

Robot's action	Robot's moves towards and points to greeb knife
Robot's utterances	The green knife
Participant action	Picks up the green knife in hand
Robot's utterances	Try again
Participant action	Puts down the green knife on the table
Robot's utterances	Move the green knife
Participant action	Was confused where to move looks up the screen twice for more instruction while picking up the knife and putting near to the original place
Robot's utterances	Try again
Participant action	Holds the knife trying to put down
Robot's utterances	Move the green knife to the right (incorrect) of the white line
Participant action	While holding the knife in hand just put in the right side (incorrect) of the white line
Robot's utterances	Try again
Participant action	Plance in the middle of right (incorrect) side of the white line)
Robot's utterances	Move the green knife to the left (correct) side of the white line where I am poiniting
Robot's action	Robot moves to the left (correct) side of the table
Participant action	Moves the green knife to the left (correct) side of the white line
Robot's utterances	Positive feedback
Robot's action	Robot moves to next utensil
Robot's utterances	Now this utensils
Participant action	Start touching pen with gripper
Robot's utterances	Try again
Participant's utterance	Asking experimenter what is utenesil ?
Robot's utterances	Move this red glass
Participant's utterance	Hold the red glass in hand
Robot's utterances	Try again
Participant's utterance	Put down the glass
Participant's gesture	Tries to read and pcik glass but changes his mind
Robot's utterances	Move the red glass to the left (incorrect) side of the white lin
Participant's utterance	Moves the red glass to the left (incorrect) side of the white line
Robot's utterances	Try again
Robot's action	Move the red glass to right side(correct) to the white line
Robot's action	Robot's move towards right side (correct)
Participant action	Participants puts the glass on the right side(correct)
Robot's utterances	positive feedback
Robot's utterances	Robot was unable to detect red bowl and green glass