

This copy of the Lingua Franca handbook for the c target was created on Tuesday, August 29, 2023 against commit <u>41c416</u>.

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#### **A First Reactor**

See the <u>requirements</u> for using this target.

### Minimal Example

A minimal but complete Lingua Franca file with one reactor is this:

```
target C;
main reactor {
    reaction(startup) {=
        printf("Hello World.\n");
    =}
}
```

Every Lingua Franca program begins with a <u>target declaration</u> that specifies the language in which reactions are written. This is also the language of the program(s) generated by the Lingua Franca code generator.

Every LF program also has a **main** reactor, which is the top level of a hierarchy of contained and interconnected reactors. The above simple example has no contained reactors.

The **main** reactor above has a single **reaction**, which is triggered by the **startup** trigger. This trigger causes the reaction to execute at the start of the program. The body of the reaction, delimited by  $\{= \ldots =\}$ , is ordinary C code which, as we will see, has access to a number of functions and variables specific to Lingua Franca.

### Examples

Examples of Lingua Franca programs can be found in the examples-lingua-franca repository.

The <u>regression tests</u> have a rich set of examples that illustrate every feature of the language.

## Structure of an LF Project

The Lingua Franca tools assume that LF programs are put into a file with a .lf extension that is stored somewhere within a directory called src. To compile and run the above example, choose a **project root** directory, create a src directory within that, and put the above code into a file

called, say, src/HelloWorld.lf. You can compile the code on the <u>command line</u>, within <u>Visual Studio Code</u>, or within the <u>Epoch IDE</u>. On the command line this will look like this:

```
> lfc src/HelloWorld.lf
... output from the code generator and compiler ...
```

#### Reactor Block

A **reactor** is a software component that reacts to input events, timer events, and internal events. It has private state variables that are not visible to any other reactor. Its reactions can consist of altering its own state, sending messages to other reactors, or affecting the environment through some kind of actuation or side effect (e.g., printing a message, as in the above HelloWorld example).

The general structure of a reactor definition is as follows:

Contents within square brackets are optional, contents within <...> are user-defined, and each line may appear zero or more times, as explained in the next pages. Parameters, inputs, outputs, timers, actions, and contained reactors all have names, and the names are required to be distinct from one another.

If the **reactor** keyword is preceded by **main**, then this reactor will be instantiated and run by the generated code.

Any number of reactors may be defined in one file, and a main reactor need not be given a name, but if it is given a name, then that name must match the file name.

Reactors may extend other reactors, inheriting their properties, and a file may import reactors from other files. If an imported LF file contains a **main** reactor, that reactor is ignored (it will not be imported). This makes it easy to create a library of reusable reactors that each come with a test case or demonstration in the form of a main reactor.

#### Comments

Lingua Franca files can have C/C++/Java-style comments and/or Python-style comments. All of the following are valid comments:

```
// Single-line C-style comment.
/*
 * Multi-line C-style comment.
 */
# Single-line Python-style comment.
```

## **Inputs and Outputs**

In this section, we will endow reactors with inputs and outputs.

### Input and Output Declarations

Input and output declarations have the form:

For example, the following reactor doubles its input and sends the result to the output:

```
target C;
reactor Double {
    input x:int;
    output y:int;
    reaction(x) -> y {=
        lf_set(y, x->value * 2);
    =}
}
```

Notice how the input value is accessed and how the output value is set. This is done differently for each target language. See the <u>Target Language Details</u> for detailed documentation of these mechanisms. Setting an output within a reaction will trigger downstream reactions at the same <u>Logical Time</u> that the reaction is invoked (or, more precisely, at the same <u>tag</u>). If a particular output port is set more than once at any tag, the last set value will be the one that downstream reactions see. Since the order in which reactions of a reactor are invoked at a logical time is deterministic, and whether inputs are present depends only on their timestamps, the final value set for an output will also be deterministic.

The **reaction** declaration above indicates that an input event on port x is a **trigger** and that an output event on port y is a (potential) **effect**. A reaction can declare more than one trigger or effect by just listing them separated by commas. For example, the following reactor has two triggers and tests each input for presence before using it:

```
target C;
reactor Destination {
   input x:int;
   input y:int;
   reaction(x, y) {=
      int sum = 0;
      if (x->is_present) {
        sum += x->value;
      }
      if (y->is_present) {
        sum += y->value;
      }
      printf("Received %d.\n", sum);
      =}
}
```

**NOTE:** if a reaction fails to test for the presence of an input and reads its value anyway, then the result it will get is target dependent. In the C target, the value read will be the most recently seen input value, or, if no input event has occurred at an earlier logical time, then zero or NULL, depending on the data type of the input.

### Triggers, Effects, and Uses

The **triggers** field can be a comma-separated list of input ports, <u>output ports of contained</u> <u>reactors</u>, <u>timers</u>, <u>actions</u>, or the special events <u>startup</u> and <u>shutdown</u>. There must be at least one trigger for each reaction. A reaction with a <u>startup</u> trigger is invoked when the program begins executing, and a reaction with a <u>shutdown</u> trigger is invoked at the end of execution.

The **uses** field, which is optional, specifies input ports (or <u>output ports of contained reactors</u>) that do not trigger execution of the reaction but may be read by the reaction.

The **effects** field, which is also optional, is a comma-separated lists of output ports ports, <u>input</u> <u>ports of contained reactors</u>, or <u>actions</u>.

### Setting an Output Multiple Times

If one or more reactions set an output multiple times at the same  $\underline{tag}$ , then only the last value set will be seen by any downstream reactors.

If a reaction wishes to test whether an output has been previously set at the current tag by some other reaction, it can test it in the same way it tests inputs for presence.

### **Mutable Inputs**

Normally, a reaction does not modify the value of an input. An input is said to be **immutable**. The degree to which this is enforced varies by target language. Most of the target languages make it rather difficult to enforce, so the programmer needs to avoid modifying the input. Modifying an input value may lead to nondeterministic results.

Occasionally, it is useful to modify an input. For example, the input may be a large data structure, and a reaction may wish to make a small modification and forward the result to an output. To accomplish this, the programmer should declare the input **mutable** as follows:

mutable input <name>;

This is a directive to the code generator indicating that reactions that read this input may also modify the value of the input. The code generator will attempt to optimize the scheduling to avoid copying the input value, but this may not be possible, in which case it will automatically insert a copy operation, making it safe to modify the input. The target-specific reference documentation has more details about how this works.

#### **Parameters and State Variables**

#### Parameter Declaration

A reactor class definition can parameterized as follows:

Types ending with a \* are treated specially by the C target. See the <u>Target Language Details</u>.

To use strings conveniently in the C target, the "type" string is an alias for {=const char\*=}.

Each parameter must have a *default value*, written  $(\langle expr \rangle)$ . An expression may be a numeric constant, a string enclosed in quotation marks, a time value such as 10 msec, a list of values, or target-language code enclosed in  $\{=\ldots=\}$ , for example. See <u>Expressions</u> for full details on what expressions are valid.

For example, the Double reactor on the <u>previous page</u> can be replaced with a more general parameterized reactor Scale as follows:

```
target C;
reactor Scale(factor:int(2)) {
    input x:int;
    output y:int;
    reaction(x) -> y {=
        lf_set(y, x->value * self->factor);
        =}
}
```

This reactor, given any input event x will produce an output y with value equal to the input scaled by the factor parameter. The default value of the factor parameter is 2, but this can be changed when the Scale reactor is instantiated.

Notice how, within the body of a reaction, the code accesses the parameter value. This is different for each target language. In the C target, a self struct is provided that contains the parameter values.

