ICPC Notebook

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template

Osettings.sh

```
export CXXFLAGS='-03 -std=c++2a -D_GLIBCXX_DEBUG -
D_GLIBCXX_DEBUG_PEDANTIC -Wfatal-errors'
```

1template.hpp

using namespace std;

#define ll long long

#include <bits/stdc++.h>

#define pii pair<int, int>

#define pll pair<ll, ll>

md5: f368a0

```
#define vi vector<int>
#define vl vector<ll>
#define ov4(a, b, c, d, name, ...) name
#define rep3(i, a, b, c) for(ll i = (a); i < (b); i += (c))
#define rep2(i, a, b) rep3(i, a, b, 1)
#define rep1(i, n) rep2(i, 0, n)
#define rep0(n) rep1(aaaaa, n)
#define rep(...) ov4(__VA_ARGS__, rep3, rep2, rep1, rep0)
(__VA_ARGS__)
#define per(i, a, b) for(ll i = (a)-1; i >= (b); i--)
#define fore(e, v) for(auto&& e : v)
#define all(a) begin(a), end(a)
#define si(a) (int)(size(a))
#define lb(v, x) (lower_bound(all(v), x) - begin(v))
#define eb emplace_back
template<typename T, typename S> bool chmin(T& a, const S& b) {
return a > b ? a = b, 1 : 0; }
template<typename T, typename S> bool chmax(T& a, const S& b) {
return a < b ? a = b, 1 : 0; }
const int INF = 1e9 + 100;
const ll INFL = 3e18 + 100;
#define i128 __int128_t
  _() { cin.tie(0)->sync_with_stdio(0), cout.tie(0); }
```

hash.sh

```
# 使い方: sh hash.sh -> コピペ -> Ctrl + D
# コメント・空白・改行を削除して md5 でハッシュする
g++ -dD -E -P -fpreprocessed - | tr -d '[:space:]' | md5sum | cut -c-6
```

rnd.hpp

md5: a81b0a

```
ll rnd(ll l, ll r) { //[l, r)
   static mt19937_64
gen(chrono::steady_clock::now().time_since_epoch().count());
   return uniform_int_distribution<ll>(l, r - 1)(gen);
template<typename T> void rndshuf(vector<T>& v) { rep(i, 1,
si(v)) swap(v[i], v[rnd(0, i)]); }
template<class T> vector<T> rvi(int n, T l, T r, bool unique =
false) {
   if(unique) {
      assert(r - l >= n);
      vector<T> res;
      rep(i, n) res.eb(rnd(l, r - n + 1));
      sort(all(res));
      rep(i, n) res[i] += i;
      rndshuf(res);
      return res;
   }
   vector<T> v(n);
   fore(e, v) e = rnd(l, r);
   return v;
```

data-structure

BIT.hpp md5: 5f098b

```
struct BIT {
   vl a;
   BIT(ll n) : a(n + 1) {}
   void add(ll i, ll x) {
      while(i < si(a)) a[i] += x, i += i & -i;
   ll sum(ll r) {
      ll s = 0;
      while(r) s += a[r], r -= r & -r;
      return s;
   ll sum(ll l, ll r) { return sum(r) - sum(l); }
   // minimize i s.t. sum(i) >= w
   int lower_bound(ll w) {
      if(w <= 0) return 0;</pre>
       int x = 0, N = si(a) + 1;
      for(int k = 1 << __lg(N); k; k >>= 1) {
   if(x + k <= N - 1 && a[x + k] < w) {</pre>
             w -= a[x + k];
              x += k;
          }
      }
      return x;
   }
};
```

FastSet.hpp

md5: 9dd1e2

```
using U = uint64_t;
const U B = 64;
struct FS {
   Un;
   vector<vector<U>>> a;
   FS(U n) : n(n) {
      do a.eb(n = (n + B - 1) / B);
      while(n > 1);
   }
   bool operator[](ll i) const { return a[0][i / B] >> (i % B)
& 1; }
   void set(ll i) {
      for(auto& v : a) {
         v[i / B] |= 1ULL << (i % B);
         i /= B;
      }
   }
   void erase(ll i) {
      for(auto& v : a) {
         v[i / B] &= ~(1ULL << (i % B));
         if(v[i / B]) break;
         i /= B;
     }
  }
   ll next(ll i) {
      rep(h, si(a)) {
         i++;
         if(i / B >= si(a[h])) break;
         U d = a[h][i / B] >> (i % B);
         if(d) {
            i += countr_zero(d);
            while(h--) i = i * B + countr_zero(a[h][i]);
            return i;
         }
         i /= B;
      }
      return n;
   }
   ll prev(ll i) {
      rep(h, si(a)) {
         if(i < 0) break;</pre>
         U d = a[h][i / B] << (~i % B);
         if(d) {
            i -= countl_zero(d);
            while(h--) i = i * B + __lg(a[h][i]);
```

```
return i;
}
i /= B;
}
return -1;
}
};
```

Skew-Heap.hpp

md5: 38dad3

```
template<typename T, bool isMin = true> struct SkewHeap {
   struct Node {
      T key, laz;
      Node *1, *r;
      int idx;
      Node() = default;
      Node(const T& k, int i = -1): key(k), laz(0),
l(nullptr), r(nullptr), idx(i) {}
   };
   using P = Node*;
   static void propagate(P x) {
      if(x->laz == 0) return;
      if(x->l) x->l->laz += x->laz;
      if(x->r) x->r->laz += x->laz;
      x \rightarrow key += x \rightarrow laz;
      x \rightarrow laz = 0;
   static P meld(P x, P y) {
      if(!x || !y) return x ? x : y;
      if(!comp(x, y)) swap(x, y);
      propagate(x);
      x->r = meld(x->r, y);
      swap(x->l, x->r);
      return x;
   static P alloc(const T& key, int idx = -1) { return new
Node(key, idx); }
   static P pop(P x) {
      propagate(x);
      return meld(x->l, x->r);
   static P push(P x, const T& key, int idx = -1) { return
meld(x, alloc(key, idx)); }
   static void apply(P x, const T& laz) {
      x->laz += laz;
      propagate(x);
   private:
   static inline bool comp(P x, P y) {
      if constexpr(isMin) {
         return x->key + x->laz < y->key + y->laz;
      } else {
         return x->key + x->laz > y->key + y->laz;
   }
};
```

cht.hpp

md5: a05621

```
template<bool isMin = true> struct CHT {
#define x first
#define y second
   CHT() = default;
   deque<pll> v;
   bool empty() { return v.empty(); }
   void clear() { return v.clear(); }
   inline int sgn(ll x) { return !x ? 0 : (x < 0 ? -1 : 1); }</pre>
   using D = long double;
   inline bool check(const pll& a, const pll& b, const pll& c)
      if(b.y == a.y \text{ or } c.y == b.y) \text{ return } sgn(b.x - a.x) *
sgn(c.y - b.y) >= sgn(c.x - b.x) * sgn(b.y - a.y);
      return D(b.x - a.x) * sgn(c.y - b.y) / D(abs(b.y - a.y))
\rightarrow= D(c.x - b.x) * sgn(b.y - a.y) / D(abs(c.y - b.y));
   }
   void add(ll a, ll b) {
      if(!isMin) a *= -1, b *= -1;
      pll line(a, b);
      if(empty()) v.emplace_front(line);
      else {
         if(ll c = v[0].x; c <= a) {
```

```
if(c == a) {
               if(v[0].y <= b) return;</pre>
               v.pop_front();
            while(si(v) \ge 2 and check(line, v[0], v[1]))
v.pop_front();
            v.emplace_front(line);
         } else {
            assert(a <= v.back().x);
            if(v.back().x == a) {
               if(v.back().y <= b) return;</pre>
               v.pop_back();
            while(si(v) >= 2 and check(v[si(v) - 2], v.back(),
line)) v.pop_back();
            v.emplace_back(line);
     }
   ll get_y(const pll& a, const ll& x) { return a.x * x + a.y;}
   ll query(ll x) {
      assert(!empty());
      int l = -1, r = si(v) - 1;
      while(l + 1 < r) {
         int m = (l + r) >> 1;
         if(get_y(v[m], x) \ge get_y(v[m + 1], x)) l = m;
         else r = m;
      }
      return get_y(v[r], x) * (isMin ? 1 : -1);
   ll query_monotone_inc(ll x) {
      assert(!empty());
      while(si(v) >= 2 and get_y(v[0], x) >= get_y(v[1], x))
v.pop_front();
      return get_y(v[0], x) * (isMin ? 1 : -1);
  ll query_monotone_dec(ll x) {
      assert(!empty());
      while(si(v) >= 2 and get_y(v.back(), x) >= get_y(v.end()
[-2], x)) v.pop_back();
      return get_y(v.back(), x) * (isMin ? 1 : -1);
  }
#undef x
#undef y
};
```

dsu-potential.hpp

md5: 8dcd42

```
class dsup {
   private:
   ll N;
   vector<ll> P; /*親ノード*/
                  /*連結成分のサイズ*/
   vector<ll> S;
   vector<type> W; /*重み*/
   pair<ll, type> root(ll now) {
      if(now != P[now]) {
         pair<ll, type> ret = root(P[now]);
         P[now] = ret.first;
         W[now] += ret.second;
      return {P[now], W[now]};
   }
   public:
   /*1-indexed*/
   dsup(ll n) {
      N = n;
      P = vector < ll > (N + 1);
      for(ll i = 0; i <= N; i++) P[i] = i;</pre>
      S = vector < ll > (N + 1, 1);
      W = \text{vector} < \text{type} > (N + 1, 0);
   }
   /*a+w=bとして連結する*/
   bool merge(ll a, ll b, type w) {
      root(a);
      root(b);
      w += W[a] - W[b];
      a = P[a];
      b = P[b];
      if(a == b) return w == 0;
```

```
Speed Star (The University of Tokyo)
```

```
Page 4 of 30
```

md5: 1893ff

```
if(S[a] <= S[b]) {</pre>
        P[b] = a;
         S[a] += S[b];
        W[b] = w;
      } else {
        P[a] = b;
         S[b] += S[a];
        W[a] -= w;
     return 1;
  }
   /*a,bの連結判定*/
  bool same(ll a, ll b) {
     a = root(a).first;
     b = root(b).first;
     return a == b;
  /*a連結成分のsizeを返す*/
  ll size(ll a) { return S[root(a).first]; }
  /*全ての連結成分を列挙(1-indexed)*/
  vector<vector<ll>> groups(void) {
     map<ll, vector<ll>> m;
      vector<vector<ll>> ret;
      for(ll i = 1; i <= N; i++) m[root(i).first].push_back(i);</pre>
     for(auto e : m) ret.push_back(e.second);
     return ret;
   /*idのpotentialを求める*/
   type get_p(ll id) { return root(id).second; }
dsu.hpp
                                                     md5: 48f8d8
```

```
class unionfind {
   private:
   ll N;
   vector<ll> P;
   vector<ll> S;
   ll root(ll now) {
      if(now != P[now]) P[now] = root(P[now]);
      return P[now];
   }
   public:
   /*1-indexed*/
   unionfind(ll n) {
      N = n;
      P = vector < ll > (N + 1);
      for(ll i = 1; i <= N; i++) P[i] = i;
      S = \text{vector} < ll > (N + 1, 1);
   }
   /*a,bを連結する*/
   void merge(ll a, ll b) {
      a = root(a);
      b = root(b);
      if(S[a] <= S[b]) {
         P[b] = a;
         S[a] += S[b];
      } else {
         P[a] = b;
         S[b] += S[a];
      }
   /*a,bの連結判定*/
   bool same(ll a, ll b) {
      a = root(a);
      b = root(b);
      return a == b;
   /*a連結成分のsizeを返す*/
   ll size(ll a) { return S[root(a)]; }
   /*全ての連結成分を列挙*/
   vector<vector<ll>>> groups(void) {
      map<ll, vector<ll>> m:
      vector<vector<ll>>> ret;
      for(ll i = 1; i <= N; i++) m[root(i)].push_back(i);</pre>
      for(auto e : m) ret.push_back(e.second);
      return ret;
   }
};
```

