

**Stochastic Volatility  
From GARCH to the SV Model**

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## **TABLE OF CONTENTS**

### **1. ARCH Family of Models**

- 1.1 Limitation of the log-normal distribution
- 1.2 Basic GARCH
- 1.3 Estimation, forecasting and Diagnostics
- 1.4 Crucial Extension: Fat-Tails
- 1.5 Crucial Extension: Asymmetric volatility
- 1.6 Factor GARCH

### **2. Stochastic Volatility Models (SVOL)**

- 2.1 Description - difference with ARCH
- 2.2 Extensions: asymmetric volatility and fat tails

# 1. ARCH Family of Models

## 1.1 Limitation of the Lognormal distribution

### Stylized facts on asset returns

returns 的问题

- Fat tails 肥尾
- Clustering: "Periods of high variance tend to follow periods of high variance."  
Mandelbrot. Volatility 聚集
- Leverage effect: Higher volatility when Returns are (more) negative  $\mu$  negative,  $\sigma \uparrow$
- Non uniform information arrival - French&Roll (JFE 1986) 信息不对称
- Not so stylized fact:  
Smile in BS-ISD vs.  $\ln(S / PV(X))$  波动率微笑  
Time varying volatility as in Hull & White can also cause this.
- Recall: Normal mixture with random  $\sigma$  is fat-tailed (Student-t if  $\sigma \sim \text{IG}$ )

## 1.2 Basic GARCH model

GARCH模型是说，今天的方差不仅依赖于过去的收益率的变化 [公式]，还依赖于过去的方差 [公式]，而ARCH只说这个方差依赖于过去收益率的变化 [公式]。

- GARCH(p,q)

$$R_t = \mu_t + u_t = \mu_t + \sqrt{h_t} \varepsilon_t, \quad u_t \sim N(0, h_t)$$

$$h_t = \omega + \alpha_1 u_{t-1}^2 + \alpha_2 u_{t-2}^2 + \dots + \alpha_q u_{t-q}^2 + \beta_1 h_{t-1} + \beta_2 h_{t-2} + \dots + \beta_p h_{t-p}$$

## 1.3 Estimation, forecasting, diagnostic and forecasting

Estimation by maximum likelihood or Bayesian MCMC methods

- Given the parameters and max(p,q) initial values, volatility is observable
- Constrained optimization needed:  $\alpha > 0, \beta > 0, \Sigma(\alpha + \beta) < 1$  否则 not, no sense
- Likelihood can be flat for small samples 小样本不太收敛

## Diagnostics

$$R_t = \mu_t + u_t, \quad u_t \sim N(0, \sigma_t)$$

$$h_t = \omega + \alpha_1 u_{t-1}^2 + \alpha_2 u_{t-2}^2 + \dots + \alpha_q u_{t-q}^2 + \beta_1 h_{t-1} + \beta_2 h_{t-2} + \dots + \beta_p h_{t-p}$$

$$\text{Estimation} \quad \Rightarrow \quad \hat{\alpha}, \hat{\beta}, \hat{h}_t, t = 1, \dots, T$$

$$\Rightarrow \hat{u}_t, t = 1, \dots, T$$

If model is correct

$$\Rightarrow \hat{u}_t / \sqrt{\hat{h}_t} \sim \text{i.i.d. } N(0,1)$$

$\Rightarrow$  test normality

$\Rightarrow$  test ACF  
GARCH(1,1)

Rarely need more than 1 lag of each

## 1.4 Crucial extension: Fat-Tailed conditional returns

- For financial returns:  $\hat{u}_t / \sqrt{\hat{h}_t}$  is **not normal** after GARCH modeling:
- That is, in  $R_t = \mu_t + \sqrt{h_t} \varepsilon_t$ ,  $\varepsilon_t$  is **not normally distributed**
- $\varepsilon_t$  is fat-tail  $\Rightarrow$  shortfall probabilities, VAR are incorrect:  
i.e.,  $\text{Prob}[R_{t+1} < \mu_{t+1} - 1.65 \sqrt{h_{t+1}}] = 0.05$

