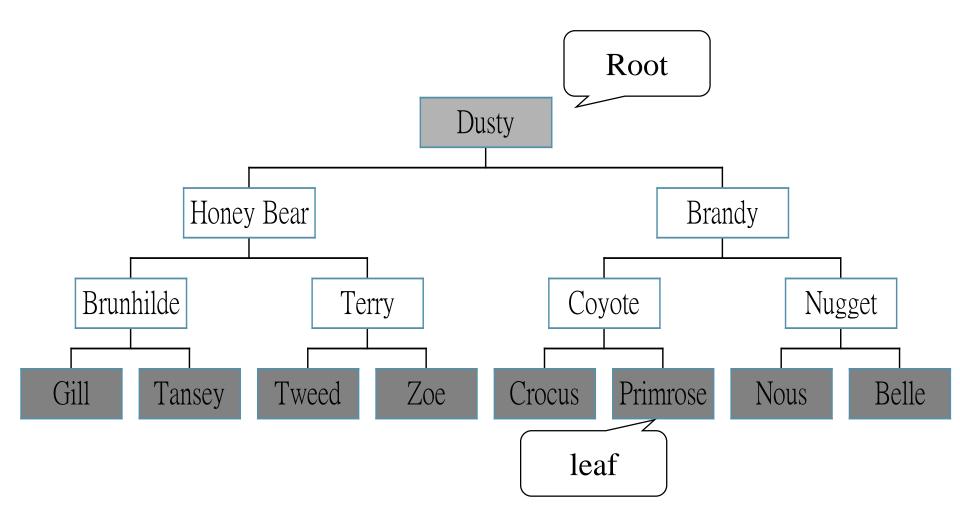
CHAPTER 5

Trees

All the programs in this file are selected from

Ellis Horowitz, Sartaj Sahni, and Susan Anderson-Freed "Fundamentals of Data Structures in C",

Trees



CHAPTER 5 2

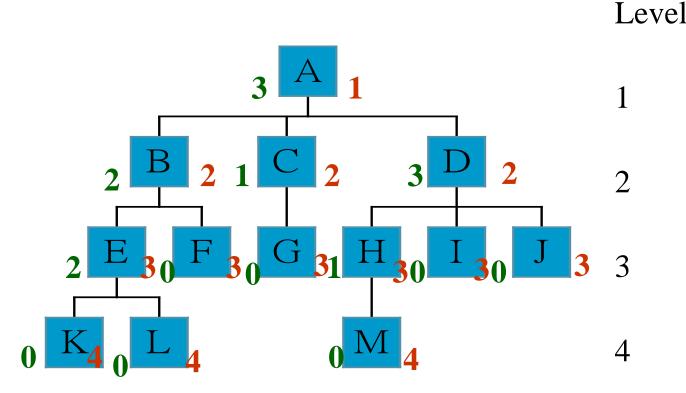
Definition of Tree

- ☐ A tree is a finite set of one or more nodes such that:
 - There is a specially designated node called the root.
 - The remaining nodes are partitioned into n>=0 disjoint sets $T_1, ..., T_n$, where each of these sets is a tree.
 - We call T_1 , ..., T_n the subtrees of the root.

CHAPTER 5

Level and Depth

- 1. node (13)
- 2. leaf (terminal)
- 3. nonterminal
- 4. parent
- 5. children
- 6. sibling
- 7. degree of a tree (3)
- 8. ancestor
- 9. level of a node
- 10. height of a tree (4)



CHAPTER 5 4

Terminology

- ☐ The *degree* of a node is the number of subtrees of the node
 - The degree of A is 3; the degree of C is 1.
- ☐ The node with degree 0 is a leaf or terminal node.
- ☐ A node that has subtrees is the *parent* of the subtrees.
- ☐ These subtrees are the *children* of the node.
- ☐ Children of the same parent are *siblings*.
- ☐ The *ancestors* of a node are all the nodes along the path from the root to the node.

Representation of Trees

☐ List Representation

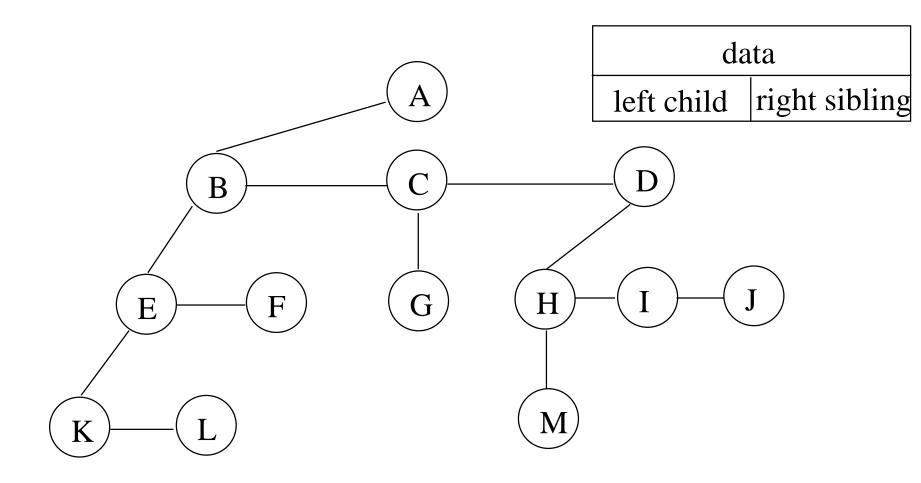
- (A(B(E(K,L),F),C(G),D(H(M),I,J)))
- The root comes first, followed by a list of sub-trees

data link 1 link 2 ... link n

How many link fields are needed in such a representation?

CHAPTER 5 6

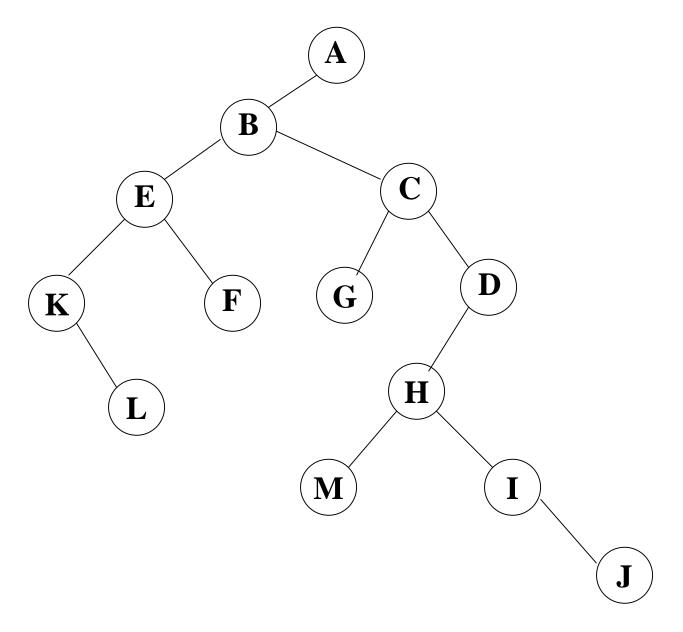
Left Child - Right Sibling



CHAPTER 5

Binary Trees

- A binary tree is a finite set of nodes that is either empty or consists of a root and two disjoint binary trees called *the left subtree* and *the right subtree*.
- ☐ Any tree can be transformed into binary tree.
 - by left child-right sibling representation
- ☐ The left subtree and the right subtree are distinguished.



*Figure 5.2 Left child-right child tree representation of a tree

Abstract Data Type Binary_Tree

- ☐ structure Binary_Tree (abbreviated BinTree)
- objects: a finite set of nodes either empty or consisting of a root node, left Binary_Tree, and right Binary_Tree.
- ☐ functions:
 - for all bt, bt1, $bt2 \in BinTree$, $item \in element$
- ☐ Bintree Create()::= creates an empty binary tree
- □ Boolean IsEmpty(bt)::= if (bt==empty binary tree) return TRUE else return FALSE

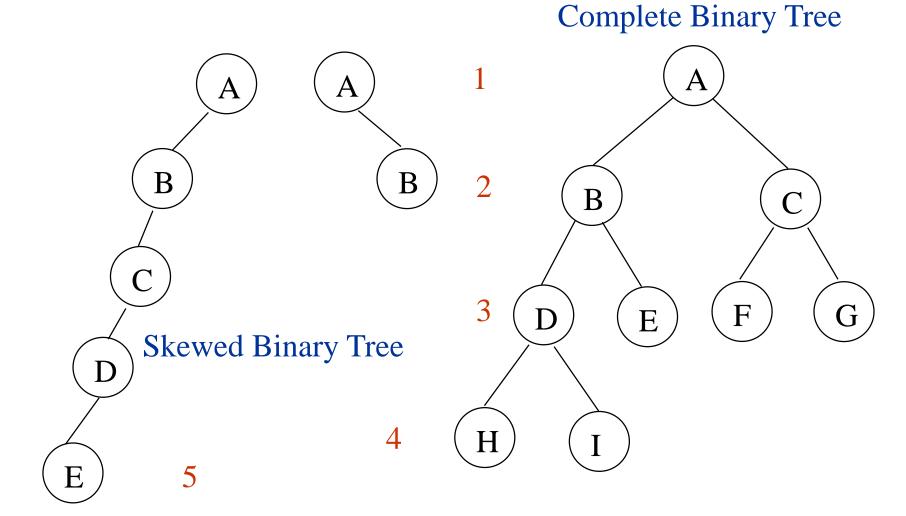
CHAPTER 5 10

Abstract Data Type Binary_Tree

$BinTree \; MakeBT(bt1, item, bt2) ::= return a binary$
tree whose left subtree is bt1, whose right subtree is
bt2, and whose root node contains the data item
$Bintree \ Lchild(bt) := if (IsEmpty(bt)) return error$
else return the left subtree of bt
element Data(bt)::= if (IsEmpty(bt)) return error
else return the data in the root node of bt
$Bintree \ Rchild(bt) ::= if (IsEmpty(bt)) return error$
else return the right subtree of bt

CHAPTER 5 11

Samples of Trees



Maximum Number of Nodes in BT

- ☐ The maximum number of nodes on level i of a binary tree is 2^{i-1} , $i \ge 1$.
- The maximum nubmer of nodes in a binary tree of depth k is 2^k-1 , k>=1.