hash_map.hpp

```
#include <bits/extc++.h>
struct chash {
   const vint64_t C = (ll)(4e18 * acos(0)) | 71;
   ll operator()(ll x) const { return __builtin_bswap64(x * C);
};
using namespace __gnu_pbds;
template<class T, class S> using hash_map = gp_hash_table<T, S,</pre>
chash>;
```

lazy-segtree.hpp

md5: e79596

```
using U = uint64 t:
template<class S, S (*op)(S, S), S (*e)(), class F, S (*mpp)(F,
S), F (*cmpo)(F, F), F (*id)()> struct lazy_segtree {
   lazy_segtree() : lazy_segtree(0) {}
   explicit lazy_segtree(int n) : lazy_segtree(vector<S>(n,
e())) {}
   explicit lazy_segtree(const vector<S>& v) : n(si(v)) {
      s = bit_ceil(U(n));
      log = countr_zero(U(s));
      d = vector < S > (2 * s, e());
      lz = vector<F>(s, id());
      rep(i, n) d[s + i] = v[i];
      per(i, s, 1) update(i);
   }
   void set(int p, S x) {
      p += s;
      PUSH(p);
      d[p] = x;
      rep(i, 1, log + 1) update(p >> i);
   S get(int p) {
      p += s;
      PUSH(p);
      return d[p];
   S prod(int l, int r) {
      if(l == r) return e();
      l += s, r += s;
      per(i, log + 1, 1) {
         if(((l >> i) << i) != l) push(l >> i);
         if(((r >> i) << i) != r) push((r - 1) >> i);
      S sml = e(), smr = e();
      while(l < r) {</pre>
         if(l \& 1) sml = op(sml, d[l++]);
         if(r \& 1) smr = op(d[--r], smr);
         l >>= 1, r >>= 1;
      return op(sml, smr);
   S all_prod() { return d[1]; }
   void apply(int p, F f) {
      // assert(0 <= p && p < n);
      p += s;
      PUSH(p);
      d[p] = mpp(f, d[p]);
      rep(i, 1, log + 1) update(p >> i);
   void apply(int l, int r, F f) {
      // assert(0 <= l && l <= r && r <= _n);
      if(l == r) return;
      l += s, r += s;
      per(i, log + 1, 1) {
         if(((l >> i) << i) != l) push(l >> i);
         if(((r >> i) << i) != r) push((r - 1) >> i);
      int ml = l, mr = r;
      while(l < r) {</pre>
         if(l & 1) all_apply(l++, f);
         if(r & 1) all_apply(--r, f);
         l >>= 1, r >>= 1;
      }
      l = ml, r = mr;
      rep(i, 1, log + 1) {
         if(((l >> i) << i) != l) update(l >> i);
         if(((r >> i) << i) != r) update((r - 1) >> i);
```

```
}
template<class G> int max_right(int l, G g) {
   assert(q(e()));
   if(l == n) return n;
   1 += s:
   PUSH(l);
   S sm = e();
   do {
      while(~l & 1) l >>= 1;
      if(!g(op(sm, d[l]))) {
         while(l < s) {</pre>
            push(l);
            l <<= 1:
            if(g(op(sm, d[l]))) {
               sm = op(sm, d[l]);
               l++;
         return 1 - s;
      sm = op(sm, d[l]);
      1++:
   } while((l & -l) != l);
   return n;
template<class G> int min_left(int r, G g) {
   assert(g(e()));
   if(r == 0) return 0;
   r += s;
   PUSH(r - 1);
   S sm = e();
   do {
      while(r > 1 && r & 1) r >>= 1;
      if(!g(op(d[r], sm))) {
         while(r < s) {</pre>
            push(r);
            r = (2 * r + 1);
            if(g(op(d[r], sm))) {
               sm = op(d[r], sm);
               r--;
            }
         }
         return r + 1 - s;
      }
      sm = op(d[r], sm);
   } while((r & -r) != r);
   return 0;
S operator[](int k) { return get(k); }
int len() { return n; }
private:
int n, s, log;
vector<S> d;
vector<F> lz;
void update(int k) { d[k] = op(d[2 * k], d[2 * k + 1]); }
void all_apply(int k, F f) {
   d[k] = mpp(f, d[k]);
   if(k < s) lz[k] = cmpo(f, lz[k]);
void push(int k) {
   all_apply(2 * k, lz[k]);
   all_apply(2 * k + 1, lz[k]);
void PUSH(int k) { per(i, log + 1, 1) push(k >> i); }
```

li-chao.hpp

md5: ca57d5

```
struct lctree {
    struct line {
        ll a, b;
        line() : a(0), b(INFL) {}
        line(Ll a, Ll b) : a(a), b(b) {}
        ll get(Ll x) { return a * x + b; }
        inline bool over(line r, ll x) { return get(x) <
        r.get(x); }
    };</pre>
```

```
int n;
   vector<ll> x;
   vector<line> seg;
   lctree() {}
   lctree(const vector<ll>& _x): x(_x)  {
      sort(all(x));
      int n2 = si(x);
      n = 1;
      while(n < n2) n <<= 1;</pre>
      x.resize(n);
      rep(i, n2, n) x[i] = x[n2 - 1];
      seg = vector < line > (n * 2);
   void upd(line L, int i, int l, int r) {
      while(true) {
         int mid = l + r >> 1;
         bool lov = L.over(seg[i], x[l]);
         bool rov = L.over(seg[i], x[r - 1]);
         if(lov == rov) {
            if(lov) swap(seg[i], L);
            return;
         bool mov = L.over(seg[i], x[mid]);
         if(mov) swap(seg[i], L);
         if(lov != mov) {
            i = (i << 1), r = mid;
         } else {
            i = (i << 1) + 1, l = mid;
     }
   }
   void upd(line L, unsigned i) {
      int ub = bit_width(i) - 1;
      int l = (n >> ub) * (i - (1 << ub));
      int r = l + (n \gg ub);
      upd(L, i, l, r);
   }
   void update(ll a, ll b) { upd(line(a, b), 1, 0, n); }
   void update_segment(ll l, ll r, ll a, ll b) {
      l = lb(x, l) + n, r = lb(x, r) + n;
      line L(a, b);
      for(; l < r; l >>= 1, r >>= 1) {
         if(l & 1) upd(L, l++);
         if(r & 1) upd(L, --r);
      }
   ll query(ll t) {
      ll k = lb(x, t);
      k += n;
      ll res = seg[k].get(t);
      while(k > 1) {
         k >>= 1:
         chmin(res, seg[k].get(t));
      }
      return res;
  }
};
```

line_container.hpp

md5: b018d9

```
struct Line {
   mutable ll k, m, p;
   bool operator<(const Line& o) const { return k < o.k; }</pre>
   bool operator<(ll x) const { return p < x; }</pre>
};
template<bool ismin = true> struct LineContainer :
multiset<Line. less<>>> {
   // (for doubles, use inf = 1/.0, div(a,b) = a/b)
   const ll inf = LLONG_MAX / 2;
   ll div(ll a, ll b) { // floored division
      return a / b - ((a ^ b) < 0 && a % b);
   }
   bool isect(iterator x, iterator y) {
      if(y == end()) {
         x->p = inf;
         return false;
      if(x->k == y->k) x->p = x->m > y->m ? inf : -inf;
      else x->p = div(y->m - x->m, x->k - y->k);
      return x->p >= y->p;
```

```
Speed Star (The University of Tokyo)

}

void add(ll k, ll m) {
   if(ismin) k = -k, m = -m;
   auto z = insert({k, m, 0}), y = z++, x = y;
   while(isect(y, z)) z = erase(z);
   if(x != begin() && isect(--x, y)) isect(x, y = erase(y));
   while((y = x) != begin() && (--x)->p >= y->p) isect(x,
erase(y));
}

ll query(ll x) {
   auto l = *lower_bound(x);
   ll s = 1;
   if(ismin) s = -1;
   return s * (l.k * x + l.m);
}
};
```

link-cut.hpp

md5: e9b023

```
struct Node {
   typedef Node* NP;
   NP l, r, p;
   bool rev;
   int v, mx, lz;
   Node(): l(NULL), r(NULL), p(NULL), rev(false), v(-inf),
mx(-inf), lz(-inf) {}
   void Propagate() {
      if(rev) {
         swap(l, r);
         if(l) l->rev ^= true;
         if(r) r->rev ^= true;
         rev = false;
      if(l) chmax(l->lz, lz);
      if(r) chmax(r->lz, lz);
      chmax(v, lz);
      chmax(mx, lz);
      lz = -inf;
   int GetMax() { return max(mx, lz); }
   int GetVert() { return max(v, lz); }
   void Update() {
      assert(lz == -inf);
      mx = v:
      if(l) { chmax(mx, l->GetMax()); }
      if(r) { chmax(mx, r->GetMax()); }
   int Pos() {
      if(p && p->l == this) return -1;
      if(p && p->r == this) return 1;
      return 0;
   void Prepare() {
      if(Pos()) p->Prepare();
      Propagate();
   void Rotate() {
      NP q = p, c;
      if(Pos() == 1) {
         c = 1;
         l = p;
         p->r = c;
      } else {
         c = r;
         r = p;
         p \rightarrow l = c;
      }
      if(c) c \rightarrow p = p;
      p = p -> p;
      q->p = this;
      if(p && p->l == q) p->l = this;
      if(p \&\& p->r == q) p->r = this;
      q->Update();
   }
   void Splay() {
      Prepare();
      while(Pos()) {
         int a = Pos(), b = p -> Pos();
         if(b && a == b) p->Rotate();
         if(b && a != b) Rotate();
         Rotate():
      }
```

```
Update();
   }
   void Expose() {
      for(NP x = this; x; x = x->p) x->Splay();
      for(NP x = this; x -> p; x = x -> p) {
         x \rightarrow p \rightarrow r = x;
         x->p->Update();
      }
      Splay();
   }
   void Evert() {
      Expose();
      if(l) {
         l->rev ^= true;
         l = NULL;
         Update();
   void Link(NP x) {
      Evert();
      p = x;
   void Set(int q) {
      Expose();
      r = NULL;
      chmax(lz, q);
   void Cut() {
      Expose();
      assert(l);
      1->p = NULL;
      l = NULL;
      Update();
   int Get() {
      Expose();
      r = NULL;
      Update();
      return GetMax();
   }
};
Node* LCA(Node* a, Node* b) {
   a->Expose();
   b->Expose();
   if(!a->p) { return NULL; }
   Node* d = a;
   while(a->p != b) {
      if(a->Pos() == 0) { d = a->p; }
      a = a - p;
   if(a == b->l) {
      return d;
   } else {
      return b;
```

