

# Shihao Cao

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Looking for challenging projects with dynamic work

## EDUCATION

### CORNELL UNIV.

GPA: 4.07 / 4.0

Computer Science

May 2023 | Ithaca, NY

### THOMAS JEFFERSON HS FOR SCI/TECH

GPA: 4.56 / 4.0

Jun 2019 | Alexandria, VA

## LINKS

LinkedIn:// shihaoceo

Github:// shihaoceo

YouTube:// ShihaoCao

Website:// shihaoceo.com

## COURSEWORK

Analysis of Algorithms

ML • CV • AI

Adv. ML Systems

Operating Systems

Computer Systems

Functional Programming

Discrete Mathematics

OOP & Data Structures

Quantum Mechanics

Mathematical Physics

Linear Algebra

Differential Equations

Multivariable Calculus

Designing New Ventures

## SKILLS

### PROGRAMMING

4+ years experience:

Python • Java • C++

OpenCV (*Python and C++*)

HOOTL/HITL Testing

Simulation • Flight Software

Experienced:

C • Scikit-learn • NumPy

TensorFlow • Elasticsearch

Flask • NodeJS • Linux

### ROBOTICS

4+ years experience:

RC Aircraft (*Design, Build, Pilot*)

Autonomous Vehicles

Prototyping • Sensors

## HOBBIES

Photography (*Astro, Portrait*)

Painting • Stargazing • Go

Climbing • Longboarding

## EXPERIENCE

### SPACEX | STARSHIP FLIGHT SOFTWARE INTERN

Jun 2021 - Aug 2021 | Hawthorne, CA

- Upgraded inter-process data sharing, deprecating 2 relay systems and 40+ config files
- Owned, and supported inter-process data sharing for flight software (200+ devs)
- Restructured GNC->FSW->Network data flow for new distributed compute architecture
- Architect-ed flight software abort relay verification system, catching 4 critical bugs
- Optimized generation speed by 100x through data caching and multi-threaded workflows

### SPACEX | VEHICLE ENGINEERING INTERN

May 2020 - Aug 2020 | Hawthorne, CA

- Responsible for production landscape and engineering of two valves on Falcon 9 and Merlin
- Performed root cause analysis of valve failures to iterate design and prevent recurring issues
- Implemented process improvements to eliminate 90% of rebuilds, doubling production rate

### EXOANALYTIC SOLUTIONS | SYSTEMS ENGINEERING INTERN

July 2019 - Aug 2019 | Reston, VA

- Owned and delivered deployable satellite detector from concept to product in one month
- Developed RF signal processing and filtering routines using GNU Radio and Python
- Iterated performance by 10x to reduce performance reqs. from desktop to RPi4 platform

### EXOANALYTIC SOLUTIONS | SYSTEMS ENGINEERING INTERN

Jun 2018 - Aug 2018 | Reston, VA

- Owned and delivered deployable drone detector from concept to product in two months
- Implemented motion tracking, and blob detection with 95% accuracy at 100 meters

## RESEARCH AND TEAMS

### SPACE SYSTEMS DESIGN STUDIO - PAN TEAM | CO-LEAD

Sept 2019 - Current | Ithaca, NY

- Spearheaded software development for the Pathfinder for Autonomous Navigation (PAN) project, two 3U Cube Satellites which will autonomously rendezvous and dock in LEO
- Developed C++ drivers and flight software for attitude control pipeline and GPS
- Simulated spacecraft sensors and dynamics in software to verify control algorithms
- Spoofed orbital GPS RF signals with software-defined radio to validate GPS code

### CORNELL DATA SCI - SELF DRIVING CAR | TEAM LEAD + SOCIAL CHAIR

Jan 2021 - Current | Ithaca, NY

- Founded and now leading a team of 7 to build a webcam based car autopilot system
- Architect-ed Python control loop to integrate CV, SLAM, and actuators on a Linux platform

### TJ UNMANNED AERIAL VEHICLE TEAM | PRESIDENT + FOUNDER

Sept 2017 - Jun 2019 | Alexandria, VA

- Spearheaded and managed development of the 2019 fixed-wing UAV for SUAS
- Integrated Python software with flight computer, data radio, and camera/sensors
- Spearheaded and developed computer vision and machine learning pipeline

## PERSONAL PROJECTS

### ELECTRIC STARSHIP HOPPER | MAY 2020

Together with a partner, we designed and built an **electric VTOL drone** with single point vectored thrust. It delivers about one kg of thrust, and can take-off/hove/land vertically. I designed the vehicle, and wrote the C++ flight software, NodeJS ground displays, and sensor data pipeline.

### REMOTE CONTROL F-86 SABRE | MAY 2018

I designed, built and flew a 700mm wingspan **RC F-86 Sabre** powered by an EDF. I used Fusion 360 for CAD modelling, and Autodesk CFD to optimize ducting and aerodynamics.