Prove by induction.

$$\sum_{i=1}^{k} 2^{i-1} = 2^k - 1$$
pp. 200

Relations between Number of Leaf Nodes and Nodes of Degree 2

□ For any nonempty binary tree, T, if n0 is the number of leaf nodes and n2 the number of nodes of degree 2, then n0=n2+1

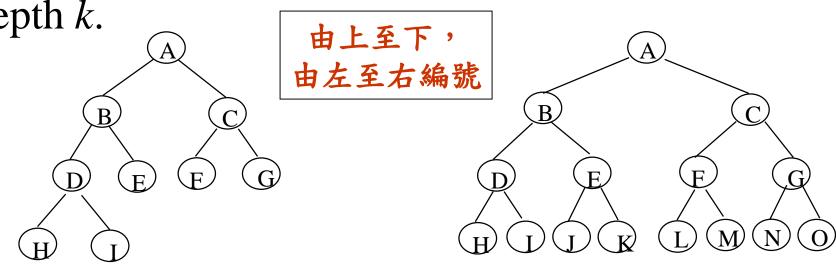
proof:

- \square Let n and B denote the total number of nodes & branches in T.
- \square Let n0, n1, n2 represent the nodes with no children, single child, and two children respectively.

$$n=n0+n1+n2$$
, $n=B+1$, $n=B+1=n1+2n2+1$, $n+2n+1=n0+n1+n2=> n0=n2+1$

Full BT VS Complete BT

- \square A <u>full binary tree</u> of depth k is a binary tree of depth k having 2^k -1 nodes, k>=0.
- A binary tree with n nodes and depth k is complete *iff* its nodes correspond to the nodes numbered from 1 to n in the full binary tree of depth k.

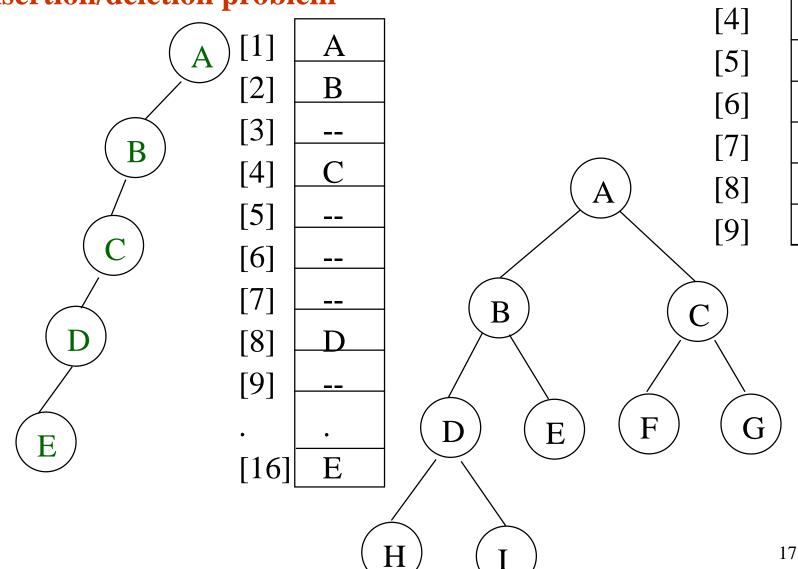


Binary Tree Representations

- If a complete binary tree with n nodes (depth = $\log n + 1$) is represented sequentially, then for any node with index i, 1 <= i <= n, we have:
 - parent(i) is at i/2 if i!=1. If i=1, i is at the root and has no parent.
 - $left_child(i)$ ia at 2i if 2i <= n. If 2i > n, then i has no left child.
 - $right_child(i)$ ia at 2i+1 if 2i+1 <= n. If 2i+1 > n, then i has no right child.

Sequential Representation

- (1) waste space
- (2) insertion/deletion problem



[1]

[2]

[3]

B

E

Linked Representation

```
typedef struct node *tree_pointer;
typedef struct node {
 int data;
 tree_pointer left_child, right_child;
                                    data
                  right_child
     left_child
             data
```

CHAPTER 5

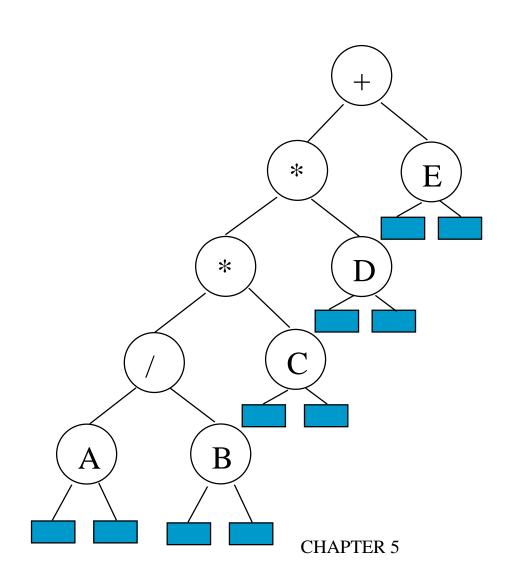
left child

right_child

Binary Tree Traversals

- ☐ Let L, V, and R stand for moving left, visiting the node, and moving right.
- ☐ There are six possible combinations of traversal
 - LVR, LRV, VLR, VRL, RVL, RLV
- ☐ Adopt convention that we traverse left before right, only 3 traversals remain
 - LVR, LRV, VLR
 - inorder, postorder, preorder

Arithmetic Expression Using BT



inorder traversal A/B*C*D+E infix expression

preorder traversal
+ * * / A B C D E
prefix expression

postorder traversal AB/C*D*E+ postfix expression

level order traversal + * E * D / C A B

Inorder Traversal (recursive version)

```
void inorder(tree_pointer ptr)
/* inorder tree traversal */
                          A/B * C * D + E
    if (ptr) {
        inorder(ptr->left_child);
        printf("%d", ptr->data);
        inorder(ptr->right_child);
                                    21
```

Preorder Traversal (recursive version)

```
void preorder(tree_pointer ptr)
/* preorder tree traversal */
                          + * * / A B C D E
    if (ptr) {
        printf("%d", ptr->data);
        preorder(ptr->left_child);
        preorder(ptr->right_child);
```

Postorder Traversal (recursive version)

```
void postorder(tree_pointer ptr)
/* postorder tree traversal */
                        AB/C*D*E+
    if (ptr) {
        postorder(ptr->left_child);
        postorder(ptr->right child);
        printf("%d", ptr->data);
                                  23
```

Iterative Inorder Traversal

(using stack)

```
void iterInorder(tree pointer node)
  int top= -1; /* initialize stack */
  tree pointer stack[MAX STACK SIZE];
  for (;;) {
   for (; node; node=node->left_child)
     push(&top, node);/* add to stack */
   node= pop(&top);
                /* delete from stack */
   if (!node) break; /* empty stack */
   printf("%D", node->data);
   node = node->right_child;
```

Trace Operations of Inorder Traversal

Call of inorder	Value in root	Action	Call of inorder	Value in root	Action
1	+		11	С	
2	*		12	NULL	
3	*		11	C	printf
4	/		13	NULL	
5	A		2	*	printf
6	NULL		14	D	
5	A	printf	15	NULL	
7	NULL		14	D	printf
4	/	printf	16	NULL	
8	В		1	+	printf
9	NULL		17	E	
8	В	printf	18	NULL	
10	NULL		17	E	printf
3	*	printf	19	NULL	



Level Order Traversal

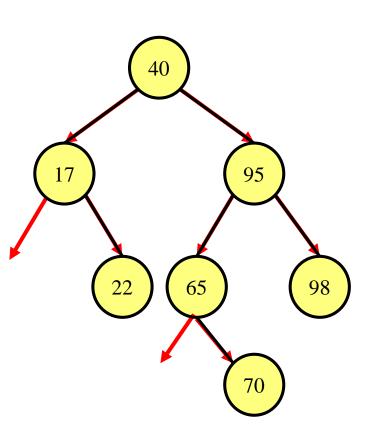
(using queue)

```
void levelOrder(tree_pointer ptr)
/* level order tree traversal */
  int front = rear = 0;
  tree_pointer queue[MAX_QUEUE_SIZE];
  if (!ptr) return; /* empty queue */
  addq(ptr);
  for (;;) {
    ptr = delete();
```

```
if (ptr) {
  printf("%d", ptr->data);
  if (ptr->left child)
    addq(ptr->left_child);
  if (ptr->right_child)
    addq(ptr->right child);
else break;
```

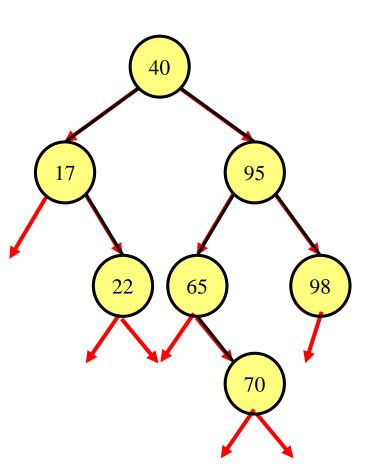
+*E*D/CAB

□前序走訪(preorder):



```
void preOrder( TreeNodePtr treePtr ){
    // if tree is not empty, then traverse
    if ( treePtr != NULL ) {
        printf( "%3d", treePtr->data );
        preOrder( treePtr->leftPtr );
        preOrder( treePtr->rightPtr );
    }
}
```

