

1 実験 2

以下にソースコードとその実行結果を示す。

```
1  clear();
2  s = %s;
3  K = 1;
4  omega = 6;
5  zeta = 0.1;
6  P1 = syslin('c', K*omega^2/(s^2 + 2 * zeta * omega*s + omega^2));
7
8
9  zeta = 0.5;
10 P2 = syslin('c', K*omega^2/(s^2 + 2 * zeta * omega*s + omega^2));
11
12
13 zeta = 1.0;
14 P3 = syslin('c', K*omega^2/(s^2 + 2 * zeta * omega*s + omega^2));
15
16 t = 0:0.1:20;
17 u = ones(t);
18
19 y1 = csim(u,t,P1);
20 y2 = csim(u,t,P2);
21 y3 = csim(u,t,P3);
22 xmin = 0; xmax = 10; ymin = -0.5; ymax = 2;
23 scf(0);
24
25 plot2d(t,u,style=color(0,0,255),rect=[xmin ymin xmax ymax]);
26
27 plot2d(t,y1,style=color(255,0,0),rect=[xmin ymin xmax ymax]);
28 plot2d(t,y2,style=color(0,255,0),rect=[xmin ymin xmax ymax]);
29 plot2d(t,y3,style=color(50,0,20),rect=[xmin ymin xmax ymax]);
30
31 xtitle('Step Response', 'time[s]', 'u, y')
32 xgrid();
33
34 xs2png(0, 'experiment1-2.png')
```

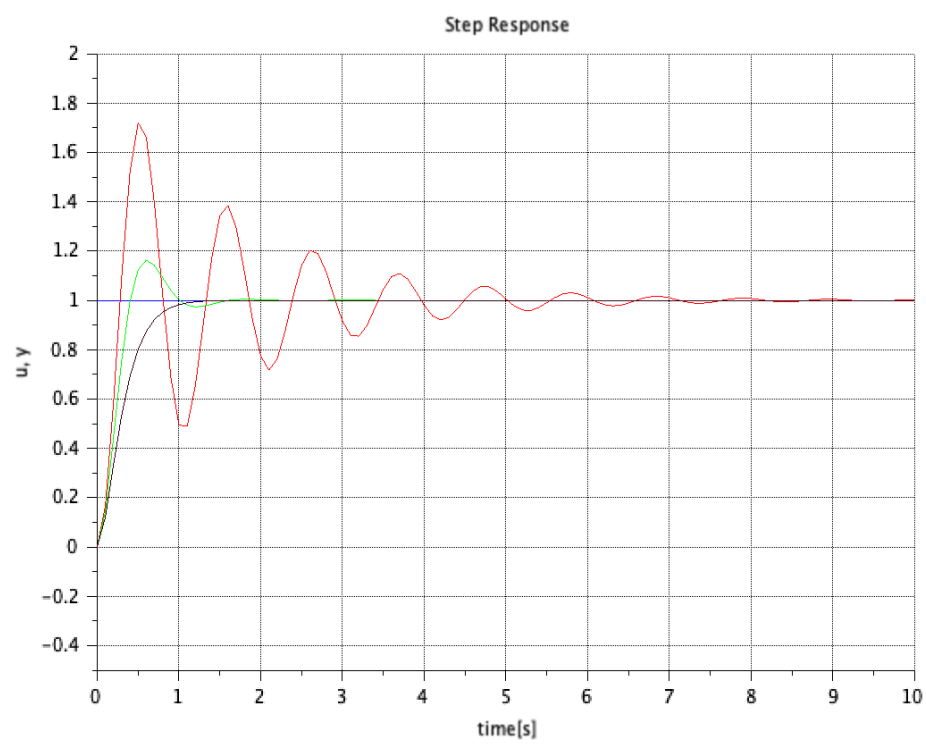


図1 実験2の実行結果