#### State Declaration

A reactor declares a state variable as follows:

The <value> is an initial value and, like parameter values, can be given as an <u>expression</u> or target language code with delimiters  $\{= \dots =\}$ . The initial value can also be given as a

parameter name. The value can be accessed and modified in a target-language-dependent way as illustrated by the following example:

```
target C;
reactor Count {
    state count:int(0);
    output y:int;
    timer t(0, 100 msec);
    reaction(t) -> y {=
        lf_set(y, self->count++);
    =}
}
```

This reactor has an integer state variable named **count**, and each time its reaction is invoked, it outputs the value of that state variable and increments it. The reaction is triggered by a **timer**, discussed in the next section.

#### **Time and Timers**

## **Logical Time**

A key property of Lingua Franca is **logical time**. All events occur at an instant in logical time. By default, the runtime system does its best to align logical time with **physical time**, which is some measurement of time on the execution platform. The **lag** is defined to be physical time minus logical time, and the goal of the runtime system is maintain a small non-negative lag.

The **lag** is allowed to go negative only if the <u>fast target property</u> or the <u>--fast</u> is set to <u>true</u>. In that case, the program will execute as fast as possible with no regard to physical time.

#### Time Values

A time value is given with units (unless the value is 0, in which case the units can be omitted). The allowable units are:

- For nanoseconds: ns , nsec , or nsecs
- For microseconds: us , usec , or usecs
- For milliseconds: ms, msec, or msecs
- For seconds: s, sec, secs, second, or seconds
- For minutes: min, minute, mins, or minutes
- For hours: h, hour, or hours
- For days: d, day, or days
- For weeks: week or weeks

The following example illustrates using time values for parameters and state variables:

```
target C;
main reactor SlowingClock(start:time(100 msec), incr:time(100 msec)) {
    state interval:time(start);
    logical action a;
    reaction(startup) -> a {=
        lf schedule(a, self->start);
    =}
    reaction(a) -> a {=
        instant t elapsed logical time = lf time logical elapsed();
        printf("Logical time since start: \%lld nsec.\n",
            elapsed_logical time
        );
        self->interval += self->incr;
        lf schedule(a, self->interval);
    =}
}
```

This has two time parameters, start and incr, each with default value 100 msec. This parameter is used to initialize the interval state variable, which also stores a time. The logical action a, explained below, is used to schedule events to occur at time start after program startup and then at intervals that are increased each time by incr. The result of executing this program will look like this:

```
Logical time since start: 100000000 nsec.
Logical time since start: 300000000 nsec.
Logical time since start: 600000000 nsec.
Logical time since start: 1000000000 nsec.
...
```

#### **Timers**

The simplest use of logical time in Lingua Franca is to invoke a reaction periodically. This is done by first declaring a timer using this syntax:

```
timer <name>(<offset>, <period>);
```

The <period>, which is optional, specifies the time interval between timer events. The <offset>, which is also optional, specifies the (logical) time interval between when the program starts executing and the first timer event. If no period is given, then the timer event occurs only once. If neither an offset nor a period is specified, then one timer event occurs at program start, simultaneous with the startup event.

The period and offset are given by a number and a units, for example, 10 msec. See the expressions documentation for allowable units. Consider the following example:

```
target C;
main reactor Timer {
    timer t(0, 1 sec);
    reaction(t) {=
        printf("Logical time is %lld.\n", lf_time_logical());
    =}
}
```

This specifies a timer named t that will first trigger at the start of execution and then repeatedly trigger at intervals of one second. Notice that the time units can be left off if the value is zero.

This target provides a built-in function for retrieving the logical time at which the reaction is invoked, get\_logical\_time(). On most platforms (with the exception of some embedded platforms), the returned value is a 64-bit number representing the number of nanoseconds that have elapsed since January 1, 1970. Executing the above displays something like the following:

```
Logical time is 1648402121312985000.
Logical time is 1648402122312985000.
Logical time is 1648402123312985000.
```

The output lines appear at one second intervals unless the fast option has been specified.

### **Elapsed Time**

The times above are a bit hard to read, so, for convenience, each target provides a built-in function to retrieve the *elapsed* time. For example:

See the <u>Target Language Details</u> for the full set of functions provided for accessing time values.

Executing this program will produce something like this:

```
Elapsed logical time is 0.
Elapsed logical time is 1000000000.
Elapsed logical time is 2000000000.
```

## Comparing Logical and Physical Times

The following program compares logical and physical times:

Execution will show something like this:

```
Elapsed logical time: 0, physical time: 855000, lag: 855000
Elapsed logical time: 1000000000, physical time: 1004714000, lag: 4714000
Elapsed logical time: 2000000000, physical time: 2004663000, lag: 4663000
Elapsed logical time: 3000000000, physical time: 3000210000, lag: 210000
```

. . .

In this case, the lag varies from a few hundred microseconds to a small number of milliseconds. The amount of lag will depend on the execution platform.

### Simultaneity and Instantaneity

If two timers have the same *offset* and *period*, then their events are logically simultaneous. No observer will be able to see that one timer has triggered and the other has not.

A reaction is always invoked at a well-defined logical time, and logical time does not advance during its execution. Any output produced by the reaction will be **logically simultaneous** with

the input. In other words, reactions are **logically instantaneous** (for an exception, see <u>Logical Execution Time</u>). Physical time, however, does elapse during execution of a reaction.

#### **Timeout**

By default, a Lingua Franca program will terminate when there are no more events to process. If there is a timer with a non-zero period, then there will always be more events to process, so the default execution will be unbounded. To specify a finite execution horizon, you can either specify a <a href="timeout target property">timeout target property</a> or a <a href="timeout command-line option">--timeout command-line option</a>. For example, the following timeout property will cause the above timer with a period of one second to terminate after 11 events:

```
target C {
    timeout: 10 sec
}
```

### Startup and Shutdown

To cause a reaction to be invoked at the start of execution, a special **startup** trigger is provided:

The **startup** trigger is equivalent to a timer with no *offset* or *period*.

To cause a reaction to be invoked at the end of execution, a special **shutdown** trigger is provided. Consider the following reactor, commonly used to build regression tests:

```
target C;
reactor TestCount(start:int(0), stride:int(1), num inputs:int(1)) {
    state count:int(start);
    state inputs received:int(0);
    input x:int;
    reaction(x) {=
        printf("Received %d.\n", x->value);
        if (x->value != self->count) {
            printf("ERROR: Expected %d.\n", self->count);
            exit(1);
        }
        self->count += self->stride;
        self->inputs received++;
    =}
    reaction(shutdown) {=
        printf("Shutdown invoked.\n");
        if (self->inputs received != self->num inputs) {
            printf("ERROR: Expected to receive %d inputs, but got %d.\n",
                self->num inputs,
                self->inputs received
            );
            exit(2);
        }
    =}
}
```

This reactor tests its inputs against expected values, which are expected to start with the value given by the start parameter and increase by stride with each successive input. It expects to receive a total of num\_inputs input events. It checks the total number of inputs received in its shutdown reaction.

The **shutdown** trigger typically occurs at <u>microstep</u> 0, but may occur at a larger microstep. See <u>Superdense Time</u> and <u>Termination</u>.

## **Composing Reactors**

#### **Contained Reactors**

Reactors can contain instances of other reactors defined in the same file or in an imported file.

Assume the Count and Scale reactors defined in <u>Parameters and State Variables</u> are stored in files Count.lf and Scale.lf, respectively, and that the <u>TestCount</u> reactor from <u>Time and</u> <u>Timers</u> is stored in <u>TestCount.lf</u>. Then the following program composes one instance of each of the three:

```
target C {
    timeout: 1 sec,
    fast: true
}
import Count from "Count.lf";
import Scale from "Scale.lf";
import TestCount from "TestCount.lf";

main reactor RegressionTest {
    c = new Count();
    s = new Scale(factor = 4);
    t = new TestCount(stride = 4, num_inputs = 11);
    c.y -> s.x;
    s.y -> t.x;
}
```

### Diagrams

As soon as programs consist of more than one reactor, it becomes particularly useful to reference the diagrams that are automatically created and displayed by the Lingua Franca IDEs. The diagram for the above program is as follows:



In this diagram, the timer is represented by a clock-like icon, the reactions by chevron shapes, and the **shutdown** event by a diamond. If there were a **startup** event in this program, it would appear as a circle.

