### **NTUEE DCLAB**

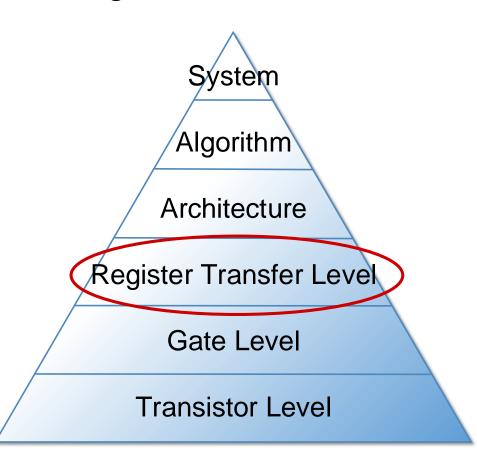
# Introduction to Verilog/System Verilog

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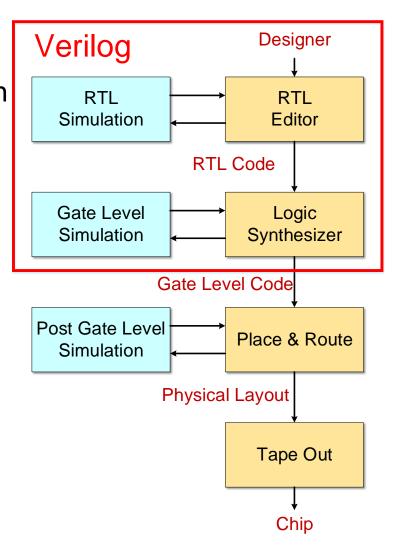
## What is Verilog HDL (Hardware Description Language)?

- Why using Hardware Description Language?
  - Hardware modeling
  - Reduce cost and time to design hardware
- Three popular HDLs
  - VHDL
  - Verilog
  - System Verilog



## What is Verilog?

- Verilog is a Hardware Description Language
  - Describes the flow of data between registers and how a design process these data
  - Model the timing
  - Express the concurrency of the system operation
  - Test the system



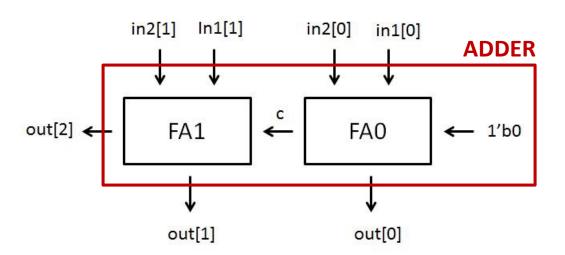
### RTL vs. Gate Level

#### 2-bit Adder

#### **RTL**

```
module ADDER (out, in1, in2);
  output [2:0] out;
  input [1:0] in1, in2;

assign out = in1 + in2;
endmodule
```

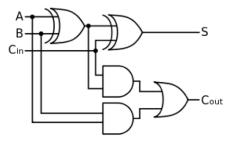


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#### RTL vs. Gate Level

#### **Gate Level**

endmodule



```
module FA1 (Cout, S, A, B, Cin);
output Cout, S;
input A, B, Cin;
```

wire N1, N2, N3;

```
EO XOR1(N1,A,B);
EO XOR2(s,N1,Cin);
AN2 AN2_1(N2,N1,Cin);
AN2 AN2_2(N3,A,B);
OR2 OR(Cout,N2,N3);
```

```
module ADDER (out, in1, in2);
output [2:0] out;
input [1:0] in1, in2;
wire c;
```

```
FA1 fa0(c, out[0], in1[0], in2[0], 1'b0);
FA1 fa1(out[2], out[1], in1[1], in2[1], c);
```