Instead:  $\varepsilon_t \sim \text{Student}(\nu)$

$\varepsilon_t \sim \text{GED}(\nu)$  Dan Nelson's EGARCH *generalized error dist (normal)*

$$\text{GED: } f(\varepsilon_t) = \frac{\nu \exp\{-0.5|\varepsilon / \lambda|^\nu\}}{\lambda 2^{[\nu+1/2]} \Gamma(1/\nu)},$$

*关于  $\varepsilon_t$*

$$\text{with } \lambda = \sqrt{2^{-2/\nu} \Gamma(1/\nu) / \Gamma(3/\nu)}$$

$$\nu = 2; \quad \text{GED} \sim \text{N}(0,1)$$

$$\nu < 2; \quad \text{Fat-tails}$$

EGARCH是从GARCH衍生出的模型，是为了解释“杠杆效应”。

先说一下“杠杆效应”，经验性的分析表明，金融资产收益率的涨跌这个定性结果对未来波动性的影响是不同的。注意，这个现象GARCH(ARCH)模型是不能解释的。因为在GARCH(ARCH)中，历史数据是以平方的形式影响未来波动率的，所以涨或跌对未来波动率的影响是一样的。

为了可以解释“杠杆效应”，必须舍弃平方这个对称函数，历史数据应该通过一个“非对称函数”影响未来波动率，EGARCH正是这样处理历史数据的。那么新的问题来了，非对称函数可能会打破GARCH模型的“合理性”，简单地讲，未来波动率可能出现“负值”。解决方法也简单，用波动率的对数代替波动率，合理性就得到了保证。

总之，杠杆效应是理解EGARCH的关键词，蔡老师的《金融时间序列分析》有一节专门讲EGARCH，阁下可以仔细阅读一下。

- $\gamma$  must be estimated for best fit.

Conditional dist is non-normal.

- Results: Strong evidence of non normality of the conditional distributions

- Normal based GARCH standard errors generally understate standard errors if  $\varepsilon_t$  is fat-tailed.

Fat-tail condition Garch  
考虑到了肥尾

## 1.5 Crucial Extension: Asymmetric volatility

EGARCH :  $R_t = \mu_t + u_t$ ,  $u_t \sim N(0, h_t)$

$$\ln h_t = \omega + \alpha_1 (\underbrace{\varphi \varepsilon_{t-1} + \gamma [|\varepsilon_{t-1}| - E|\varepsilon_{t-1}|]}_{g(\varepsilon)}) + \beta_1 \ln h_{t-1}$$

No restriction on parameters for  $h_t > 0$   
 $g(\varepsilon) \Rightarrow$  条件均值为 0  
 所有参数均可正或负，因为是 log，e 出来就都为正了。

Volatility cycles are possible

If  $\alpha_1 \varphi < 0$ ,  $h_t$  rises after a  $< 0$  shock more than after a positive shock.

Recall: The leverage effect is a misnomer, better term: Volatility Feedback

市场对负面消息的影响更大

Assymetric GARCH (Glosten, Jagannathan, Runkle GJR): *也考虑到了正负收益的不对称性*

$$R_t = \mu_t + u_t, \quad u_t \sim N(0, h_t)$$

$$h_t = \omega + \alpha_1 D_{t-1} \varepsilon_{t-1}^2 + \alpha_2 \varepsilon_{t-1}^2 + \beta_1 \ln h_{t-1} \text{ where } D_t = 0 \text{ if } \varepsilon_t < 0$$

*more shock on negative return*

## 1.6 Multivariate Factor GARCH

Best first pass at a multivariate GARCH model

Start with a classic K factor model.