### **Creating Reactor Instances**

An instance is created with the syntax:

```
<instance name> = new <class name>(<parameters>)
```

A bank with several instances can be created in one such statement, as explained in the <u>banks</u> of reactors documentation.

The <parameters> argument is a comma-separated list of assignments:

```
<parameter_name> = <value>, ...
```

Like the default value for parameters, <value> can be a numeric constant, a string enclosed in quotation marks, a time value such as 10 msec, target-language code enclosed in  $\{= \ldots =\}$ , or any of the list forms described in  $\underline{\text{Expressions}}$ .

#### Connections

Connections between ports are specified with the syntax:

```
<source_port_reference> -> <destination_port_reference>
```

where the port references are either <instance\_name>.<port\_name> or just <port\_name>, where the latter form is used for connections that cross hierarchical boundaries, as illustrated in the next section.

On the left and right of a connection statement, you can put a comma-separated list. For example, the above pair of connections can be written,

$$c.y$$
,  $s.y \rightarrow s.x$ ,  $t.x$ 

The only constraint is that the total number of channels on the left match the total number on the right.

A destination port (on the right) can only be connected to a single source port (on the left). However, a source port may be connected to multiple destinations, as in the following example:



Lingua Franca provides a convenient shortcut for such multicast connections, where the above two lines can be replaced by one as follows:

$$(a.y) + -> b1.x, b2.x$$

The enclosing ( . . . )+ means to repeat the enclosed comma-separated list of sources however many times is needed to provide inputs to all the sinks on the right of the connection - > .

### Import Statement

An import statement has the form:

```
import <classname> as <alias> from "<path>"
```

where <classname> and <alias> can be a comma-separated list to import multiple reactors from the same file. The <path> specifies another .lf file relative to the location of the current file. The as <alias> portion is optional and specifies alternative class names to use in the new statements.

## Hierarchy

Reactors can be composed in arbitrarily deep hierarchies. For example, the following program combines the Count and Scale reactors within on Container:

```
target C;
import Count from "Count.lf";
import Scale from "Scale.lf";
import TestCount from "TestCount.lf";
reactor Container(stride:int(2)) {
    output y:int;
    c = new Count();
    s = new Scale(factor = stride);
    c.y \rightarrow s.x;
    s.y \rightarrow y;
}
main reactor Hierarchy {
    c = new Container(stride = 4);
    t = new TestCount(stride = 4, num inputs = 11);
    c.y -> t.x;
}
```



The Container has a parameter named stride, whose value is passed to the factor parameter of the Scale reactor. The line

$$s.y \rightarrow y;$$

establishes a connection across levels of the hierarchy. This propagates the output of a contained reactor to the output of the container. A similar notation may be used to propagate the input of a container to the input of a contained reactor,

$$X \rightarrow S.X;$$

## Connections with Logical Delays

Connections may include a logical delay using the after keyword, as follows:

<source\_port\_reference> -> <destination\_port\_reference> after <time\_val
where <time\_value> can be any of the forms described in <a href="Expressions">Expressions</a>.

The **after** keyword specifies that the logical time of the event delivered to the destination port will be larger than the logical time of the reaction that wrote to source port. The time value is required to be non-negative, but it can be zero, in which case the input event at the receiving end will be one <u>microstep</u> later than the event that triggered it.

## **Physical Connections**

A subtle and rarely used variant of the -> connection is a **physical connection**, denoted ~> . For example:

```
main reactor {
    a = new A();
    b = new B();
    a.y ~> b.x;
}
```

This is rendered in by the diagram synthesizer as follows:



In such a connection, the logical time at the recipient is derived from the local physical clock rather than being equal to the logical time at the sender. The physical time will always exceed the logical time of the sender (unless fast is set to true), so this type of connection incurs a nondeterministic positive logical time delay. Physical connections are useful sometimes in <a href="Distributed-Execution">Distributed-Execution</a> in situations where the nondeterministic logical delay is tolerable. Such connections are more efficient because timestamps need not be transmitted and messages do not need to flow through through a centralized coordinator (if a centralized coordinator is being used).

#### **Reactions and Methods**

#### **Reaction Order**

A reactor may have multiple reactions, and more than one reaction may be enabled at any given tag. In Lingua Franca semantics, if two or more reactions of the same reactor are **simultaneously enabled**, then they will be invoked sequentially in the order in which they are declared. More strongly, the reactions of a reactor are **mutually exclusive** and are invoked in tag order primarily and declaration order secondarily. Consider the following example:

```
target C {
    timeout: 3 secs
}
main reactor Alignment {
    state s:int(0);
    timer t1(100 msec, 100 msec);
    timer t2(200 msec, 200 msec);
    timer t4(400 msec, 400 msec);
    reaction(t1) {=
        self->s += 1;
    =}
    reaction(t2) {=
        self->s -= 2;
    =}
    reaction(t4) {=
        printf("s = %d\n", self->s);
    =}
}
```

Every 100 ms, this increments the state variable s by 1, every 200 ms, it decrements s by 2, and every 400 ms, it prints the value of s. When these reactions align, they are invoked in declaration order, and, as a result, the printed value of s is always 0.

## **Overwriting Outputs**

Just as the reactions of the Alignment reactor overwrite the state variable s, logically simultaneous reactions can overwrite outputs. Consider the following example:

```
target C;
reactor Overwriting {
    output y:int;
    state s:int(0);
    timer t1(100 msec, 100 msec);
    timer t2(200 msec, 200 msec);
    reaction(t1) -> y {=
        self->s += 1;
        lf_set(y, self->s);
    =}
    reaction(t2) -> y {=
        self->s -= 2;
        lf_set(y, self->s);
    =}
}
```

Here, the reaction to t1 will set the output to 1 or 2, but every time it sets it to 2, the second reaction (to t2) will overwrite the output with the value 0. As a consequence, the outputs will be 1, 0, 1, 0, ... deterministically.

### Reacting to Outputs of Contained Reactors

A reaction may be triggered by the an input to the reactor, but also by an output of a contained reactor, as illustrated in the following example:



This instantiates the above Overwriting reactor and monitors its outputs.

## **Triggering Contained Reactors**

A reaction can set the input of a contained reactor, thereby triggering its reactions, as illustrated in the following example:

```
target C
reactor Inside {
  input x: int
  reaction(x) {=
    printf("Received %d\n", x->value);=
    =}
}
main reactor {
  i = new Inside()
  reaction(startup) -> i.x {=
    lf_set(i.x, 42);
    =}
}
```

The reaction to **startup** declares the input port of the inside reactor as an effect and then sets it with value 42. This will cause the inside reactor's reaction to execute and print Received 42.

#### **Method Declaration**

## **Causality Loops**

## Cycles

The interconnection pattern for a collection of reactors can form a cycle, but some care is required. Consider the following example:

```
target C;
reactor A {
    input x:int;
    output y:int;
    reaction(x) -> y {=
        // ... something here ...
    =}
}
reactor B {
    input x:int;
    output y:int;
    reaction(x) {=
        // ... something here ...
    =}
    reaction(startup) -> y {=
        // ... something here ...
    =}
}
main reactor {
    a = new A();
    b = new B();
    a.y -> b.x;
    b.y \rightarrow a.x;
}
```

This program yields the following diagram:



The diagram highlights a **causality loop** in the program. At each tag, in reactor B, the first reaction has to execute before the second if it is enabled, a precedence indicated with the red dashed arrow. But the first can't execute until the reaction of A has executed, and that reaction cannot execute until the second reaction B has executed. There is no way to satisfy these requirements, so the tools refuse to generated code.