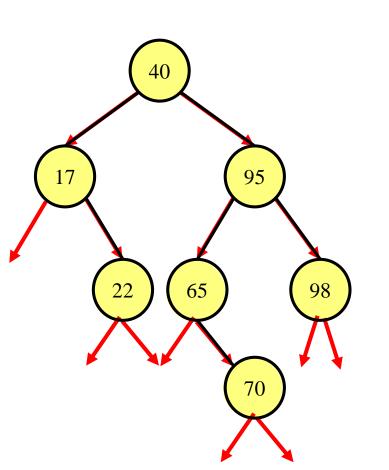
□中序走訪(inorder):





```
void inOrder( TreeNodePtr treePtr ){
    // if tree is not empty, then traverse
    if ( treePtr != NULL ) {
        inOrder( treePtr->leftPtr );
        printf( "%3d", treePtr->data );
        inOrder( treePtr->rightPtr );
    }
}
```

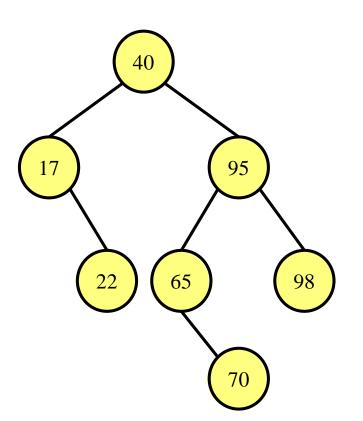
□後序走訪(postorder):





```
void postOrder( TreeNodePtr treePtr ){
    // if tree is not empty, then traverse
    if ( treePtr != NULL ) {
        postOrder( treePtr->leftPtr );
        postOrder( treePtr->rightPtr );
        printf( "%3d", treePtr->data );
    }
}
```

□階層走訪(level-order)(40)(17)(95)(22)(65)(98)(70)



```
    40
    17
    95
    22
    65
    98
    70
```

```
void levelOrder(TreeNodePtr treePtr){
   if(!treePtr) return;
   addq(treePtr);
   for(;;){
      treePtr = deleteq();
      if(treePtr){
         printf("%3d", treePtr->data);
         if(treePtr->leftPtr)
            addq(treePtr->leftPtr);
         if(treePtr->rightPtr)
            addq(treePtr->rightPtr);
      else
         break;
```

Copying Binary Trees

```
tree_pointer copy(tree_pointer original)
tree_pointer temp;
if (original) {
  temp=(tree_pointer) malloc(sizeof(node));
  if (IS_FULL(temp)) {
    fprintf(stderr, "the memory is full\n");
    exit(1);
  temp->left_child=copy(original->left_child);
  temp->right_child=copy(original->right_child);
  temp->data=original->data;
  return temp;
return NULL;
```

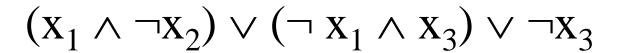
Equality of Binary Trees

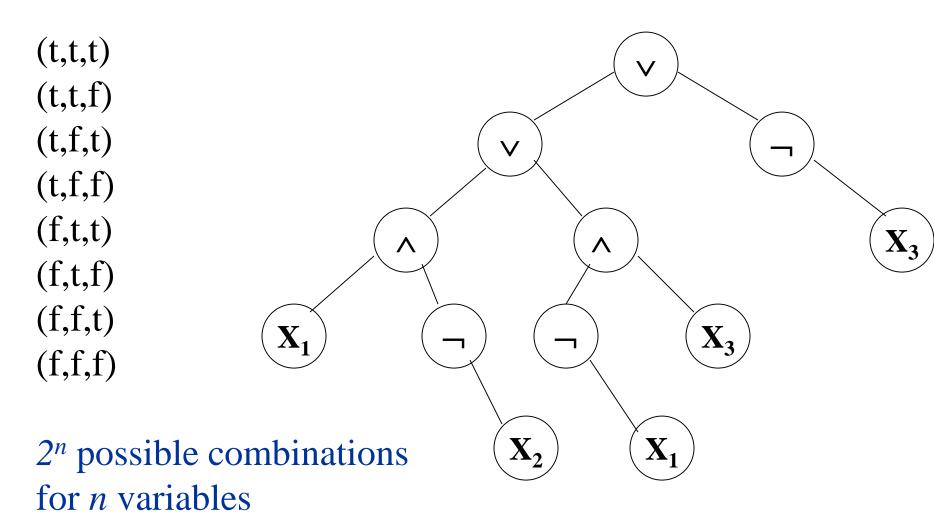
the same topology and data

```
int equal(tree_pointer first, tree_pointer second)
/* function returns FALSE if the binary trees first
 and second are not equal, otherwise it returns TRUE
  * /
 return ((!first && !second) | (first && second &&
       (first->data == second->data) &&
       equal(first->left_child, second->left_child) &&
      equal(first->right_child, second->right_child))
```

Propositional Calculus Expression

- ☐ A variable is an expression.
- ☐ If x and y are expressions, then $\neg x$, $x \land y$, $x \lor y$ are expressions.
- \square Parentheses can be used to alter the normal order of evaluation ($\neg > \land > \lor$).
- \square Example: $x_1 \lor (x_2 \land \neg x_3)$
- ☐ satisfiability problem: Is there an assignment to make an expression true?





postorder traversal (postfix evaluation)

Node Structure

```
left_child data value right_child
```

```
typedef emun {not, and, or, true, false } logical;
typedef struct node *tree_pointer;
typedef struct node {
         tree_pointer left_child;
         logical data;
         short int value;
         tree_pointer right_child;
        };
```

First version of satisfiability algorithm

```
for (all 2<sup>n</sup> possible combinations) {
    generate the next combination;
   replace the variables by their values;
    evaluate root by traversing it in postorder;
   if (root->value) {
        printf(<combination>);
        return;
printf("No satisfiable combination \n");
```

Post-order-eval function

```
void postOrderEval(tree_pointer node)
/* modified post order traversal to evaluate a propositional
calculus tree */
  if (node) {
     post_order_eval(node->left_child);
     post_order_eval(node->right_child);
     switch(node->data) {
       case not: node->value =
            !node->right_child->value;
            break;
```

```
case and: node->value =
    node->right_child->value &&
    node->left child->value;
    break;
           node->value =
case or:
    node->right_child->value | |
    node->left_child->value;
    break;
case true: node->value = TRUE;
    break;
case false: node->value = FALSE;
```

Threaded Binary Trees

Many null pointers in current representation of binary trees

n: number of nodes;

total links: 2n

number of non-null links: n-1

null links: 2n-(n-1) => n+1

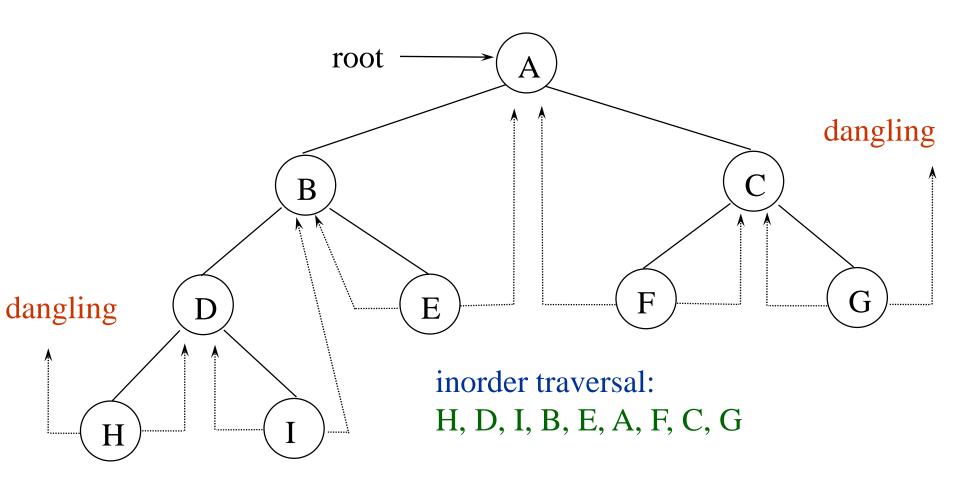
□ Replace these null pointers with some useful "threads".

