计算天文期中报告

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Q

Lecture 03 P64

$$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = 0 \tag{1}$$

- 1 试任找若干种差分格式对模型方程及一定的初条进行模拟,并对不同格式下的结果进行比较。
- 2 找一种格式分析其稳定性条件。
- 3 找一种格式分析其精度。

Α

- 1. 我们使用 Python 求解在波速大于 0(c > 0) 情况下的单波方程。用代码实现了: a. 迎风格式,b. Lax-Friedrichs 格式,c. Lax-Wendroff 格式,d. 跳点格式,e. 全隐格式,f. Crack Nicholson 格式. 对该方程的数值求解。代码见附录:Code in Python,结果比较图见 PPT.
- 2. 我们以时间向前,空间中心差分格式为例,详细推导其 von Neumann 稳定性分析的过程。任意差分方程的本征模为:

$$u_j^n = \xi^n e^{ikj\Delta x} \tag{2}$$

若存在某一波数 k 使 $|\xi(k)| > 1$,则差分方程不稳定。时间向前,空间中心差分格式为:

$$u_j^{n+1} = u_j^n - \frac{c\Delta t}{2\Delta x} (u_{j+1}^n - u_{j-1}^n)$$
(3)

将方程(2)带入方程(3)可得:

$$u_j^{n+1} = \xi^{n+1} e^{ikj\Delta x} \tag{4}$$

$$u_j^n = \xi^n e^{ikj\Delta x} \tag{5}$$

$$u_{j+1}^n = \xi^n e^{ik(j+1)\Delta x} \tag{6}$$

$$u_{i-1}^n = \xi^n e^{ik(j-1)\Delta x} \tag{7}$$

联立方程(3)-(7), 并化简可得:

$$\xi^{n+1}e^{ijk\Delta x} = \xi^n e^{ijk\Delta x} \left[1 - \frac{c\Delta t}{2\Delta x} (e^{ik\Delta x} - e^{-ik\Delta x}) \right]$$
 (8)

也即:

$$\xi(k) = 1 - ic \frac{\Delta t}{\Delta x} sin(k\Delta x) \tag{9}$$

由(9)式可知,对时间向前,空间中心差分格式而言 $|\xi(k)|>1$ 恒成立,因此无论怎么划分空间,时间格点,该格式均不稳定。

3. 我们使用 von Neumann 稳定性分析对对迎风格式和 Lax-Wendroff 格式的精度进行定性分析,遵循 2 中的推导过程。首先对迎风格式,其增长因子为:

$$\xi(k) = 1 - ar(1 - e^{-ik\Delta x}) \tag{10}$$

其中 $r = \frac{\Delta t}{\Delta x}$,由此可以计算增长因子的模为:

$$|\xi(k)| = sqrt(1 - 4ar(1 - ar)sin^2(\frac{k\Delta x}{2}))$$
(11)

辐角为:

$$arg(\xi(k)) = -tan^{-1} \left[\frac{arsin(k\Delta x)}{1 - ar + arcos(k\Delta x)} \right] = -ark\Delta x \left[1 - \frac{1}{6}(1 - ar)(1 - 2ar)(k\Delta x)^2 + \dots \right]$$
 (12)

对 Lax-Wendroff 格式,可以计算其增长因子为:

$$\xi(k) = 1 - i \arcsin(k\Delta x) - 2a^2 r^2 \sin^2(\frac{k\Delta x}{2})$$
(13)

由此可以计算增长因子的模为:

$$|\xi(k)| = 1 - 4a^2r^2(1 - a^2r^2)\sin^4(\frac{k\Delta x}{2})$$
(14)

辐角为:

$$arg(\xi(k)) = -tan^{-1} \left[\frac{arsin(k\Delta x)}{1 - 2a^{2}r^{2}sin^{2}(\frac{k\Delta x}{2})} \right] = -ark\Delta x \left[1 - \frac{1}{6}(1 - a^{2}r^{2})(k\Delta x)^{2} + \dots \right]$$
 (15)

增长因子的模和辐角则分别代表了该格式的耗散和色散。在 Lax-Wendroff 格式中,振幅衰减依旧存在,但每步的误差为 $O(\Delta x^4)$,相比于迎风格式中的误差阶数 $O(\Delta x^2)$,有很大的改善。而代价在于 Lax-Wendroff 格式存在相位延迟,虽然两种格式的相位误差都为 $O(\Delta x^2)$,但当波数取某些特定值(ar=1/2)时,迎风格式的相位误差会穿过零点,即通过特殊的空间,时间格点选取可以避免在迎风格式中出现相位误差,而对 Lax-Wendroff 格式则不存在特殊的时间,空间格点选取,其相位误差恒为 $O(\Delta x^2)$ 。

