

Coadjoint Orbits of $SU(n)$

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In this note, we will consider the coadjoint orbits of $SU(n)$, and show that they are Kähler manifolds.

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1 Adjoint and Coadjoint Orbits

Define the Lie algebra

$$\mathfrak{su}(n) = \{A \in \text{Mat}(n, \mathbb{C}) \mid A^* + A = 0, \text{tr}(A) = 0\}$$

where A^* is the conjugate transpose of A , and with the Lie bracket being the matrix commutator. We can define the adjoint representation of $SU(n)$ as

$$\begin{aligned} \text{Ad} : SU(n) &\rightarrow \text{GL}(\mathfrak{su}(n)) \\ \text{Ad}_g(X) &= gXg^\dagger \end{aligned}$$

Taking the dual representation, we get the coadjoint representation, which is

$$\begin{aligned} \text{Ad}^* : SU(n) &\rightarrow \text{GL}(\mathfrak{su}(n)^*) \\ \text{Ad}_g^*(\alpha)(X) &= \alpha(\text{Ad}_{g^{-1}}(X)) \end{aligned}$$

Now note that

$$\langle A, B \rangle = -\text{tr}(AB) = \text{tr}(AB^*)$$

defines an inner product on $\mathfrak{su}(n)^1$, which means that we have a natural isomorphism

¹In fact, $\langle A, B \rangle = \text{tr}(AB^*)$ defines a Hermitian inner product on the space of complex matrices.

$$\begin{aligned}\Phi : \mathfrak{su}(n) &\rightarrow \mathfrak{su}(n)^* \\ A &\mapsto \langle A, \cdot \rangle\end{aligned}$$

With this, suppose $\alpha = \Phi(A)$, then

$$\text{Ad}_g^*(\alpha)(X) = \langle A, \text{Ad}_{g^{-1}}(X) \rangle = -\text{tr}(Ag^{-1}Xg) = -\text{tr}(gAg^{-1}X) = \Phi(\text{Ad}_g(A))(X)$$

Therefore, up to identification by Φ , the adjoint and coadjoint representations are the same.

2 Tangent space

Let \mathcal{O}^* be a coadjoint orbit. For $X \in \mathfrak{su}(n)$, consider the curve $g(t) = \exp(tX)$ in G . This has $g'(0) = X$, and we have a curve

$$\mu(t) = \text{Ad}_{g(t)}^*(\mu)$$

through $\mu \in \mathcal{O}^*$. In particular, we have that for $Y \in \mathfrak{su}(n)$,

$$\langle \mu(t), Y \rangle = \langle \mu, \text{Ad}_{g(t)^{-1}}(Y) \rangle$$

Differentiating this at $t = 0$, we get

$$\langle \mu'(0), Y \rangle = -\langle \mu, \text{ad}_X(Y) \rangle = -\langle (\text{ad}_X)^*(\mu), Y \rangle$$

That is, $\mu'(0) = -(\text{ad}_X)^*(\mu)$. Hence we have that

$$T_\mu(\mathcal{O}^*) = \{(\text{ad}_X)^*(\mu) \mid X \in \mathfrak{su}(n)\}$$

If $\alpha = \Phi(A)$, then

$$\begin{aligned}\langle (\text{ad}_X)^*(\alpha), Y \rangle &= \langle \alpha, \text{ad}_X(Y) \rangle \\ &= \langle A, [X, Y] \rangle \\ &= -\text{tr}(AXY - AYX) \\ &= -\text{tr}(AXY - XAY) \\ &= \langle [A, X], Y \rangle \\ &= \langle -\text{ad}_X(A), Y \rangle\end{aligned}$$

Hence by identification with Φ , $(\text{ad}_X)^* = -\text{ad}_X$. Thus, in this case we have the tangent space to the corresponding adjoint orbit as

$$T_A\mathcal{O} = \{\text{ad}_X(A) \mid X \in \mathfrak{su}(n)\}$$

3 Diagonalisation

Since all elements in \mathcal{O} are diagonalisable by $\text{SU}(n)$, we can choose $A \in \mathcal{O}$ to be diagonal. Moreover, the eigenvalues are pure imaginary, so we can assume

$$A = \begin{pmatrix} i\lambda_1 & & \\ & \ddots & \\ & & i\lambda_n \end{pmatrix}$$

with $\lambda_1 \geq \dots \geq \lambda_n$. Then define the projection map $\pi : \text{SU}(n) \rightarrow \mathcal{O}$ by

$$\pi(g) = \text{Ad}_g(A) = gAg^t$$

and it is easy to check that π is a surjective submersion. In particular, if α is any form on \mathcal{O} , then α is determined by its pullback $\pi^*\alpha$.