endmodule

### RTL Example

#### 1. Operator

#### 6. Call Module

```
module speed_machine (
                                                                          t-state logic (NL) ---
                 // system clock
                                                                           tate er accelerator er brake ) begin
        eleck.
                                                         35 4
                                                                 always@(
                  // high-active asynchronous reset
        reset.
                                                         36
                                                                     if( brake ) begin
                        // input: accelarator signal
                                                         37
                                                                         case( state )
                        // input: brake signal
        brake.
                                                         38
                                                                             stopped: next_state = stopped;
                        // output: current speed
        speed
                                                         39
                                                                             s low:
                                                                                      next state = stopped;
 7
    );
                                                                             s medium:next state =
                                                         40
                                                                             s high: next_state = s_medium;
                                                         41
    //--- PARAMETER DEFINITION -----
                                                                             default: next_state = stopped;
                                                         42
        // using sequential code for state encoding
10
                                                                         endcase
                                                         43
        parameter stopped = 2'b00;
11
                                                         44
                                                                     end
        parameter s_low
                           = 2'b01:
                                                                     else if( accelerator ) begin
                                                         45
        parameter s medium = 2'b10;
13
                                                                         case( state )
                                                         46
                          = 2'b11;
14
        parameter s_high
                                                                             stopped: next_state = s_low;
                                                         47
                                                                                      next state = s medium;
15
                                                         48
16
    //--- IN/OUT DECLARATION -----
                                                                             s medium:next state = s high;
                                                         49
17
        input
                     clock, reset:
                                                                             s high: next state = s high;
                                                         50
182
        input
                     accelerator, brake;
                                                                             default: next state = stopped;
                                                         51
19
        output [1:0] speed;
                                                         52
                                                                         endcase
20
                                                         53
                                                                     end
21
    //--- REG/WIRE DECLARATION -----
                                                                     else next_state = state;
                                                         54
22
              wires ---
                                                         55
                                                                 end
23
            [1:0] next state;
                                                         56
210.
        wire [1:0] next_speed;
                                                             //--- SEQUENTIAL CIRCUIT -----
25
                                                         58
                                                                       menory elements ---
26
        //--- flip-flops ---
                                                         59 4.
                                                                 always@( posedge clock or posedge reset ) begin
27
        req [1:0] state;
                           // memory for current state
                                                         60
                                                                     1f( reset ) begin
        reg [1:0] speed;
                           // memory for current output 61
28
                                                                        state <= 2'd0;
                                                                       speed <= 2'd0:
29
                                                         62
    //---- COMBINATIONAL CIRCUIT ------
                                                         63
                                                                     end.
31
              next-output logic (OL) ---
                                                                     else begin
                                                         64
        assign rext_speed = state;
                                                         65
                                                                        state <= next_state;
                                                                        speed <= next speed;
33
                                                         66
                                                         67
                                                                     end
                                                         68
                                                                 end
      source: CVSD "Behavior Modeling"
                                                             endmodule
```

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## **Difference in System Verilog**

- In System Verilog, logic is used to replace reg and wire in Verilog
- In System Verilog
  - Combinational circuit
    - always\_comb is used to replace always@(\*)
  - Sequential circuit
    - always\_ff@(posedge clk) is used to replace always@(posedge clk)

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### **Lexical Convention: Identifier and Comment**

- Verilog is a case sensitive language
- Terminate lines with semicolon;
- Identifiers
  - Starts only with a letter or an \_(underscore), can be any sequence of letters, digits, \$, \_
  - Case-sensitive

```
E.g. shiftreg_a
_bus3
n$657
12_reg  illegal
```

#### Comments

```
– Single line: //
```

– Multiple line: /\*...\*/

### **Lexical Convention: Naming Conventions**

- Consistent naming convention for the design
- Lowercase letters for signal names
- Uppercase letters for constants
- clk sub-string for clocks
- rst sub-string for resets
- Suffix
  - \_n for active-low, \_z for tri-state, \_a for async , ...
  - \_r, (\_cs) for current state, \_w, (\_ns) for next state
- Identical (similar) names for connected signals and ports
- Consistency within group, division and corporation

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### **Lexical Convention: Value Logic System**

- 4-value logic system in Verilog: 0, 1, x or X, z or Z
  - **-** 0
    - Zero, false, low
  - **-** 1
- One, true, high
- X or x
  - unknown, occurs at un-initialized storage elements or un-resolvable logic conflicts
- Z or z
  - High impedance, float

#### **Lexical Convention: Number**

- Number specification: <size>'<base><value>
  - Size: the size in bits
  - Base:
    - b (binary), o (octal), d (decimal) or h(hexadecimal)
  - Value: any legal number in selected base, including "x" and "z" When <size> is smaller than <value>: left-most bits of <value> are truncated When <size> is larger than <value>, then left-most bits are filled based on the value of the left-most bit in <value>