pbds.hpp md5: a38245

```
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/priority_queue.hpp>
#include <ext/pb_ds/tag_and_trait.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace __gnu_pbds;
// using namespace __gnu_pbds;
template<typename T> using PQ = __gnu_pbds::priority_queue<T,</pre>
greater<T>, __gnu_pbds::rc_binomial_heap_tag>;
using Trie = __gnu_pbds::trie<string,</pre>
                               __gnu_pbds::null_type,
__gnu_pbds::trie_string_access_traits<>,
                               __gnu_pbds::pat_trie_tag,
__gnu_pbds::trie_prefix_search_node_update>;
// not a multiset
// find_by_order(k) -> itr of k-th(0-based) element
// order_of_key(k) -> index of lower_bound(k)
using ordered_set = tree<int, null_type, less<int>,
rb_tree_tag, tree_order_statistics_node_update>;
```

```
#include <ext/rope>
using namespace __gnu_cxx;
```

rbst.hpp

md5: b392ca

```
template<typename T, T (*f)(T, T), T (*e)()> struct RBST {
  inline int rnd() {
      static int x = 123456789;
      static int y = 362436069;
      static int z = 521288629;
      static int w = 88675123;
      t = x ^ (x << 11);
     x = y;
      y = z;
      z = w:
      return w = (w ^ (w >> 19)) ^ (t ^ (t >> 8));
  struct node {
      node *l, *r;
      int cnt;
      T x, sum;
      node() = default;
      node(T x) : x(x), sum(x), l(0), r(0) { cnt = 1; }
  RBST(int n) : pool(n) {}
  int cnt(const node* t) { return t ? t->cnt : 0; }
  T sum(const node* t) { return t ? t->sum : e(); }
  node* update(node* t) {
      t\rightarrow cnt = cnt(t\rightarrow l) + cnt(t\rightarrow r) + 1;
      t\rightarrow sum = f(f(sum(t\rightarrow l), t\rightarrow x), sum(t\rightarrow r));
      return t;
  vector<node> pool;
  int ptr = 0;
  inline node* alloc(const T& v) {
      if(si(pool) == ptr) pool.resize(si(pool) * 2);
      return &(pool[ptr++] = node(v));
  node* merge(node* l, node* r) {
      if(!l or !r) return l ? l : r;
      if(rnd() % (cnt(l) + cnt(r)) < cnt(l)) {
         l->r = merge(l->r, r);
         return update(l);
      r->l = merge(l, r->l);
      return update(r);
  pair<node*, node*> split(node* t, int k) {
      if(!t) return {t, t};
      if(k <= cnt(t->l)) {
         auto [l, r] = split(t->l, k);
         t->l = r
         return {l, update(t)};
      }
      auto [l, r] = split(t->r, k - cnt(t->l) - 1);
      t->r = 1:
      return {update(t), r};
  }
  void insert(node*& t, int k, const T& v) {
      auto [l, r] = split(t, k);
      t = merge(merge(l, alloc(v)), r);
  }
```

segbeats.hpp

md5: 2fbe43

```
struct Segtree_beats {
    ll op(int type, ll x, ll y) { return type ? min(x, y) :
    max(x, y); }
    bool cmp(int type, ll x, ll y) { return type ? x < y : x >
    y; }
    struct alignas(32) Node {
        ll sum = 0;
        ll a1[2] = {}, a2[2] = {-INFL, INFL}, ac[2] = {1, 1}, add
    = 0;
```

```
vector<Node> v;
   ll n, log, e[3] = {-INFL, INFL, 0};
   Segtree_beats() {}
   Segtree_beats(int n) : Segtree_beats(vl(n)) {}
   Segtree_beats(const vl& a) {
      n = 1, log = 0;
      while(n < si(a)) n <<= 1, log++;
      v.resize(2 * n);
      rep(i, si(a)) { v[i + n].sum = v[i + n].a1[0] = v[i + n]
n].a1[1] = a[i]; }
      per(i, n, 1) update(i);
   // 0 : add, 1 : chmin, 2 : chmax, 3 : update
   template<int cmd> void apply(int l, int r, ll x) {
      if(l == r) return;
      l += n, r += n;
      per(i, log + 1, 1) {
         if(((l >> i) << i) != l) push(l >> i);
         if(((r >> i) << i) != r) push((r - 1) >> i);
         int 12 = 1, r2 = r;
         while(l < r) {</pre>
            if(l \& 1) _apply<cmd>(l++, x);
            if(r & 1) _apply<cmd>(--r, x);
            l >>= 1:
            r >>= 1;
         }
         1 = 12;
         r = r2;
      rep(i, 1, log + 1) {
         if(((l >> i) << i) != l) update(l >> i);
         if(((r >> i) << i) != r) update((r - 1) >> i);
   }
   // 0 : max, 1 : min, 2 : sum
   template<int cmd> ll fold(int l, int r) {
      if(l == r) return e[cmd];
      l += n, r += n;
      per(i, log + 1, 1) {
         if(((l >> i) << i) != l) push(l >> i);
         if(((r >> i) << i) != r) push((r - 1) >> i);
      ll lx = e[cmd], rx = e[cmd];
      while(l < r) {</pre>
         if(l & 1) op<cmd>(lx, v[l++]);
         if(r & 1) op<cmd>(rx, v[--r]);
         l >>= 1:
      }
      if constexpr(cmd <= 1) lx = op(cmd, lx, rx);</pre>
      if constexpr(cmd == 2) lx += rx;
      return lx;
   }
   private:
   void update(int k) {
      Node& p = v[k];
      Node& l = v[k * 2 + 0];
      Node& r = v[k * 2 + 1];
      p.sum = l.sum + r.sum;
      rep(t, 2) {
         if(l.a1[t] == r.a1[t]) {
            p.a1[t] = l.a1[t];
            p.a2[t] = op(t, l.a2[t], r.a2[t]);
            p.ac[t] = l.ac[t] + r.ac[t];
         } else {
            bool f = cmp(t, l.a1[t], r.a1[t]);
            p.a1[t] = f ? l.a1[t] : r.a1[t];
            p.ac[t] = f ? l.ac[t] : r.ac[t];
            p.a2[t] = op(t, f ? r.a1[t] : l.a1[t], f ? l.a2[t]
: r.a2[t]);
      }
   }
   void push_add(int k, ll x) {
      Node p = v[k];
      p.sum += x << (log + __builtin_clz(k) - 31);
```

```
Speed Star (The University of Tokyo)
```

```
rep(t, 2) {
         p.a1[t] += x;
         if(p.a2[t] != e[t]) p.a2[t] += x;
      }
      p.add += x;
   }
   void push(int cmd, int k, ll x) {
      Node& p = v[k];
      p.sum += (x - p.a1[cmd]) * p.ac[cmd];
      if(p.a1[cmd ^ 1] == p.a1[cmd]) p.a1[cmd ^ 1] = x;
      if(p.a2[cmd ^{\prime} 1] == p.a1[cmd]) p.a2[cmd ^{\prime} 1] = x;
      p.a1[cmd] = x;
   void push(int k) {
      Node& p = v[k];
      if(p.add) {
         rep(t, 2) push_add(k * 2 + t, p.add);
         p.add = 0;
      rep(t, 2) rep(s, 2) if(cmp(t, v[k * 2 + s].a1[t],
p.a1[t])) push(t, k * 2 + s, p.a1[t]);
   void subtree_ch(int cmd, int k, ll x) {
      if(!cmp(cmd, v[k].a1[cmd], x)) return;
      if(cmp(cmd, x, v[k].a2[cmd])) { return push(cmd, k, x); }
      rep(t, 2) subtree_ch(cmd, k * 2 + t, x);
      update(k);
   template<int cmd> inline void _apply(int k, ll x) {
      rep(i, 2) if(cmd >> i & 1) subtree_ch(i, k, x);
      if constexpr(cmd == 0) push_add(k, x);
   template<int cmd> inline void op(ll& a, const Node& b) {
      if constexpr(cmd <= 1) a = op(cmd, a, b.a1[cmd]);</pre>
      if constexpr(cmd == 2) a += b.sum;
segtree-2d.hpp
                                                      md5: 1301f7
```

```
template<typename T, T (*op)(T, T), T (*e)()> class RangeTree {
   private:
   int n, sz;
   vector<segtree<T, op, e>> seg;
   vector<vector<pll>>> yx;
   vector<pll> sorted;
   void update_(int id, ll x, ll y, T val) {
      id += n - 1;
      int yid = lb(yx[id], pll(y, x));
      seg[id].set(yid, val);
      while(id > 0) {
         id = (id - 1) / 2;
         int yid = lb(yx[id], pll(y, x));
         seg[id].set(yid, val);
      }
   T query(int lxid, int rxid, ll ly, ll ry, int k, int l, int
      if(r <= lxid || rxid <= l) return e();</pre>
      if(lxid <= l && r <= rxid) {</pre>
         int lyid = lb(yx[k], pll(ly, -INFL));
         int ryid = lb(yx[k], pll(ry, -INFL));
         return (lyid >= ryid) ? e() : seg[k].prod(lyid, ryid);
      } else {
         return op(query(lxid, rxid, ly, ry, 2 * k + 1, l, (l +
r) / 2),
                   query(lxid, rxid, ly, ry, 2 * k + 2, (l + r)
/ 2, r));
   }
   nublic:
   // 座標, 点の値
   RangeTree(vector<pll>& cand, vector<T>& val) : n(1),
sz(si(cand)), sorted(sz) {
```

```
while(n < sz) n *= 2;
      rep(i, sz) sorted[i] = {cand[i].first, i};
      sort(all(sorted), [&](pll& a, pll& b) {
         return (a.first == b.first) ? (cand[a.second].second <</pre>
cand[b.second].second) : (a.first < b.first);</pre>
     }):
      yx.resize(2 * n - 1), seg.resize(2 * n - 1);
      rep(i, sz) {
         yx[i + n - 1] = {{sorted[i].second, sorted[i].first}};
         vector<T> arg = {val[sorted[i].second]};
         seg[i + n - 1] = segtree < T, op, e > (arg);
         sorted[i].second = cand[sorted[i].second].second;
      per(i, n - 1, 0) {
         yx[i].resize(si(yx[2 * i + 1]) + si(yx[2 * i + 2]));
         if(yx[i].empty()) continue;
         merge(all(yx[2 * i + 1]), all(yx[2 * i + 2]),
yx[i].begin(), [&](pll& a, pll& b) {
            return (cand[a.first].second ==
cand[b.first].second) ? (a.second < b.second)</pre>
: (cand[a.first].second < cand[b.first].second);
         });
         vector<T> arg((int)yx[i].size());
         rep(j, si(yx[i])) arg[j] = val[yx[i][j].first];
         seg[i] = segtree<T, op, e>(arg);
      rep(i, 2 * n - 1) {
         for(auto& [a, b] : yx[i]) a = cand[a].second;
  }
   void update(ll x, ll y, T val) {
      int id = lb(sorted, pll(x, y));
      return update_(id, x, y, val);
   T query(ll lx, ll ly, ll rx, ll ry) {
      int lxid = lb(sorted, pll(lx, -INFL));
      int rxid = lb(sorted, pll(rx, -INFL));
      return (lxid >= rxid) ? e() : query(lxid, rxid, ly, ry,
0, 0, n);
  }
};
```