4 Symplectic structure

For details in this section, see [kirillov-kostant.pdf](#) or Marsden-Ratiu Chapter 14.

The Kirillov-Kostant-Souriau form on \mathcal{O}^* is given by

$$\omega_\mu(-(\text{ad}_X)^*(\mu), -(\text{ad}_Y)^*(\mu)) = -\langle \mu, [X, Y] \rangle$$

Therefore, using the isomorphism Φ , we have a corresponding symplectic form on \mathcal{O} given by

$$\omega_B(\text{ad}_X(B), \text{ad}_Y(B)) = -\langle B, [X, Y] \rangle \quad (1)$$

Then $\pi^*\omega = d\alpha_\ell$, where $\alpha = \Phi(A)$, and α_ℓ is the left-invariant 1-form on $\text{SU}(n)$ taking value α at 1. That is,

$$\alpha_\ell(g) = ((d\ell_{g^{-1}})_g)^*(\alpha)$$

Using this, we get that $\pi^*d\omega = d\pi^*\omega = d^2\alpha_\ell = 0$, and as π is a surjective submersion, $d\omega = 0$. The facts that eq. (1) is well defined and non-degenerate are easy to check as well.

5 Complex structure

From §3, we assumed that A is diagonal. Suppose the eigenvalues have algebraic multiplicities n_1, \dots, n_k . Then we have that the stabiliser of A is the block diagonal subgroup

$$\text{Stab}(A) = \text{S}(\text{U}(n_1) \times \dots \times \text{U}(n_k))$$

and the quotient space is the flag manifold

$$\mathcal{F}(n_1, \dots, n_k) = \frac{\text{SU}(n)}{\text{Stab}(A)}$$

We won't discuss this any further, see [coadjoint-orbits-sln.pdf](#) for details. We will now focus on the generic case, where A has distinct eigenvalues. In this case, the stabiliser is the diagonal subgroup T , which is isomorphic to the torus $T^{n-1} = (S^1)^{n-1}$.

Let P be the subgroup of lower triangular matrices in $\text{SL}(n, \mathbb{C})$. Consider the composition $\varphi : \text{SU}(n) \rightarrow \text{SL}(n, \mathbb{C})/P$ given by the composition

$$\text{SU}(n) \hookrightarrow \text{SL}(n) \twoheadrightarrow \text{SL}(n, \mathbb{C})/P$$

Suppose $\varphi(g) = \varphi(h)$. That is, $gP = hP$. This is true if and only if there exists $p \in P$, such that $h = gp$. In this case, $p = g^{-1}h \in \text{SU}(n)$, therefore, $p \in \text{SU}(n) \cap P = T$, since $p^\dagger = p^{-1}$ is also lower triangular. This means that φ induces a homeomorphism $\text{SU}(n)/T \cong \text{SL}(n, \mathbb{C})/P$. The right hand side is a complex manifold ($\text{SL}(n, \mathbb{C})$) quotiented by a complex Lie group P , so it is a complex manifold. Using the above, we can get a complex structure on $\text{SU}(n)/T \cong \mathcal{O}$.

6 Local coordinates

This section is from [un_kks.pdf](#), which follows an exercise from Prof. Bryant's notes. The computations to verify these expressions can be found in [un_kks.pdf](#), and have been omitted.

let θ be the Maurer-Cartan form on $\text{SU}(n)$. That is, it is the $\mathfrak{su}(n)$ -valued 1-form on $\text{SU}(n)$ given by

$$\theta_g(u) = d(\ell_{g^{-1}})_g(u) \in T_e \text{SU}(n) = \mathfrak{su}(n)$$

Writing $\theta = \sum_{j,k} \theta_{jk} dg^{jk}$ where (g^{jk}) are the matrix entries on $\text{SU}(n)$. Then we have that

$$\pi^*\omega = i \sum_{k>j} (\lambda_j - \lambda_k) \theta_{kj} \wedge \overline{\theta_{kj}}$$

and the Hermitian metric h on \mathcal{O} is given by

$$\pi^*h = \sum_{k>j} 2(\lambda_j - \lambda_k) \theta_{kj} \overline{\theta_{kj}}$$