### Cycles with Delays

One way to break the causality loop and get an executable program is to introduce a <u>logical</u> <u>delay</u> into the loop, as shown below:

```
target C;
reactor A {
    input x:int;
    output y:int;
    reaction(x) -> y {=
        // ... something here ...
    =}
}
reactor B {
    input x:int;
    output y:int;
    reaction(x) {=
        // ... something here ...
    =}
    reaction(startup) -> y {=
        // ... something here ...
    =}
}
main reactor {
   a = new A();
    b = new B();
    a.y -> b.x after 0;
    b.y -> a.x;
}
Lingua Franca diagram
```

Here, we have used a delay of 0, which results in a delay of one <u>microstep</u>. We could equally well have specified a positive time value.

#### **Reaction Order**

Frequently, a program will have such cycles, but you don't want a logical delay in the loop. To get a cycle without logical delays, the reactions need to be reordered, as shown below:

```
target C;
reactor A {
    input x:int;
    output y:int;
    reaction(x) -> y {=
        // ... something here ...
    =}
}
reactor B {
    input x:int;
    output y:int;
    reaction(startup) -> y {=
         // ... something here ...
    =}
    reaction(x) {=
        // ... something here ...
    =}
}
main reactor {
    a = new A();
    b = new B();
    a.y \rightarrow b.x;
    b.y \rightarrow a.x;
}
```

Lingua Franca diagram	

There is no longer any causality loop.

# **Extending Reactors**

Extending a Base Reactor

### **Actions**

#### **Action Declaration**

An action declaration has one of the following forms:

```
logical action <name>(<min_delay>, <min_spacing>, <policy>)
physical action <name>(<min_delay>, <min_spacing>, <policy>)
```

The min\_delay, min\_spacing, and policy are all optional. If only one argument is given in parentheses, then it is interpreted as an min\_delay, if two are given, then they are interpreted as min\_delay and min\_spacing. The min\_delay and min\_spacing are time values. The policy argument is a string that can be one of the following: "defer" (the default), "drop", or "replace". Note that the quotation marks are needed.

## **Logical Actions**

Timers are useful to trigger reactions once or periodically. Actions are used to trigger reactions more irregularly. An action, like an output or input port, can carry data, but unlike a port, an action is visible only within the reactor that defines it.

There are two kinds of actions, **logical** and **physical**. A **logical action** is used by a reactor to schedule a trigger at a fixed logical time interval d into the future. The time interval d, which is called a **delay**, is relative to the logical time t at which the scheduling occurs. If a reaction executes at logical time t and schedules an action a with delay d, then any reaction that is triggered by a will be invoked at logical time t + d. For example, the following reaction schedules something (printing the current elapsed logical time) 200 msec after an input x arrives:

```
target C;
reactor Schedule {
    input x:int;
    logical action a;
    reaction(x) -> a {=
        lf_schedule(a, MSEC(200));
    =}
    reaction(a) {=
        interval_t elapsed_time = lf_time_logical_elapsed();
        printf("Action triggered at logical time %lld nsec after start.\n",
    =}
}
```



Here, the delay is specified in the call to schedule within the target language code. Notice that in the diagram, a logical action is shown as a triangle with an **L**. Logical actions are always scheduled within a reaction of the reactor that declares the action.

The time argument is required to be non-negative. If it is zero, then the action will be scheduled one **microstep** later. See <u>Superdense Time</u>.

The arguments to the lf\_schedule() function are the action named a and a time. The action a has to be declared as an effect of the reaction in order to reference it in the call to lf\_schedule(). If you fail to declare it as an effect (after the -> in the reaction signature), then you will get an error message.

The time argument to the <code>lf\_schedule()</code> function has data type <code>interval\_t</code>, which, with the exception of some embedded platforms, is a <code>C int64\_t</code>. A collection of convenience macros is provided like the <code>MSEC</code> macro above to specify time values in a more readable way. The provided macros are <code>NSEC</code>, <code>USEC</code> (for microseconds), <code>MSEC</code>, <code>SEC</code>, <code>MINUTE</code>, <code>HOUR</code>, <code>DAY</code>, and <code>WEEK</code>. You may also use the plural of any of these, e.g. <code>WEEKS(2)</code>.

An action may have a data type, in which case, a variant of the lf\_schedule() function can be used to specify a **payload**, a data value that is carried from where the lf\_schedule() function

is called to the reaction that is triggered by the action. See the <u>Target Language Details</u>.

### **Physical Actions**

A **physical action** is used to schedule reactions at logical times determined by the local physical clock. If a physical action with delay d is scheduled at *physical* time T, then the *logical time* assigned to the event is T + d. For example, the following reactor schedules the physical action T + d to trigger at a **logical time** equal to the **physical time** at which the input T + d arrives:

```
target C;
reactor Physical {
    input x:int;
    physical action a;
    reaction(x) -> a {=
        lf_schedule(a, 0);
    =}
    reaction(a) {=
        interval_t elapsed_time = lf_time_logical_elapsed();
        printf("Action triggered at logical time %lld nsec after start.\n",
    =}
}
```



If you drive this with a timer, using for example the following structure:



then running the program will yield an output something like this:

```
Action triggered at logical time 201491000 nsec after start. Action triggered at logical time 403685000 nsec after start. Action triggered at logical time 603669000 nsec after start. ...
```

Here, logical time is lagging physical time by a few milliseconds. Note that, unless the <u>fast option</u> is given, logical time t chases physical time t, so t < t. Hence, the event being scheduled in the reaction to input  $\mathbf{x}$  is assured of being in the future in logical time.

Whereas logical actions are required to be scheduled within a reaction of the reactor that declares the action, physical actions can be scheduled by code that is outside the Lingua Franca system. For example, some other thread or a callback function may call schedule(), passing it a physical action. For example:

```
target C {
    keepalive: true // Do not exit when event queue is empty.
}
preamble {=
    #include "platform.h" // Defines If sleep() and thread functions.
=}
main reactor {
    preamble {=
        // Schedule an event roughly every 200 msec.
        void* external(void* a) {
            while (true) {
                lf sleep(MSEC(200));
                lf_schedule(a, 0);
            }
        }
    =}
    state thread id: If thread t(0)
    physical action a(100 msec): int
    reaction(startup) -> a {=
        // Start a thread to schedule physical actions.
        lf thread create(&self->thread id, &external, a);
    =}
    reaction(a) {=
        interval t elapsed time = lf time logical elapsed();
        printf("Action triggered at logical time %lld nsec after start.\n",
    =}
}
```



Physical actions are the mechanism for obtaining input from the outside world. Because they are assigned a logical time derived from the physical clock, their logical time can be interpreted as a measure of the time at which some external event occurred.

In the above example, at **startup**, the main reactor creates an external thread that schedules a physical action roughly every 200 msec.

First, the <u>file-level preamble</u> has #include "platform.h", which includes the declarations for functions it uses, lf\_sleep and lf\_thread\_create (see <u>Libraries Available to Programmers</u>).

Second, the thread uses a function <code>lf\_sleep()</code>, which abstracts platform-specific mechanisms for stalling the thread for a specified amount of time, and <code>lf\_thread\_create()</code>, which abstracts platform-specific mechanisms for creating threads.

The external function executed by the thread is defined in a reactor-level **preamble** section. See Preambles.

**Important Note:** Asynchronous calls to <a href="left">lf\_schedule()</a> will not work if you set the <a href="mailto:threading">threading</a> target parameter to <a href="mailto:false">false</a>. You must use a threaded runtime for such asynchronous calls to work correctly.

