model

Vs 52V

V3 < 2 55V

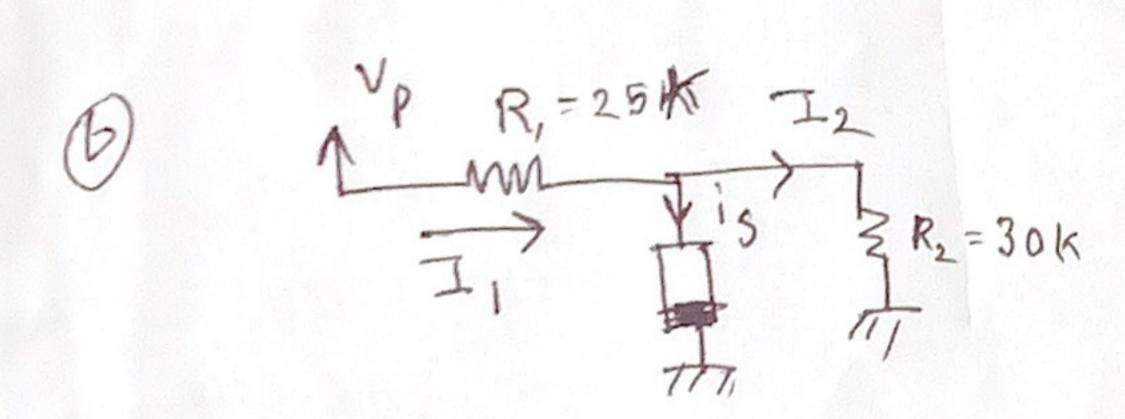
$$V_0 = x - intercept$$

= $2V$

$$\frac{y=1.25(x-2)}{i_s=1.25(x_s-2)}$$

$$J_0 = 1.25(5-2)$$

= $3.25mA$



(e) From graph, when vs=3V=) segment 2.

Hense, is=1'25(vs-2)=1'25mA

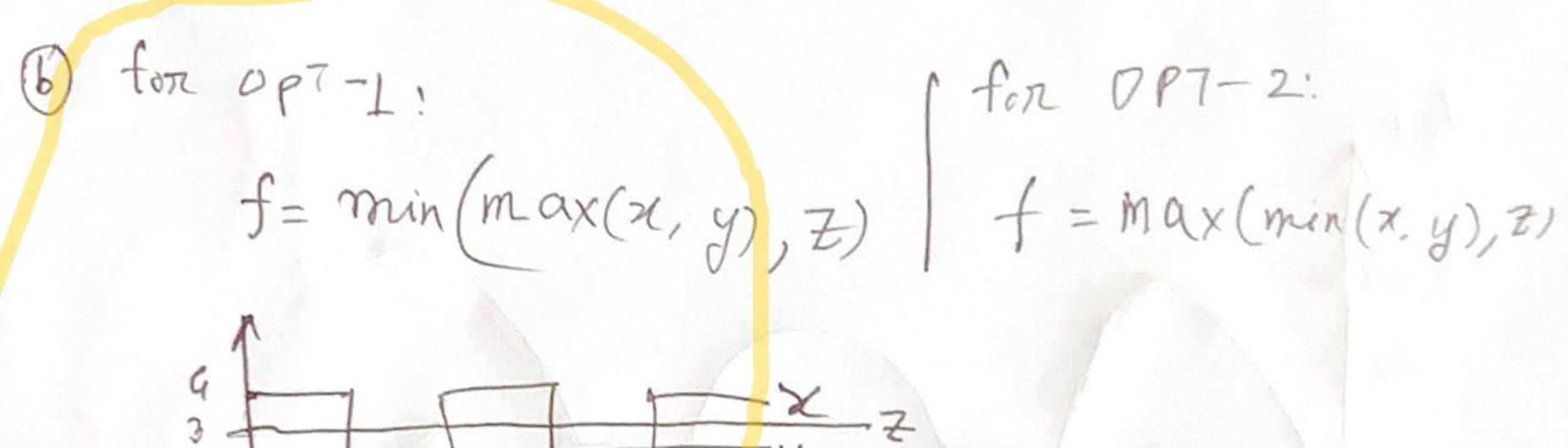
(a)
$$KCL \Rightarrow J_1 = i_5 + J_2 \neq 6 \text{hm/s} \quad law \rightarrow J_2 = \frac{3V}{R_2} = \frac{3V}{30K} = 0.1 \text{ mA}$$

