

INDIAN INSTITUTE OF TECHNOLOGY

KHARAGPUR

DEPARTMENT OF ELECTRONICS AND ELECTRICAL COMMUNICATION

EC49001

MICROCONTROLLER SYSTEMS
LABORATORY

ASSIGNMENT 2



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E & ECE

(B. Tech)

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Questions

1. Store the binary truth table outputs of a four input combinational function at locations 30H to 3FH. Design a circuit that uses 4 LEDs to represent the inputs and a fifth LED for the output, such that the program will cyclically show all the inputs from 0000 to 1111 as well as the corresponding outputs.
2. Consider a switch input **sw0**. If the switch is pressed, all 5 LED's blink and when released, the operation comes back to its normal mode starting at the combination 0000.

Objectives

1. Implement a truth table with the help of LED's and perform iteration through its inputs in assembly code using a 4-bit counter.
2. Add a switch to run a special routine and reset the truth table.

Description

1. We create a counter for traversing through the truth table. This counter ranges from 0 to 15, which we add to our accumulator. **ACC** now has information regarding the 4-bit counter in its last 4 bits. Then we swap the first and last 4 bits of **ACC** so that bits 7,6,5,4 represent the inputs ABCD, and we add the output stored in the ram RAM. E.g. if at the 11th input (3BH) we have 1, the 8 bits of our **ACC** would be 1011001. This perfectly describes what our LEDs should output, so we simply complement this using the **CPL** operation and move it to P1, where it is displayed accordingly.
2. At the beginning of every iteration we check if **sw0** is active/pressed (assigned to P2.0). If it is pressed, we move to the **EXCEPTION** subroutine. All 5 LEDs (at position 7, 6, 5, 4 and 1) high means the value of P1 is 00001110 (high LEDs have low bits since P1 is active low), so we move the value 14 to P1 to make all the LEDs high. This is followed by a **DELAY_MODULE**, which just consists of a single memory operation performed multiple times by nested loops. To turn all LEDs off, we simply move the value 255 to P1, followed by another

call to the DELAY_MODULE subroutine. This repeats indefinitely until the switch is released, in which case the iteration starts again from 0000.

Code

```
1. ; Author: Shikhar Mohan
2. ; Date: 20/09/2021
3. ; EC49001: Assignment 2
4.
5.
6. MOV 30H,#1
7. MOV 31H,#1
8. MOV 32H,#1
9. MOV 33H,#0
10. MOV 34H,#1
11. MOV 35H,#1
12. MOV 36H,#1
13. MOV 37H,#0
14. MOV 38H,#0
15. MOV 39H,#0
16. MOV 3AH,#1
17. MOV 3BH,#0
18. MOV 3CH,#0
19. MOV 3DH,#0
20. MOV 3EH,#1
21. MOV 3FH,#0
22.
23. MOV R0,#30H
24. MOV P2,#255
25. MOV R1,#0
26.
27. OUTER_LOOP:
28. JNB P2.0,EXCEPTION
29. MOV A,R1
30. SWAP A
31. ADD A,@R0
32. CPL A
33. MOV P1,A
34.
35. MOV A,R1
36. SUBB A,#15
37. JZ RESET
38. INC R0
39. INC R1
40. JMP OUTER_LOOP
41.
42. RESET:
43. MOV R0,#30H
44. MOV R1,#00H
45. JMP OUTER_LOOP
46.
47. EXCEPTION:
48. MOV P1,#14
49. CALL DELAY_MODULE
50. MOV P1,#255
51. CALL DELAY_MODULE
```

```

52. JMP RESET
53.
54. DELAY_MODULE: MOV R5, #1
55. DELAY1:  MOV R6, #1
56. DELAY2:  MOV R4, #32
57. STAY:    DJNZ R4, STAY
58.          DJNZ R6, DELAY2
59.          DJNZ R5, DELAY1
60.          RET

```

Screenshots

The screenshot displays the Proteus ISIS simulation environment for an 8051 microcontroller. The top window shows the 8051 register set and memory. The registers are as follows:

R/O	W/O	TH0	TL0	R7	B
0x00	0x00	0x00	0x00	0x00	0x00
RXD	TXD	TMOD	0x00	R6	ACC 0x4F
1	1	TCON	0x00	R5	PSW 0x01
SCON	0x00			R4	IP 0x00
				R3	IE 0x00
				R2	PCON 0x00
				R1	DPH 0x00
				R0	DPL 0x00
					SP 0x07

The memory window shows the following data:

addr	0x00	0x00	value
0	00	33	03
1	00	00	00
2	00	00	00
3	00	00	00
4	00	00	00
5	00	00	00
6	00	00	00
7	00	00	00
8	00	00	00
9	00	00	00
A	00	00	00
B	00	00	00
C	00	00	00
D	00	00	00
E	00	00	00
F	00	00	00

The bottom window shows the I/O components, including the 8051 microcontroller, the 8255 PPI, and the 8257 DMA controller. The 8255 PPI is configured with the following settings:

- Mode: Standard
- Parity: No Parity
- Baud Rate: 8-bit UART @ 4800 Baud

The 8257 DMA controller is configured with the following settings:

- Mode: Standard
- Parity: No Parity
- Baud Rate: 8-bit UART @ 4800 Baud

The 8051 microcontroller is configured with the following settings:

- Mode: Standard
- Parity: No Parity
- Baud Rate: 8-bit UART @ 4800 Baud

The 8255 PPI is configured with the following settings:

- Mode: Standard
- Parity: No Parity
- Baud Rate: 8-bit UART @ 4800 Baud

The 8257 DMA controller is configured with the following settings:

- Mode: Standard
- Parity: No Parity
- Baud Rate: 8-bit UART @ 4800 Baud

The 8051 microcontroller is configured with the following settings:

- Mode: Standard
- Parity: No Parity
- Baud Rate: 8-bit UART @ 4800 Baud

Fig.1: The LEDs tell us that the functional output at 10 (1010₂) is 1, which we can see by directly inspecting the memory byte 3A.