## **Triggering Time for Actions**

An action will trigger at a logical time that depends on the arguments given to the schedule function, the <min\_delay>, <min\_spacing>, and <policy> arguments in the action declaration, and whether the action is physical or logical.

For a **logical** action a, the tag assigned to the event resulting from a call to schedule() is computed as follows. First, let t be the *current logical time*. For a logical action, t is just the logical time at which the reaction calling schedule() is called. The **preliminary time** of the action is then just  $t + \langle \min_{d \in \mathcal{U}} t \rangle + \langle \inf_{d \in \mathcal{U}} t \rangle$ . This preliminary time may be further modified, as explained below.

For a **physical** action, the preliminary time is similar, except that t is replaced by the current *physical* time T when schedule() is called.

If a <min\_spacing> has been declared, then it gives a minimum logical time interval between the tags of two subsequently scheduled events. If the preliminary time is closer than <min\_spacing> to the time of the previously scheduled event (if there is one), then <policy> (if supported by the target) determines how the minimum spacing constraint is enforced.

## Testing an Action for Presence

When a reaction is triggered by more than one action or by an action and an input, it may be necessary to test within the reaction whether the action is present. Just like for inputs, this can be done in the C target with a->is present, where a is the name of the action.

## **Superdense Time**

#### Tag vs. Time

The model of time in Lingua Franca is a bit more sophisticated than we have hinted at. Specifically, a **superdense** model of time is used. In particular, instead of a **timestamp**, LF uses a **tag**, which consists of a **logical time** *t* and a **microstep** *m*.

A <u>logical action</u> may have a <min\_delay> of zero, and the <offset> argument to the schedule() function may be zero. In this case, the call to schedule() appears to be requesting that the action trigger at the *current logical time*. Here is where superdense time comes in. The action will indeed trigger at the current logical time, but one microstep later. Consider the following example:

```
target C;
main reactor {
    state count:int(1);
    logical action a;
    reaction(startup, a) -> a {=
        printf("%d. Logical time is %lld. Microstep is %d.\n",
            self->count, lf_tag().time, lf_tag().microstep
    );
    if (self->count++ < 5) {
        lf_schedule(a, 0);
    }
    =}
}</pre>
```



Executing this program will yield something like this:

```
    Logical time is 1649607749415269000. Microstep is 0.
    Logical time is 1649607749415269000. Microstep is 1.
    Logical time is 1649607749415269000. Microstep is 2.
    Logical time is 1649607749415269000. Microstep is 3.
    Logical time is 1649607749415269000. Microstep is 4.
```

Notice that the logical time is not advancing, but the microstep is (the logical time, in this case, gives the number of nanoseconds that have elapsed since January 1, 1970). The general rule is that **every** call to **schedule()** advances the tag by at least one microstep.

### **Logical Simultaneity**

Two events are **logically simultaneous** only if *both* the logical time and the microstep are equal. The following example illustrates this:

```
target C;
reactor Destination {
    input x:int;
    input y:int;
    reaction(x, y) {=
        printf("Time since start: %lld, microstep: %d\n",
            lf time logical elapsed(), lf tag().microstep
        );
        if (x->is present) {
            printf(" x is present.\n");
        }
        if (y->is present) {
            printf(" y is present.\n");
        }
    =}
}
main reactor {
    logical action repeat;
    d = new Destination();
    reaction(startup) -> d.x, repeat {=
        lf set(d.x, 1);
        lf_schedule(repeat, 0);
    =}
    reaction(repeat) -> d.y {=
        lf set(d.y, 1);
    =}
}
```



The Destination reactor has two inputs, x and y, and it reports in a reaction to either input what is the logical time, the microstep, and which input is present. The main reactor reacts to startup by sending data to the x input of Destination. It then schedules a repeat action with an <offset> of zero. The repeat reaction is invoked strictly later, one microstep later. The output printed, therefore, will look like this:

```
Time since start: 0, microstep: 0
  x is present.
Time since start: 0, microstep: 1
  y is present.
```

The reported elapsed logical time has not advanced in the second reaction, but the fact that x is not present in the second reaction proves that the first reaction and the second are not logically simultaneous. The second occurs one microstep later.

## Alignment of Logical and Physical Times

Recall that in Lingua Franca, logical time "chases" physical time, invoking reactions at a physical time close to their logical time. For that purpose, the microstep is ignored.

## **Modal Reactors**

#### **Deadlines**

Lingua Franca includes a notion of a **deadline**, which is a constraint on the relation between logical time and physical time. Specifically, a program may specify that the invocation of a reaction must occur within some *physical* time interval of the *logical* time of the message. If a reaction is invoked at logical time 12 noon, for example, and the reaction has a deadline of one hour, then the reaction is required to be invoked before the physical-time clock of the execution platform reaches 1 PM. If the deadline is violated, then the specified deadline handler is invoked instead of the reaction.

## Purposes for Deadlines

A deadline in an LF program serves two purposes. First, it can guide scheduling in that a scheduler may prioritize reactions with deadlines over those without or those with longer deadlines. For this purpose, if a reaction has a deadline, then all upstream reactions on which it depends (without logical delay) inherit its deadline. Hence, those upstream reactions will also be given higher priority.

Second, the deadline mechanism provides a **fault handler**, a section of code to invoke when the deadline requirement is violated. Because invocation of the fault handler depends on factors beyond the control of the LF program, an LF program with deadlines becomes **nondeterministic**. The behavior of the program depends on the exact timing of the execution.

There remains the question of when the fault handler should be invoked. By default, deadlines in LF are **lazy**, meaning that the fault handler is invoked at the logical time of the event triggering the reaction whose deadline is missed. Specifically, the possible violation of a deadline is not checked until the reaction with the deadline is ready to execute. Only then is the determination made whether to invoke the regular reaction or the fault handler.

An alternative is an **eager deadline**, where a fault handler is invoked as soon as possible after a deadline violation becomes inevitable. With an eager deadline, if an event with tag (t, m) triggers a reaction with deadline D, then as soon as the runtime system detects that physical time T > t + D, the fault handler becomes enabled. This can occur at a logical time *earlier* than t. Hence, a fault handler may be invoked at a logical time earlier than that of the event that triggered the fault.

**Note:** As of this writing, eager deadlines are not implemented in any LF target language, so all deadlines are lazy.

## Lazy Deadline

A lazy deadline is specified as follows:

```
target C;
reactor Deadline {
    input x:int;
    output d:int; // Produced if the deadline is violated.
    reaction(x) -> d {=
        printf("Normal reaction.\n");
    =} deadline(10 msec) {=
        printf("Deadline violation detected.\n");
        lf_set(d, x->value);
    =}
}
```

This reactor specifies a deadline of 10 milliseconds (this can be a parameter of the reactor). If the reaction to x is triggered later in physical time than 10 msec past the timestamp of x, then the second body of code is executed instead of the first. That second body of code has access to anything the first body of code has access to, including the input x and the output x and the output can be used to notify the rest of the system that a deadline violation occurred. This reactor can be tested as follows:

```
target C
import Deadline from "Deadline.lf"
preamble {=
    #include "platform.h"
=}
main reactor {
    logical action a
    d = new Deadline()
    reaction(startup) -> d.x, a {=
        lf_set(d.x, 0);
        lf_schedule(a, 0);
    =}
    reaction(a) -> d.x {=
        lf_set(d.x, 0);
        lf_sleep(MSEC(20));
    =}
    reaction(d.d) {= printf("Deadline reactor produced an output.\n"); =}
}
```



Running this program will result in the following output:

Normal reaction.

Deadline violation detected.

Deadline reactor produced an output.

