

Math 164 - Assignment #5, Fall 2024

• **Due Date:** 11:59 pm on November 8st, 2024

1. Consider the following algorithm for minimizing a function f :

$$\mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} + \alpha_k \mathbf{d}^{(k)},$$

where $\alpha_k = \arg \min_{\alpha} f(\mathbf{x}^{(k)} + \alpha \mathbf{d}^{(k)})$. Let $\mathbf{g}^{(k)} = \nabla f(\mathbf{x}^{(k)})$ (as usual).

Suppose that f is quadratic with Hessian \mathbf{Q} . We choose $\mathbf{d}^{(k+1)} = \gamma_k \mathbf{g}^{(k+1)} + \mathbf{d}^{(k)}$, and we wish the directions $\mathbf{d}^{(k)}$ and $\mathbf{d}^{(k+1)}$ to be \mathbf{Q} -conjugate. Find a formula for γ_k in terms of $\mathbf{d}^{(k)}$, $\mathbf{g}^{(k+1)}$, and \mathbf{Q} .

2. Represent the function

$$f(\mathbf{x}) = \frac{5}{2}x_1^2 + x_2^2 - 3x_1x_2 - x_2 - 7$$

In the form $f(\mathbf{x}) = \frac{1}{2}\mathbf{x}^\top \mathbf{Q}\mathbf{x} - \mathbf{x}^\top \mathbf{b} + c$. Then, use the conjugate gradient algorithm to find a minimizer with $\mathbf{d}^{(0)} = \nabla f(\mathbf{x}^{(0)})$, where $\mathbf{x}^{(0)} = \mathbf{0}$.

3. Consider the DFP algorithm applied to the quadratic function

$$f(\mathbf{x}) = \frac{1}{2}\mathbf{x}^\top \mathbf{Q}\mathbf{x} - \mathbf{x}^\top \mathbf{b}$$

where $\mathbf{Q} = \mathbf{Q}^\top > 0$.

- (a) Write down a formula for α_k in terms of \mathbf{Q} , $\mathbf{g}^{(k)}$, and $\mathbf{d}^{(k)}$.
 - (b) Show that if $\mathbf{g}^{(k)} \neq 0$, then $\alpha_k > 0$.
4. Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be such that $f \in \mathcal{C}^1$. Consider an optimization algorithm applied to this f , of the usual form $\mathbf{x}^{(k+1)} = \mathbf{x}^{(0)} + a_k \mathbf{d}^{(k)}$, where $\alpha_k \geq 0$ is chosen according to line search. Suppose that $\mathbf{d}^{(k)} = -\mathbf{H}_k \mathbf{g}^{(k)}$, where $\mathbf{g}^{(k)} = \nabla f(\mathbf{x}^{(k)})$ and \mathbf{H}_k is symmetric.
 - (a) Show that if \mathbf{H}_k satisfies the following conditions whenever the algorithm is applied to a quadratic, then the algorithm is quasi-Newton:
 - i. $\mathbf{H}_{k+1} = \mathbf{H}_k + \mathbf{U}_k$.
 - ii. $\mathbf{U}_k \Delta \mathbf{g}^{(k)} = \Delta \mathbf{x}^{(k)} - \mathbf{H}_k \Delta \mathbf{g}^{(k)}$.
 - iii. $\mathbf{U}_k = \mathbf{a}^{(k)} (\Delta \mathbf{x}^{(k)})^\top + \mathbf{b}^{(k)} (\Delta \mathbf{g}^{(k)})^\top \mathbf{H}_k$, where $\mathbf{a}^{(k)}$ and $\mathbf{b}^{(k)}$ are in \mathbb{R}^n .
 - (b) Which (if any) among the rank-one, DFP, and BFGS algorithms satisfy the three conditions in part a (whenever the algorithm is applied to a quadratic)? For those that do, specify the vectors $\mathbf{a}^{(k)}$ and $\mathbf{b}^{(k)}$.
 5. Given a function $f : \mathbb{R}^n \rightarrow \mathbb{R}$, consider an algorithm $\mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} - \alpha_k \mathbf{H}_k \mathbf{g}^{(k)}$ for finding the minimizer of f , where $\mathbf{g}^{(k)} = \nabla f(\mathbf{x}^{(k)})$ and $\mathbf{H}_k \in \mathbb{R}^{n \times n}$ is symmetric. Suppose that $\mathbf{H}_k = \phi \mathbf{H}_k^{\text{DFP}} + (1 - \phi) \mathbf{H}_k^{\text{BFGS}}$, where $\phi \in \mathbb{R}$, and $\mathbf{H}_k^{\text{DFP}}$ and $\mathbf{H}_k^{\text{BFGS}}$ are matrices generated by the DFP and BFGS algorithms, respectively.
 - (a) Show that the algorithm above is a quasi-Newton algorithm. Is the above algorithm a conjugate direction algorithm?
 - (b) Suppose that $0 \leq \phi \leq 1$. Show that if $\mathbf{H}_0^{\text{DFP}} > 0$ and $\mathbf{H}_0^{\text{BFGS}} > 0$, then $\mathbf{H}_k > 0$ for all k . What can you conclude from this about whether or not the algorithm has the descent property?