# $\underbrace{ \text{Yeke } \text{CHen}}_{\text{chenyeke@zju.edu.cn}} \underbrace{ \text{Chenyeke@zju.edu.cn}}_{\text{https://github.com/shieldkeke}}$

#### Education

Zhejiang University Hangzhou, China

Bachelors of Automation (overall GPA: 3.94/4.00, 89.8/100, ranking: 3/58)

2020 - Present

- Selected Coursework: Lectures on Programming 98, Foundamentals of C Programming 95, Engineering Graphics 96, Calculus 95, Linear Algebra 92, Probability and Mathematical Statistics 96, Signal Analysis and Processing 95, Robot Modeling and Control 92, Air-robots 92, Comprehensive Practice of Robot and Intelligent System 97
- Scholarships: two Zhejiang provincial government scholarships; two second-class scholarships

## Experience

#### ZJUNlict(Zhejiang University)

Hangzhou, China

RoboCup SSL Team member

6/2022-6/2023

- developed the parallel multi-vehicle-ball-passing-point calculating module based on OpenAcc
- refined the zero and non-zero speed ball interception modules
- regularized the passing strength

# ZJU-Robotics-Lab advised by Yue Wang and Rong Xiong (Zhejiang University)

Hangzhou, China

7/2023-Present

Research Intern

- Learnt the foothold planning algorithm for quadruped robots based on elevation map
- Trying to implement a learning-based method for foothold planning

# Personal Projects

## Continuous Trajectory Generation for Autonomous Driving

5/2022-5/2023

• Participated in datasets making and networks training

### Supermarket Shopping Robot - LINK

12/2021-5/2022

• Designed the robot from scratch and implemented functions such as object detection, multi-device communication, object grasping, and line-following

#### (course project)Path Planning and Tracking - LINK

7/2023

• realized path planning of RRT\*, A\* and JPS; realized DWA and ordinary trajectory tracking

### (course project)Space Robot - LINK

7/2023

• completed the inverse kinematics code of space robot and the trajectory planning code of joint space based on polynomial interpolation

## Selected Awards

Zhejiang Robot Competition-First Prize

5/2023

China Robot Competition/Robocup China (SSL) -Third Place

11/2022

Zhejiang Robot Competition-Second Prize

8/2022

Zhejiang University Robot Competition-First Prize

5/2022&5/2021

#### **Technical Skills**

Languages: CET-6:579

**Developer Tools**: Python;C;C++;MATLAB **Technologies/Frameworks**: Pytorch;ROS