The first reaction of the <code>Deadline</code> reactor does not violate the deadline, but the second does. Notice that the sleep in the <code>main</code> reactor occurs after setting the output, but because of the deterministic semantics of LF, this does not matter. The actual value of an output cannot be known until every reaction that sets that output <code>completes</code> its execution. Since this reaction takes at least 20 msec to complete, the deadline is assured of being violated.

Notice that the deadline is annotated in the diagram with a small clock symbol.

Notice that the deadline violation here is caused by an invocation of <code>lf\_sleep</code>, defined in <code>"platform.h"</code> (see <u>Libraries Available to Programmers</u>). It is not generally advisable for a reaction to sleep because this can block other reactions from executing. But this is exactly what we are trying to accomplish here in order to force a deadline to be violated.

### **Deadline Violations During Execution**

Whether a deadline violation occurs is checked only *before* invoking the reaction with a deadline. What if the reaction itself runs for long enough that the deadline gets violated *during* the reaction execution? For this purpose, a target-language function is provided to check whether a deadline is violated during execution of a reaction with a deadline.

Consider this example:

```
target C;
reactor Count {
    output out:int;
    reaction(startup) -> out {=
        int count = 0;
        while (!lf_check deadline(self, true)) {
            count++;
        }
        lf set(out, count);
    =} deadline (3 msec) {=
        printf("Stopped counting.\n");
    =}
}
main reactor {
    c = new Count();
    reaction(c.out) {=
        printf("Counted to %d\n", c.out->value);
    =}
}
```

The Count reactor has a single reaction with a deadline of 3 msec. If the deadline is not already violated when this reaction becomes enabled (at startup), then the reaction begins executing a loop. In each iteration of the loop, it calls <code>lf\_check\_deadline(self, true)</code>, which returns <code>true</code> if the deadline has been violated and <code>false</code> otherwise. Hence, this reaction will increment the <code>count</code> variable as many times as possible before the deadline is violated and, at that point, will exit the loop and produce on the output the count. Running this program will produce something like this:

```
Stopped counting. Counted to 20257
```

This is a (rather trivial) example of an **anytime computation**. Such computations proceed to improve results until time runs out and then produce the most improved result.

The arguments to the lf\_check\_deadline are the self struct and a boolean that indicates whether the deadline violation handler should be invoked upon detecting a deadline violation. Because the argument is true above, the handler is invoked and Stopped counting is printed.

## **Multiports and Banks**

Lingua Franca provides a compact syntax for ports that can send or receive over multiple channels and another syntax for multiple instances of a reactor class. These are respectively called **multiports** and **banks of reactors**.

### Multiports

To declare an input or output port to be a **multiport**, use the following syntax:

where <width> is a positive integer. This can be given either as an integer literal or a parameter name. Consider the following example:

```
target C;
reactor Source {
    output[4] out:int;
    reaction(startup) -> out {=
        for(int i = 0; i < out width; i++) {
            lf_set(out[i], i);
        }
    =}
}
reactor Destination {
    input[4] in:int;
    reaction(in) {=
        int sum = 0;
        for (int i = 0; i < in width; i++) {
            if (in[i]->is present) sum += in[i]->value;
        }
        printf("Sum of received: %d.\n", sum);
    =}
}
main reactor {
    a = new Source();
    b = new Destination();
    a.out -> b.in;
}
```



Executing this program will yield:

Sum of received: 6.

The Source reactor has a four-way multiport output and the Destination reactor has a four-way multiport input. These channels are connected all at once on one line, the second line from the last. Notice that the generated diagram shows multiports with hollow triangles. Whether it shows the widths is controlled by an option in the diagram generator.

The Source reactor specifies out as an effect of its reaction using the syntax -> out. This brings into scope of the reaction body a way to access the width of the port and a way to write to each channel of the port.

**NOTE**: In Destination, the reaction is triggered by in, not by some individual channel of the multiport input. Hence, it is important when using multiport inputs to test for presence of the input on each channel, as done above with the syntax if (in[i]->is\_present) ... An event on any one of the channels is sufficient to trigger the reaction.

## Sparse Inputs

Sometimes, a program needs a wide multiport input, but when reactions are triggered by this input, few of the channels are present. In this case, it can be inefficient to iterate over all the channels to determine which are present. If you know that a multiport input will be **sparse** in this way, then you can provide a hint to the compiler and use a more efficient iterator to access the port. For example:

```
target C;
reactor Sparse {
   @sparse
    input[100] in:int;
    reaction(in) {=
        // Create an iterator over the input channels.
        struct lf multiport iterator t i = lf multiport iterator(in);
        // Get the least index of a channel with present inputs.
        int channel = lf multiport next(&i);
        // Iterate until no more channels have present inputs.
        while(channel >= 0) {
            printf("Received %d on channel %d\n", in[channel]->value, chann
            // Get the next channel with a present input.
            channel = lf multiport next(&i);
        }
   =}
}
```

Notice the @sparse annotation on the input declaration. This provides a hint to the compiler to optimize for sparse inputs. Then, instead of iterating over all input channels, this code uses the built-in function <code>lf\_multiport\_iterator()</code> to construct an iterator. The function <code>lf\_multiport\_next()</code> returns the first (and later, the next) channel index that is present. It returns -1 when no more channels have present inputs.

The multiport iterator can be used for any input multiport, even if it is not marked sparse. But if it is not marked sparse, then the lf\_multiport\_next() function will not optimize for sparse inputs and will simply iterate over the channels until it finds one that is present.

#### Parameterized Widths

The width of a port may be given by a parameter. For example, the above Source reactor can be rewritten

```
reactor Source(width:int(4)) {
    output[width] out:int;
    reaction(startup) -> out {=
        ...
    =}
}
```

## Connecting Reactors with Different Widths

Assume that the Source and Destination reactors above both use a parameter width to specify the width of their ports. Then the following connection is valid:

```
main reactor {
    a1 = new Source(width = 3);
    a2 = new Source(width = 2);
    b = new Destination(width = 5);
    a1.out, a2.out -> b.in;
}
```

The first three ports of b will received input from a1, and the last two ports will receive input from a2. Parallel composition can appear on either side of a connection. For example:

```
al.out, a2.out -> b1.out, b2.out, b3.out;
```

If the total width on the left does not match the total width on the right, then a warning is issued. If the left side is wider than the right, then output data will be discarded. If the right side is wider than the left, then input channels will be absent.

Any given port can appear only once on the right side of the -> connection operator, so all connections to a multiport destination must be made in one single connection statement.

### **Banks of Reactors**

Using a similar notation, it is possible to create a bank of reactors. For example, we can create a bank of four instances of Source and four instances of Destination and connect them as follows:

```
main reactor {
    a = new[4] Source();
    b = new[4] Destination();
    a.out -> b.in;
}
```



If the Source and Destination reactors have multiport inputs and outputs, as in the examples above, then a warning will be issued if the total width on the left does not match the total width on the right. For example, the following is balanced:

```
main reactor {
    a = new[3] Source(width = 4);
    b = new[4] Destination(width = 3);
    a.out -> b.in;
}
```

There will be three instances of Source, each with an output of width four, and four instances of Destination, each with an input of width 3, for a total of 12 connections.