Threaded Binary Trees (Continued)

If ptr->left_child is null,
replace it with a pointer to the node that would be
visited before ptr in an inorder traversal

If ptr->right_child is null,
replace it with a pointer to the node that would be
visited after ptr in an inorder traversal

A Threaded Binary Tree

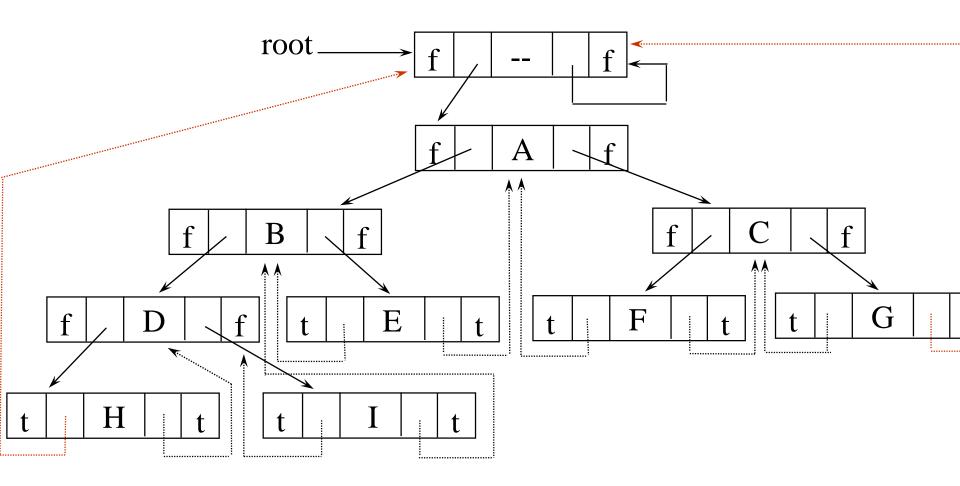


CHAPTER 5

Data Structures for Threaded BT

left_thread left_child data right_child right_thread TRUE **FALSE** FALSE: child TRUE: thread typedef struct threaded_tree *threaded_pointer; typedef struct threaded_tree { short int left thread; threaded_pointer left_child; char data; threaded_pointer right_child; short int right_thread;

Memory Representation of A Threaded BT



CHAPTER 5

Next Node in Threaded BT

```
threaded_pointer insucc(threaded_pointer
 tree)
  threaded pointer temp;
  temp = tree->right_child;
  if (!tree->right_thread)
    while (!temp->left thread)
      temp = temp->left child;
  return temp;
```

CHAPTER 5

45

Inorder Traversal of Threaded BT

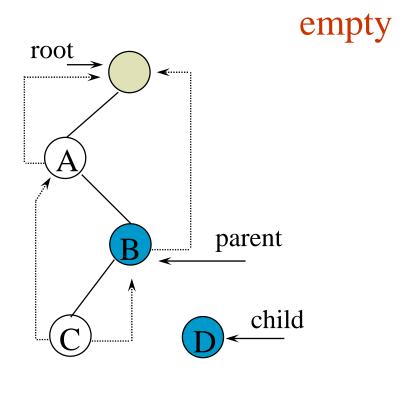
```
void tinorder(threaded_pointer tree)
/* traverse the threaded binary tree
 inorder */
    threaded_pointer temp = tree;
    for (;;) {
        temp = insucc(temp);
        if (temp==tree) break;
        printf("%3c", temp->data);
                                   46
```

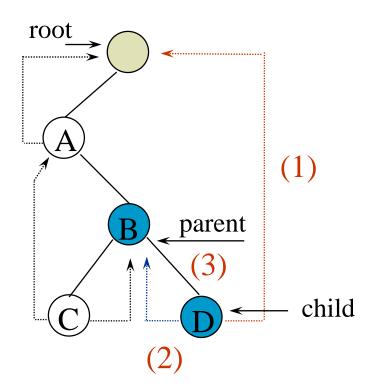
Inserting Nodes into Threaded BTs

- Insert child as the right child of node (parent)
 - change parent->right_thread to FALSE
 - set child->left_thread and child->right_thread
 to TRUE
 - 1. set child->right_child to parent->right_child
 - 2. set child->left_child to point to parent
 - change parent->right_child to point to child

Examples

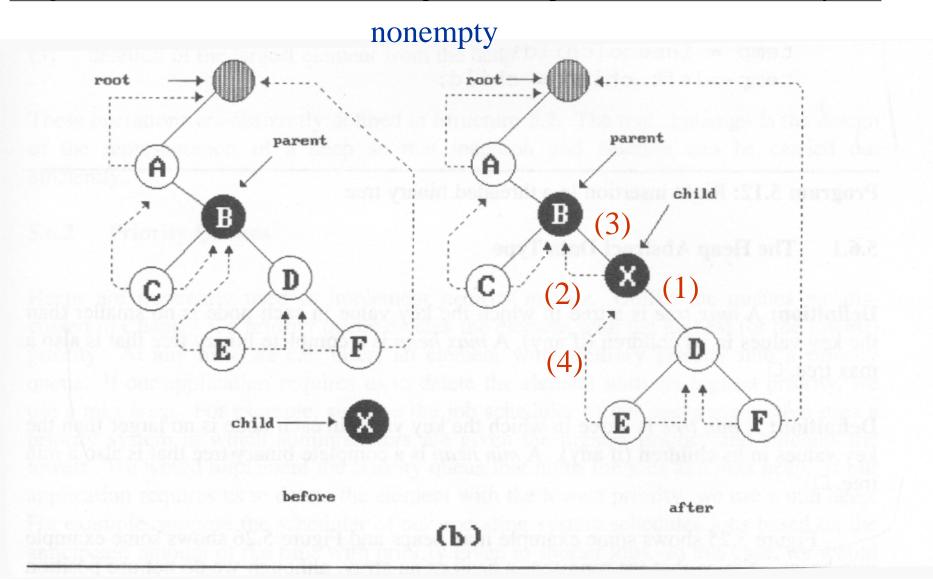
Insert a node D as a right child of B.





(a)

*Figure 5.24: Insertion of child as a right child of parent in a threaded binary tree



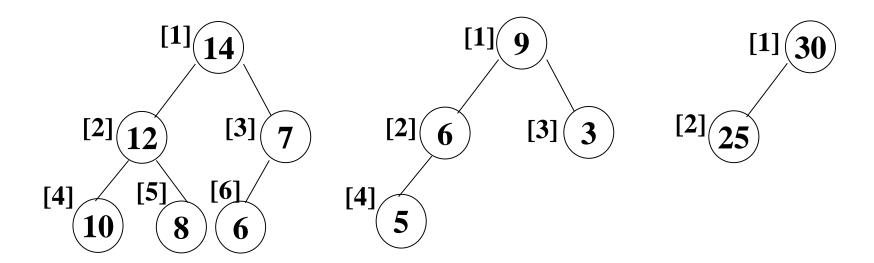
Right Insertion in Threaded BTs

```
void insertRight(threaded_pointer parent,
                    threaded_pointer child)
   threaded_pointer temp;
(1) child->right_child = parent->right_child;
   child->right_thread = parent->right_thread;
(2) child->left_child = parent;
                                  case (a)
   child->left_thread = TRUE;
(3) parent->right_child = child;
   parent->right_thread = FALSE;
   if (!child->right_thread) {
                                  case (b)
     temp = insucc(child);
     temp->left_child = child;
                    CHAPTER 5
                                            50
```

Heap

- ☐ A max tree is a tree in which the key value in each node is no smaller than the key values in its children.
 - A max heap is a complete binary tree that is also a max tree.
- □ A min tree is a tree in which the key value in each node is no larger than the key values in its children.
 - A min heap is a complete binary tree that is also a min tree.
- Operations on heaps
 - creation of an empty heap
 - insertion of a new element into the heap
 - deletion of the largest element from the heap

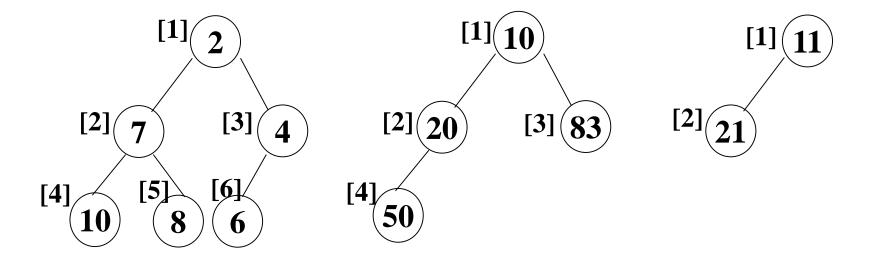
CHAPTER 5



Property:

The root of max heap (min heap) contains the largest (smallest).

*Figure 5.26: Min heaps



ADT for Max Heap

structure MaxHeap

- □ objects: a complete binary tree of n > 0 elements organized so that the value in each node is at least as large as those in its children functions:
 - for all *heap* belong to *MaxHeap*, *item* belong to *Element*, *n*, *max_size* belong to integer
- □ Boolean HeapFull(heap, n)::= if (n==max_size) return TRUE else return FALSE
- ☐ Boolean HeapEmpty(heap, n)::= if (n>0) return FALSE else return TRUE
- ☐ Element Delete(heap,n)::= if (!HeapEmpty(heap,n)) return one instance of the **largest** element in the heap and remove it from the heap

else return error

Application: priority queue

- ☐ Machine service (Example 5.1)
 - amount of time (min heap)
 - amount of payment (max heap)
- ☐ Factory (Example 5.2)
 - time tag (min heap)

ADT MaxPriorityQuere是

物件:n個元素形成的集合(n>0),每個元素有一個鍵值

函式:對所有的q∈MaxPriorityQueue,item∈Element,n是整

數

MaxPriorityQueue ::= 建立一個空的優先權佇列

create(max_size)

Boolean is Empty(q,n) ::= if (n>0) return FALSE

else return TRUE

最大的元素

else return 錯誤

最大的元素並把它從堆積中

移除

else return 錯誤

MaxPriorityQueue ::= 把item插入q中並回傳優先

權佇列的結果

MaxPriorityQueue push(q,item,n)

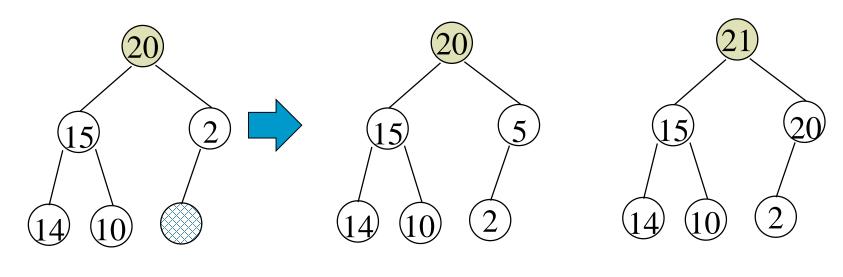
Data Structures

- unordered linked list
- unordered array
- □ sorted linked list
- □ sorted array
- ☐ heap