Using the fact that

$$T_g \mathrm{SU}(n) = g \mathfrak{su}(n)$$

and that

$$d\pi_g(h) = hAg^\dagger + gAh^\dagger$$

we get that

$$d\pi_g(h) = [B, hg^\dagger]$$

where $B = \pi(g) = gAg^\dagger$. With this, we can recover the hermitian metric, as

$$h_B([B, C], [B, D]) = \sum_{k>j} 2(\lambda_j - \lambda_k)(g^\dagger Cg)_{kj} \overline{(g^\dagger Dg)_{kj}}$$

With this, we can see that $\omega = -\mathrm{Im}(h)$, and that the real part $g = \mathrm{Re}(h)^2$ defines a Riemannian metric. Moreover, we can recover the almost complex structure from the symplectic form and the Riemannian metric, via

$$J = \tilde{g}^{-1} \circ \tilde{\omega}$$

where $\tilde{\omega}, \tilde{g} : T\mathrm{SU}(n) \rightarrow T^*\mathrm{SU}(n)$ are linear isomorphisms given by

$$\begin{aligned} \tilde{\omega}(u)(v) &= \omega(u, v) \\ \tilde{g}(u)(v) &= g(u, v) \end{aligned}$$

This follows as we have that $g(u, v) = \omega(u, Jv)$.

7 Root decomposition

As the expressions we have above for $\pi^*\omega$ and π^*h are left invariant, suffices to consider them at A , since we can then use left translation in $\mathrm{SU}(n)$ to get the expression at a different tangent space. This section should connect the results in the previous two sections.

Consider the Lie algebra $\mathfrak{sl}(n, \mathbb{C})$. Then we have the Cartan subalgebra \mathfrak{t} of diagonal matrices. Let E_{ij} be the standard basis matrices for $\mathrm{Mat}(n, \mathbb{C})$, $B \in \mathfrak{t}$. Say

$$B = \begin{pmatrix} b_1 & & \\ & \ddots & \\ & & b_n \end{pmatrix}$$

Then $[B, E_{ij}] = (b_i - b_j)E_{ij}$. This means that we have the eigendecomposition

$$\mathfrak{sl}(n, \mathbb{C}) = \mathfrak{t} \oplus \bigoplus_{1 \leq i, j \leq n, i \neq j} \mathbb{C}E_{ij} \quad (2)$$

In particular, if we restrict this to the subalgebra $\mathfrak{su}(n)$, we get the decomposition

$$\mathfrak{su}(n) = \tilde{\mathfrak{t}} \oplus \bigoplus_{1 \leq i < j \leq n} (\mathbb{R}(E_{ij} - E_{ji}) \oplus i\mathbb{R}(E_{ij} + E_{ji}))$$

where $\tilde{\mathfrak{t}} = \mathfrak{t} \cap \mathfrak{su}(n)$ is the subalgebra of $\mathfrak{su}(n)$ of diagonal matrices. In particular, we have that (assuming the eigenvalues of A are distinct)

$$T_A \mathcal{O} \cong T_{[1]} \left(\frac{\mathrm{SU}(n)}{T^{n-1}} \right) \cong \frac{\mathfrak{su}(n)}{\tilde{\mathfrak{t}}} = \bigoplus_{1 \leq i < j \leq n} (\mathbb{R}(E_{ij} - E_{ji}) \oplus i\mathbb{R}(E_{ij} + E_{ji}))$$

Then the almost complex structure is given by

²The usual notation for a Riemannian metric is g , but I've also used g as the element of $\mathrm{SU}(n)$. Hopefully it should be clear from context which one is which.

$$\begin{aligned}\mathbb{R}(E_{ij} - E_{ji}) &\mapsto i\mathbb{R}(E_{ij} + E_{ji}) \\ i\mathbb{R}(E_{ij} + E_{ji}) &\mapsto i\mathbb{R}(E_{ij} - E_{ji})\end{aligned}$$

is

1. The action of multiplication by i in eq. (2),
2. The complex structure linking our expressions for $\pi^*\omega$ and π^*h .

In particular, this means that the coadjoint orbits are Kähler.

8 Another proof

This section contains details which I have not checked. But assuming the claims are true, this should give another construction for the Kähler structure on coadjoint orbits of $SU(n)$.

The idea here is that we can make $T^*SU(n)$ into a Kähler manifold, and if we define an appropriate moment map, then we can use Kähler reduction (see appendix) to get a Kähler structure on coadjoint orbits.