To distinguish the instances in a bank of reactors, the reactor can define a parameter called **bank\_index**. If such a parameter is defined for the reactor, then when the reactor is instantiated in a bank, each instance will be assigned a number between 0 and *n*-1, where *n* is the number of reactor instances in the bank. For example, the following source reactor increments the output it produces by the value of bank\_index on each reaction to the timer:

```
target C;
reactor MultiportSource(
    bank index:int(0)
) {
    timer t(0, 200 \text{ msec});
    output out:int;
    state s:int(0);
    reaction(t) -> out {=
        lf set(out, self->s);
        self->s += self->bank index;
    =}
}
The width of a bank may also be given by a parameter, as in
main reactor(
    source bank width:int(3),
    destination bank width:int(4)
) {
    a = new[source bank width] Source(width = 4);
    b = new[destination bank width] Destination(width = 3);
    a.out -> b.in;
}
```

#### **Contained Banks**

Banks of reactors can be nested. For example, note the following program:

```
target C;
reactor Child (
    bank index:int(0)
) {
    reaction(startup) {=
        printf("My bank index: %d.\n", self->bank index);
    =}
}
reactor Parent (
    bank index:int(0)
) {
    c = new[2] Child();
}
main reactor {
    p = new[2] Parent();
}
```



In this program, the Parent reactor contains a bank of Child reactor instances with a width of 2. In the main reactor, a bank of Parent reactors is instantiated with a width of 2, therefore, creating 4 Child instances in the program in total. The output of this program will be:

```
My bank index: 0.
My bank index: 1.
My bank index: 0.
My bank index: 1.
```

The order of these outputs will be nondeterministic if the execution is multithreaded (which it will be by default) because there is no dependence between the reactions, and, hence, they can execute in parallel.

The bank index of a container (parent) reactor can be passed down to contained (child) reactors. For example, note the following program:

```
target C;
reactor Child (
    bank index:int(0),
    parent bank index:int(0)
) {
    reaction(startup) {=
        printf(
            "My bank index: %d. My parent's bank index: %d.\n",
            self->bank index, self->parent bank index
        );
    =}
}
reactor Parent (
    bank index:int(0)
) {
    c = new[2] Child(parent bank index = bank index);
}
main reactor {
    p = new[2] Parent();
}
```

In this example, the bank index of the Parent reactor is passed to the parent\_bank\_index parameter of the Child reactor instances. The output from this program will be:

```
My bank index: 1. My parent's bank index: 1. My bank index: 0. My parent's bank index: 0. My bank index: 0. My parent's bank index: 1. My bank index: 1. My parent's bank index: 0.
```

Again, note that the order of these outputs is nondeterministic.

Finally, members of contained banks of reactors can be individually addressed in the body of reactions of the parent reactor if their input/output port appears in the reaction signature. For example, note the following program:

```
target C;
reactor Child (
    bank index:int(0),
    parent_bank index:int(0)
) {
    output out:int;
    reaction(startup) -> out {=
        lf_set(out, self->parent_bank_index * 2 + self->bank_index);
    =}
}
reactor Parent (
    bank index:int(0)
) {
    c = new[2] Child(parent bank index = bank index);
    reaction(c.out) {=
        for (int i=0; i < c_width; i++) {</pre>
            printf("Received %d from child %d.\n", c[i].out->value, i);
        }
    =}
}
main reactor {
    p = new[2] Parent();
}
```

Lingua Franca diagram

Running this program will give something like the following:

```
Received 0 from child 0.
Received 1 from child 1.
Received 2 from child 0.
Received 3 from child 1.
```

## **Combining Banks and Multiports**

Banks of reactors may be combined with multiports, as in the following example:

```
target C;
reactor Source {
    output[3] out:int;
    reaction(startup) -> out {=
        for(int i = 0; i < out_width; i++) {
            lf set(out[i], i);
        }
    =}
}
reactor Destination(
    bank index:int(0)
) {
    input in:int;
    reaction(in) {=
        printf("Destination %d received %d.\n", self->bank index, in->value
    =}
}
main reactor MultiportToBank {
    a = new Source();
    b = new[3] Destination();
    a.out -> b.in;
}
```



The three outputs from the Source instance a will be sent, respectively, to each of three instances of Destination, b[0], b[1], and b[2]. The result of the program will be something like the following:

```
Destination 0 received 0.
Destination 1 received 1.
Destination 2 received 2.
```

Again, the order is nondeterministic in a multithreaded context.

The reactors in a bank may themselves have multiports. In all cases, the number of ports on the left of a connection must match the number on the right, unless the ones on the left are iterated, as explained next.

### **Broadcast Connections**

Occasionally, you will want to have fewer ports on the left of a connection and have their outputs used repeatedly to broadcast to the ports on the right. In the following example, the outputs from an ordinary port are broadcast to the inputs of all instances of a bank of reactors:

```
reactor Source {
        output out:int;
        reaction(startup) -> out {=
                 ... write to out ...
        =}
}
reactor Destination {
        input in:int;
        reaction(in) {=
                 ... read from in ...
        =}
}
main reactor ThreadedThreaded(width:int(4)) {
        a = new Source();
        d = new[width] Destination();
        (a.out) + -> d.in;
}
```

The syntax (a.out)+ means "repeat the output port a.out one or more times as needed to supply all the input ports of d.in." The content inside the parentheses can be a commaseparated list of ports, the ports inside can be ordinary ports or multiports, and the reactors inside can be ordinary reactors or banks of reactors. In all cases, the number of ports inside the parentheses on the left must divide the number of ports on the right.

#### **Interleaved Connections**

Sometimes, we don't want to broadcast messages to all reactors, but need more fine-grained control as to which reactor within a bank receives a message. If we have separate source and destination reactors, this can be done by combining multiports and banks as was shown in <a href="Combining Banks and Multiports">Combining Banks and Multiports</a>. Setting a value on the index n of the output multiport, will result in a message to the n-th reactor instance within the destination bank. However, this pattern gets slightly more complicated, if we want to exchange addressable messages between instances of the same bank. This pattern is shown in the following example:

```
target C;
reactor Node(
    num nodes: size t(4),
    bank index: int(0)
) {
    input[num nodes] in: int;
    output[num nodes] out: int;
    reaction (startup) -> out {=
        lf set(out[1], 42);
        printf("Bank index %d sent 42 on channel 1.\n", self->bank index);
    =}
    reaction (in) {=
        for (int i = 0; i < in width; i++) {
            if (in[i]->is present) {
                printf("Bank index %d received %d on channel %d.\n",
                    self->bank index, in[i]->value, i
                );
            }
        }
    =}
}
main reactor(num nodes: size t(4)) {
    nodes = new[num nodes] Node(num nodes=num nodes);
    nodes.out -> interleaved(nodes.in);
}
```

Lingua Franca diagram

In the above program, four instance of Node are created, and, at startup, each instance sends 42 to its second (index 1) output channel. The result is that the second bank member

(bank\_index 1) will receive the number 42 on each input channel of its multiport input. Running this program gives something like the following:

```
Bank index 0 sent 42 on channel 1.
Bank index 1 sent 42 on channel 1.
Bank index 2 sent 42 on channel 1.
Bank index 3 sent 42 on channel 1.
Bank index 1 received 42 on channel 0.
Bank index 1 received 42 on channel 1.
Bank index 1 received 42 on channel 2.
Bank index 1 received 42 on channel 3.
```

In bank index 1, the 0-th channel receives from bank\_index 0, the 1-th channel from bank\_index 1, etc. In effect, the choice of output channel specifies the destination reactor in the bank, and the input channel specifies the source reactor from which the input comes.

This style of connection is accomplished using the new keyword **interleaved** in the connection. Normally, a port reference such as **nodes** out where **nodes** is a bank and out is a multiport, would list all the individual ports by first iterating over the banks and then, for each bank index, iterating over the ports. If we consider the tuple (b,p) to denote the index b within the bank and the index p within the multiport, then the following list is created: (0,0), (0,1), (0,2), (0,3), (1,0), (1,1), (1,2), (1,3), (2,0), (2,1), (2,2), (2,3), (3,0), (3,1), (3,2), (3,3). However, if we use **interleaved** (nodes out) instead, the connection logic will iterate over the ports first and then the banks, creating the following list: (0,0), (1,0), (2,0), (3,0), (0,1), (1,1), (2,1), (3,1), (0,2), (1,2), (2,2), (3,2), (0,3), (1,3), (2,3), (3,3). By combining a normal port reference with a interleaved reference, we can construct a fully connected network. The figure below visualizes this how this pattern would look without banks or multiports:

gua Franca dia	ıgram		

If we were to use a normal connection <code>nodes.out -> nodes.in;</code> instead of the <code>interleaved</code> connection, then the following pattern would be created:

Lingua Franca diagram							

Effectively, this connects each reactor instance to itself, which isn't very useful.

