Education

Zhejiang University Hangzhou, China

Bachelors of Automation

2020 - Present

- overall GPA: 3.94/4.00, 89.8/100
- ranking: 3/58
- Selected Coursework: Lectures on Programming 98, Foundamentals of C Programming 95, Robot Modeling and Control 92, Air-robots 92, Comprehensive Practice of Robot and Intelligent System 97
- Scholarships: two Zhejiang provincial government scholarships; two second-class scholarships

Experience

ZJUNlict(a RoboCup SSL team)

Zhejiang University

Team member

6/2022-6/2023

- Developed the parallel multi-vehicle-ball-passing-point calculating module based on OpenAcc
- Refined the zero and non-zero speed ball interception modules
- Regularized the passing strength

the State Key Laboratory of Industrial Control and Technology - Robotics Lab

Zhejiang University

Research intern advised by Professor Rong Xiong and Professor Yue Wang

7/2023-Present

- Learnt the foothold planning algorithm for quadruped robots based on elevation map
- Proposed a learning-based method for foothold planning

Personal Projects

Continuous Trajectory Generation for Autonomous Driving

5/2022-5/2023

Participated in datasets making and neural networks training

Supermarket Shopping Robot - <u>LINK</u>

12/2021-5/2022

• Designed the robot from scratch and implemented functions such as object detection, multi-device communication, object grasping, and line-following

(course project)Path Planning and Tracking - LINK

7/2023

• Realized RRT*, A* and JPS path planning methods; realized DWA and simple trajectory tracking methods

(course project)Space Robot - LINK

7/2023

• Completed the inverse kinematics code of the space robot and the trajectory planning code of joint space based on polynomial interpolation

Selected Awards

Zhejiang Robot Competition-First Prize

5/2023

China Robot Competition/Robocup China (SSL) -Third Place

11/2022

Zhejiang Robot Competition-Second Prize

8/2022

Zhejiang University Robot Competition-First Prize

5/2022&5/2021

Technical Skills

Python/C/C++/MATLAB/ROS/Pytorch/SolidWorks/OpenCV/CUDA C