```
1
     #define GRID SIZE 256
     #define BLOCK SIZE 128
 2
 3
4
      global
5
     void gpu dotproduct stage1 (const double *gpu x, const double *gpu y, size t size,
     double *gpu result stage1) {
6
         size_t thread_id_global = blockIdx.x*blockDim.x + threadIdx.x;
 7
8
         shared double shared m[BLOCK SIZE];
9
10
         // I think, this is the right way:
         double thread_dp = 0;
11
12
         for (unsigned int i = thread id global; i<size; i += blockDim.x * gridDim.x)</pre>
13
             thread_dp += gpu_x[i] * gpu_y[i];
14
         shared m[threadIdx.x] = thread dp;
15
16
17
         // now the reduction
18
         for(int stride = blockDim.x/2; stride>0; stride/=2){
19
               syncthreads();
20
             if (threadIdx.x < stride){</pre>
21
                 shared m[threadIdx.x] += shared m[threadIdx.x + stride];
22
23
         }
24
25
         // thread 0 writes result
2.6
         if (threadIdx.x == 0) {
27
             gpu result stage1[blockIdx.x] = shared m[0];
28
         }
29
     }
30
       global
31
     void gpu dotproduct stage2(double *gpu result stage1, double *gpu result stage2){
32
33
34
         // only one block has a job here
35
         if (blockIdx.x == 0) {
36
             //size_t thread_id_global = blockIdx.x*blockDim.x + threadIdx.x;
37
             shared double shared m[BLOCK SIZE];
38
             \ensuremath{//} this time, the lecture is correct
39
40
             double thread_sum = 0;
41
             for (unsigned int i = threadIdx.x; i<GRID SIZE; i += blockDim.x)</pre>
42
                 thread_sum += gpu_result_stage1[i];
             shared_m[threadIdx.x] = thread_sum;
43
44
45
             // now the reduction
46
             for(int stride = blockDim.x/2; stride>0; stride/=2){
47
                   syncthreads();
48
                 if (threadIdx.x < stride) {</pre>
49
                      shared_m[threadIdx.x] += shared_m[threadIdx.x + stride];
50
51
             }
             // thread 0 writes result
52
             if (threadIdx.x == 0){
53
54
                 //printf("hi, im thread 0 and im now writing %1.5e\n", shared m[0]);
55
                 *gpu result stage2 = shared m[0];
56
             }
57
         }
58
     }
59
60
61
       global
62
     void gpu dotproduct atomicAdd(const double *gpu x, const double *gpu y, size t size,
     double *gpu result){
63
64
         size t thread id global = blockIdx.x*blockDim.x + threadIdx.x;
65
         if (thread id global == 0)
66
             *gpu result = 0;
67
68
          __shared__ double shared_m[BLOCK SIZE];
70
         // I think, this is the right way:
         double thread dp = 0;
```

```
72
         for (unsigned int i = thread id global; i<size; i += blockDim.x * gridDim.x)</pre>
73
              thread dp += gpu x[i] * gpu y[i];
74
         shared m[threadIdx.x] = thread dp;
75
76
77
         // now the reduction
         for(int stride = blockDim.x/2; stride>0; stride/=2){
78
79
                _syncthreads();
              if (threadIdx.x < stride) {</pre>
80
81
                  shared_m[threadIdx.x] += shared_m[threadIdx.x + stride];
82
              }
83
         }
84
         \frac{}{//} syncthreads(); \frac{}{//} thread 0 writes result
85
86
87
         if (threadIdx.x == 0){
88
              atomicAdd(gpu_result, shared_m[0]);
89
              //gpu result stage1[blockIdx.x] = shared m[0];
90
         }
91
     }
92
```