## **Generic Reactors**

#### **Preambles**

#### Preamble

Reactions may contain arbitrary target-language code, but often it is convenient for that code to invoke external libraries or to share procedure definitions. For either purpose, a reactor may include a **preamble** section.

For example, the following reactor uses the math C library for its trigonometric functions:

```
main reactor {
    preamble {=
         #include <math.h>
        =}
    reaction(startup) {=
        printf("The cosine of 1 is %f.\n", cos(1));
        =}
}
```

This will print:

The cosine of 1 is 0.540302.

By putting the #include in the preamble, the library becomes available in all reactions of this reactor. If you wish to have the library available in all reactors in the same file, you can provide the preamble outside the reactor, as shown here:

```
preamble {=
    #include <math.h>
=}
reactor Cos {
    reaction(startup) {=
         printf("The cosine of 1 is f.\n", cos(1));
    =}
}
reactor Sin {
    reaction(startup) {=
         printf("The sine of 1 is f.\n", sin(1));
    =}
}
main reactor {
    c = new Cos()
    s = new Sin()
}
You can also use the preamble to define functions that are shared across reactions within a
reactor, as in this example:
main reactor {
    preamble {=
         int add 42(int i) {
             return i + 42;
         }
    =}
    reaction(startup) {=
         printf("42 plus 42 is %d.\n", add 42(42));
    =}
    reaction(startup) {=
        printf("42 plus 1 is %d.\n", add_42(1));
    =}
}
Not surprisingly, this will print:
42 plus 42 is 84.
42 plus 1 is 43.
```

(The order in which these are printed is arbitrary because the reactions can execute in parallel.)

To share a function across *reactors*, however, is a bit trickers. A **preamble** that is put outside the **reactor** definition can only contain *declarations* not *definitions* of functions or variables. The

following code, for example will fail to compile:

```
preamble {=
    int add_42(int i) {
        return i + 42;
    }
=}
reactor Add 42 {
    reaction(startup) {=
        printf("42 plus 42 is %d.\n", add 42(42));
    =}
}
reactor Add_1 {
    reaction(startup) {=
        printf("42 plus 1 is %d.\n", add_42(1));
    =}
}
main reactor {
    a = new Add 42()
    b = new Add 1()
}
```

The compiler will issue a **duplicate symbol** error because the function definition gets repeated in the separate C files generated for the two reactor classes, Add\_42 and Add\_1. When the compiled C code gets linked, the linker will find two definitions for the function add 42.

To correct this compile error, the file-level preamble should contain only a *declaration*, not a *definition*, as here:

```
preamble {=
    int add 42(int i);
=}
reactor Add 42 {
    reaction(startup) {=
        printf("42 plus 42 is %d.\n", add 42(42));
    =}
}
reactor Add 1 {
    reaction(startup) {=
        printf("42 plus 1 is %d.\n", add 42(1));
    =}
}
main reactor {
    preamble {=
        int add 42(int i) {
            return i + 42;
        }
    =}
    a = new Add 42()
    b = new Add 1()
}
```

The function *definition* here is put into the main reactor, but it can be put in any reactor defined in the file.

Most header files contain only declarations, and hence can be safely included using #include in a file-level preamble. If you wish to use a header file that includes both declarations and definitions, then you will need to include it within each reactor that uses it.

If you wish to share *variables* across reactors, similar constraints apply. Note that sharing variables across reactors is **strongly discouraged** because it can undermine the determinacy of Lingua Franca, and you may have to implement mutual-exclusion locks to access such variables. But it is occassionaly justfiable, as in the following example:

```
preamble {=
    extern const char shared string[];
=}
reactor A {
    reaction(startup) {=
        printf("Reactor A says %s.\n", shared string);
    =}
}
reactor B {
    reaction(startup) {=
        printf("Reactor B says %s.\n", shared string);
    =}
}
main reactor {
    preamble {=
        const char shared string[] = "Hello";
    =}
    a = new A()
    b = new B()
}
```

Notice the use of the extern keyword in C, which is required because the *definition* of the shared\_string variable will be in a separate (code-generated) C file, the one for main, not the ones for A and B.

One subtlety is that if you define symbols that you will use in **input**, **output**, or **state** declarations, then the symbols *must* be defined in a file-level **preamble**. Specifically, the following code will **fail to compile**:

```
main reactor {
    preamble {=
        typedef int foo;
    =}
    state x:foo = 0
    reaction(startup) {=
        lf_print("State is %d", self->x);
    =}
}
```

The compiler will issue an **unknown type name** error. To correct this, just move the declaration to a file-level **preamble**:

```
preamble {=
    typedef int foo;
=}
main reactor {
    state x:foo = 0
    reaction(startup) {=
        lf_print("State is %d", self->x);
    =}
}
```

# **Distributed Execution**

#### **Termination**

#### Shutdown Reactions

There are several mechanisms for terminating a Lingua Franca in an orderly fashion. All of these mechanisms result in a **final tag** at which any reaction that declares **shutdown** as a trigger will be invoked (recall that a **tag** is a tuple (**logical time**, **microstep**)). Other reactions may also be invoked at this final tag, and the order in which reactions are invoked will be constrained by the normal precedence rules.

If a reaction triggered by **shutdown** produces outputs, then downstream reactors will also be invoked at the final tag. If the reaction schedules any actions by calling **schedule()**, those will be ignored. In fact, any event after the final tag will be ignored. After the completion of the final tag, the program will exit.

There are four ways to terminate a program:

- **Timeout**: The program specifies the last logical time at which reactions should be triggered.
- **Starvation**: At the conclusion of some tag, there are no events in the event queue at future tags.
- **Stop request**: Some reaction requests that the program terminate.
- External signal: Program is terminated externally using operating services like control-C or kill.

We address each of these in turn.

#### **Timeout**

The <u>target property timeout</u> specifies the last logical time at which reactions should be triggered. The last invocation of reactions will be at tag (timeout, 0).

There is a significant subtlety when using <u>physical connections</u>, which are connections using the syntax ~> . Such connections specify that the tag at the receiving end will be based on the physical time at which the message is received. If the tag assigned at the receiving end is greater than the final tag, then the message is lost. Hence, **messages sent near the timeout time are likely to be lost!** 

#### Starvation

If a Lingua Franca program has no <u>physical actions</u>, and if at any time during execution there are no future events waiting to be processed, then there is no possibility for any more reactions to occur and the program will exit. This situation is called **starvation**. If there is a **timer** anywhere in the program with a period, then this condition never occurs.

One subtlety is that reactions triggered by **shutdown** will be invoked one microstep later than the last tag at which there was an event. They cannot be invoked at the same tag because it is only after that last tag has completed that the runtime system can be sure that there are no future events. It would not be correct to trigger the **shutdown** reactions at that point because it would be impossible to respect the required reaction ordering.

#### Stop Request

If a reaction calls the built-in <code>request\_stop()</code> function, then it is requesting that the program cease execution as soon as possible. This cessation will normally occur in the next microstep. The current tag will be completed as normal. Then the tag will be advanced by one microstep, and reactions triggered by <code>shutdown</code> will be executed, along with any other reactions with triggers at that tag, with all reactions executed in precedence order.

## **External Signal**

A control-C or other kill signal to a running Lingua Franca program will cause execution to stop immediately.