Code in Python

packages and settings

```
import numpy as np
import time
import matplotlib.pyplot as plt
import matplotlib as mpl
from matplotlib import animation
import warnings
warnings.filterwarnings("ignore")

# different methods
def upwind(r,X,T,U_init,U_left):
    U = np.zeros((len(X),len(T)))
    U[:,0] = U_init
    U[0,:] = U_left
    for n in np.arange(len(T)-1):
        U[1:, n+1] = U[1:, n] - r*(U[1:, n] - U[0:-1,n])
    return U
```

```
def Lax_Friedrichs(r,X,T,U_init,U_left,U_right):
    U = np.zeros((len(X), len(T)))
    U[:,0] = U_init
    U[0,:] = U_{left}
    U[-1,:]= U_right
    for n in np.arange(len(T)-1):
        U[1:-1,n+1] = 0.5*(U[2:,n]+U[:-2,n])-0.5*r*(U[2:,n]-U[:-2,n])
    return U
\operatorname{def} \operatorname{Lax}_{\operatorname{Wendroff}}(r,X,T,U_{\operatorname{init}},U_{\operatorname{left}},U_{\operatorname{right}}):
    U = np.zeros((len(X), len(T)))
    U[:,0] = U_{init}
    U[0,:] = U_{left}
    U[-1,:] = U_right
    for n in np.arange(len(T)-1):
        U[1:-1,n+1] = U[1:-1,n] - 0.5*r*(U[2:,n] - U[:-2,n]) + 0.5*r**2*(U[2:,n] - 2*U[1:-1,n] + U[:-2,n])
    return U
def hopscotch(r,X,T,U_init,U_left,U_right):
    U = np.zeros((len(X), len(T)))
    U[:,0] = U_{init}
    U[0,:] = U_{left}
    for n in np.arange(len(T)-1):
        for i in np.arange(len(X)-2):
             if (n+i+1)\%2 == 0:
                 U[i+1,n+1] = U[i+1,n]-0.5*r*(U[i+2,n]-U[i,n])
        for i in np.arange(len(X)-2):
             if (n+i+1)\%2!=0:
                 U[i+1,n+1] = U[i+1,n]-0.5*r*(U[i+2,n+1]-U[i,n+1])
    return U
def Thomas(La, Mb, Uc, b):
    Arguments:
        La -- [lower item for tri-diagonal matrix]
        Mb -- [mian item for tri-diagonal matrix]
        Uc -- [upper item for tri-diagonal matrix]
        b - [AX = b, where A is the tri-diagonal matrix]
    n = len(Mb)
    Uc[0] = Uc[0] / Mb[0]
    for i in range(1, n-1):
        Uc[i] = Uc[i] / (Mb[i] - La[i - 1] * Uc[i - 1])
    b[0] = b[0] / Mb[0]
    for i in range(1, n):
        b[i] = (b[i] - La[i-1]*b[i-1]) / (Mb[i] - La[i-1] * Uc[i-1])
    ls = list(range(n-1)) [::-1]
    for i in ls:
        b[i\,]\,=\,b[i]\,\text{-}\,\operatorname{Uc}[i]^*b[i\!+\!1]
    return np.array(b)
```

```
def full_implicate(r,X,T,U_init,U_left,U_right):
   U = np.zeros((len(X), len(T)))
   U[:,0] = U_init
   U[0,:] = U_{left}
   U[-1,:] = U_right
   for n in range(len(T)-1):
       a = -0.5*r*np.ones((len(X)-3))#给出矩阵三条对角线的值
       b = np.ones((len(X)-2))
       C = 0.5*r*np.ones((len(X)-3))
       k = []
       for i in range(len(X)-2):
           k.append(U[i+1,n])
       k[0] += 0.5*r*U[0,n+1]
       k[-1] = 0.5*r*U[-1,n+1]#计算Ax=b中的b
       U[1:-1,n+1] = Thomas(a,b,C,k)
   return U
def Crack_Nicholson(r,X,T,U_init,U_left,U_right):
   U = np.zeros((len(X), len(T)))
   U[:,0] = U_{init}
   U[0,:] = U_{left}
   U[-1,:] = U_right
   for n in range(len(T)-1):
       a = -0.25 r*np.ones((len(X)-3))
       b = np.ones((len(X)-2))
       C = 0.25*r*np.ones((len(X)-3))
       k = []
       for i in range(len(X)-2):
           k.append(U[i+1,n]-0.25*r*(U[i+2,n]-U[i,n]))
       k[0] += 0.25*r*U[0,n+1]
       k[-1] = 0.25*r*U[-1,n+1]
       U[1:-1,n+1] = Thomas(a,b,C,k)
   return U
def solve(r,X,T,U\_init,U\_left,U\_right,method):
    if method == 'upwind':