*Figure 5.27: Priority queue representations

Representation	Insertion	Deletion
Unordered array	$\Theta(1)$	$\Theta(n)$
Unordered linked list	$\Theta(1)$	$\Theta(n)$
Sorted array	O(n)	$\Theta(1)$
Sorted linked list	O(n)	$\Theta(1)$
Max heap	$O(\log_2 n)$	$O(\log_2 n)$

Example of Insertion to Max Heap



initial location of new node

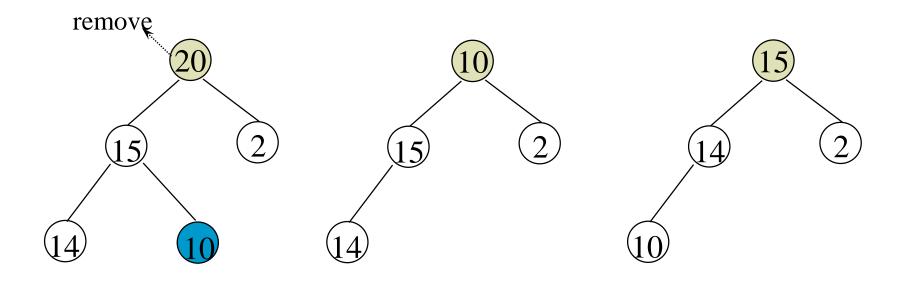
insert 5 into heap

insert 21 into heap

Insertion into a Max Heap

```
void push(element item, int *n)
{/* 把項目加入目前大小是n的最大堆積 */
  int i;
                               O(\log_2 n)
  if (HEAP_FULL(*n)) {
    fprintf(stderr, "the heap is full.\n");
    exit(1);
  i = ++(*n);
  while ((i!=1)&&(item.key>heap[i/2].key)) {
    heap[i] = heap[i/2]; // moving up to root
    i /= 2;
                      2^{k}-1=n ==> k= \lceil \log_{2}(n+1) \rceil
  heap[i] = item;
                     CHAPTER 5
                                              60
```

Example of Deletion from Max Heap



Deletion from a Max Heap

```
element pop(int *n)
{/*從堆積中刪除鍵最高的元素 */
  int parent, child;
  element item, temp;
  if (HEAP_EMPTY(*n)) {
    fprintf(stderr, "The heap is empty\n");
    exit(1);
   /* save value of the element with the
   highest key */
  item = heap[1];
  /* use last element in heap to adjust heap */
  temp = heap[(*n)--];
  parent = 1;
  child = 2i
                    CHAPTER 5
                                           62
```

```
while (child <= *n) {
    /* find the larger child of the current
       parent */
    if ((child < *n) \& \&
        (heap[child].key<heap[child+1].key))
      child++;
    if (temp.key >= heap[child].key) break;
    /* move to the next lower level */
    heap[parent] = heap[child];
    head = child;
    child *= 2;
  heap[parent] = temp;
  return item;
```

ADT Dictionary是

物件:n個資料對形成的集合(n>0),每個資料對有一個鍵值和搭配的項目

對於所有的d∈Dictionary,item∈Item,k∈Key,n是整數

Dictionary Create(max_size) ::= 建立一個空的字典

Boolean IsEmpty(d,n) ::= if(n>0) return FALSE

else return TRUE

Element Search(d,k) ::= return 鍵值為k的項目

return NULL 如果沒有此元

素

Element Delete(d,k) ::= 刪除並回傳(如果有)鍵值為k

的項目

void Insert(d,item,k) ::= 把鍵值為k的item插入d中

Binary Search Tree

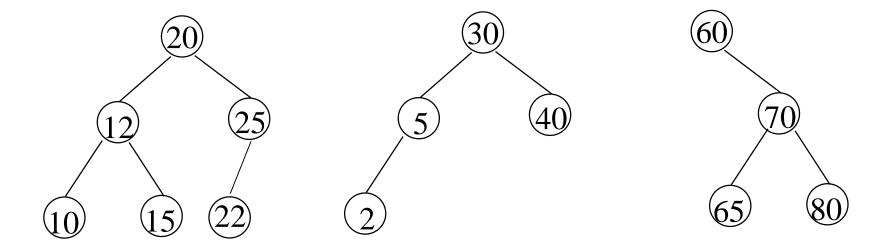
☐ Heap

- a min (max) element is deleted. $O(log_2n)$
- deletion of an arbitrary element O(n)
- search for an arbitrary element O(n)

☐ Binary search tree

- Every element has a unique key.
- The keys in a nonempty left subtree (right subtree) are smaller (larger) than the key in the root of subtree.
- The left and right subtrees are also binary search trees.

Examples of Binary Search Trees



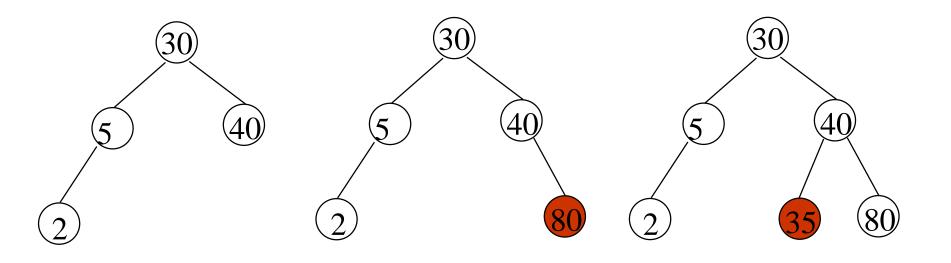
Searching a Binary Search Tree

```
tree pointer search(tree pointer root,
                     int key)
 /* return a pointer to the node that
 contains key. If there is no such
 node, return NULL */
  if (!root) return NULL;
  if (key == root->data) return root;
  if (key < root->data)
      return search(root->left child,
                     key);
  return search(root->right_child,key);
                 CHAPTER 5
                                      67
```

Another Searching Algorithm

```
tree_pointer iterSearch(tree_pointer
 tree, int key)
 while (tree) {
    if (key == tree->data) return tree;
    if (key < tree->data)
        tree = tree->left child;
    else tree = tree->right child;
  return NULL;
                   CHAPTER 5
```

Insert Node in Binary Search Tree



Insert 80

Insert 35

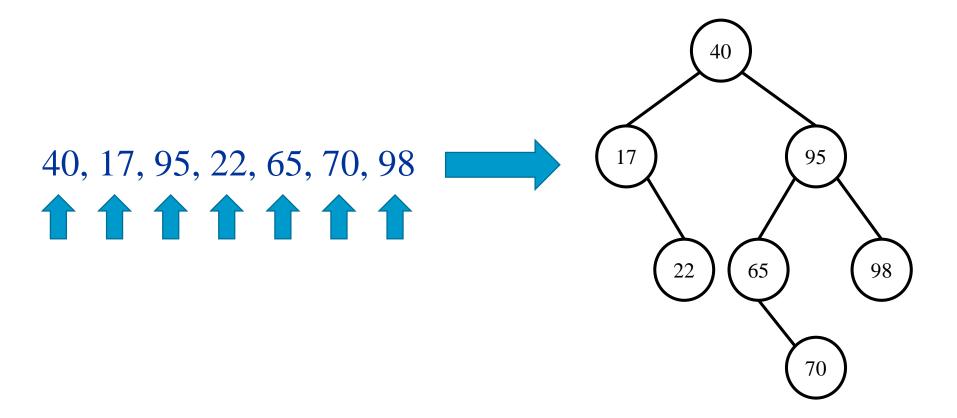
```
Insertion into a Binary Search Tree
void insert(tree_pointer *node, int k,iType
  theItem)
{tree_pointer ptr,
      temp = modified_search(*node, k);
  if (temp | ! (*node)) {/* k不在樹中 */
   ptr = (tree_pointer) malloc(sizeof(node));
   if (IS_FULL(ptr)) {
     fprintf(stderr, "The memory is full\n");
     exit(1);
   ptr->data.key = k; ptr->data.item = theItem;
   ptr->left_child = ptr->right_child = NULL;
   if (*node)
     if (k < temp->data) temp->left_child=ptr;
        else temp->right_child = ptr;
   else *node = ptr;
```

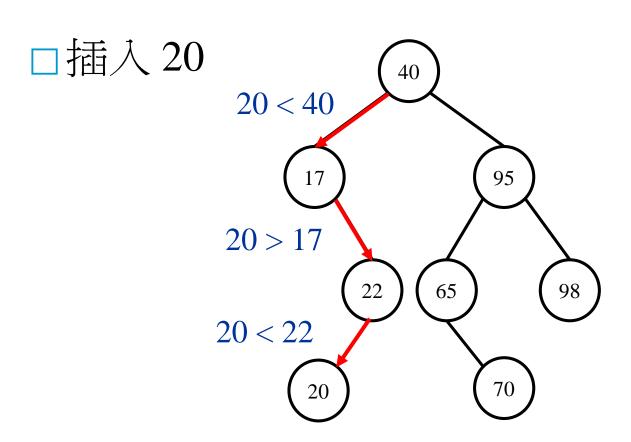
Binary search tree insert and search

- □用list的方式實作binary search tree的插入 和搜尋
- □實作步驟
- 1. 建立樹的node結構(struct)
- 2. 建立一棵binary search tree
- 3. 主要function
 - 插入: insertNode()
 - 搜尋: searchNode()