Left most '0' or '1' are filled with '0', 'Z' are filled with 'Z' and 'X' with 'X'

Default size is 32-bits decimal number

## **Value and Number Examples**

4'd10: 4-bit, 10, decimal

6'hca: 6-bit, store as 6'b001010 (truncated, not 11001010)

6'ha: 6-bit, store as 6'b001010 (filled with 2-bit '0' on left)

Negative: : <size>'<base><value>

```
E.g. -8'd38'd-3 //illegal
```

# 1. Operator: Arithmetic and Bit-wise

Operator Type	Operator Symbol	Meaning
Arithmetic	+	Add
	-	Subtract
	*	Multiply
	/	Division
	%	Modulus (some synthesis tools don't support this operator)
Bit-wise Operator	~	NOT
	&	AND
		OR
	۸	XOR

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# 1. Operator: Logical, Relational and Equality

Operator Type	Operator Symbol	Meaning
Logical: return 1-bit	!	Logic NOT
	&&	Logic AND
	П	Logic OR
Relational (conditional)	<=	Less than or equal
	<	Less than
	>=	Greater than and equal
	>	Greater than
Equality (conditional)	==	Equality
Equality (conditional)	!=	Inequality

### 1. Operator: Logical vs. Bit-wise Operator

- Logical Operator: return 1-bit true/false
  - E.g. a || b, a && b
    - 4'b1001 || 4'b1100 -> true, 1'b1
    - if( (a<=b)&&(c==d)||(e>f) )
- Bit-wise Operator
  - E.g. a | b
    - 4'b1001 | 4'b1100 -> 4'b1101

### 1. Operator: Conditional Description

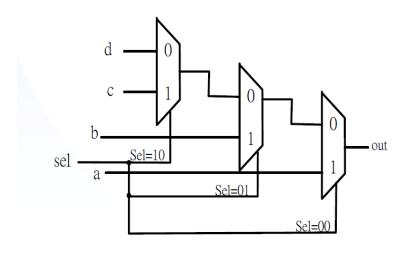
- if elseif else
- **?**:
  - c = sel ? a : b;
  - d = sel ? e : f;
- case endcase

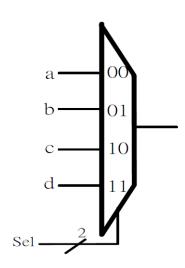
```
if (sel == 1'b1)
begin
        c = a;
        d = e;
end
else begin
        c = b;
        d = f;
end
```

```
case (sel)
        1'b0: begin
       c = b;
       d = e;
       end
       1'b1: begin
       c = a;
       d = f;
        end
endcase
```

### 1. Operator: if-then-else vs. Case

- *if-then-else* often infers a cascaded encoder
  - Inputs signals with different arrival time
- case infers a single-level mux
  - case is better if priority encoding is not required
  - case is generally simulated faster than if-then-else
- conditional assignment (? :)
  - Infers a mux with slower simulation performance





### 1. Operator: Shift Operator

#### Shift Operator (bit-wise)

- A = B >> 2; → shift right B by 2-bit
  - B=4'b1000; A=B>>2; A=4'b0010
- A = B << 2; → shift left B by 2-bit
  - B=4'b0100; A=B<<2; A=4'b0000</li>

#### Shift Operator (arithmetic)

- -A = B >>> 2;  $\Rightarrow$  shift right B by 2-bit
  - B=4'b1000; A=B>>>2; A=4'b1110
  - B=4'b0100; A=B>>>2; A=4'b0001
- A = B <<< 2; → shift left B by 2-bit
  - B=4'b0100; A=B<<<2; A=4'b0000

### 1. Operator: Concatenation

- ♦ {}  $\Rightarrow$  a = {b,c} - E.g. a = {b[3:0],c[3:0]} a = {b[3],b[2],b[1],b[0],c[3],c[2],c[1],c[0]} b[3] b[0] c[3] a[7]
- {{}} → a={2{c}}
  - $a = \{c,c\}$

