Machine Learning, Decision Trees, Overfitting

Recommended reading: Mitchell, Chapter 3

Machine Learning 10-701

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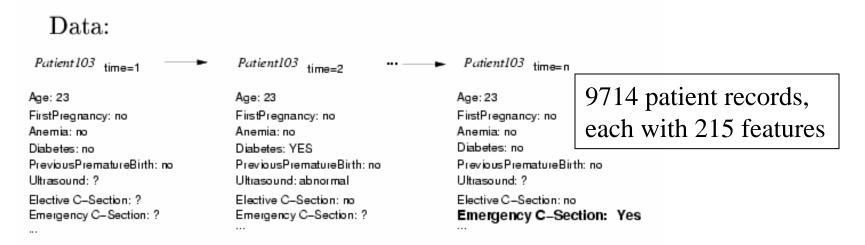
Machine Learning:

Study of algorithms that

- improve their <u>performance</u>
- at some task
- with <u>experience</u>

Learning to Predict Emergency C-Sections

[Sims et al., 2000]



One of 18 learned rules:

If No previous vaginal delivery, and
Abnormal 2nd Trimester Ultrasound, and
Malpresentation at admission
Then Probability of Emergency C-Section is 0.6

Over training data: 26/41 = .63,

Over test data: 12/20 = .60

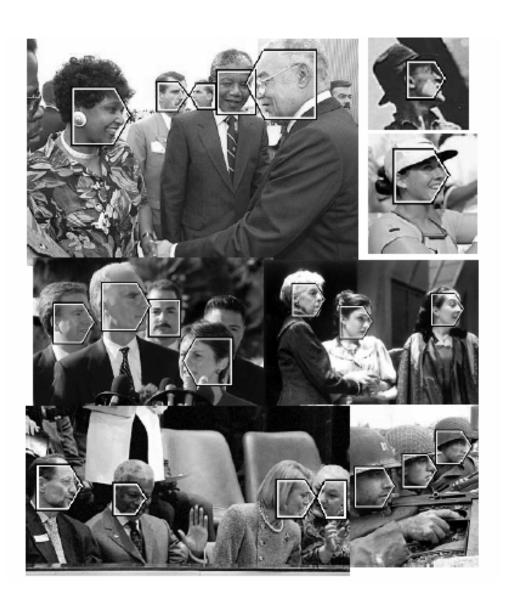
Object Detection

(Prof. H. Schneiderman)