md5: f8e201

```
segtree.hpp
template<class S, S (*op)(S, S), S (*e)()> struct segtree {
   segtree(int n) : segtree(vector<S>(n, e())) {}
   segtree(const\ vector<S>\&\ v) : n(si(v)) {
      s = bit_ceil(unsigned(n));
      log = countr_zero(unsigned(s));
      d = vector < S > (2 * s, e());
      rep(i, n) d[s + i] = v[i];
      per(i, s, 1) update(i);
   }
   void set(int p, S x) {
      d[p += s] = x;
      rep(i, 1, log + 1) update(p >> i);
   S prod(int l, int r) const {
      S sml = e(), smr = e();
      l += s, r += s;
      while(l < r) {</pre>
         if(l & 1) sml = op(sml, d[l++]);
         if(r \& 1) smr = op(d[--r], smr);
         l >>= 1, r >>= 1;
      }
      return op(sml, smr);
   S all_prod() const { return d[1]; }
   template<typename F> int max_right(int l, F f) const {
      if(l == n) return n;
      l += s;
      S sm = e();
      do {
         while(~l & 1) l >>= 1;
         if(!f(op(sm, d[l]))) {
            while(l < s) {
               l <<= 1;
               if(f(op(sm, d[l]))) sm = op(sm, d[l++]);
            return 1 - s;
```

```
Speed Star (The University of Tokyo)
         sm = op(sm, d[l++]);
      } while((l & -l) != l);
      return n;
   }
   template<typename F> int min_left(int r, F f) const {
      if(!r) return 0;
      r += s;
      S sm = e():
      do {
        r--:
         while(r > 1 and r & 1) r >>= 1;
         if(!f(op(d[r], sm))) {
            while(r < s) {</pre>
               r = (2 * r + 1);
               if(f(op(d[r], sm))) sm = op(d[r--], sm);
            return r + 1 - s;
         }
         sm = op(d[r], sm);
      } while((r & -r) != r);
      return 0;
   }
   private:
   int n, s, log;
   vector<S> d;
   void update(int k) { d[k] = op(d[k * 2], d[k * 2 + 1]); }
sparse-table-disjoint.hpp
                                                     md5: 198e80
   const F f;
```

```
template<typename T, typename F> struct sptable {
   vector<vector<T>> a;
   vi l;
   sptable(const vector< T> & v, F f) : f(f) {
      int m = 0;
      while((1 << m) <= si(v)) ++m;</pre>
      a.resize(m, vector<T>(si(v), T()));
      rep(i, si(v)) a[0][i] = v[i];
      rep(i, 1, m) {
         int s = 1 << i;
         for(int j = 0; j < si(v); j += s * 2) {
            int t = min(j + s, si(v));
            a[i][t - 1] = v[t - 1];
            per(k, t - 1, j) a[i][k] = f(v[k], a[i][k + 1]);
            if(si(v) <= t) break;</pre>
            a[i][t] = v[t];
            int r = min(t + s, si(v));
            rep(k, t + 1, r) a[i][k] = f(a[i][k - 1], v[k]);
         }
      }
      l.resize(1 << m);
      rep(i, 2, si(l)) l[i] = l[i >> 1] + 1;
   T query(int x, int y) {
      if(x \ge --y) return a[0][x];
      int p = l[x ^ y];
      return f(a[p][x], a[p][y]);
  }
};
```

swag.hpp

md5: 85c3df

```
template<typename T, typename F> struct SWAG {
  using vp = vector<pair<T, T>>;
  vp a, b;
  Ff;
  TI;
  SWAG(F f, T i) : f(f), I(i) {}
  private:
  T get(vp& v) { return empty(v) ? I : v.back().second; }
  void pusha(T x) { a.eb(x, f(x, get(a))); }
  void pushb(T x) { b.eb(x, f(get(b), x)); } // reversed!!
  void rebalance() {
     int n = si(a) + si(b);
     int s0 = n / 2 + (empty(a) ? n & 1 : 0);
     vp v{a};
     reverse(all(v));
```

```
copy(all(b), back_inserter(v));
      a.clear(), b.clear();
      per(i, s0, 0) pusha(v[i].first);
      rep(i, s0, n) pushb(v[i].first);
   T front() { return (a.empty() ? b.front() : a.back()).first;
   T back() { return (b.empty() ? a.front() : b.back()).first;
}
   void pop_front() {
      if(empty(a)) rebalance();
      a.pop_back();
   void pop_back() {
      if(empty(b)) rebalance();
      b.pop_back();
   T query() { return f(get(a), get(b)); }
};
```

wavelet_matrix.hpp

md5: dec827

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```
#define U uint32_t
#define L uint64_t
struct bit_vector {
   static constexpr U w = 64;
   vector<L> block:
   vector<U> count;
   int n, zeros;
   inline U get(U i) const { return U(block[i / w] >> (i % w))
& 1; }
   inline void set(U i) { block[i / w] |= 1LL << (i % w); }</pre>
   bit_vector() {}
   bit_vector(int n) { init(n); }
   void init(int _n) {
      n = zeros = _n;
      block.resize(n / w + 1, 0);
      count.resize(si(block), 0);
   void build() {
      rep(i, 1, si(block)) count[i] = count[i - 1] +
popcount(block[i - 1]);
      zeros = rank0(n);
   inline U rank0(U i) const { return i - rank1(i); }
   inline U rank1(U i) const { return count[i / w] +
popcount(block[i / w] & ((1ULL << i % w) - 1)); }</pre>
template<typename T, const int lg = 31> struct WaveletMatrix {
   int n;
   vector<T> a;
   array<bit_vector, lg> bv;
   WaveletMatrix(const vector<T>& _a) : n(_a.size()), a(_a) {
build2(); }
   void build() {
      rep(i, lg) bv[i] = bit_vector(n);
      vector<T> cur = a, nxt(n);
      per(h, lg, 0) {
         rep(i, n) if(cur[i] >> h & 1) bv[h].set(i);
         bv[h].build();
         array<decltype(begin(nxt)), 2> it{begin(nxt),
begin(nxt) + bv[h].zeros};
         rep(i, n) * it[bv[h].get(i)]++ = cur[i];
         swap(cur, nxt);
      }
      return;
   }
   inline pair<U, U> succ0(int l, int r, int h) const { return
make_pair(bv[h].rank0(l), bv[h].rank0(r)); }
   inline pair<U, U> succ1(int l, int r, int h) const {
      U l0 = bv[h].rank0(l);
      U r0 = bv[h].rank0(r);
```

```
Speed Star (The University of Tokyo)
      U zeros = bv[h].zeros;
      return make_pair(l + zeros - l0, r + zeros - r0);
   }
   T access(U k) const {
      T ret = 0:
      per(h, lg, 0) {
        U f = bv[h].get(k);
         ret |= f ? T(1) << h : 0;
         k = f ? bv[h].rank1(k) + bv[h].zeros : bv[h].rank0(k);
      }
      return ret;
   T kth_smallest(U l, U r, U k) const {
      T res = 0;
      for(int h = lg - 1; h >= 0; --h) {
         U l0 = bv[h].rank0(l), r0 = bv[h].rank0(r);
         if(k < r0 - l0) l = l0, r = r0;
         else {
            k = r0 - 10;
            res |= (T)1 << h;
            l += bv[h].zeros - l0, r += bv[h].zeros - r0;
         }
      return res;
   T kth_largest(int l, int r, int k) { return kth_smallest(l,
r, r - l - k - 1); }
   int range_freq(int l, int r, T upper) {
      if(upper >= (T(1) << lg)) return r - l;
      int ret = 0;
      per(h, lg, 0) {
         bool f = (upper >> h) & 1;
         U l0 = bv[h].rank0(l), r0 = bv[h].rank0(r);
         if(f) {
            ret += r0 - l0;
            l += bv[h].zeros - l0;
            r += bv[h].zeros - r0;
         } else {
            l = 10;
            r = r0;
        }
      }
      return ret;
   }
   int range_freq(int l, int r, T lower, T upper) { return
range_freq(l, r, upper) - range_freq(l, r, lower); }
   array<vector<ll>, lg> sums;
   vector<ll> acc;
   void build2() {
      rep(i, lg) bv[i] = bit_vector(n), sums[i].assign(n + 1,
0):
      acc.resize(si(a) + 1);
      vector<T> cur = a, nxt(n);
      per(h, lg, 0) {
         rep(i, n) if((cur[i] >> h) & 1) bv[h].set(i);
         bv[h].build();
         array<decltype(begin(nxt)), 2> it{begin(nxt),
begin(nxt) + bv[h].zeros};
        rep(i, n) * it[bv[h].get(i)]++ = cur[i];
         swap(cur, nxt);
         rep(i, n) sums[h][i + 1] = sums[h][i] + cur[i];
      rep(i, n) acc[i + 1] = acc[i] + a[i];
   }
   ll bottom_k_sum(int l, int r, int k) {
      ll res = 0;
      per(h, lg, 0) {
         U l0 = bv[h].rank0(l), r0 = bv[h].rank0(r);
         if(k < r0 - l0) {
            l = l0, r = r0;
         } else {
            res += sums[h][r0] - sums[h][l0];
            k = r0 - 10;
            l += bv[h].zeros - l0;
```

r += bv[h].zeros - r0;

}