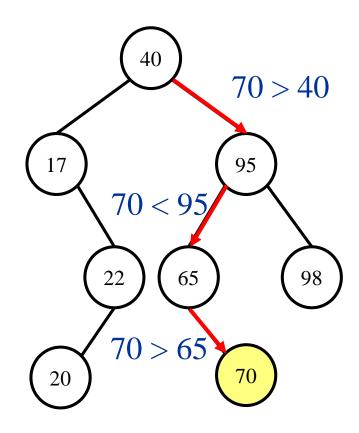
Binary search tree insert and search

□建立一棵binary search tree





□搜尋 70



□建立樹的node結構(struct)

```
struct treeNode {
   struct treeNode *leftPtr; // pointer to left subtree
   int data; // node value
   struct treeNode *rightPtr; // pointer to right subtree
};
typedef struct treeNode TreeNode; // synonym for struct treeNode
typedef TreeNode *TreeNodePtr; // synonym for TreeNode*
```

□插入: insertNode()

```
void insertNode( TreeNodePtr *treePtr, int value ){
    // if tree is empty
    if ( *treePtr == NULL ) {
        *treePtr = malloc( sizeof( TreeNode ) );
        // if memory was allocated, then assign data
        if ( *treePtr != NULL ) {
            ( *treePtr )->data = value;
            ( *treePtr )->leftPtr = NULL;
            ( *treePtr )->rightPtr = NULL;
        else {
            printf( "%d not inserted. No memory available.\n", value );
```

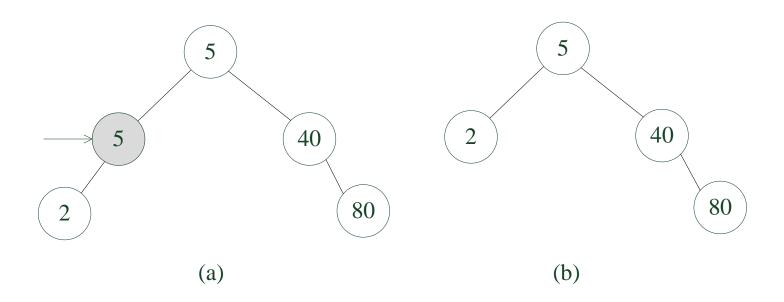
□插入: insertNode()

```
else { // tree is not empty
    // data to insert is less than data in current node
    if ( value < ( *treePtr )->data ) {
        insertNode( &( ( *treePtr )->leftPtr ), value );
    // data to insert is greater than data in current node
    else if ( value > ( *treePtr )->data ) {
        insertNode( &( ( *treePtr )->rightPtr ), value );
    else { // duplicate data value ignored
        printf( "%s", "dup" );
```

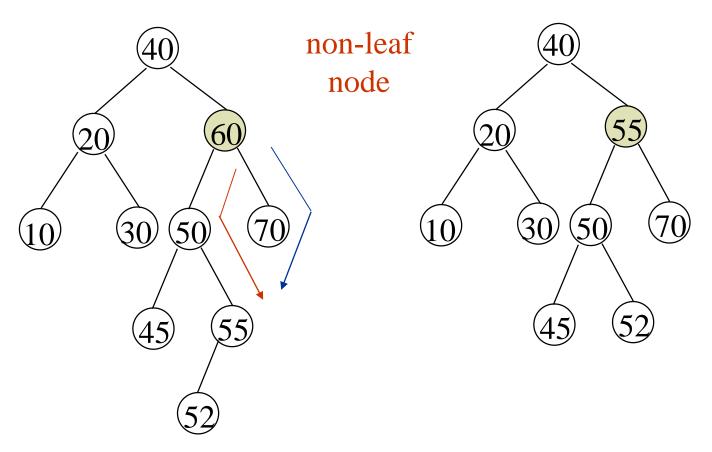
□搜尋: searchNode()

```
TreeNodePtr searchNode(TreeNodePtr treePtr, int key){
    if(!treePtr){
        printf("Not in tree!!\n");
        return NULL;
    else if(key == treePtr->data){ // key in tree
        printf("treePtr->data = %d\n", treePtr->data);
        return treePtr;
    else if(key < treePtr->data) // search next key
        return searchNode(treePtr->leftPtr, key);
    return searchNode(treePtr->rightPtr, key);
```

Deletion for a Binary Search Tree



Deletion for a Binary Search Tree



Before deleting 60

After deleting 60

In the left, to find the maximum In the right, to find the minmum

Split a Binary Search Tree

```
void split (nodePointer *theTree, int k, nodePointer *samll,
element *mid, nodePointer *big)
{ /* 根據鍵k來分割二元搜尋樹 */
  if (!theTree) \{*small = *big = 0; (*mid).key = -1; return; \}
 /* 空樹 */
  nodePointer sHead, bHead, s, b, currentNode;
 /* 替small和big建立標頭節點 */
 MALLOC(sHead, sizeof(*sHead));
 MALLOC(bHead, sizeof(*bHead));
 s = sHead, b = bHead;
  /* 執行分割 */
  currentNode = *theTree;
  while (currentNode)
                                                       81
                         CHAPTER 5
```

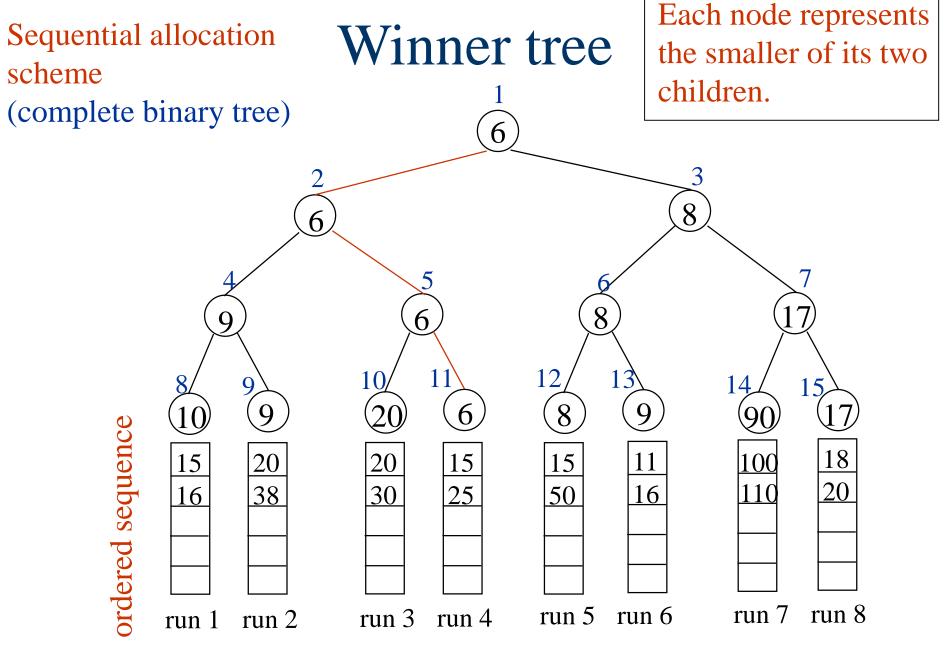
```
if (k < currentNode→data.key) { /* 加到big */
b→leftChild = currentNode; b = currentNode;
currentNode = currentNode→leftChild; }
else if (k > currentNode→data.key) { /* 加到 small */
s \rightarrow rightChild = currentNode; s = currentNode;
currentNode = currentNode→rightChild; }
else { /* 在currentNode做分割 */
s→rightChild = currentNode→leftChild;
b→leftChild = currentNode→rightChild;
*small = sHead -> rightChild; free(sHead);
*big = bHead→leftChild; free(bHead);
(*mid).item = currentNode→data.item;
(*mid).key = currentNode→data.key;
free(currentNode);
return; }
                          CHAPTER 5
```

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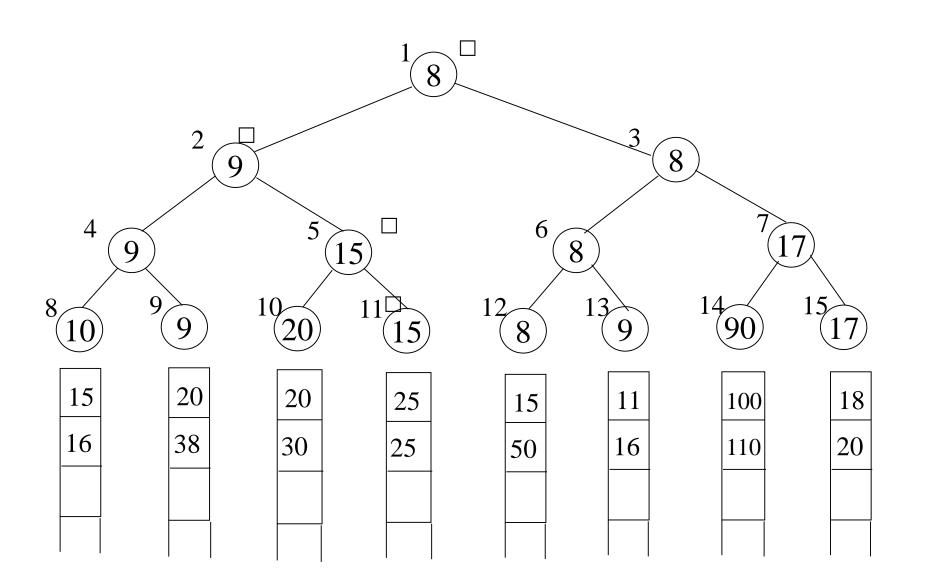
```
/* 沒有鍵為k的字典對 */
s→rightChild = b→leftChild = 0;
*small = sHead→rightChild; free(sHead);
*big = bHead→leftChild; free(bHead);
(*mid).key = -1;
return;
}
```