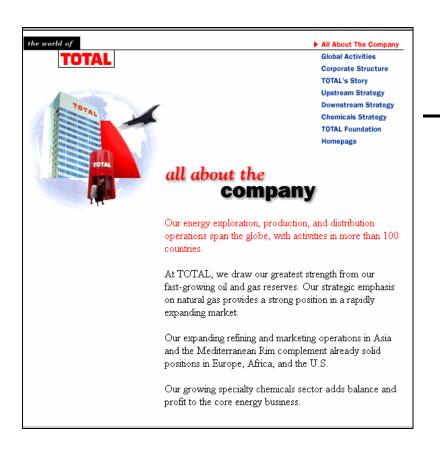




Example training images for each orientation



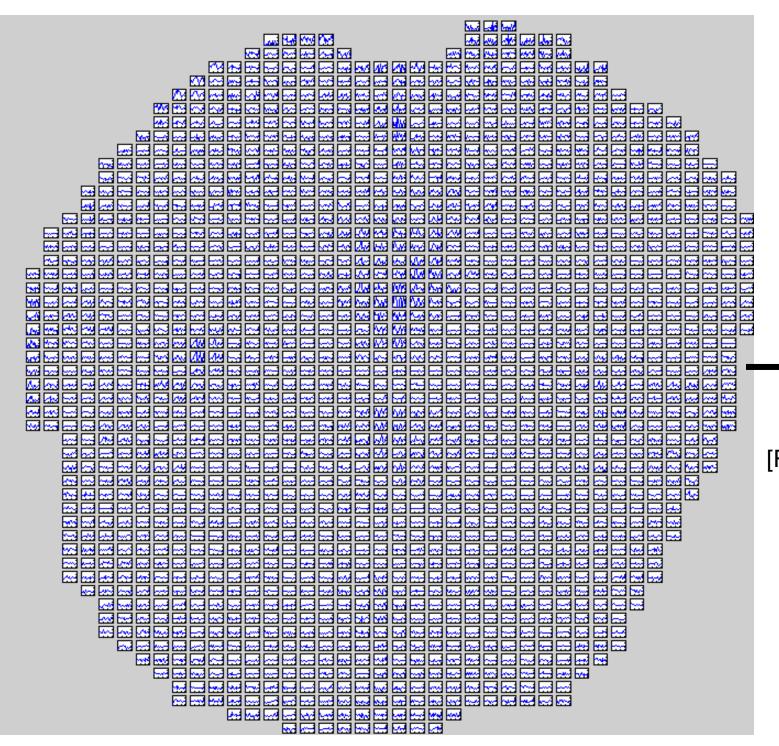
Text Classification



Company home page
vs
Personal home page
vs
Univeristy home page

. . .

VS



Reading a noun (vs verb)

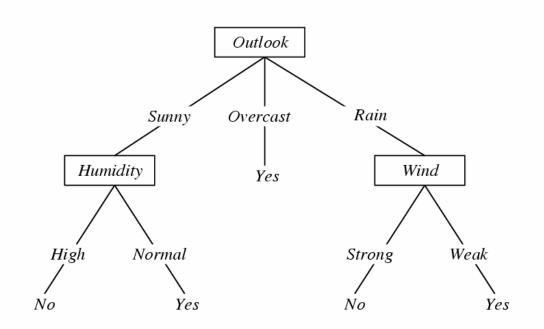
[Rustandi et al., 2005]

Growth of Machine Learning

- Machine learning is preferred approach to
 - Speech recognition, Natural language processing
 - Computer vision
 - Medical outcomes analysis
 - Robot control
 - **–** ...
- This trend is accelerating
 - Improved machine learning algorithms
 - Improved data capture, networking, faster computers
 - Software too complex to write by hand
 - New sensors / IO devices
 - Demand for self-customization to user, environment

Decision tree learning

Decision Tree for PlayTennis



How would you represent

AB V CD (¬E)?

Each internal node: test one attribute X_i

Each branch from a node: selects one value for X_i

Each leaf node: predict Y (or $P(Y|X \in leaf)$)

A Tree to Predict C-Section Risk

Learned from medical records of 1000 women Negative examples are C-sections

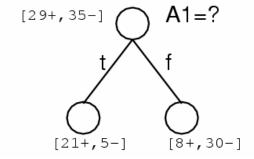
```
[833+,167-] .83+ .17-
Fetal_Presentation = 1: [822+,116-] .88+ .12-
| Previous_Csection = 0: [767+,81-] .90+ .10-
| | Primiparous = 0: [399+,13-] .97+ .03-
| | Primiparous = 1: [368+,68-] .84+ .16-
| \ | \ | Fetal_Distress = 0: [334+,47-] .88+ .12-
| | | Birth_Weight < 3349: [201+,10.6-] .95+ .
| \ | \ | \ | Birth_Weight >= 3349: [133+,36.4-] .78+
| \ | \ | Fetal_Distress = 1: [34+,21-] .62+ .38-
| Previous_Csection = 1: [55+,35-] .61+ .39-
Fetal_Presentation = 2: [3+,29-] .11+ .89-
Fetal_Presentation = 3: [8+,22-] .27+ .73-
```

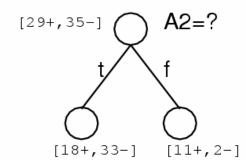
node = Root

Main loop:

- 1. $A \leftarrow$ the "best" decision attribute for next node
- 2. Assign A as decision attribute for node
- 3. For each value of A, create new descendant of node
- 4. Sort training examples to leaf nodes
- 5. If training examples perfectly classified, Then STOP, Else iterate over new leaf nodes

Which attribute is best?





Entropy

Entropy H(X) of a random variable X

$$H(X) = -\sum_{i=1}^{n} P(X = i) \log_2 P(X = i)$$

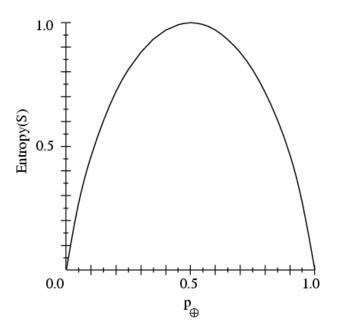
H(X) is the expected number of bits needed to encode a randomly drawn value of X (under most efficient code)

Why? Information theory:

- Most efficient code assigns -log₂P(X=i) bits to encode the message X=i
- So, expected number of bits is:

$$\sum_{i=1}^{n} P(X = i)(-\log_2 P(X = i))$$

Sample Entropy



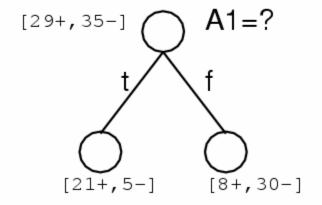
- \bullet S is a sample of training examples
- p_{\oplus} is the proportion of positive examples in S
- p_{\ominus} is the proportion of negative examples in S
- \bullet Entropy measures the impurity of S

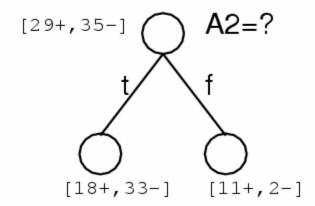
$$Entropy(S) \equiv -p_{\oplus} \log_2 p_{\oplus} - p_{\ominus} \log_2 p_{\ominus}$$

Information Gain

Gain(S, A) = expected reduction in entropy due to sorting on A

$$Gain(S, A) \equiv Entropy(S) - \sum_{v \in Values(A)} \frac{|S_v|}{|S|} Entropy(S_v)$$



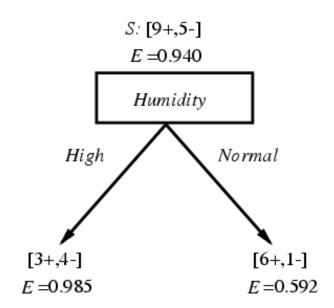


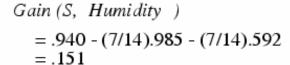
Training Examples

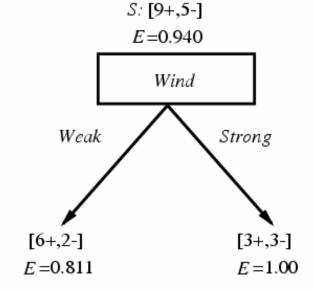
Day	Outlook	Temperature	Humidity	Wind	PlayTenr
D1	Sunny	Hot	High	Weak	No
D2	Sunny	Hot	High	Strong	No
D3	Overcast	Hot	High	Weak	Yes
D4	Rain	Mild	High	Weak	Yes
D5	Rain	Cool	Normal	Weak	Yes
D6	Rain	Cool	Normal	Strong	No
D7	Overcast	Cool	Normal	Strong	Yes
D8	Sunny	Mild	High	Weak	No
D9	Sunny	Cool	Normal	Weak	Yes
D10	Rain	Mild	Normal	Weak	Yes
D11	Sunny	Mild	Normal	Strong	Yes
D12	Overcast	Mild	High	Strong	Yes
D13	Overcast	Hot	Normal	Weak	Yes
D14	Rain	Mild	High	Strong	No

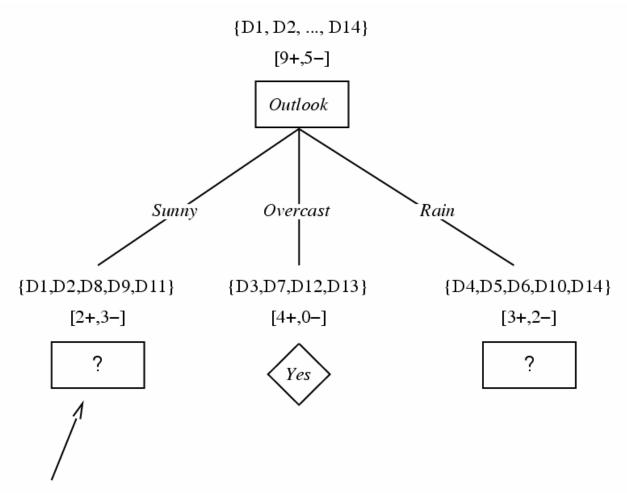
Selecting the Next Attribute

Which attribute is the best classifier?









Which attribute should be tested here?

$$S_{sunny} = \{D1,D2,D8,D9,D11\}$$

$$Gain (S_{sunny}, Humidity) = .970 - (3/5) 0.0 - (2/5) 0.0 = .970$$

$$Gain (S_{sunny}, Temperature) = .970 - (2/5) 0.0 - (2/5) 1.0 - (1/5) 0.0 = .570$$

$$Gain (S_{sunny}, Wind) = .970 - (2/5) 1.0 - (3/5) .918 = .019$$

Occam's Razor

Why prefer short hypotheses?

