

# Killing form

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## 1 Solvability

In this section, let  $\mathfrak{g}$  be a real Lie algebra.

### Definition 1.1 (ideal)

A subspace  $I \subseteq \mathfrak{g}$  is an *ideal* if  $[I, \mathfrak{g}] \subseteq I$ .

**Remark 1.2.** Every ideal is a Lie subalgebra of  $\mathfrak{g}$ .

### Definition 1.3 (simple)

$\mathfrak{g}$  is simple if  $\mathfrak{g} \neq 0$ , and the only ideals of  $\mathfrak{g}$  are 0 and  $\mathfrak{g}$ .

### Definition 1.4 (derived series, solvable)

The *derived series* of  $\mathfrak{g}$  is

$$\mathfrak{g}^{(0)} = \mathfrak{g} \quad \text{and} \quad \mathfrak{g}^{(i+1)} = [\mathfrak{g}^{(i)}, \mathfrak{g}^{(i)}]$$

Each  $\mathfrak{g}^{(i)}$  is an ideal of  $\mathfrak{g}$ . We say that  $\mathfrak{g}$  is *solvable* if  $\mathfrak{g}^{(n)} = 0$  for some  $n$ .

### Definition 1.5 (radical, semisimple)

$\mathfrak{g}$  has a unique maximal solvable ideal, called the *radical* of  $\mathfrak{g}$ , and denoted  $\text{rad}(\mathfrak{g})$ . We say that  $\mathfrak{g}$  is *semisimple* if  $\text{rad}(\mathfrak{g}) = 0$ .

**Lemma 1.6.** Suppose  $\mathfrak{g}$  is a complex Lie algebra,  $\text{tr}(\text{ad}_x \text{ad}_y) = 0$  for all  $x \in \mathfrak{g}, y \in [\mathfrak{g}, \mathfrak{g}]$ . Then  $\mathfrak{g}$  is solvable.

## 2 Killing form

In this section,  $\mathfrak{g}$  is a finite dimensional complex Lie algebra.

### Definition 2.1 (Killing form)

The *Killing form* of  $\mathfrak{g}$  is

$$\kappa(x, y) = \text{tr}(\text{ad}_x \text{ad}_y)$$

where  $\text{ad}_x(y) = [x, y]$ ,  $\text{ad} : \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g})$  is the adjoint representation of  $\mathfrak{g}$ .

**Lemma 2.2.**  $\kappa$  defines a symmetric bilinear form on  $\mathfrak{g}$ . Moreover,

$$\kappa([x, y], z) = \kappa(x, [y, z])$$

**Definition 2.3** (radical)

The radical of  $\kappa$  is the ideal

$$\text{rad}(\kappa) = \{x \in \mathfrak{g} \mid \kappa(x, y) = 0 \text{ for all } y \in \mathfrak{g}\}$$

**Theorem 2.4.** The following are equivalent:

- (i)  $\mathfrak{g}$  is semisimple,
- (ii)  $\kappa$  is non-degenerate, that is,  $\text{rad}(\kappa) = 0$ ,
- (iii) if  $x_1, \dots, x_n$  is a basis of  $\mathfrak{g}$ , then  $\det(\kappa(x_i, x_j)) \neq 0$ .

**Theorem 2.5.** Suppose  $\mathfrak{g}$  is semisimple. Then there exists ideals  $l_1, \dots, l_t$  of  $\mathfrak{g}$  which are simple (as Lie algebras), such that

$$\mathfrak{g} = l_1 \oplus \dots \oplus l_t$$

Moreover, each simple ideal of  $\mathfrak{g}$  is one of the  $l_j$ , and the Killing form of  $l_j$  is  $\kappa|_{l_j}$ .

## 2.1 Killing form over $\mathbb{R}$

Now suppose instead that  $\mathfrak{g}$  is a real Lie algebra.

**Definition 2.6** (abelian)

$\mathfrak{g}$  is abelian if  $[x, y] = 0$  for all  $x, y \in \mathfrak{g}$ .

