

# <u>ÔN HỒ ĐAN</u> DƯƠNG

- 🛗 January 1, 1997
- <u> Male</u>
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- 🤨 Danang, Vietnam

#### **SUMMARY**

I am passionate about programming and electronics. My ultimate goal is to become master in Embedded System developing and Robotics. I consider myself as a risk-taker since I always willing to explore something new, challenge myself and improving knowledge

#### **SKILLS**

Programming

Logical thinking and creative

English

French

#### INTERESTS

- Robotics
- Programming
- Electronics
- Reading books
- Playing guitar



#### DANANG UNIVERSITY OF SCIENCE AND TECHNOLOGY

Major: Industrial Informatics (Automation Engineering)



#### **VOLUNTEER IN MÙA HÈ XANH 2017**

12/7/2017 - 26/7/2017

**2015 - PRESENT** 

Member

- Participating in building houses for poor families
- Teaching for children in remote areas

#### **VOLUNTEER IN DEVDAY 2018**

18/4/2018 - 18/4/2018

Supporter

-Prepare for the presentation of the speakers

#### **ORANGE FAB ASIA PITCH COMPETITION**

4/3/2019 - 4/3 2019

Participant

-Call for investment and funding for my Smart Walking Can - a product that supports blind people

#### STEMCON INTERNATIONAL CONFERENCE

14/3/2019 - 15/3/2019

Participant

-Present my projects of Maze Solver Robot and Smart Walking Cane



### **HONORS & AWARDS**

-Potential Product in Smart Campus 2017 final contest (Emergency Callbox).	24/4/2018
-1st Prize in Robot Contest of Emaker Science Research Club	14/6/2018
-1st Prize in Maze Runner Robot Contest of Faculty of Advanced Science and Technology	1/11/2018
-3rd Prize in Maze Solver Robot Contest of Danang University of Technology and Education	16/11/2018
-1st Prize in Engineering Projects in Community Service 2018	18/1/2019



## **PROJECTS**

#### +Garden Automation System

-An aquaponics system that automatically watering plants and can be monitored and controlled via Internet

#### +Solar Tracker

-A solar battery system automatically tracks the sun to optimize received energy

#### +Maze Solver Robot

-Known as Micromouse, with an ability to follow the shortest path to expected destination in a maze

#### +Auto Leveling Quadcopter

-A drone that can automatically return to balance position without human control

#### +Smart Walking Cane

-Create to help blind people avoid obstacle and warning the relatives if user has an accident