Argument in favor:

- Fewer short hyps. than long hyps.
- → a short hyp that fits data unlikely to be coincidence
- \rightarrow a long hyp that fits data might be coincidence

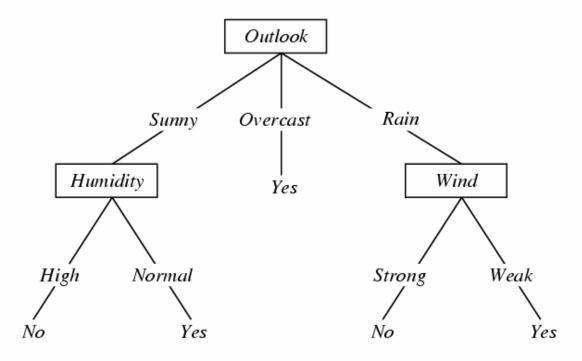
Argument opposed:

- There are many ways to define small sets of hyps
- e.g., all trees with a prime number of nodes that use attributes beginning with "Z"
- What's so special about small sets based on *size* of hypothesis??

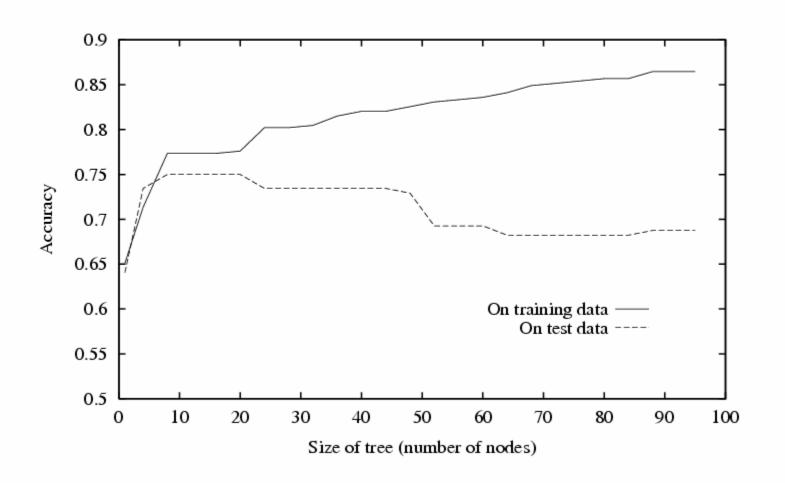
Overfitting in Decision Trees

Consider adding noisy training example #15:

Sunny, Hot, Normal, Strong, PlayTennis = NoWhat effect on earlier tree?



Overfitting in Decision Tree Learning



Avoiding Overfitting

How can we avoid overfitting?

- stop growing when data split not statistically significant
- grow full tree, then post-prune

How to select "best" tree:

- Measure performance over training data
- Measure performance over separate validation data set
- MDL: minimize size(tree) + size(misclassifications(tree))

Minimum Description Length Principle

Occam's razor: prefer the shortest hypothesis

MDL: prefer the hypothesis h that minimizes

$$h_{MDL} = \operatorname*{argmin}_{h \in H} L_{C_1}(h) + L_{C_2}(D|h)$$

where $L_C(x)$ is the description length of x under encoding C

Example: H =decision trees, D =training data labels

- $L_{C_1}(h)$ is # bits to describe tree h
- $L_{C_2}(D|h)$ is # bits to describe D given h
 - Note $L_{C_2}(D|h) = 0$ if examples classified perfectly by h. Need only describe exceptions
- Hence h_{MDL} trades off tree size for training errors

Assume X values known, labels Y encoded

Minimum Description Length Principle

$$h_{MAP} = \arg \max_{h \in H} P(D|h)P(h)$$

$$= \arg \max_{h \in H} \log_2 P(D|h) + \log_2 P(h)$$

$$= \arg \min_{h \in H} - \log_2 P(D|h) - \log_2 P(h) \quad (1)$$

Interesting fact from information theory:

The optimal (shortest expected coding length) code for an event with probability p is $-\log_2 p$ bits.