```
res += sums[0][l + k] - sums[0][l];
    return res;
}

ll top_k_sum(int l, int r, int k) { return acc[r] - acc[l] -
bottom_k_sum(l, r, r - l - k); }
};
#undef U
#undef L
```

dp

d-edge-monge.hpp

md5: 4ab7ee

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```
template<class C, class T = decltype(std::declval<C>().get())>
T incremental_monge_shortest_path(const int n, C init) {
     public:
               C mid;
               C last;
               int prev;
        };
        std::vector<env> nodes;
               int n_ = n;
               int d = 0;
               while(n_ != 0) {
                       n_ /= 2;
                       d += 1;
               }
               nodes.assign(d, {init, init, 0});
        std::vector<T> dp(n + 1, static_cast<T>(0));
        const auto f = [&](const auto& f, const int d, const int r)
-> int {
               auto& [mid, last, prev] = nodes[d];
               const int w = 1 \ll d;
                if((r >> d) \% 2 == 1) {
                        for(int i = std::max(0, r - 2 * w); i != r; i += 1) {
mid.push_back(i); }
                       const int next = r + w \le n ? f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r + w) : r - f(f, d + 1, r +
w:
                        int argmin = prev;
                       dp[r] = dp[argmin] + mid.get();
                        for(int i = prev; i != next;) {
                               mid.pop_front(i);
                               i += 1;
                               const T t = dp[i] + mid.get();
                                if(dp[r] > t) {
                                       dp[r] = t;
                                        argmin = i;
                               }
                       }
                       prev = next;
                        return argmin;
               } else {
                       for(int i = std::max(0, r - 2 * w); i != r; i += 1) {
last.push_back(i); }
                        for(int i = std::max(0, r - 3 * w); i != r - 2 * w; i
+= 1) { last.pop_front(i); }
                       int argmin = prev;
                       for(int i = r - 2 * w; i != r - w;) {
                                last.pop_front(i);
                               i += 1:
                                const T t = dp[i] + last.get();
                               if(dp[r] > t) {
                                       dp[r] = t;
                                        argmin = i;
                               }
                       return argmin;
               }
        };
        for(int i = 1; i != n + 1; i += 1) { f(f, 0, i); }
        return dp[n];
}
namespace golden_section_search_impl {
```

```
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```

```
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```

```
using i64 = std::int64_t;
template<class F, class T = decltype(std::declval<F>()
(std::declval<i64>())), class Compare = std::less<T>>
std::pair<i64, T> golden_section_search(F f, i64 min, i64 max,
Compare comp = Compare()) {
   assert(min <= max);</pre>
   i64 = min - 1, x, b;
   {
      i64 s = 1, t = 2;
      while(t < max - min + 2) { std::swap(s += t, t); }
      x = a + t - s;
      b = a + t;
   T fx = f(x), fy;
   while(a + b != 2 * x) {
      const i64 y = a + b - x;
      if(max < y \mid \mid comp(fx, (fy = f(y)))) {
         b = a;
         a = y;
      } else {
         a = x;
         x = y;
         fx = fy;
      }
   return {x, fx};
} // namespace golden_section_search_impl
using golden_section_search_impl::golden_section_search;
struct cost {
   const vector<ll>* a;
   ll lambda;
   ll cost;
   void pop_front(int l) {}
   void push_back(int r) {}
   ll get() { return lambda + c } // 最小化なら -
};
// k : 使う辺の本数
const auto f = [&](ll l) -> ll {
   auto res = incremental_monge_shortest_path(n + 1, cost{l, 0,
0}) - 1 * (k + 1);
  return res;
// L = - max(|e|) * 3, R = max(|e|) * 3
OUT(golden_section_search(f, L, R, greater<ll>()).se);
```

mo-rollback.hpp

md5: 5737bf

```
struct MoRollBack {
   using ADD = function<void(int)>;
   using REM = function<void(int)>;
   using RESET = function<void()>;
   using SNAP = function<void()>;
   using ROLLBACK = function<void()>;
   int w;
   vector<int> l, r, ord;
   MoRollBack(int n, int q) : w((int)sqrt(n)), ord(q) {
iota(all(ord), 0); }
   void add(int a, int b) { /* [l, r) */
      l.emplace_back(a);
      r.emplace_back(b);
   void run(const ADD& add, const REM& rem, const RESET& reset,
const SNAP& snap, const ROLLBACK& rollback) {
      sort(begin(ord), end(ord), [\&](int a, int b) {
         int ab = l[a] / w, bb = l[b] / w;
         if(ab != bb) return ab < bb;</pre>
         return r[a] < r[b];</pre>
      });
      reset();
      for(auto idx : ord) {
         if(r[idx] - l[idx] < w) {
            rep(i, l[idx], r[idx]) add(i);
            rem(idx);
            rollback():
```

```
}
      int nr = 0, lb = -1;
      for(auto idx : ord) {
         if(r[idx] - l[idx] < w) continue;</pre>
         int b = l[idx] / w;
         if(lb != b) {
             reset():
             lb = b;
             nr = (b + 1) * w;
         while(nr < r[idx]) add(nr++);</pre>
         snap();
per(j, (b + 1) * w, l[idx]) add(j);
         rem(idx);
         rollback();
      }
   }
};
```

mo.hpp

md5: 6ff6db

```
struct Mo {
   int n;
   vector<pii> lr;
   Mo(int n) : n(n) {}
   void add(int l, int r) { lr.eb(l, r); }
   template<typename AL, typename AR, typename EL, typename ER,
   void build(const AL& add_left, const AR& add_right, const
EL& erase_left, const ER& erase_right, const O& out) {
      int q = (int)lr.size();
      int bs = n / min<int>(n, sqrt(q));
      vector<int> ord(q);
      iota(all(ord), 0);
      sort(all(ord), [&](int a, int b) {
         int ab = lr[a].first / bs, bb = lr[b].first / bs;
         if(ab != bb) return ab < bb;</pre>
         return (ab & 1) ? lr[a].second > lr[b].second :
lr[a].second < lr[b].second;</pre>
      });
      int l = 0, r = 0;
      for(auto idx : ord) {
         while(l > lr[idx].first) add_left(--l);
         while(r < lr[idx].second) add_right(r++);</pre>
         while(l < lr[idx].first) erase_left(l++);</pre>
         while(r > lr[idx].second) erase_right(--r);
         out(idx);
      }
   template<typename A, typename E, typename O> void
build(const A& add, const E& erase, const O& out) {
      build(add, add, erase, erase, out);
   }
};
```

monge-incremental-rowmin.hpp

md5: 2cff0f

```
// A[N + 1][N + 1]: Monge が i > j のみ存在しているとき、i(= 0,
..., N)行目の最小値を返す
// f(i, j, v) で、j 行目の最小値が求まっている v を用いて、A[i][j] に
アクセス
template<typename T, typename F> vector<T> monge_rowmin(int n,
const F& f) {
  vector<T> mi(n + 1, numeric_limits<T>::max());
  mi[0] = 0;
   vector<int> amin(n + 1);
   auto check = [&](int i, int j) {
     if(chmin(mi[i], f(i, j, mi))) { amin[i] = j; }
  };
  check(n, 0);
   auto solve = [&](auto&& self, int l, int r) {
     if(r - l == 1) return;
      int mid = l + r \gg 1;
     rep(k, amin[l], amin[r] + 1) check(mid, k);
      self(self, l, mid);
     rep(k, l + 1, mid + 1) check(r, k);
      self(self, mid, r);
  };
   solve(solve, 0, n);
```

md5: 930ca0

```
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   return mi;
```

monotone-minima.hpp

md5: 187a2d

```
// monotone 行列の各行について、最小値を取る場所とその値を返す
template<typename T, typename F> vector<pair<int, T>>
monotone_minima(int h, int w, const F& f) {
  vector<pair<int, T>> dp(h, pair(-1, T()));
  auto rec = [&](auto&& rec, int u, int d, int l, int r) {
    if(u > d) return;
    int mid = u + d >> 1;
    auto& [idx, mi] = dp[mid];
    idx = l, mi = f(mid, l);
    rep(i, l + 1, r + 1) if(chmin(mi, f(mid, i))) idx = i;
    rec(rec, u, mid - 1, l, idx);
    rec(rec, mid + 1, d, idx, r);
  };
  rec(rec, 0, h - 1, 0, w - 1);
  return dp;
}
```

math

ExtGCD.hpp

md5: 88cb1c

```
// returns gcd(a, b) and assign x, y to integers
// s.t. ax + by = gcd(a, b) and |x| + |y| is minimized
ll extgcd(ll a, ll b, ll& x, ll& y) {
    // assert(a >= 0 && b >= 0);
    if(!b) return x = 1, y = 0, a;
    ll d = extgcd(b, a % b, y, x);
    y -= a / b * x;
    return d;
}
ll inv_mod(ll x, ll md) {
    ll y, z;
    extgcd(x, md, y, z);
    return (y % md + md) % md;
}
```

and-or-convolution.hpp

md5: da6157

```
// and / or convolution
template<bool isOR, typename T> void fzt(vector<T>& a, bool inv
= false) {
   int n = si(a);
   int m = __lg(n);
   rep(i, m) {
        rep(b, n) {
        if((b >> i & 1) == isOR) a[b] += a[b ^ 1 << i] * (inv
? -1 : 1);
      }
   }
}</pre>
```

binom.hpp

md5: abc57b

```
constexpr int N = 1e6 + 100;
mint fact[N], ifact[N];
void pre() {
    fact[0] = 1;
    rep(i, 1, N) fact[i] = i * fact[i - 1];
    ifact[N - 1] = fact[N - 1].inv();
    per(i, N - 1, 0) ifact[i] = ifact[i + 1] * (i + 1);
}
mint C(int n, int m) { return (n < m or m < 0 ? 0 : fact[n] *
ifact[m] * ifact[n - m]); }
mint P(int n, int m) { return (n < m or m < 0 ? 0 : fact[n] *
ifact[n - m]); }
mint H(int n, int m) { return (n == 0 and m == 0 ? 1 : C(n + m - 1, m)); }</pre>
```

crt.hpp

md5: 0e9c10

```
// (rem, mod)
pll crt(const vl& b, const vl& c) {
   int n = si(b);
   ll r = 0, m = 1;
```

```
rep(i, n) {
    ll g, im, x;
    g = extgcd(m, c[i], im, x);
    if((b[i] - r) % g) return {0, -1};
    ll tmp = (b[i] - r) / g * im % (c[i] / g);
    r += m * tmp;
    m *= c[i] / g;
}
return {(r % m + m) % m, m};
}
```

```
// x_i=floor((a*i+b)/c), i=0,1,..n-1
// a,c>0, b>=0
ll floor_sum(ll n, ll a, ll b, ll c) {
    if(n == 0) return 0;
    ll res = 0;
    res += n * (n - 1) / 2 * (a / c);
    a %= c;
    res += n * (b / c);
    b %= c;
    if(a == 0) return res;
```

if(h <= top) res -= floor_sum(top - h + 1, c, c * h - (b + 1)

lagrange-hokan.hpp

res += top * n;

