Realistic Car Controller Pro

Thank you for purchasing and using Realistic Car Controller Pro. This documentation will guide you on how to use Logitech Steering Wheels with RCCP.

In order to use with any steering wheel, you have to switch to the new input system (explained in the **RCC Pro – Inputs** documentation). Once you switch to the new input system, editor will recognize the connected steering wheel automatically. Logitech SDK is not necessary to receive inputs from the steering wheel. SDK will be used for force feedback only.

RCCP_InputActions has preset for **G920** model. If you have the same model, it would work out of the box. But for the other models, you would need to change some inputs in the **RCCP_InputActions**. Open the **RCCP_InputActions** located in the resources folder, and search for the steering wheel inputs. You can change them with your own inputs. Always check your live input data with the **Input Debugger**. You can open the **Input Debugger** from **Window → Analysis → Input Debugger**. Select your steering wheel, and live input data of your steering will be on your screen.

There are some options you should disable on vehicles. When you are using the steering wheel, you won't need to use automatic transmission, auto shift to reverse gear, cut throttle while shifting, counter steering etc… Please follow the steps below;

1. Disable **counter steering** and **steering limiter** in the **RCCP_Inputs**. This has been used to emulate counter steering effect, but no need to use it with the steering wheel.
2. Disable **automatic transmission** in the **RCCP_Gearbox**. It's optional, but if you have H shifter, you may want to disable automatic transmission.
3. Disable **automatic clutch** in the **RCCP_Clutch**. If you want to use manual clutch, you may want to disable this option.
4. Disable **auto reverse gear**, **inverse throttle**, **cut throttle while shifting** options in the **RCCP_Inputs**. You won't need them.

Steering factor can be adjusted directly in the **RCCP_InputActions**. Open the **RCCP_InputActions**, and click steering input for the steering wheel. You can adjust scale factor of the steering input.