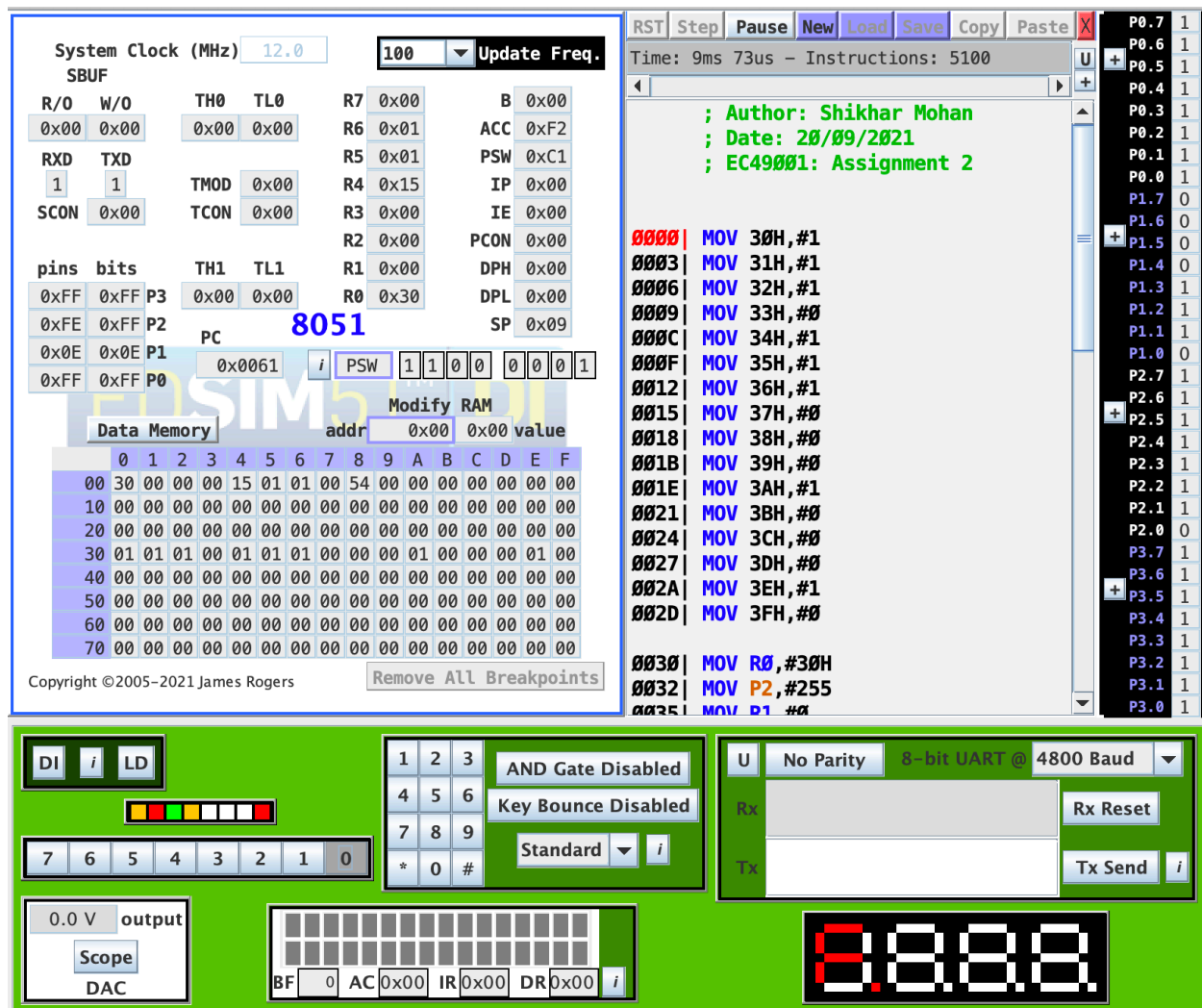


Fig. 2: Here we can see that the P2.0 switch is pressed and all LEDs are high.

Results

1. We observe that the 4-bit counter implementation is working fine and the required output is observed on the LEDs while traversing through the truth table.
2. When the switch is pressed all LEDs blink until it is released, upon which the LEDs start at zero.

Discussion

1. Creating the LED array inside our accumulator makes the counter very simple to implement because it uses the fact that **ACC** and **P1** are both 8-bit values and saves us the trouble of obtaining bits manually. Directly adding the RAM value means the LED stays low when it's zero and is high when the value is one. One needs to keep in mind that **P1** is active low, so the complement needs to be taken in operations like these prior to moving. It can also be observed that random segments of the 7-segment panel are glowing as well. This is because the LED panel is connected to the 7-segment display panel, which is active low as well (i.e. common cathode).
2. Instead of using a time based delay, we implement a simple delay module subroutine where a memory operation is carried out 10 times with a loop, and this loop is nested twice so that the operation is carried out a 1000 times. This provides sufficient reliable delay.

Summary

We utilise an efficient algorithm to create the LED output in our **ACC** itself, and add an **EXCEPTION** subroutine to blink our LEDs based on the input of a switch **sw0**.