1), a) + top - h + 1;

return res:

ll top = (a * (n - 1) + b) / c;

ll h = (b + 1 + c - 1) / c;

floor_sum.hpp

md5: 22b9e3

```
template<typename T> T lagrange_polynomial(const vector<T>& y,
ll t) {
   int n = si(y) - 1;
   if(t <= n) return y[t];
   T ret(0);
   vector<T> dp(n + 1, 1), pd(n + 1, 1);
   rep(i, n) dp[i + 1] = dp[i] * (t - i);
   per(i, n + 1, 1) pd[i - 1] = pd[i] * (t - i);
   rep(i, n + 1) {
        T tmp = y[i] * dp[i] * pd[i] * ifact[i] * ifact[n - i];
        ret -= ((n - i) & 1 ? tmp : -tmp);
   }
   return ret;
}
```

matrix.hpp

md5: 472f21

```
template<typename T> struct M {
   vector<vector<T>> a;
   int n. m:
   M(int n, int m) : n(n), m(m), a(n, vector<T>(m)) {}
   M(int n = 0) : M<T>(n, n) {}
   vector<T>& operator[](int k) { return a[k]; }
   const vector<T>& operator[](int k) const { return a[k]; }
   static M I(int n) {
      M mat(n):
      rep(i, n) mat[i][i] = 1;
      return mat;
   M& operator+=(const M& b) {
      rep(i, n) rep(j, m)(*this)[i][j] += b[i][j];
      return *this;
   M& operator -= (const M& b) {
      rep(i, n) rep(j, m)(*this)[i][j] -= b[i][j];
      return *this;
   M& operator*=(const M& b) {
      int l = b.m;
      vector c(n, vector<T>(l));
      rep(i, n) rep(j, m) rep(k, l) c[i][k] += (*this)[i][j] *
b[j][k];
      a.swap(c);
      return *this;
   M& operator^=(ll k) {
      M b = M::I(n);
```

```
while(k) {
         if(k & 1) b *= *this;
         *this *= *this;
         k >>= 1;
      }
      a.swap(b.a);
      return *this;
   M operator+(const M& b) const { return (M(*this) += b); }
   M operator-(const M& b) const { return (M(*this) -= b); }
   M operator*(const M& b) const { return (M(*this) *= b); }
   M operator^(const M& b) const { return (M(*this) ^= b); }
}:
template<typename T> pair<int, T> GaussElimination(M<T>& a,
bool LE = false) {
   int n = a.n, m = a.m;
   int rank = 0, je = LE ? m - 1 : m;
   mint det = 1;
   rep(j, je) {
      int idx = -1;
      rep(i, rank, n) {
         if(a[i][j].x) {
            idx = i;
            break;
         }
      if(idx == -1) {
         det = 0;
         continue;
      if(rank != idx) {
         det = -det;
         swap(a[rank], a[idx]);
      det *= a[rank][j];
      if(LE && a[rank][j].x != 1) {
         mint coeff = a[rank][j].inv();
         rep(k, j, m) a[rank][k] *= coeff;
      }
      int is = LE ? 0 : rank + 1;
      rep(i, is, n) {
         if(i == rank) continue;
         if(a[i][j].x) {
            mint coeff = a[i][j] / a[rank][j];
            rep(k, j, m) a[i][k] -= a[rank][k] * coeff;
         }
      }
      rank++;
   return make_pair(rank, det);
template<tvpename T> vector<vector<T>> LinearEquation(M<T> a.
vector<T> b) {
   int n = a.n, m = a.m;
   rep(i, n) a[i].eb(b[i]);
   a.m++;
   auto p = GaussElimination(a, true);
   int rank = p.first;
   rep(i, rank, n) {
      if(a[i][m].x != 0) return {};
   vector<vector<T>> res(1, vector<T>(m));
   vi piv(m, -1);
   int j = 0;
   rep(i, rank) {
      while(a[i][j].x == 0) ++j;
      res[0][j] = a[i][m], piv[j] = i;
   }
   rep(j, m) {
      if(piv[j] == -1) {
         vector<T> x(m);
         x[j] = 1;
         rep(k, j) {
            if(piv[k] != -1) x[k] = -a[piv[k]][j];
         res.eb(x);
     }
  }
   return res;
template<typename T> T determinant(M<T> a) {
```

}

```
Page 13 of 30
   int n = a.n;
   T det = 1;
   for(int i = 0; i < n; ++i) {</pre>
     int pivot = i;
      for(int j = i + 1; j < n; ++j) {</pre>
         if(abs(a[j][i]) > abs(a[pivot][i])) pivot = j;
     if(a[pivot][i] == 0) return 0; // 行列が特異行列の場合
      if(i != pivot) {
         swap(a[i], a[pivot]);
         det = -det; // 行を交換すると符号が変わる
     det *= a[i][i];
     T inv = 1 / a[i][i]; // ピボット要素の逆数
     for(int j = i + 1; j < n; ++j) {
         T coeff = a[j][i] * inv;
         for(int k = i; k < n; ++k) { a[j][k] -= coeff * a[i]</pre>
[k]; }
  }
   return det;
prime.hpp
                                                     md5: 94a4a8
template<class T, class U> T pow_mod(T x, U n, T md) {
   T r = 1 \% md;
   x \% = md;
```

while(n) { if(n & 1) r = (r * x) % md;x = (x * x) % md;n >>= 1; } return r; bool is_prime(ll n) { if(n <= 1) return false;</pre> if(n == 2) return true; if(n % 2 == 0) return false; ll d = n - 1;while(d % 2 == 0) d /= 2; for(ll a : {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37}) { if(n <= a) break;</pre> ll t = d; $ll y = pow_mod < i128 > (a, t, n); // over$ while(t != n - 1 && y != 1 && y != n - 1) { y = i128(y) * y % n; // flowt <<= 1: if(y != n - 1 && t % 2 == 0) { return false; } return true; ll pollard_single(ll n) { auto $f = [\&](ll x) \{ return (i128(x) * x + R) % n; \};$ if(is_prime(n)) return n; if(n % 2 == 0) return 2; ll st = 0;while(true) { R = rnd(1, n);st++; ll x = st, y = f(x); while(true) { ll p = gcd((y - x + n), n);if($p == 0 \mid\mid p == n$) break; if(p != 1) return p; x = f(x);y = f(f(y));} } vl factor(ll n) { if(n == 1) return {};

ll x = pollard_single(n);

vl l = factor(x), r = factor(n / x);

if(x == n) return $\{x\}$;

```
Page 14 of 30
```

```
Speed Star (The University of Tokyo)
   return l.insert(end(l), all(r)), l;
primitive-root.hpp
                                                     md5: 4088f5
ll primitive_root(ll p) {
   auto v = factor(p - 1);
   sort(all(v)), v.erase(unique(all(v)), end(v));
   while(true) {
      ll g = rnd(1, p);
      bool ok = true;
      for(auto d : v) {
         ll f = (p - 1) / d;
         if(pow_mod < i128 > (g, f, p) == 1) {
            ok = false;
            break;
         }
      if(ok) return g;
   }
xor-convolution.hpp
                                                     md5: f5168d
template<typename T> void fwt(vector<T>& f, bool inv = false) {
   int n = si(f), m = __lg(n);
   rep(i, m) {
      rep(b, n) {
         if(~b >> i & 1) {
            T x = f[b], y = f[b ^ 1 << i];
            f[b] = x + y, f[b ^ 1 << i] = x - y;
      }
   }
   if(inv) {
      T iz = T(1) / T(si(f));
      fore(e, f) e \star= iz;
   }
graph
bcc.hpp
                                                     md5: 3df588
template<typename G> struct BCC : LL<G> {
   vi used:
   vector<vector<pii>>> bc;
   vector<pii> tmp;
   using L = LL<G>;
   using L::g;
   using L::low;
   using L::ord;
   BCC(G g) : L(g) { build(); }
   void build() {
      used.assign(si(g), 0);
      rep(i, si(used)) if(!used[i]) dfs(i, -1);
```

void dfs(int x, int p) {

if(!used[e]) {

dfs(e, x);

if(e == p) continue;

bc.eb();

if(low[e] >= ord[x]) {

auto p = tmp.back();

bc.back().eb(p);

tmp.pop_back();

while(true) {

if(!used[e] || ord[e] < ord[x]) tmp.eb(minmax(x, e));</pre>

if(p.first == min(x, e) and p.second ==

used[x] = true;

fore(e, g[x]) {

max(x, e)) break;

}

}

```
dijkstra.hpp
                                                    md5: 7df7d3
pair<vector<ll>, vector<int>> Dijkstra(int s, const
vector<vector<pair<int, int>>>& graph) {
   int n = graph.size();
   vector<ll> dist(n, INF);
// 最短距離
   vector<int> bef(n, -1);
// 経路を保存する配列
   priority_queue<pair<ll, int>, vector<pair<ll, int>>,
greater<pair<ll, int>>> hq; // 優先度付きキュー
   dist[s] = 0;
   bef[s] = s;
   hq.push({0, s});
   while(!hq.empty()) {
     ll c = hq.top().first;
      int now = hq.top().second;
     hq.pop();
      // 現在の距離がすでに最短距離より大きければスキップ
      if(c > dist[now]) continue;
      // 隣接ノードを更新
      for(const auto& edge : graph[now]) {
        int to = edge.first;
         ll cost = edge.second;
        if(dist[now] + cost < dist[to]) {</pre>
            dist[to] = dist[now] + cost;
           bef[to] = now;
            hq.push({dist[to], to});
        }
     }
   }
   return {dist, bef};
// 経路の復元
vector<pair<int, int>> DijkstraRest(const vector<int>& bef, int
t) {
   vector<pair<int, int>> ret;
   int now = t:
   while(bef[now] != now) {
     ret.push_back({bef[now], now});
     now = bef[now];
   }
   reverse(ret.begin(), ret.end());
   return ret;
eulerian-trail.hpp
                                                    md5: 5d421d
struct edge {
   int x, y, idx;
vector<edge> eulerian_path(vector<edge> es, int s, bool
directed = false) {
   if(es.empty()) return {};
   int n = 0;
   fore(e, es) chmax(n, max(e.x, e.y) + 1);
   vector<vector<pair<edge, int>>> g(n);
   for(auto& e : es) {
      int p = si(g[e.y]);
      g[e.x].emplace_back(e, p);
      if(!directed) {
        int q = si(g[e.x]) - 1;
         swap(e.x, e.y);
        g[e.x].emplace_back(e, q);
   }
```

vector<edge> ord;

while(st.size()) {

stack<pair<int, edge>> st;

st.emplace(s, edge{-1, -1, -1});

int x = st.top().first; if(empty(g[x])) {

lowlink.hpp

md5: e3987c

```
template<typename G> struct LL {
   int n:
   const G q;
   vi ord, low, arti;
   vector<pii> bridge;
   LL(G g) : n(si(g)), g(g), ord(si(g), -1), low(si(g), -1) {
      int k = 0;
      rep(i, n) {
         if(ord[i] == -1) k = dfs(i, k, -1);
   }
   int dfs(int x, int k, int p) {
      low[x] = (ord[x] = k++);
      int cnt = 0;
      bool is_arti = false, second = false;
      fore(e, g[x]) {
         if(ord[e] == -1) {
            cnt++;
            k = dfs(e, k, x);
            chmin(low[x], low[e]);
            is_arti = (p != -1) && (low[e] >= ord[x]);
            if(ord[x] < low[e]) bridge.eb(minmax(x, e));</pre>
         } else if(e != p or second) {
            chmin(low[x], ord[e]);
         } else {
            second = true;
      is_arti |= p == -1 && cnt > 1;
      if(is_arti) arti.eb(x);
      return k;
};
```