Allow the covariance matrix of factors to vary with time.

$$\begin{matrix} R_t & = & \mu & + & B & f_t & + & v_t \\ \text{nx1} & & \text{nx1} & & \text{nxk} & \text{kx1} & & \text{nx1} \end{matrix} \quad \begin{matrix} k \text{ factors} & \ll & n \text{ stocks} \end{matrix}$$

Factors  $f_{1t}, \dots, f_{kt}$ :

Observable,

Or Unobservables (Principal Components, Gibbs Sampling) *见 EJ. 13*



$$E(f_{kt} f_{lt}) = 0 \quad E(F_k' F_l) = 0$$

Diagonal Factor Covariance Matrix

$$E_t(f_{k,t+1}^2) = h_{k,t+1} = \omega_k + \beta_k h_{k,t} + \alpha_k (f_{k,t})^2 \quad \text{GARCH on factor volatility}$$

$$E_t(v_{t+1} v_{t+1}^T) = D_{t+1} \quad \text{If needed GARCH on diagonal idiosyncratic covariance matrix}$$

$$E[\varepsilon_{t+1} \varepsilon_{t+1}'] = D_{t+1}$$

$$\Omega_{t+1} = E_t(u_{t+1}, u_{t+1}^T) = B E_t(f_{t+1} f_{t+1}^T) B^T + D_{t+1}$$

## 2 Stochastic Volatility Model (SV)

### 2.1 Difference with GARCH

- SVOL(1):  
 $R_t = \sqrt{h_t} e_t,$   
 $\log h_t = \alpha + \delta \log h_{t-1} + v_t, \quad v_t \sim N(0, \sigma_v)$

Why logarithm? It is a discrete time model

- $v_t$  adds variability to  $h_t$   
induces more kurtosis than the ARCH.
- GARCH: kurtosis is linked to persistence via  $\alpha, \beta$ . Can't model separately  
SVOL: kurtosis is modeled separately via  $\sigma_v$  不一样

### Why does GARCH work relatively well?

Many GARCH models, even if misspecified, have some good filtering properties for the true continuous time model: asymptotically consistent estimation of  $\sigma_t$  因为渐进

- ARCH filter is asymptotically more efficient than the Kalman filter often used for estimating SV models!

# SV model

## 2.2 Estimation

$$R_t = h_t^{0.5} e_t,$$

$$\text{Log } h_t = \alpha + \delta \log h_{t-1} + v_t, \quad v_t \sim N(0, \sigma_v)$$

Parameters:  $\theta = (\alpha, \delta, \sigma_v)$

- Maximum Likelihood:

$$L(\theta | R) = p(R | \alpha, \delta, \sigma_v) ??$$

$$= \int \dots \int p(R | h, \alpha, \delta, \sigma) p(h | \alpha, \delta, \sigma) dh$$

Very difficult numerically,

- Bayesian:  $p(\theta | R) \sim p(R | \theta) p(\theta)$  Not easier !

- Trick: **Data Augmentation:**  $p(\theta, h | R)$  ★

Consider the  $h$ s as parameters to estimate

- Bayes Theorem again:  $p(\theta, \mathbf{h} | R) \sim p(R | \theta, \mathbf{h}) \frac{p(\theta, \mathbf{h})}{p(\mathbf{h} | \theta) p(\theta)}$

- Gibbs Cycle:

$$[1] \quad p(\alpha, \overset{\theta}{\delta}, \overset{h}{\sigma} | \mathbf{h}, R)$$

$$[2] \quad p(\underset{h}{\mathbf{h}} | \underset{\theta}{\alpha}, \delta, \sigma, R)$$

$$p(R | \theta, h) \underbrace{p(h | \theta) p(\theta)}_{p(\theta, h)}$$

[1] a linear regression      Easy

[2] Smoothing:  $p(\mathbf{h} | R, \cdot)$  A T-dimensional vector ??