**Lemma 2.7.**  $\mathfrak{g}$  is semisimple if and only if there are no non-zero abelian ideals of  $\mathfrak{g}$ .

**Lemma 2.8.** Any abelian ideal of  $\mathfrak{g}$  is contained in  $\text{rad}(\kappa)$ .

*Proof.* Let  $I \trianglelefteq \mathfrak{g}$  be an abelian ideal,  $x \in I$ ,  $y \in \mathfrak{g}$ . We want to show that  $\kappa(x, y) = 0$ . First, note that we have

$$\mathfrak{g} \xrightarrow{\text{ad}_y} \mathfrak{g} \xrightarrow{\text{ad}_x} I \xrightarrow{\text{ad}_y} I \xrightarrow{\text{ad}_x} 0$$

as  $I$  is an ideal, and  $I$  is abelian. Therefore, we have that  $(\text{ad}_x \text{ad}_y)^2 = 0$ . As any nilpotent endomorphism is tracefree, we must have that  $\kappa(x, y) = 0$ .  $\square$

**Theorem 2.9.**  $\mathfrak{g}$  is semisimple if and only if  $\kappa$  is non-degenerate.

*Proof.* Suppose  $\kappa$  is non-degenerate. Then we've shown any abelian ideal is contained in  $\text{rad}(\kappa) = 0$ , therefore we must have that  $\text{rad}(\mathfrak{g}) = 0$ , i.e.  $\mathfrak{g}$  is semisimple.

On the other hand, suppose  $\text{rad}(\kappa) \neq 0$ . Let  $\mathfrak{h}$  be any real Lie algebra.  $\mathfrak{h}_{\mathbb{C}} = \mathfrak{h} \otimes_{\mathbb{R}} \mathbb{C}$  be the complexification of  $\mathfrak{h}$ . We can make  $\mathfrak{h}_{\mathbb{C}}$  into a complex Lie algebra via

$$[v \otimes \lambda, w \otimes \mu] = [v, w] \otimes (\lambda\mu)$$

With this, we can see that  $\mathfrak{h}$  is abelian if and only if  $\mathfrak{h}_{\mathbb{C}}$  is abelian, and as  $[\mathfrak{h}_{\mathbb{C}}, \mathfrak{h}_{\mathbb{C}}] = [\mathfrak{h}, \mathfrak{h}]_{\mathbb{C}}$ ,  $\mathfrak{h}$  is solvable if and only if  $\mathfrak{h}_{\mathbb{C}}$  is solvable. Moreover, by the above definition of the Lie bracket, we can see that the Killing form of  $\mathfrak{g}_{\mathbb{C}}$  is the complexification of the Killing form of  $\mathfrak{g}$ , i.e.

$$\kappa_{\mathbb{C}}(v \otimes \lambda, w \otimes \mu) = \lambda\mu \cdot \kappa(v, w)$$

Therefore, we get that  $\text{rad}(\kappa_{\mathbb{C}}) = \text{rad}(\kappa)_{\mathbb{C}}$ . In particular, by lemma 1.6, we see that  $\text{rad}(\kappa)_{\mathbb{C}}$  is solvable, hence  $\text{rad}(\kappa)$  is solvable. Therefore,  $\mathfrak{g}$  is not semisimple.  $\square$

Moreover, we have a similar result to the complex case, in

**Theorem 2.10.** Suppose  $\mathfrak{g}$  is semisimple. Then there exists ideals  $l_1, \dots, l_t$  of  $\mathfrak{g}$  which are simple (as Lie algebras), such that

$$\mathfrak{g} = l_1 \oplus \dots \oplus l_t$$

Moreover, each simple ideal of  $\mathfrak{g}$  is one of the  $l_j$ , and the Killing form of  $l_j$  is  $\kappa|_{l_j}$ .

## 2.2 Diagonalisation

Recall Sylvester's law of inertia:

**Theorem 2.11** (Sylvester's law of inertia). Let  $A$  be a symmetric bilinear form on a finite dimensional real vector space  $V$ . Then there exists a basis of  $V$  such that

$$[A] = \begin{pmatrix} I_p & & \\ & -I_q & \\ & & 0 \end{pmatrix}$$

In the complex case, we can get

**Corollary 2.12.** Let  $A$  be a symmetric bilinear form on a finite dimensional complex vector space  $V$ . Then there exists a basis of  $V$  such that

$$[A] = \begin{pmatrix} I_{p+q} & \\ & 0 \end{pmatrix}$$

Note however a general symmetric bilinear form on a complex vector space will *not* be positive definite, since  $A(iv, iv) = -A(v, v)$ .