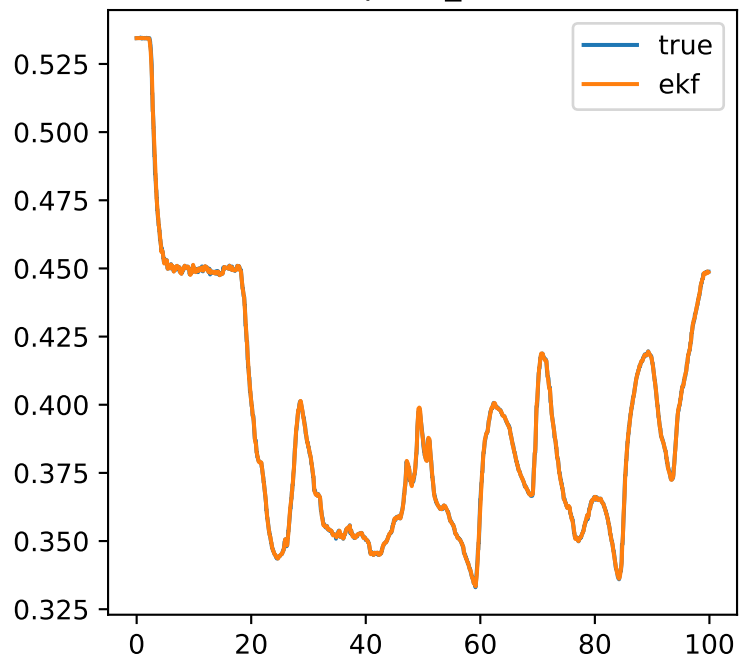
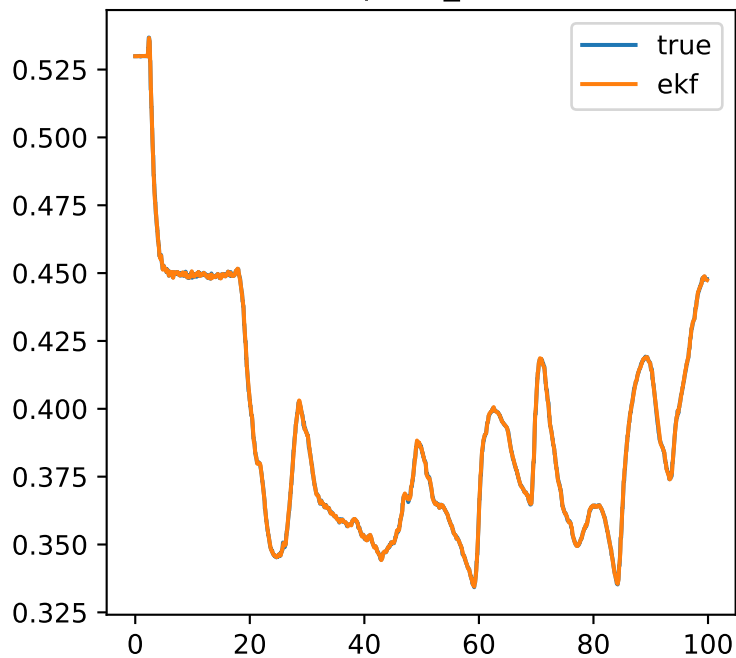


Depth estimates (EKF)

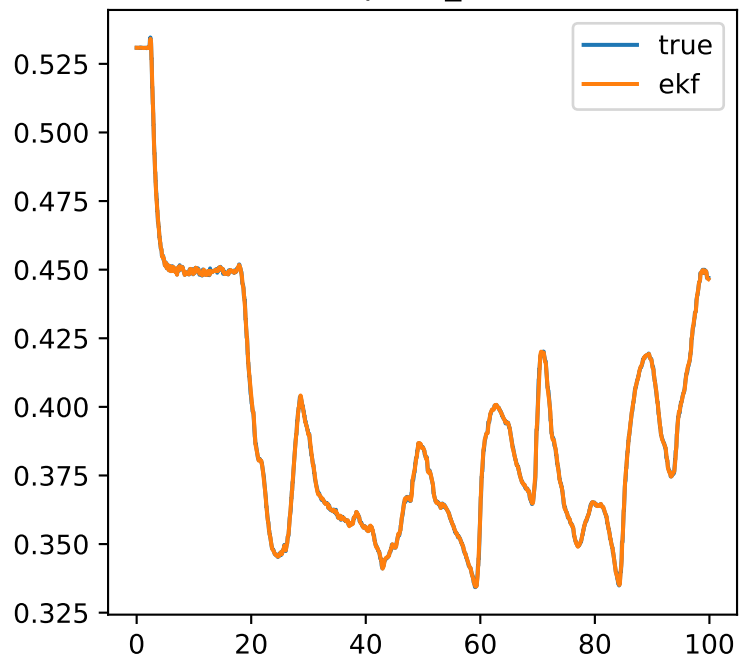
point_1



point_2



point_3



point_4