max_matching.hpp

md5: 2ece25

```
struct Matching {
   int n;
   vector<vi> g;
   vi mt;
   vi is_ev, gr_buf;
   vector<pii> nx;
   int group(int x) {
      if(gr_buf[x] == -1 \mid | is_ev[gr_buf[x]] != st) return
gr_buf[x];
     return gr_buf[x] = group(gr_buf[x]);
   }
   void match(int p, int b) {
      int d = mt[p];
      mt[p] = b;
      if(d == -1 || mt[d] != p) return;
      if(nx[p].second == -1) {
         mt[d] = nx[p].first;
         match(nx[p].first, d);
      } else {
         match(nx[p].first, nx[p].second);
         match(nx[p].second, nx[p].first);
   bool arg() {
      is_ev[st] = st;
```

```
gr_buf[st] = -1;
      nx[st] = pii(-1, -1);
      queue<int> q;
      q.push(st);
      while(q.size()) {
         int a = q.front();
         q.pop();
         for(auto b : g[a]) {
             if(b == st) continue;
             if(mt[b] == -1) {
                mt[b] = a;
                match(a, b);
                return true;
             if(is_ev[b] == st) {
                int x = group(a), y = group(b);
                if(x == y) continue;
                int z = -1;
                while(x != -1 || y != -1) {
                   if(y != -1) swap(x, y);
                   if(nx[x] == pii(a, b)) {
                      z = x;
                      break;
                   }
                   nx[x] = pii(a, b);
                   x = group(nx[mt[x]].first);
                for(int v : {group(a), group(b)}) {
                   while(v != z) {
                      q.push(v);
                      is_ev[v] = st;
                      gr_buf[v] = z;
                      v = group(nx[mt[v]].first);
                }
            } else if(is_ev[mt[b]] != st) {
                is_ev[mt[b]] = st;
                nx[b] = pii(-1, -1);
                nx[mt[b]] = pii(a, -1);
                gr_buf[mt[b]] = b;
                q.push(mt[b]);
            }
         }
      }
      return false;
   \label{eq:matching} \verb"Matching" (const vector < vi> & _g) : n(int(_g.size())), g(_g),
mt(n, -1), is_{ev}(n, -1), gr_{buf}(n), nx(n) {
      for(st = 0; st < n; st++)</pre>
         if(mt[st] == -1) arg();
   }
   vector<pii> max_match() {
      vector<pii> res;
      rep(i, n) if(i < mt[i]) res.eb(i, mt[i]);</pre>
      return res:
   }
};
```

maximum-independent-set.hpp

md5: ac1384

```
unsigned ll maximum_independent_set(vector<vi> q) {
   using U = unsigned long long;
   int n = si(g);
   vector<U> nbd(n);
   rep(i, n) fore(e, g[i]) nbd[i] |= 1ULL << e;</pre>
   int best = 0;
   U res = 0:
   auto dfs = [&](auto&& dfs, U now, U rest) -> void {
      pii p(-1, -1);
      while(true) {
         bool upd = 0;
         rep(v, n) {
            if(rest >> v & 1) {
                int d = popcount(nbd[v] & rest);
                if(chmax(p.second, d)) p.first = v;
                if(d <= 1) rest ^= 1ULL << v, rest &= ~nbd[v],</pre>
now \mid = 1ULL << v, upd = 1;
            }
         if(!upd) break;
         p = \{-1, -1\};
```

md5: 651912

```
int a = popcount(now), b = popcount(rest);
    if(chmax(best, a)) res = now;
    if(!b or a + b <= best) return;
    int v = p.first;
    rest &= ~(1ULL << v);
    if(p.second >= 3) dfs(dfs, now, rest);
    now |= 1ULL << v;
    dfs(dfs, now, rest & ~(nbd[v]));
};
U now = 0, rest = (1ULL << n) - 1;
dfs(dfs, now, rest);
return res;
}</pre>
scc.hpp
```

```
template<typename G> struct SCC {
  vector<vi> rg;
  vi comp, ord, used;
  int num; // 連結成分の数
  SCC(G g) : g(g), rg(si(g)), comp(si(g), -1), ord(si(g)),
     rep(i, si(g)) fore(e, g[i]) rg[e].eb(i);
     build();
  };
  int operator[](int k) { return comp[k]; }
  void dfs(int x) {
     if(used[x]) return;
     used[x] = true;
     fore(e, g[x]) if(!used[e]) dfs(e);
     ord.eb(x);
  }
  void rdfs(int x, int cnt) {
     if(comp[x] != -1) return;
     comp[x] = cnt;
     fore(e, rg[x]) if(comp[e] == -1) rdfs(e, cnt);
```

fore(i, ord) if(comp[i] == -1) { rdfs(i, num), num++; }

tecc.hpp

}

void build() {

num = 0;

rep(i, g.size()) dfs(i);

reverse(all(ord));

```
template<typename G> struct TCC : LL<G> {
  using L = LL<G>;
  using L::bridge;
  using L::g;
  using L::low;
  using L::ord;
  vi cmp;
  vector<vi> tree, group;
  void build() {
     cmp.assign(si(g), -1);
      int k = 0;
     rep(i, si(cmp)) if(cmp[i] == -1) dfs(i, -1, k);
      group.resize(k);
     rep(i, si(g)) group[cmp[i]].eb(i);
     tree.resize(k);
     for(auto [a, b] : bridge) {
        tree[cmp[a]].eb(cmp[b]);
        tree[cmp[b]].eb(cmp[a]);
     }
  TCC(const G& g) : L(g) { build(); }
  void dfs(int x, int p, int& k) {
     if(p >= 0 and ord[p] >= low[x]) cmp[x] = cmp[p];
      else cmp[x] = k++;
      fore(e, g[x]) if(cmp[e] == -1) dfs(e, x, k);
  }
```

modint

BarrettReduction.hpp

```
using U = uint64_t;
struct Barret {
   U m, im;
   Barret(U mod) : m(mod), im(-1ULL / m + 1) {}
   U mul(U a, U b) const {
      a *= b:
      U x = ((\_uint128\_t)a * im) >> 64;
      a -= x * m;
      if((ll)a < 0) a += m;</pre>
      return a;
  }
};
constexpr ll mod = 998244353;
static Barret b(mod);
struct mint {
   int x;
   mint(ll x_ = 0) : x((x_ % mod) + mod) {
      if(x \ge mod) x -= mod;
  mint& s(uint xx) { return x = xx < mod ? xx : xx - mod,}
*this; }
   mint operator-() { return mint(-x); }
   mint& operator+=(const mint& r) { return s(x + r.x); }
   mint& operator-=(const mint& r) { return s(x + mod - r.x); }
   mint& operator*=(const mint& r) { return x = b.mul(x, r.x),
*this; }
   mint& operator/=(const mint& r) { return *this *= r.inv(); }
   friend mint operator+(mint l, mint r) { return l += r; }
   friend mint operator-(mint l, mint r) { return l -= r; }
   friend mint operator*(mint l, mint r) { return l *= r; }
   friend mint operator/(mint l, mint r) { return l /= r; }
   mint inv() const { return pow(mod - 2); }
   mint pow(ll b) const {
      mint a = *this, c = 1;
      while(b) {
         if(b & 1) c *= a;
         a *= a;
         b >>= 1;
      }
      return c;
}:
```

modint.hpp

using vm = vector<mint>;

md5: 17c69f

md5: 3db9f2

```
constexpr int mod = 998244353;
struct mint {
   int x;
   mint(ll x_ = 0) : x(x_ % mod) {
      if(x < 0) x += mod;
   mint operator-() {
      auto res = *this;
      res.x = (x ? mod - x : 0);
      return res;
   mint& operator+=(mint r) {
      if((x += r.x) >= mod) x -= mod;
      return *this;
   }
   mint& operator-=(mint r) {
      if((x -= r.x) < 0) x += mod;
      return *this:
   mint& operator*=(mint r) {
      x = 1LL * x * r.x % mod;
      return *this;
   }
   mint& operator/=(mint r) { return *this *= r.inv(); }
   friend mint operator+(mint a, mint b) { return a += b; }
   friend mint operator-(mint a, mint b) { return a -= b; }
   friend mint operator*(mint a, mint b) { return a *= b; }
   friend mint operator/(mint a, mint b) { return a /= b; }
```

```
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for(int i = 0; i < t.size(); i += 2) q[i >> 1] = t[i];
   k >>= 1;
}
return ret + p[0];
}
// a * q = 0
mint kitamasa(ll n, fps q, fps a) {
   if(n < si(a)) return a[n];</pre>
```

auto p = a.pre(si(q) - 1) * q;

return LinearRecurrence(n, q, p);

p.resize(si(q) - 1);

}; Using vm = vector<mint>;

Speed Star (The University of Tokyo)

mint a = *this, c = 1;

if(b & 1) c *= a;

mint pow(ll b) const {

while(b) {

return c;

a *= a;

b >>= 1:

mint inv() const { return pow(mod - 2); }

FPS

}

FFT.hpp md5: f769b5

```
mint g = 3; // 原始根
void fft(vm& a, bool inv = false) {
   int n = si(a), s = __lg(n);
   static vm z, iz;
   while(si(z) <= s) {</pre>
      z.eb(g.pow(mint(-1).x / (1 << si(z))));
      iz.eb(z.back().inv());
   }
   vm b(n);
   rep(i, 1, s + 1) {
      int w = 1 << s - i;
      mint base = inv ? iz[i] : z[i], now = 1;
      for(int y = 0; y < n / 2; y += w) {
         rep(x, w) {
            auto l = a[y << 1 | x], r = now * a[y << 1 | x |
w];
            b[y \mid x] = l + r, b[y \mid x \mid n >> 1] = l - r;
         now *= base;
      }
      swap(a, b);
   }
vm mul(vm a, vm b) {
   int n = si(a), m = si(b);
   if(!n or !m) return {};
   if(min(n, m) <= 30) {
      vm ans(n + m - 1);
      rep(i, n) rep(j, m) ans[i + j] += a[i] * b[j];
      return ans;
   int N = n + m - 1;
   int z = bit_ceil(unsigned(N));
   a.resize(z), b.resize(z);
   fft(a), fft(b);
   rep(i, z) a[i] *= b[i];
   fft(a, true);
   a.resize(n + m - 1):
   mint iz = mint(z).inv();
   fore(e, a) e *= iz;
   return a;
```

linear-recurrence.hpp

md5: 7ef16a

```
// [x ^ k] p / q
mint LinearRecurrence(ll k, fps q, fps p) {
   q.shrink();
   mint ret = 0;
   if(si(p) >= si(q)) {
      auto r = p / q;
      p -= r * q;
      p.shrink();
      if(k < r.size()) ret += r[k];</pre>
   if(p.size() == 0) return ret;
   p.resize(q.size() - 1);
   while(k) {
      auto q2 = q;
      for(int i = 1; i < q2.size(); i += 2) q2[i] = -q2[i];</pre>
      auto s = p * q2, t = q * q2;
      for(int i = (k \& 1); i < s.size(); i += 2) p[i >> 1] =
s[i];
```

