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import os, sys
sys.path.append(os.path.join(os.path.dirname(__file__), '../ch02'))
from program2_1 import Dvector
from program2_2 import Dmatrix
from program2_3 import input_vector
M = 6 # データのペア数
N = 3 # N次式で近似
def main():
    global M, N
    x = Dvector(1, M) # x[1...M]
y = Dvector(1, M) # y[1...M]
    # ファイルのオーブン
    with open("input_func.dat", "r") as fin:
with open("output_func.dat", "w") as fout:
input_vector( x, 'x', fin, fout ) # ベクトル x の入出力
input_vector( y, 'y', fin, fout ) # ベクトル y の入出力
              least square( x, y, fout ) # 最小2乗近似
def least_square(x: Dvector, y: Dvector, fout):
     global M, N
     p = Dmatrix(1, N+1, 1, N+1) # p[1...N+1][1...N+1]
     a = Dvector(1, N+1)
                                      # a[1...N-1]
     # 右辺ベクトルの作成
     for i in range(1, N+2):
         a[i] = 0.0
         for j in range(1, M+1):
    a[i] += y[j] * (x[j] ** (i - 1))
    # 係数行列の作成
     for i in range(1, N+2):
         for j in range(1, i+1):
              p[i][i] = 0.0
              for k in range(1, M+1):

p[i][j] += x[k] ** (i+j-2)
              p[j][i] = p[i][j]
    # 連立一次方程式を解く. 結果は a に上書き
    a = gauss2( p, a, N+1 )
     # 結果の出力
     fout.write("最小2乗近似式は y=\n")
     for i in range(N+1, 0, -1):
    fout.write("+ {:5.2f} x^{} ".format(a[i], i-1))
     fout.write("\n")
# 部分ビポット選択付きガウス消去法
def gauss2(a: Dvector, b: Dvector, n: int):
eps = 2.0 ** -50.0 # eps = 2^{-50} とする
     for k in range(1,
         # ビボットの選択
            ax = abs(a[k][k])
         for i in range(k+1, n+1):
    if abs(a[i][k]) > amax:
                  amax = abs(a[i][k])
         # 正則性の判定
         if amax < eps:
              print("入力した行列は正則ではない!!")
         # 行交換
         if ip != k:
              for j in range(k, n+1):
                  tmp = a[k][j]
                  a[k][j] = a[ip][j]
a[ip][j] = tmp
              tmp = b[k]
              b[k] = b[ip]
              b[ip] = tmp
         # 前進消去
         for i in range(k+1, n+1):
              alpha = -a[i][k] / a[k][k]
for j in range(k+1, n+1):
              a[i][j] = a[i][j] + alpha * a[k][j]
b[i] = b[i] + alpha * b[k]
     # 後退代入
           = b[n] / a[n][n]
    b[n]
     for k in range(n-1, 0,
         tmp = b[k]
         for j in range(k+1, n+1):
               tmp = tmp - a[k][j] * b[j]
         b[k] = tmp / a[k][k]
     return b
    main()
```