       U = upwind(r,X,T,U_init,U_left)
    elif method == 'Lax_Friedrichs':
       U = Lax_Friedrichs(r, X, T, U_init, U_left, U_right)
    elif method == 'Lax_Wendroff':
       U = Lax\_Wendroff(r,X,T,U\_init,U\_left,U\_right)
    elif method == 'hopscotch':
       U = hopscotch(r, X, T, U_init, U_left, U_right)
    elif method == 'full_implicate':
       U = full\_implicate(r,X,T,U\_init,U\_left,U\_right)
```

```
elif method == 'Crack Nicholson':
        U = Crack\_Nicholson(r,X,T,U\_init,U\_left,U\_right)
    return U
methods = np.array(['upwind', 'Lax_Friedrichs', 'Lax_Wendroff', 'hopscotch', 'full_implicate', 'Crack_Nicholson'])
[xl,xr] = [0,10]
[ti, tf] = [0,10]
# solving & plotting
## Case 1: 谐波
def analytic_function(x,t):
    return np.\sin(2*np.pi*(x-c*t))
dx = 0.1
dt = 0.05
c = 1
r = c*dt/dx
T = np.arange(ti, tf+dt, dt)
X = \text{np.arange}(xl, xr+dx, dx)
U_{init} = analytic_{function}(X,ti)
U_{left} = analytic_{function}(xl,T)
U_right= analytic_function(xr,T)
tt,xx = np.meshgrid(T,X)
U_a = analytic_function(xx,tt)
for m, method in enumerate(methods):
    U_n = solve(r, X, T, U_init, U_left, U_right, method)
    fig = plt.figure(figsize = (6,4.5),dpi=100)
    plt.grid(ls='--')
    ani_a, = plt.plot(X,U_a[:,0],color='red', ls='-', label='analytic solution')
   ani_n, = plt.plot(X,U_n[:,0],color='blue',ls='--',label=method)
    plt.xlabel("X", fontsize = 16)
    plt.ylabel("Amptitude", fontsize = 16)
    plt.legend(loc='upper right', fontsize=8)
    text_ani = plt.text(0.05, 1, '', fontsize=12,color='black')
    plt.ylim (-1.8,1.8)
   def update(n):
        ani_a.set_data(X,U_a[:,n])
        ani_n.set_data(X,U_n[:,n])
        ti = dt*n
        text_ani.set_text('t=%.3f'%ti)
        return [ani_a,ani_n,text_ani]
    ani = animation.FuncAnimation(fig=fig, func = update, frames = np.arange(0,len(T)), interval = 100)
    ani.save('image/case1/'+method+'.gif')
    plt.show()
## Case 2: 矩形波, 锯齿波, 高斯波
```

```
def analytic_function(x,c,t):
   D = 0.4
   return np.exp(-(x- c * t - 7 ) ** 2 / D) \
           + np.heaviside(x - c * t- 2, 0.5) * np.heaviside(-(x- c * t - 3 ), 0.5) \setminus
           + np.minimum(np.maximum(x - c * t - 4, 0), np.maximum(-(x- c * t - 5 ), 0)) * 2
U_{init} = analytic_{function}(X,c,0)
U_{left} = analytic_{function}(xl,c,T)
U_right= analytic_function(xr,c,T)
tt,xx = np.meshgrid(T,X)
U_a = analytic_function(xx,c,tt)
for m, method in enumerate(methods):
   U_n = solve(r, X, T, U_init, U_left, U_right, method)
    fig = plt.figure(figsize = (6,4.5), dpi=100)
    plt.grid(ls='--')
    ani_a, = plt.plot(X,U_a[:,0],color='red', ls='-', label='analytic solution')
   ani_n, = plt.plot(X,U_n[:,0],color='blue',ls='--', label=method)
    plt.xlabel("X", fontsize = 16)
    plt.ylabel("Amptitude", fontsize = 16)
    plt.legend(loc='upper right', fontsize=8)
    text_ani = plt.text(0.05, 1, '', fontsize=12,color='black')
    plt.ylim(-1.2,1.8)
   def update(n):
       ani_a.set_data(X,U_a[:,n])
       ani_n.set_data(X,U_n[:,n])
        ti \; = dt*n
        text_ani.set_text('t=%.3f'%ti)
        return [ani_a,ani_n,text_ani]
   ani = animation.FuncAnimation(fig=fig, func = update, frames = np.arange(0,len(T)), interval = 80)
    ani.save('image/case2/'+method+'.gif')
    plt.show()
```