First of all, any cotangent bundle T^*M has a symplectic form, called the *canonical symplectic form*

$$\omega = -d\alpha$$

where $\alpha_p = (d\pi_p)^*\xi \in T_p^*M$, $p = (x, \xi)$. In local cotangent coordinates,

$$\omega = \sum_i dx^i \wedge d\xi^i$$

See da Silva §2.3 for details.

In this case, $SU(n)$ is a Lie group, so we can left trivialise the cotangent bundle, via the map

$$\begin{aligned}T^*SU(n) &\rightarrow SU(n) \times \mathfrak{su}(n)^* \\ (g, \alpha) &\mapsto (g, ((d\ell_g)_e)^*\alpha)\end{aligned}$$

where $\ell_g(x) = gx$ is the left multiplication map on $SU(n)$. Using the isomorphism $\Phi : \mathfrak{su}(n) \rightarrow \mathfrak{su}(n)^*$ from above, we get an diffeomorphism

$$T^*SU(n) \cong SU(n) \times \mathfrak{su}(n)$$

Moreover, the polar decomposition

$$\begin{aligned}U(n) \times \mathfrak{u}(n) &\rightarrow GL(n, \mathbb{C}) \\ (U, X) &\mapsto U \exp(X)\end{aligned}$$

Gives a diffeomorphism $SU(n) \times \mathfrak{su}(n) \cong SL(n, \mathbb{C})$. Therefore, we also have a complex structure on $T^*SU(n)$.

Unchecked claim: This is compatible with the symplectic structure, making $T^*SU(n)$ into a Kähler manifold.

Assuming the claim, let $SU(n)$ act on $SU(n) \times \mathfrak{su}(n)^*$ by

$$g \cdot (h, \xi) = (h, \text{Ad}_g^*(\xi))$$

and define a map $\mu : SU(n) \times \mathfrak{su}(n)^*$ by $\mu(h, \xi) = \xi$. Then μ is equivariant, and

Unchecked claim: μ defines a moment map.

Assuming this claim, then for $\xi \in \mathfrak{su}(n)^*$, $\mu^{-1}(\xi)$ is a copy of $SU(n)$, and so if we perform Kähler reduction with momentum ξ , then we get a Kähler structure on the coadjoint orbit

$$\frac{SU(n)}{\text{Stab}(\xi)} \cong \text{Orb}(\xi)$$

A Kähler reduction

This section is copied from `kahler-reduction.tex`. It is included for completeness as the “proof” from §8 uses the Kähler reduction.

Throughout,

1. (M, ω, g, I) is a Kähler manifold,
2. G is a compact Lie group acting on M ,
3. (M, ω, G, μ) is a Hamiltonian G -space,
4. G acts by biholomorphisms on M ,
5. G acts freely on $\mu^{-1}(0)$.

In particular, as $\omega(u, v) = g(I(u), v)$, I is an isometry on M , G acts by isometries on M . Let $Z = \mu^{-1}(0)/G$. Let

$$\begin{array}{ccc} \mu^{-1}(0) & \xhookrightarrow{i} & M \\ \pi \downarrow & & \\ Z = \mu^{-1}(0)/G & & \end{array}$$

be the natural inclusion and quotient maps. In particular, note that π is a surjective submersion. Therefore, any tensor α of type $(0, r)$ on Z is determined by its pullback $\pi^*\alpha$.

The Marsden-Weinstein reduction theorem from symplectic geometry states that there exists a symplectic form $\tilde{\omega}$ on Z , such that

$$\pi^*\tilde{\omega} = i^*\omega$$

We will now construct the almost complex structure and Riemannian metric on Z .

Since π is a submersion, for $p \in \mu^{-1}(0)$, $z = \pi(p)$, we have

$$d\pi_p : T_p\mu^{-1}(0) \twoheadrightarrow T_zZ$$

Let $V_p = \ker(d\pi_p)$ be the vertical bundle, and $H_p = V_p^\perp \leq T_p\mu^{-1}(0)$ be the horizontal bundle. Therefore, we have an isomorphism

$$d\pi_p|_{H_p} : H_p \xrightarrow{\cong} T_zZ$$

For brevity, we write this isomorphism as

$$\begin{array}{ccc} d\pi_p|_{H_p} : H_p & \rightarrow & T_zZ \\ v & \mapsto & v_* \\ w^* & \mapsto & w \end{array}$$