•  $a[4:0] = \{b[3:0], 1'b0\};$   $\rightarrow$  a = b << 1;

### 2. Module

- Basic building blocks
- Begin with module, end with endmodule
- All modules run concurrently

```
module module_name(port_list);

//port declaration
//data type declaration
//task & function declaration
//module functionality or structure

endmodule
```

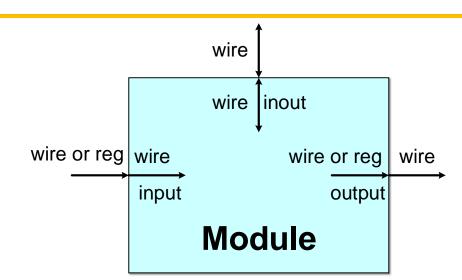
```
module test(Q, S, clk);
input S,clk;
output Q;
reg Q;
always@(*)
   Q = (S & clk);
endmodule
```

### 3. Module Ports

- Interface is defined by ports
- Port declaration
  - input: input port
  - output: output port
  - inout: bidirectional port

#### Port connection

- input: only wire can be assigned to represent this port in the module
- output: only wire can be assigned to represent this port out of module
- inout: register assignment is forbidden neither in module nor out of module [Tri-state]



#### 3. Module Ports: Module Connection

#### Port ordering

- One port per line with appropriate comments
- inputs first then outputs
- Modules connected by port order (implicit)
  - Here order shall match correctly. Normally, it is not a good idea to connect ports implicitly. It could cause problem in debugging when any new port is added or deleted.
  - e.g. FA U01( A, B, CIN, SUM, COUT );
- - Use named mapping instead of positional mapping
  - Name shall match correctly
  - e.g. FA U01( .a(A), .b(B), .cin(CIN), .sum(SUM), .cout(COUT) );

## 3. Module Ports: Examples

```
module MUX(out, a, b, sel, clk, rst);
input sel,clk,rst;
input a,b;
output out;
wire c;
reg a,b; //incorrect define
reg out;
//Continuous assignment
assign c = (sel==1'b0)?a:b;
//Procedural assignment
//only reg data type can be assigned value
always@(posedge rst or posedge clk)
begin
         if(rst==1'b1) out <= 0;
         else out <= c:
end
endmodule
```

```
`include "mux.v"
module test
reg out; //incorrect define
reg a,b;
reg clk,sel,rst;
wire out:
// 1. connect port by ordering
MUX mux 1(out, a, b, sel, clk, reset);
// 2. connect port by name
MUX mux 2(.clk(clk), .rst(rst), .sel(sel),
.a(a), .(b)b, .out(out));
endmodule
```

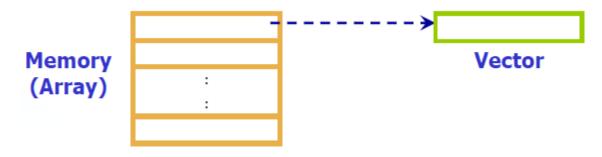
### 4. Data Type

- Declaration Syntax <data\_type>[MSB:LSB]<list\_of\_identifier>
  - Nets: represent physical connections between devices (default=z)
    - wire [MSB:LSB] variables;
    - Represent connections between things
    - Cannot be assigned in an initial or always block
  - Register: represent abstract data storage element(default=x)
    - reg [MSB:LSB] variables;
    - Hold their value until explicitly assigned in an initial or always block

Register Type	Attribute	
reg	Unsigned value with varying bit width	
integer	32-bit signed (2's complement)	
time	64-bit unsigned	
real	Real number	

### 4. Data Type: Vector and Array

- Vectors: the wire and register can be represented as a vector
  - wire [7:0] vec; → 8-bit bus
  - reg [0:7] vec;  $\rightarrow$  vec[0] is the MSB
- Arrays: <array\_name>[<subscript>]
  - It isn't well for the backend verifications
  - integer mem[0:7]  $\rightarrow$  (8x32)-bit mem
  - reg [7:0] mem[0:1023]
- Difference between Vector and Array
  - Vector: single-element with multiple-bit
  - Array: multiple-element with multiple-bit