So interpret (1):

- $-\log_2 P(h)$ is length of h under optimal code
- $-\log_2 P(D|h)$ is length of D given h under optimal code
- \rightarrow prefer the hypothesis that minimizes length(h) + length(misclassifications)

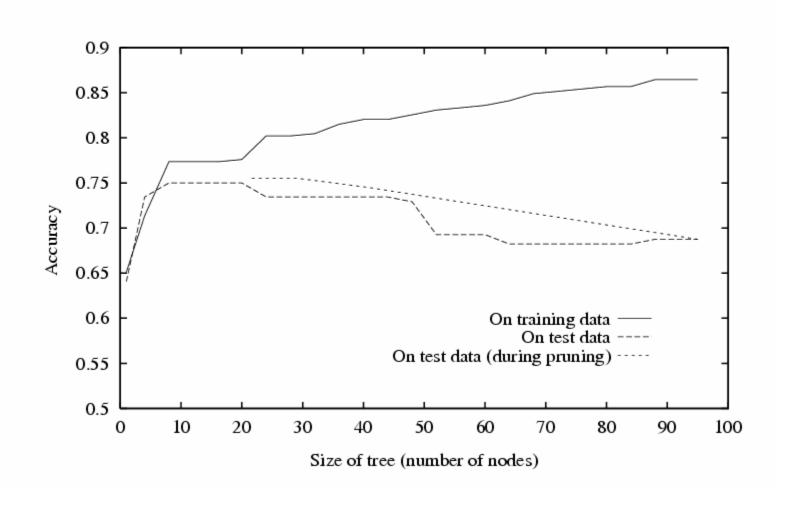
Reduced-Error Pruning

Split data into training and validation set

Do until further pruning is harmful:

- 1. Evaluate impact on *validation* set of pruning each possible node (plus those below it)
- 2. Greedily remove the one that most improves validation set accuracy
- produces smallest version of most accurate subtree
- What if data is limited?

Effect of Reduced-Error Pruning

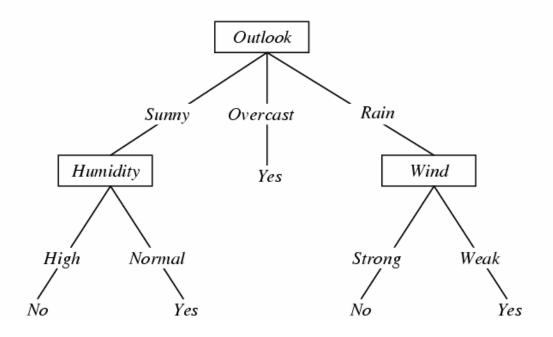


Rule Post-Pruning

- 1. Convert tree to equivalent set of rules
- 2. Prune each rule independently of others
- 3. Sort final rules into desired sequence for use

Perhaps most frequently used method (e.g., C4.5)

Converting A Tree to Rules



$$\begin{array}{ll} \text{IF} & (Outlook = Sunny) \land (Humidity = High) \\ \text{THEN} & PlayTennis = No \\ \end{array}$$

$$\begin{array}{ll} \text{IF} & (Outlook = Sunny) \land (Humidity = Normal) \\ \text{THEN} & PlayTennis = Yes \end{array}$$

Continuous Valued Attributes

Create a discrete attribute to test continuous

- \bullet Temperature = 82.5
- (Temperature > 72.3) = t, f

Temperature: 40 48 60 72 80 90

PlayTennis: No No Yes Yes Yes No

Attributes with Many Values

Problem:

- If attribute has many values, Gain will select it
- Imagine using $Date = Jun_3_1996$ as attribute

One approach: use GainRatio instead

$$GainRatio(S, A) \equiv \frac{Gain(S, A)}{SplitInformation(S, A)}$$

$$SplitInformation(S, A) \equiv -\sum_{i=1}^{c} \frac{|S_i|}{|S|} \log_2 \frac{|S_i|}{|S|}$$

where S_i is subset of S for which A has value v_i

Unknown Attribute Values

What if some examples missing values of A? Use training example anyway, sort through tree

- If node n tests A, assign most common value of A among other examples sorted to node n
- assign most common value of A among other examples with same target value
- assign probability p_i to each possible value v_i of A
 - assign fraction p_i of example to each descendant in tree

Classify new examples in same fashion

What you should know:

- Well posed function approximation problems:
 - Instance space, X
 - Sample of labeled training data, D = $\{ \langle x_i, y_i \rangle \}$
 - Hypothesis space, H = { f: X→Y }
- Learning is a search/optimization problem over H
 - Various objective functions
 - Today: minimize training error (0-1 loss)
- Decision tree learning
 - Greedy top-down learning of decision trees (ID3, C4.5, ...)
 - Overfitting and tree/rule post-pruning
 - Extensions...