML - (\alpha L + S).$$
 (14)

This holds because if we assume otherwise, i.e., $H(\mathbf{c}_A) \leq$ $ML - (\alpha L + S) - \epsilon$ for any $\epsilon > 0$, then we could always find a new index $j \notin A$ such that adding the corresponding coded block c_i would increase the total entropy by at most $(\alpha L + S)$, keeping the total entropy below ML. This contradicts the exit condition of the algorithm.

For the lower bound on ℓ , we analyze the entropy increment in each iteration. From the locality constraint, we know $a_i - \delta +$ $1 \le r$, which together with (10) implies that $h_i \le r(\alpha L + S)$. This means each iteration can contribute at most $r(\alpha L + S)$ to the total entropy increment. Furthermore, from (14) we know that the total entropy increment must reach at least ML - $(\alpha L + S)$. Therefore:

$$\ell \ge \left\lceil \frac{H(\mathbf{c}_{\mathcal{A}})}{r(\alpha L + S)} \right\rceil \ge \left\lceil \frac{M}{r(\alpha + \frac{S}{L})} \right\rceil - 1$$
 (15)

Combining (13), (14), and (15) yields:

$$|\mathcal{A}_{\ell}| \ge \left\lceil \frac{M}{\alpha + \frac{S}{L}} \right\rceil - 1 + \left(\left\lceil \frac{M}{r(\alpha + \frac{S}{L})} \right\rceil - 1 \right) (\delta - 1).$$
 (16)

Case 2: Here, the algorithm terminates at step 12 in the ℓ -th iteration because:

$$H(\mathbf{c}_{\mathcal{A}_{\ell-1} \cup \Gamma(j_{\ell})}) \ge ML.$$
 (17)

Since each iteration increases the entropy by at most $r(\alpha L +$ S), we have:

$$\ell \ge \left\lceil \frac{ML}{r(\alpha L + S)} \right\rceil. \tag{18}$$

The size increments are bounded as in Case 1:

$$a_i \ge \frac{h_i}{\alpha L + S} + \delta - 1, \quad \text{for } i \le \ell - 1.$$
 (19)

Note that in the last iteration, we only add a subset $\mathcal{T} \subset \Gamma(j_{\ell})$ rather than the set, thus we cannot guarantee $|\mathcal{T}| \geq \delta - 1$ and the existence of $\delta-1$ deterministic blocks. For the last iteration,

$$a_{\ell} \ge \frac{h_{\ell}}{\alpha L + S}.\tag{20}$$

Combining (8), (14), (18), (19), and (20), we obtain:

$$|\mathcal{A}_{\ell}| = \sum_{i=1}^{\ell} a_{i}$$

$$\geq \sum_{i=1}^{\ell-1} \left(\frac{h_{i}}{\alpha L + S} + \delta - 1 \right) + \frac{h_{\ell}}{\alpha L + S}$$

$$= \frac{1}{\alpha L + S} H(\mathbf{c}_{\mathcal{A}}) + (\ell - 1)(\delta - 1)$$

$$\geq \left[\frac{M}{\alpha + \frac{S}{L}} \right] - 1 + \left(\left[\frac{M}{r(\alpha + \frac{S}{L})} \right] - 1 \right) (\delta - 1). \quad (21)$$

Finally, combining (5), (16), and (21), we establish the lower

$$k \ge \left\lceil \frac{M}{\alpha + \frac{S}{L}} \right\rceil + \left(\left\lceil \frac{M}{r(\alpha + \frac{S}{L})} \right\rceil - 1 \right) (\delta - 1).$$

Proof of Theorem 2. Each sequence with subscript j in the fail node of repair group $i, i \in [N]$ is contained in a $(\delta - 1, r)$ shift-XOR system

$$[p_j^1, p_j^2, \dots, p_j^{\delta-1}]^T = \mathbf{\Omega}[y_j^1, \dots, y_j^r]^T,$$

where $j \in [(i-1)(r+\delta-1), i(r+\delta-1)], i \in [N]$. We have $\sum_{(i-1)(r+\delta-1)} \sigma_j = r(\delta-1)$, which is independent of helper node selection. The recovery of sequences in Y requires $(r-1)r(\delta-1)L$ XOR operations. Generating local parity sequences requires an additional $(r-1)(\delta-1)(L+O(r\delta))$ XOR operations, totaling $(r^2 - 1)(\delta - 1)(L + O(r\delta))$ XOR operations.