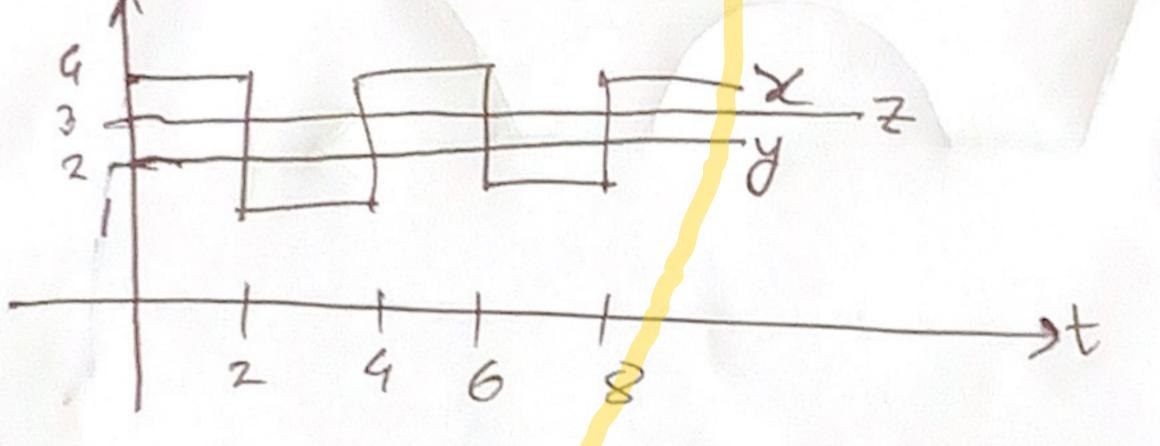
$$= 1.25 + 0.1 = 1.35 \text{ mA}$$

$$KVL \Rightarrow V_2 = J_1 R_1 + V_5 = 1.35 \times 25 K + 3 = 36.75V$$

Fither
$$f = (x+y)z$$

The state of $f = (x+y)z$





C)
$$f = x \cdot y \cdot z$$

$$\begin{cases}
f = x + y + z \\
x - y + z \\
z - z + z
\end{cases}$$

a

$$D_1 = ON$$
, $D_2 = OFF$

$$T_4 = T_{D_1} = \frac{11 - 0.5}{4} = 2.625 \text{ mA}$$

(b) DI(ON)=> TO(>0) =)TRUE

D2COFF) => 3-10V = - 9.5V

· VDO -> TRUE

Therefore, assumption correct!

$$T_{4} = \frac{1(-V_{x})}{4} \Rightarrow V_{x} = 11 - T_{4} \times 4$$

$$\Rightarrow V_{x} = -5.4V$$

$$\frac{O_3 4}{D_4}$$

$$\frac{O_4}{D_4}$$

$$\frac{O_7}{D_7}$$

Hence,
$$V_{Avg} = V_{DC} = \frac{2}{\pi c} V_{M} - 2V_{DO}$$

$$= \frac{2}{3.14} \times 10 - 2 \times 0.7$$

$$= \frac{3.14}{3.14} \times 10 - 2 \times 0.7$$

©
$$V_p = V_M - 2V_{Do} = 8.6V$$

 $f_R = 2f_i = \frac{2xW}{2\pi} = \frac{2x100\pi}{2\pi} = 100 \text{ Hz}$
 $V_p = \frac{V_p}{f_R RC} = \frac{8.6}{100 \times 50 \times 10^3 \times 5 \times 10^{-6}} = 1250 \text{ 0.344}$

$$V_{DC} = V_{P} - \frac{V_{P}}{2} = 8.6 - \frac{0.344}{2} = 8.428V$$