Trick 2: break it further:  $p(h_t | \textcircled{h_{-t}}, R, \theta)$  去掉  $h_t$

Overall, a T+3 dimensional Gibbs cycle

- Simplification:  $p(h_t | \mathbf{h}_{-t}, R, \theta) = p(h_t | \mathbf{h}_{t-1}, \mathbf{h}_{t+1}, R, \theta)$

- A bit of Bayes theorem to find  $p(h_t | \cdot)$  :

$$p(h_t | \theta, r_t, h_{t-1}, h_{t+1})$$

$$\propto p(r_t | \theta, h_t, h_{t-1}, h_{t+1}) p(h_t | \theta, h_{t-1}, h_{t+1})$$

$$\propto p(r_t | \theta, h_t) p(h_{t+1} | \theta, h_t, h_{t-1}) p(h_t | \theta, h_{t-1})$$

$$\propto p(r_t | \theta, h_t) p(h_{t+1} | \theta, h_t) p(h_t | \theta, h_{t-1})$$

- We have a Normal ( $r_t$ ) and two Lognormals ( $h_{t+1}$  and  $h_t$ ).

$$\begin{aligned}
 p(h_t | \theta, R, h_{-t}) &\propto p(h_t | \theta, r_t, h_{t-1}, h_{t+1}) \\
 &\propto \underbrace{p(h_t | \theta, h_{t-1})}_{\text{LN}} \underbrace{p(h_{t+1} | \theta, h_t)}_{\text{LN}} \underbrace{p(r_t | h_t)}_{\text{IG}}
 \end{aligned}$$

$$\propto \frac{1}{h_t} \exp\left\{-\frac{(\log h_t - \mu_t)^2}{2\sigma^2}\right\} \frac{1}{h_t^{1/2}} \exp\left\{-\frac{r_t^2}{2h_t}\right\}$$

$$\begin{cases} \sigma^2 \equiv \sigma^2(\theta) \\ \mu_t \equiv \mu_t(h_{t-1}, h_{t+1}, \theta) \end{cases}$$

$$\begin{aligned}
 \mu_t &= (\alpha(1 - \delta) + \delta(\log h_{t+1} + \log h_{t-1})) / (1 + \delta^2) \\
 \sigma^2 &= \sigma_v^2 / (1 + \delta^2).
 \end{aligned}$$

- How to draw from  $p(h_t | \dots)$ ? Metropolis

Independence: Choose  $q(h_t)$  as Inverse Gamma (fatter tail than Log-normal)

Random walk: No need to approximate  $p^*(h_t)$

选  $q(h_t)$  为 IG, 比 log 肥尾.

## 2.3 Needed Extensions to the SV model

### 2.3.1 Asymmetric volatility

$$\begin{aligned} R_t &= \mu + h_t^{0.5} \varepsilon_t, & \varepsilon_t &\sim N(0,1) \\ \log h_t &= \alpha + \delta \log h_{t-1} + v_t, & v_t &\sim N(0, \sigma_v) \end{aligned}$$

$\rho(v_t, \varepsilon_t) < 0$  as in Hull & White or Heston.

Result: Needed for stock indices and interest rates  
Not so crucial for most exchange rates and individual stocks

### 2.3.2 Conditional Fat tails

$$\begin{aligned} R_t &= h_t^{0.5} \lambda_t^{0.5} \varepsilon_t, & \varepsilon_t &\sim N(0,1), & v / \lambda_t^{0.5} &\sim \chi^2(v) \\ \log h_t &= \alpha + \delta \log h_{t-1} + \underbrace{\sigma_v}_{\text{fat tails}} v_t, & v_t &\sim N(0,1) \end{aligned}$$

Algorithm  $\Rightarrow p(\lambda_t | R, h_t), p(h_t | R), p(\alpha, \delta, \sigma_v, v | R)$

Results:  $\left\{ \begin{array}{l} v \text{ higher than for GARCH } \text{比garch的} v \text{ 高} \\ \text{Still crucial around periods of high variance to control outliers} \\ \text{Omitting this extension leads to biased forecasts..} \end{array} \right.$