(15) Proof of Theorem 3. As $B = \left\lceil \frac{rk}{r_{\delta}} \right\rceil + \left(\left\lceil \frac{k}{r_{\delta}} \right\rceil - 1 \right) (\delta - 1)$, and $k = r_{\delta}(\left\lceil \frac{k}{r_{\delta}} \right\rceil - 1) + t$ where $1 \le t < r_{\delta}$, we have:

$$B - k = r\left(\left\lceil \frac{k}{r_{\delta}} \right\rceil - 1\right) + \left\lceil \frac{rt}{r_{\delta}} \right\rceil + \left(\left\lceil \frac{k}{r_{\delta}} \right\rceil - 1\right)(\delta - 1)$$
$$- r_{\delta}\left(\left\lceil \frac{k}{r_{\delta}} \right\rceil - 1\right) - t$$
$$= \left\lceil \frac{rt}{r_{\delta}} \right\rceil - t$$

Since $\frac{rt}{r_{\delta}} = \frac{rt}{r+\delta-1} < t$, we have $B - k \le 0$. On the other hand, since $\left\lceil \frac{rt}{r_{\delta}} \right\rceil \ge \frac{rt}{r_{\delta}}$ and $1 \le t < r_{\delta}$:

$$B-k \geq -t \left(\frac{\delta-1}{r_\delta}\right) \geq -(r_\delta-1) \left(\frac{\delta-1}{r_\delta}\right) > -(\delta-1).$$

Therefore, $-(\delta - 1) < B - k \le 0$. Since both B and k are integers:

$$|B - k| \le \delta - 2.$$

For B = k to hold, we require:

$$\left\lceil \frac{rt}{r_{\delta}} \right\rceil = t \Leftrightarrow \frac{rt}{r_{\delta}} > t - 1 \Leftrightarrow r > (\delta - 1)(t - 1)$$

When $\delta = 2$, k = B always holds.

Proof of Theorem 4. When b = 0, for each codeword, accessing any r nodes from each of the q parity groups allows recovery of all rg^F global parity sequences and computation of new global parity sequences. This requires accessing λqr nodes in the initial codewords and g^F nodes in the final codeword for data writing.

When $b \neq 0$ and $g^F \leq b$, all required global parity sequences are in the mixed group. By accessing any r nodes in the mixed group, we need λr node accesses in the initial codewords. Additionally, regrouping the systematic sequences in the mixed group of each initial codeword requires accessing $\lambda(r_{\delta}-d)$ nodes in the final codeword.

When $b \neq 0$ and $g^F > b$: If h = 0, the required global parity sequences span over (q+1) repair groups, requiring $\lambda(q+1)r$ node accesses in the initial codewords, plus $\lambda(r_{\delta} - b)$ nodes in the final codeword for regrouping.

If h>0, the required global parity sequences span over (q+2) repair groups, necessitating $\lambda(q+2)r$ node accesses in the initial codewords, plus $\lambda(r_\delta-b)$ nodes in the final codeword for regrouping. Due to the cyclic shift pattern, collecting global parity sequences with the same subscript requires accessing r nodes within a repair group, making this strategy consistently more efficient than direct access.

In all cases, we need additional g^F nodes access for writing the new global parity sequences.

Proof of Theorem 5. From [17], for an (n, k) Two-Tone shift-XOR system, the storage overhead is at least

$$\begin{cases} \frac{(n^2-1)(k-1)}{4}, & \text{if } n \text{ is odd} \\ \frac{n^2(k-1)}{4}, & \text{if } n \text{ is even} \end{cases}$$

with equality if and only if using a reflected Vandermonde matrix.

For the global parity generation, matrix Φ can be viewed as r separate (n-k,k) shift-XOR systems. Each system has a storage overhead of at least:

$$S(\mathbf{\Phi}) = (k-1)\eta_1$$

where $\eta_1 = \frac{(n-k)^2 - \alpha_1}{4}$ and $\alpha_1 = 1$ if n-k is odd (0 if even). Similarly, the local parity generation through matrix Ω can be viewed as n separate $(\delta - 1, r)$ shift-XOR systems, where

$$S(\mathbf{\Omega}) = (r-1)\eta_2$$

where $\eta_2 = \frac{(\delta-1)^2 - \alpha_2}{4}$ and $\alpha_2 = 1$ if $\delta-1$ is odd (0 if even). Since the local parity generation operates on shifted sequences from \mathbf{Y} , it introduces an extra storage overhead of $(\delta-1)S(\mathbf{\Phi})$.

Therefore, the total storage overhead is $S' = (r + \delta - 1)S(\Phi) + nS(\Omega)$, which equals \hat{S} if and only if both Φ and Ω are Reflected Vandermonde matrices.