Pixel estimates (EKF) point\_1 point\_2 point\_3 point\_4 — ekf\_x — ekf\_x
— true\_x — ekf\_x --- ekf\_x 0.2 0.2 ---- true\_x --- true\_x --- true\_x 0.4 -0.4 0.1 0.1 0.3 -0.3 0.0 0.0 -0.2 -0.2 -0.1-0.10.1 -0.1 -0.2 -0.20.0 -0.0 -0.3 -**-**0.3 -0.1 -0.1-0.4-0.4-0.2 --0.280 100 20 60 80 100 80 100 20 100 20 60 40 20 60 60 80 point\_3 point\_1 point\_2 point\_4 --- ekf\_y ekf\_y
true\_y — ekf\_y --- ekf\_y 0.35 -0.10 -0.10 -— true\_y — true\_y — true\_y 0.30 -0.30 -0.05 0.05 0.25 -0.25 -0.00 0.00 0.20 -0.20 --0.05-0.050.15 0.15 -0.10-0.10 0.10 -0.10 -0.15-0.150.05 0.05 -0.20 -0.20

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