### 5. Data Assignment

- Continuous Assignment for wire assignment
  - Implies that whenever any change on the RHS of the assignment occurs, it is evaluated and assigned to the LHS.
    - E.g. wire[3:0] a;assign a = b + c; // continuous assignment
- Procedural Assignment for reg assignment
  - Assignment to "register" data types may occur within always, initial, task and function. These expressions are controlled by triggers which cause the assignment to evaluate

```
    E.g. reg a, b;
    always@(b) //procedural assignment with triggers
    a = ~b;
```

## 5. Case Study: Behavioral Modeling

#### Description in Verilog

- assign
- always
  - Used in event-driven expression
  - Must contain a sensitive list
    - posedge, negedge

```
posedge negedge
```

```
always @(a or b or c)

begin

output1 = a & b & c;

end
```

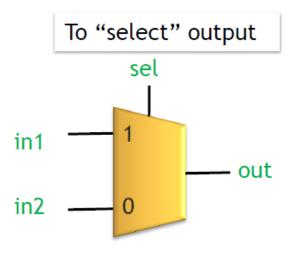
When a/b/c changes, (0->1/1->0) output1 will be updated

```
always @(posedge clk or negedge rst)

begin
    if (!rst) output1 <= 1'b0;
    else         output1 <= next_output;
end</pre>
```

Output1 will change when at posedge of clock or negedge of reset

## 5. Case Study: Mux



```
if(sel==1)
out = in1;
else
out = in2;
```

```
out = (sel\&in1)+(sel'\&in2)
```

```
module mux2(out,in1,in2,sel);
input in1,in2,sel;
output out;
assign out = sel?in1:in2;
endmodule
```

```
module mux2(out,in1,in2,sel);
input in1,in2,sel;
output out;
reg out

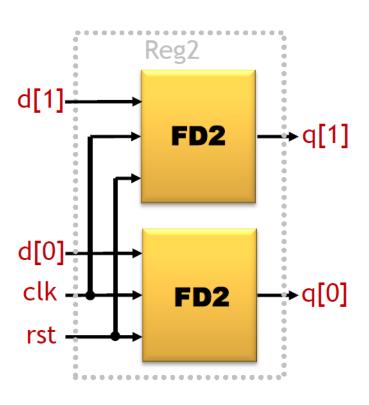
always@(in1 or in2 or sel)

begin
    if(sel) out = in1;
    else    out = in2;
end

endmodule
```

### 6. Module Instances

Create a higher-level system by connecting lower-level components



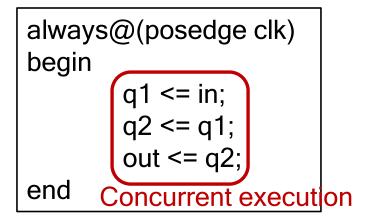
```
module Reg2(q, d, clk, rst);
input clk,rst;
input [1:0] d;
output [1:0] q;

FD2 f0(.Q(q[1]), .D(d[1]), .clk(clk),
   .rst(rst));
FD2 f1(q[0], d[0], clk, rst);

endmodule
```

## 7. Blocking and Non-blocking

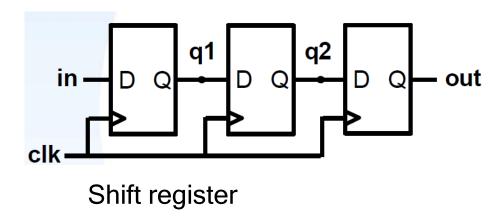
#### Blocking

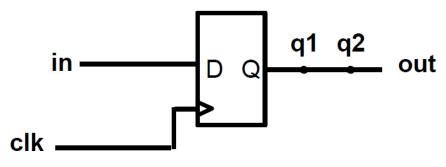


#### Non-blocking

```
always@(posedge clk)
begin

q1 = in;
q2 = q1;
out = q2;
end Sequential execution
```





### References

- James M. Lee, "Verilog® Quickstart A Practical Guide to Simulation and Synthesis in Verilog," Springer, 2005.
- S. Churiwala and S. Garg, "Principles of VLSI RTL Design," Springer, 2011.
- M. Keating, "The Simple Art of SoC Design Closing the Gap between RTL and ESL," Springer, 2011.
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