Selection Trees

- (1) Winner tree
- (2) Loser tree



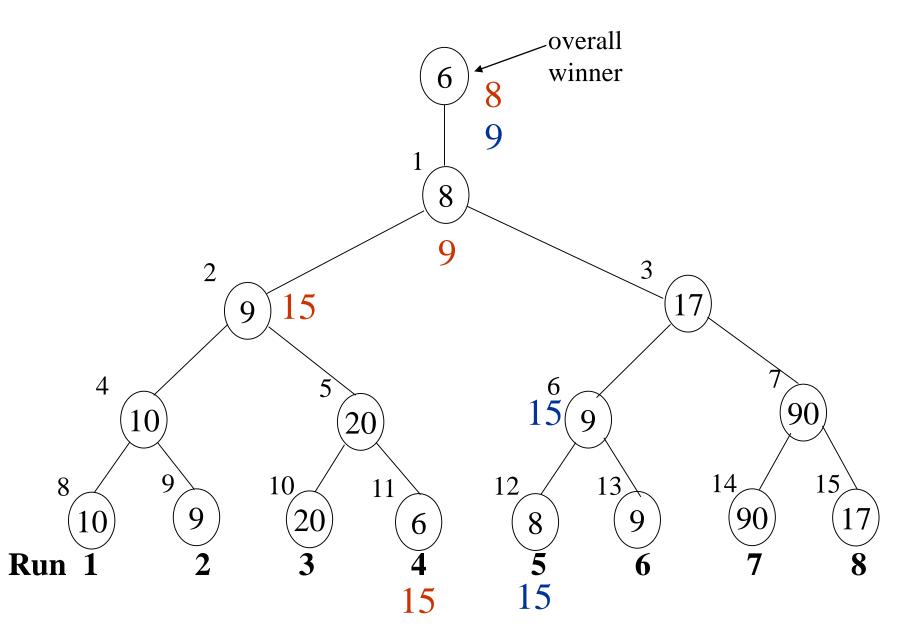
*Figure 5.35: Selection tree of Figure 5.34 after one record has been output and the tree restructured (nodes that were changed are ticked)



Analysis

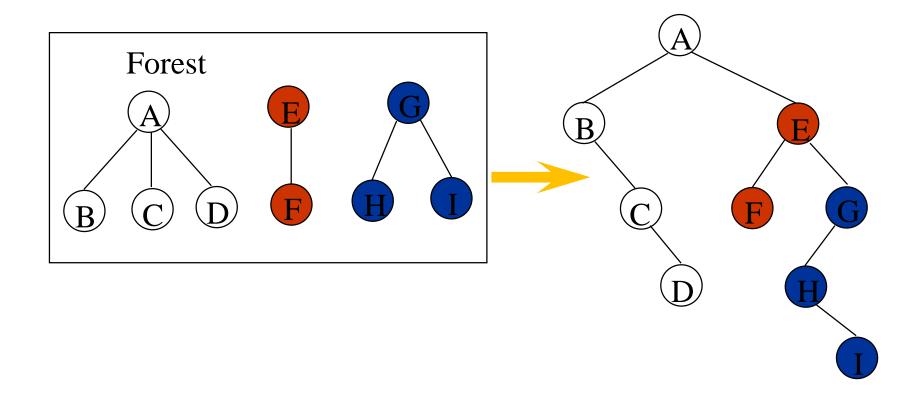
- ☐ K: # of runs
- n: # of records
- \square setup time: O(K) (K-1)
- \square restructure time: $O(\log_2 K)$ $\lceil \log_2(K+1) \rceil$
- \square merge time: O(nlog₂K)
- ☐ slight modification: loser tree
 - consider the parent node only (vs. sibling nodes)

*Figure 5.34: Tree of losers corresponding to Figure 5.32



Forest

 \square Definition: A forest is a set of $n \ge 0$ disjoint trees



Transform a forest into a binary tree

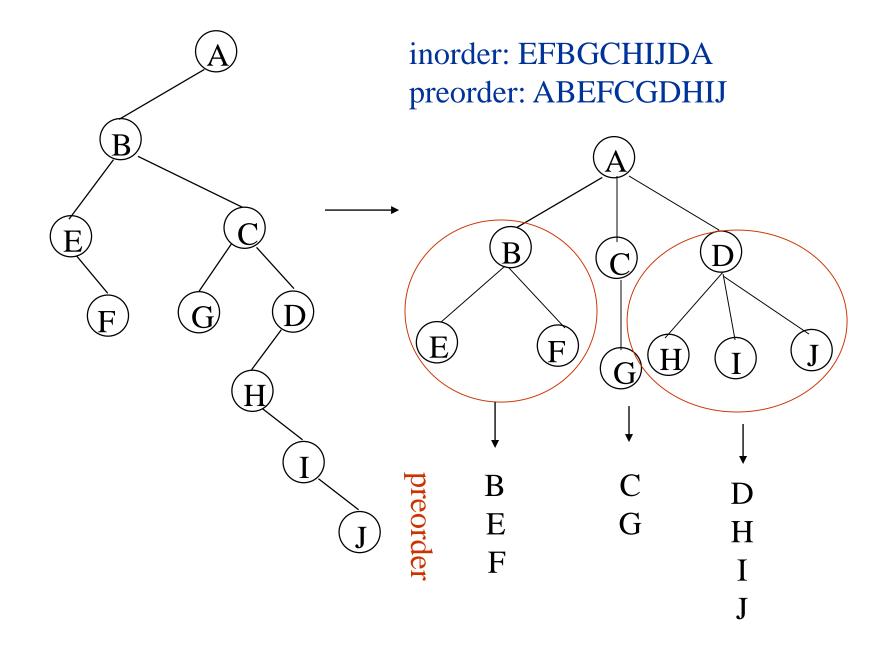
- \square T1, T2, ..., Tn: a forest of trees
- □ B(T1, T2, ..., Tn): a binary tree corresponding to this forest
- ☐ Algorithm
 - (1) empty, if n = 0
 - (2) has root equal to root(T1)
 has left subtree equal to B(T11,T12,...,T1m)
 has right subtree equal to B(T2,T3,...,Tn)

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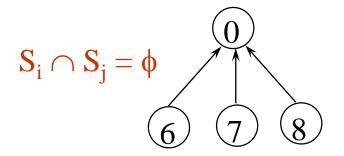
Forest Traversals

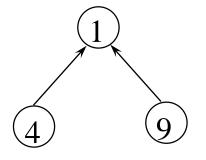
- ☐ Preorder (VLR)
 - If F is empty, then return
 - Visit the root of the first tree of F
 - Taverse the subtrees of the first tree in tree preorder
 - Traverse the remaining trees of F in preorder
- ☐ Inorder (LVR)
 - If F is empty, then return
 - Traverse the subtrees of the first tree in tree inorder
 - Visit the root of the first tree
 - Traverse the remaining trees of F is indorer

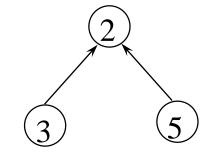


Set Representation

$$\square S_1 = \{0, 6, 7, 8\}, S_2 = \{1, 4, 9\}, S_3 = \{2, 3, 5\}$$







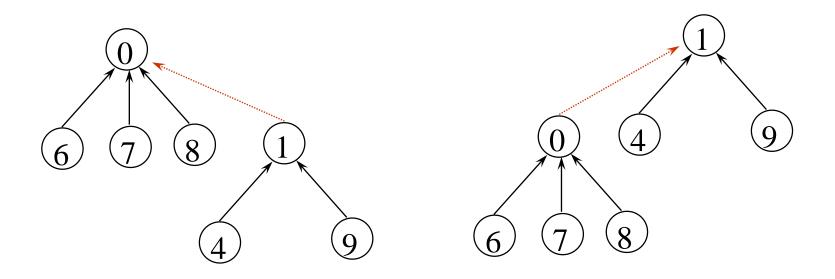
☐ Two operations considered here

- Disjoint set union $S_1 \cup S_2 = \{0,6,7,8,1,4,9\}$
- -Find(i): Find the set containing the element i.

$$3 \in S_3, 8 \in S_1$$

Disjoint Set Union

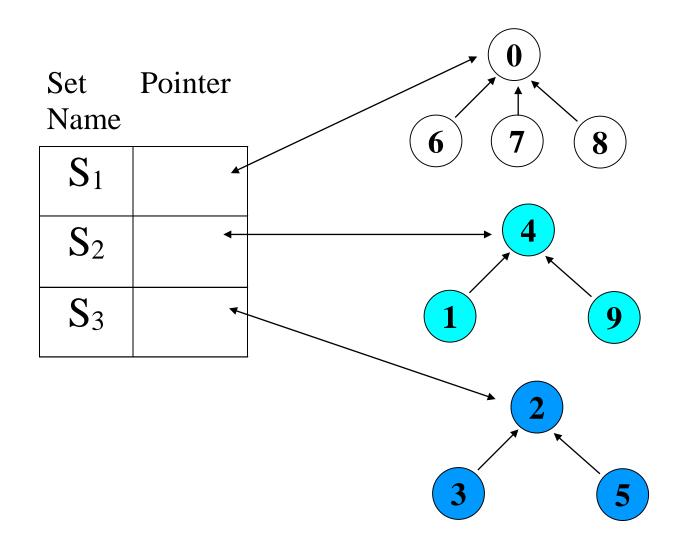
Make one of the trees a subtree of the other



Possible representation for S₁ union S₂

$$S_1 \cup S_2$$

*Figure 5.39: Data Representation of S₁S₂and S₃



Array Representation for Set

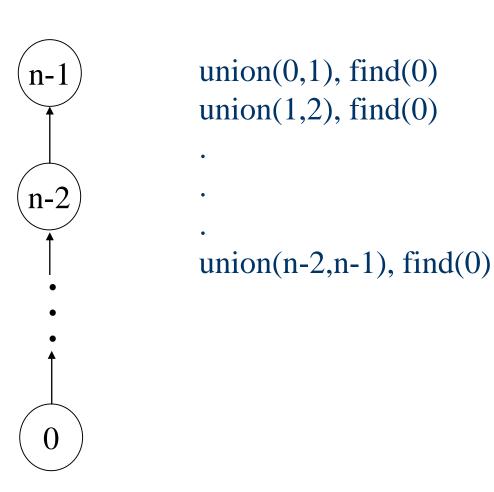
i	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]
parent	-1	4	-1	2	-1	2	0	0	0	4

```
int simpleFind(int i)
    for (; parent[i]>=0; i=parent[i]);
    return i;
yoid simpleUnion(int i, int j)
   parent[i]= j;
```