With this, we can see that

$$\tilde{\omega}(u, v) = \omega(u^*, v^*)$$

and that

$$\tilde{g}(u, v) = g(u^*, v^*)$$

defines a Riemannian metric on Z . Therefore, the almost complex structure we want must be given by

$$\tilde{I}(u) = I(u^*)_*$$

Assuming this is well defined, then we have that

$$\begin{aligned}
\tilde{\omega}(u, v) &= \omega(u^*, v^*) \\
&= g(l(u^*), v^*) \\
&= g(\tilde{l}(u)^*, v^*) \\
&= \tilde{g}(\tilde{l}(u), v)
\end{aligned}$$

so $(\tilde{\omega}, \tilde{g}, \tilde{l})$ is a compatible triple.

Lemma. l restricts to a map $H_p \rightarrow H_p$.

Proof. Let $N_p = (T_p \mu^{-1}(0))^\perp \leq T_p M$ be the normal bundle of $\mu^{-1}(0) \subseteq M$. This gives us an orthogonal direct sum

$$T_p M = N_p \oplus V_p \oplus H_p$$

Fix $X \in \mathfrak{g}$. Then for $v \in T_p M$,

$$g(\text{grad}(\mu^X), v) = d\mu^X(v) = \omega(X^\#, v) = g(l(X^\#), v)$$

where $\text{grad}(f)$ is the g -dual of df . In particular, this means that $\text{grad}(\mu^X) = l(X^\#)$. Let X_1, \dots, X_k be a basis of \mathfrak{g} , with corresponding dual basis ξ^1, \dots, ξ^k . Then the moment map can be written as

$$\mu(p) = \mu^{X_1}(p)\xi^1 + \dots + \mu^{X_k}(p)\xi^k$$

But this means that

$$\{\text{grad}(\mu^{X_1}), \dots, \text{grad}(\mu^{X_k})\} = \{l(X_1^\#), \dots, l(X_k^\#)\}$$

is a basis of N_p . As $X_1^\#, \dots, X_k^\#$ is a basis for V_p , we have that l restricts to a map $N_p \oplus V_p \rightarrow N_p \oplus V_p$. By orthogonality, this means that l restricts to a map $H_p \rightarrow H_p$. \square

Therefore, the map \tilde{l} as above is well defined. Finally, we need to show that we have a Kähler structure. That is, l is integrable.

Lemma. Let M be a manifold, (ω, g, l) a compatible triple on M . Then (M, ω, g, l) is a Kähler manifold if and only if $\nabla l = 0$, where ∇ is the Levi-Civita connection induced by g .

Moreover, we have the expression

$$\nabla l(u) = \nabla(l(u)) - l(\nabla u)$$

and so $\nabla l = 0$ if and only if $\nabla(l(u)) = l(\nabla u)$ for all vector fields u .

Proof. See Huybrechts, §4.A. for the first part. For the second part, see Nicolaescu page 96. \square

Lemma. The Levi-Civita connection induced by \tilde{g} is

$$\tilde{\nabla}_X Y = \text{pr}_H(\nabla_{X^*} Y^*)_*$$

for vector fields X, Y on Z , and we extend X^*, Y^* arbitrarily to a neighbourhood of $\mu^{-1}(0) \subseteq M$. In addition, $\text{pr}_H : T_p M \rightarrow H_p$ is the orthogonal projection.

Proof. Omitted. \square

Finally, we note that since I respects the orthogonal decomposition

$$T_p M = (N_p \oplus V_p) \oplus H_p$$

pr_H and I commute. With this, we can now compute $\tilde{\nabla} \tilde{I}$.

$$\begin{aligned} \left(\tilde{\nabla}_X \tilde{I}(Y) \right)^* &= \text{pr}_H \left(\nabla_{X^*} \tilde{I}(Y)^* \right) \\ &= \text{pr}_H (\nabla_{X^*} I(Y^*)) \\ &= \text{pr}_H (I(\nabla_{X^*} Y^*)) \\ &= I(\text{pr}_H(\nabla_{X^*} Y^*)) \\ &= \tilde{I}(\tilde{\nabla}_X Y)^* \end{aligned}$$

Hence we have that

$$\tilde{\nabla}_X \tilde{I}(Y) = \tilde{I}(\tilde{\nabla}_X Y)$$

for any vector fields X, Y on Z , and so $\tilde{\nabla} \tilde{I} = 0$, and $(Z, \tilde{\omega}, \tilde{g}, \tilde{I})$ is a Kähler manifold.