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sys.path.append(os.path.join(os.path.dirname(__file__), '../../ch02'))
    from typing import List, Tuple
    from program2_1 import Dvector
    from program2_2 import Dmatrix
    from program2_3 import input_vector, input_matrix
   N = 4 # N次正方行列
   def main():
       global N
        a = Dmatrix(1, N, 1, N) # 行列 a[1...N][1...N]
        b = Dvector(1,N) # b[1...N]
        # ファイルのオーブン
        with open("input_lu.dat", "r") as fin:
           with open("output_lu.dat", "w") as fout:
               input_matrix( a, 'A', fin, fout ) # 行列 A の入力
                input_vector( b, 'B', fin, fout ) # ベクトル b の入出力
               a_lu, p = lu_decomp( a )
                                              # LU分解
               b_lu = lu_solve( a_lu, b, p ) # 前進代入・後退代入
               # 結果の出力
               fout.write("Ax=b の解は次の通りです\n")
               for i in b_lu:
                   fout.write(f"{i}\n")
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    # LU分解
   def lu_decomp(a: Dmatrix, N: int=N) -> Tuple[Dmatrix, List[int]]:
       eps = 2.0 ** -50.0 # eps = 2^{-50}とする
       p = [0] * (a.row_last_idx - a.row_head_idx + 1) # p[1...N-1] を利用, p[0] は未使用
       a_lu = a.copy() # 値渡し
       for k in range(1, N):
           # ピボットの選択
           amax = abs(a_lu[k][k])
           ip = k
           for i in range(k+1, N+1):
               if abs(a_lu[i][k]) > amax:
                   amax = abs(a_lu[i][k])
                   ip = i
           # 正則性の判定
           if amax < eps:
               print("入力した行列は正則ではない!!")
           # ipを配列plc保存
           p[k] = ip
           # 行交換
           if ip != k:
                for j in range(k, N+1):
                   a_lu[k][j], a_lu[ip][j] = a_lu[ip][j], a_lu[k][j]
            # 前進消去
            for i in range(k+1, N+1):
               alpha = - a_lu[i][k] / a_lu[k][k]
                a_lu[i][k] = alpha
                for j in range(k+1, N+1):
                   a_lu[i][j] += alpha * a_lu[k][j]
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       return (a_lu, p)
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   # LU分解を利用して連立一次方程式を解く
    def lu_solve(a: Dmatrix, b: Dvector, p: List[int], N:int=N) -> Dvector:
        b_lu = b.copy() # 値渡し
        # 右辺の行交換
        for k in range(1, N):
           b_{u[k]}, b_{u[p[k]]} = b_{u[p[k]]}, b_{u[k]}
            # 前進代入
            for i in range(k+1, N+1):
               b_lu[i] += a[i][k] * b_lu[k]
        # 後退代入
        b_lu[N] /= a[N][N]
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        for k in range(N-1, 0, -1):
           b_{u}[k] = (b_{u}[k] - sum((a[k][j] * b_{u}[j] for j in range(k+1, N+1)))) / a[k][k]
       return b_lu
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    if __name__ == "__main__":
87
       main()
```

import os, sys