*Figure 5.41:Degenerate tree (退化樹)

union operation O(n) n-1

find operation $O(n^2)$ $\sum_{i=1}^{n} i$

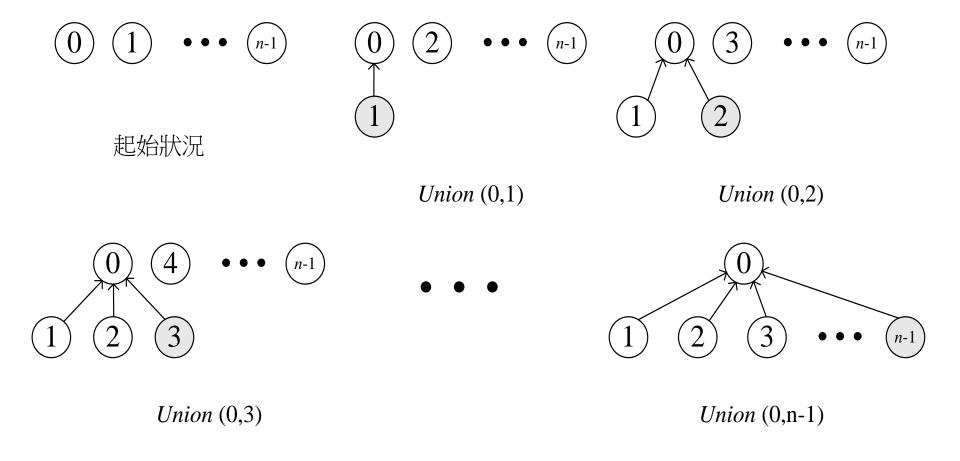


degenerate tree

*Figure 5.42: Trees obtained using the weighting rule

weighting rule for union(i,j):

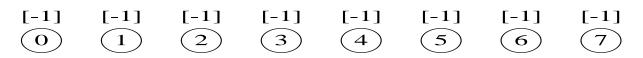
if # of nodes in i < # in j then make j the parent of i



Modified Union Operation

```
void weightedUnion(int i, int j)
      Keep a count in the root of tree
 //parent[i]=-count[i] and parent[i]=-count[j]
     int temp = parent[i]+ parent[j];
     if (parent[i]>parent[j]) {
         parent[i]=j;
     /* make j the new root*/
         parent[j]=temp;
     else {
         parent[j]=i;
   make i the new root*/
         parent[i]=temp;
                            If the number of nodes in tree i is
                            less than the number in tree j, then
                            make j the parent of i; otherwise
```

make i the parent of j.



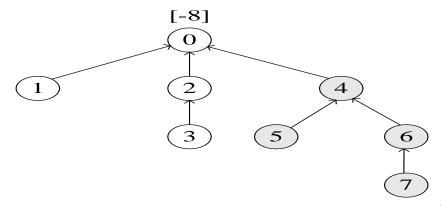
(a) 一開始樹的高度都是1



(b) 執行*Union* (0,1), (2,3), (4,5), 與 (6,7)後樹之高度為 2



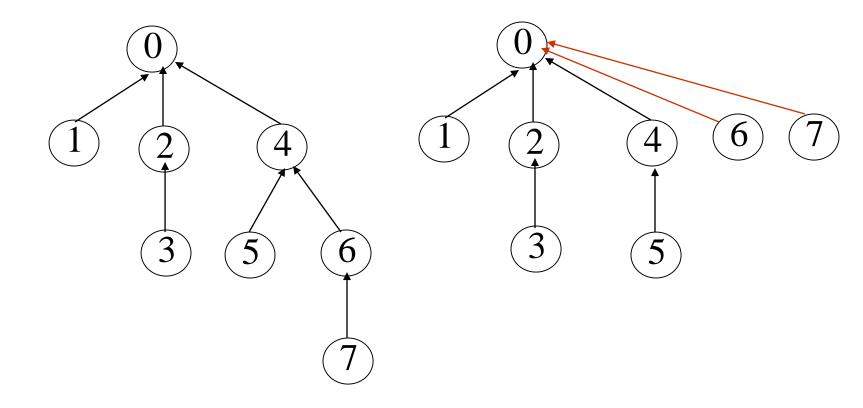
(c) 執行Union (0,2) 與 (4,6) 後樹之高度為 3



(d) 執行Union (0,4) 後樹之高度為 4 Figure 5.43:Trees ach

collapsingFind(i) Operation

```
int collapsingFind(int i)
    int root, trail, lead;
    for (root=i; parent[root]>=0;
                      root=parent[root]);
    for (trail=i; trail!=root;
                      trail=lead) {
         lead = parent[trail];
         parent[trail] = root;
                         If j is a node on the path from
    return root:
                         i to its root then make j a child
                         of the root
```



find(7) find(7) find(7) find(7) find(7) find(7) find(7)

go up	3	1	1	1	1	1	1	1
reset	2							

13 moves (vs. 24 moves)

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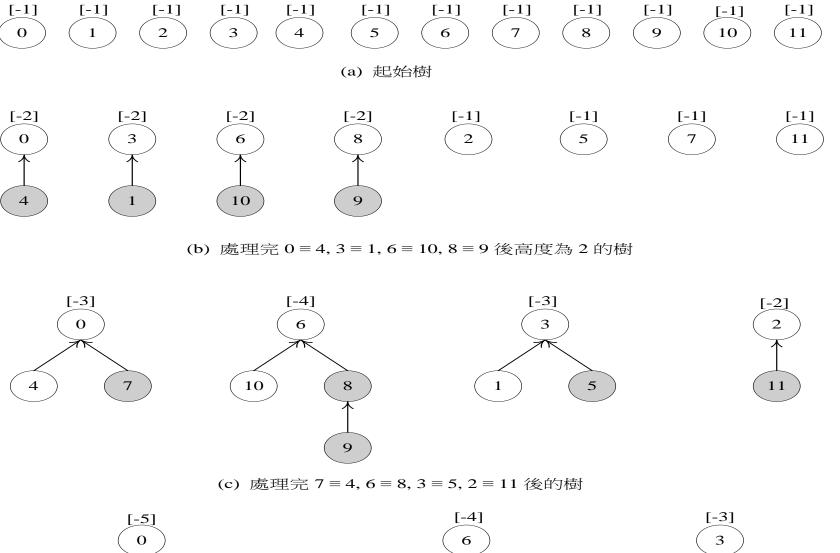
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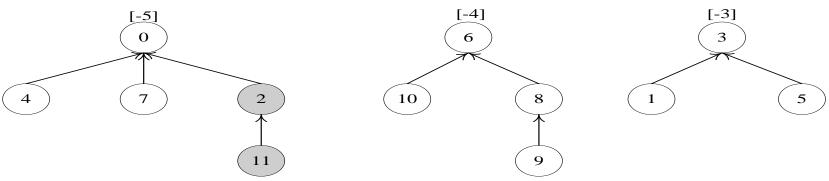
Application to Equivalence Classes

- \square Find equivalence class $i \equiv j$
- ☐ Find S_i and S_j such that $i \in S_i$ and $j \in S_j$ (two finds)
 - $-S_i = S_j$ do nothing
 - $-S_i \neq S_i \text{ union}(S_i, S_i)$
- example

$$0 \equiv 4, 3 \equiv 1, 6 \equiv 10, 8 \equiv 9, 7 \equiv 4, 6 \equiv 8,$$

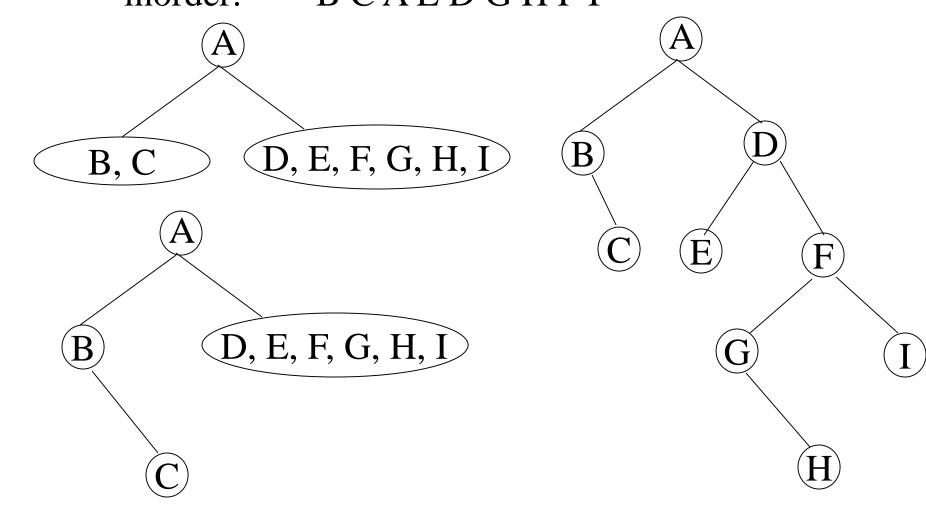
 $3 \equiv 5, 2 \equiv 11, 11 \equiv 0$
 $\{0, 2, 4, 7, 11\}, \{1, 3, 5\}, \{6, 8, 9, 10\}$





(d) 處理完 11 ≡ 0 後的樹

preorder: ABCDEFGHI inorder: BCAEDGHFI



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