poly.hpp md5: 8da6ee

```
struct fps {
   vm v;
   fps(const vm& v = \{\}) : v(v) \{\}
   fps(int n) : v(n) {}
   void shrink() {
      while(v.size() && !v.back().x) v.pop_back();
  }
   void resize(int n) { v.resize(n); }
   int size() const { return int(v.size()); }
   mint freq(int p) const { return (p < size()) ? v[p] : 0; }</pre>
   mint& operator[](int k) { return v[k]; }
   void emplace_back(mint x) { v.eb(x); }
   fps pre(int le) const { return {{v.begin(), v.begin() +
min(size(), le)}}; }
   fps operator-() const {
      vm res{v};
      fore(e, res) e = -e;
      return res;
   fps operator+(const fps& r) const {
      auto n = max(size(), r.size());
      vm res(n);
      rep(i, n) res[i] = freq(i) + r.freq(i);
      return res:
   }
   fps operator-(const fps& r) const { return (*this) + (-r); }
   fps operator*(const fps& r) const { return {mul(v, r.v)}; }
   fps operator*(const mint& r) const {
      int n = size();
      vm res(n);
      for(int i = 0; i < n; i++) res[i] = v[i] * r;
      return res:
   }
   fps operator/(const mint& r) const { return *this * r.inv();
}
   fps operator/(const fps& r) const {
      if(size() < r.size()) return {{}};</pre>
      int n = size() - r.size() + 1;
      return (rev().pre(n) * r.rev().inv(n)).pre(n).rev();
   fps operator%(const fps& r) const { return *this - *this / r
* r; }
   fps operator<<(int s) const {</pre>
      vm res(size() + s);
      rep(i, size()) res[i + s] = v[i];
      return res:
   fps operator>>(int s) const {
      if(size() <= s) return fps();</pre>
      vm res(size() - s);
      rep(i, size() - s) res[i] = v[i + s];
      return res;
  fps& operator+=(const fps& r) { return *this = *this + r; }
   fps& operator-=(const fps& r) { return *this = *this - r; }
   fps& operator*=(const fps& r) { return *this = *this * r; }
   fps& operator*=(const mint& r) { return *this = *this * r; }
   fps& operator/=(const fps& r) { return *this = *this / r; }
   fps& operator/=(const mint& r) { return *this = *this / r; }
   fps& operator%=(const fps& r) { return *this = *this % r; }
   fps& operator<<=(int n) { return *this = *this << n; }</pre>
   fps& operator>>=(int n) { return *this = *this >> n; }
   fps rev(int n = -1) const {
      vm res = v;
      if(n != -1) res.resize(n);
      reverse(res.begin(), res.end());
      return res;
```

```
Speed Star (The University of Tokyo)
   fps diff() const {
      vm res(max(0, size() - 1));
      rep(i, 1, size()) res[i - 1] = freq(i) * i;
      return res;
   fps integ() const {
      vm res(size() + 1);
      rep(i, size()) res[i + 1] = freq(i) / (i + 1);
      return res;
   // f * f.inv() = 1 + g(x)x^m
   fps inv(int m) const {
      fps res = fps(vm{mint(1) / freq(0)});
      for(int i = 1; i < m; i *= 2) { res = (res * mint(2) -
res * res * pre(2 * i)).pre(2 * i); }
      return res.pre(m);
   fps exp(int n) const {
      assert(freq(0).x == 0);
      fps g = fps(vm{1});
      fps(vm{1}) - g.log(i * 2))).pre(i * 2); }
      return g.pre(n);
   fps log(int n) const {
      assert(freq(0).x == 1);
      auto f = pre(n);
      return (f.diff() * f.inv(n - 1)).pre(n - 1).integ();
   fps sqrt(int n) const {
      assert(freq(0).x == 1);
      fps f = pre(n + 1);
      fps g({1});
      for(int i = 1; i < n; i *= 2) { g = (g + f.pre(2 * i) *
g.inv(2 * i)) * mint((mod + 1) / 2); }
     return g.pre(n + 1);
   fps pow(ll k, ll n) {
      if(k == 0) {
        fps res(n);
        res[0] = 1;
        return res;
      }
      rep(i, size()) {
         if((*this)[i].x) {
           mint rev = mint(1) / (*this)[i];
            fps ret = (((*this * rev) >> i).log(n) *
mint(k)).exp(n);
           ret *= (*this)[i].pow(k);
           ret = (ret << (i * k)).pre(n);
           if(ret.size() < n) ret.resize(n);</pre>
           return ret:
        if(i128(i + 1) * k >= n) return fps(n);
      }
      return fps(n);
   fps pow_mod(ll n, const fps& mod) {
      fps x = *this, r = {\{1\}};
```

relaxed-convolution.hpp

x = x * x % mod;

if(n & 1) r = r * x % mod;

while(n) {

return r:

}

}

n >>= 1;

md5: f1c765

```
struct relaxed_multiplication {
  vector<mint> f, g, h;

// fg_prefix_ntts[d] = (NTTs of first 2^d terms of f and g)
  vector<pair<vector<mint>, vector<mint>>>> fg_prefix_ntts;

const auto& get_fg_prefix_ntt(int d) {
   while(int(fg_prefix_ntts.size()) <= d) {
      int fftlen = 1 << fg_prefix_ntts.size();
      vector<mint> vf(f.begin(), f.begin() + fftlen);
      vector<mint> vg(g.begin(), g.begin() + fftlen);
```

```
Page 18 of 30
         ntt(vf, false), ntt(vg, false);
         fg_prefix_ntts.emplace_back(vf, vg);
      return fg_prefix_ntts[d];
   relaxed_multiplication() {}
   mint add(const mint& f_i, const mint& g_i) {
      f.push_back(f_i), g.push_back(g_i);
      const int n = f.size(), d = __builtin_ctz(n), D = 1 << d;</pre>
      if(int gsz = n - 1 + D; h.size() < gsz) h.resize(gsz);</pre>
      if(n == D) {
         // Convolve f[0, D) * g[0, D) -> h[D - 1, D * 2 - 1)
         const auto& [nttf, nttg] = get_fg_prefix_ntt(d);
         vector<mint> tmp(nttf.size());
         for(int i = 0; i < nttf.size(); ++i) tmp[i] = nttf[i]</pre>
* nttg[i];
         ntt(tmp, true);
         for(int i = 0; i < n - 1; ++i) h[n + i] += tmp[i] -
h[i]; // 回り込みを削除
         h[n - 1] += tmp[n - 1];
      } else {
         // Convolve f[0, 2 * D) * g[n - D, n) -> h[n - 1, n -
1 + D
         if(d <= 4) { // Bruteforce threshold</pre>
            for(int i = n - D; i < n; ++i) {</pre>
               for(int k = n - 1; k < n - 1 + D; ++k) { h[k] +=
f[i] * g[k - i] + f[k - i] * g[i]; }
            }
         } else {
            vector<mint> tmpf{f.end() - D, f.end()},
tmpg{g.end() - D, g.end()};
            tmpf.resize(D * 2), tmpg.resize(D * 2);
            ntt(tmpf, false), ntt(tmpg, false);
            const auto& [nttf, nttg] = get_fg_prefix_ntt(d +
1);
            for(int i = 0; i < tmpf.size(); ++i) { tmpf[i] =</pre>
tmpf[i] * nttg[i] + tmpg[i] * nttf[i]; }
            ntt(tmpf, true);
            for(int i = 0; i < D; ++i) h[n - 1 + i] += tmpf[D - 1]
1 + i];
      return h[n - 1];
  }
};
```

tree

block-cut-tree.hpp

md5: bf0113

```
struct extended_block_cut_tree {
   int N, cnt;
   vector<vector<int>> G;
   extended_block_cut_tree(vector<vector<int>>& E) {
      N = E.size();
      vector<int> next(N, -1);
      vector<int> d(N, -1);
      vector<int> imos(N, 0);
      for(int i = 0; i < N; i++) {</pre>
         if(d[i] == -1) {
            d[i] = 0;
            dfs1(E, next, d, imos, i);
         }
      }
      cnt = 0;
      G.resize(N + 1);
      vector<bool> used(N, false);
      for(int i = 0; i < N; i++) {</pre>
         if(d[i] == 0) { dfs2(E, d, imos, used, cnt, i); }
         if(E[i].empty()) {
            G[i].push_back(N + cnt);
            G[N + cnt].push_back(i);
```

```
Speed Star (The University of Tokyo)
```

```
Page 19 of 30
```

```
G.push_back({});
         }
      }
      G.pop_back();
   }
   void dfs1(vector<vector<int>& E, vector<int>& next,
vector<int>& d, vector<int>& imos, int v) {
      for(int w : E[v]) {
         if(d[w] == -1) {
            d[w] = d[v] + 1;
            next[v] = w;
            dfs1(E, next, d, imos, w);
            imos[v] += imos[w];
         } else if(d[w] < d[v] - 1) {</pre>
            imos[v]++;
            imos[next[w]]--;
      }
   }
   void dfs2(vector<vector<int>>& E, vector<int>& d,
vector<int>& imos, vector<bool>& used, int b, int v) {
      used[v] = true;
      bool ok = false;
      for(int w : E[v]) {
         if(d[w] == d[v] + 1 \&\& !used[w]) {
            if(imos[w] > 0) {
               if(!ok) {
                  ok = true;
                  G[v].push_back(N + b);
                  G[N + b].push_back(v);
               dfs2(E, d, imos, used, b, w);
            } else {
               G[v].push_back(N + cnt);
               G[N + cnt].push_back(v);
               cnt++;
               G.push_back({});
               dfs2(E, d, imos, used, cnt - 1, w);
            }
         }
      }
      if(!ok \&\& d[v] > 0) {
         G[v].push_back(N + b);
         G[N + b].push_back(v);
   int size() { return G.size(); }
   vector<int>& operator[](int v) { return G[v]; }
```

hld.hpp

md5: fa40a1

```
template<typename G> struct HLD {
  int n;
  G& g;
  vector<int> sub, in, out, head, rev, par, d;
  HLD(G\& g) : n(si(g)), g(g), sub(n), in(n), out(n), head(n),
rev(n), par(n), d(n) {}
   void dfs1(int x, int p) {
      par[x] = p;
      sub[x] = 1;
      if(g[x].size() and g[x][0] == p) swap(g[x][0],
g[x].back());
      fore(e, g[x]) {
         if(e == p) continue;
         d[e] = d[x] + 1;
         dfs1(e, x);
         sub[x] += sub[e];
         if(sub[g[x][0]] < sub[e]) swap(g[x][0], e);
     }
  }
  void dfs2(int x, int p, int& t) {
      in[x] = t++;
      rev[in[x]] = x;
      fore(e, g[x]) {
         if(e == p) continue;
         head[e] = (g[x][0] == e ? head[x] : e);
         dfs2(e, x, t);
      out[x] = t;
```

```
void build() {
      int t = 0;
      head[0] = 0;
      dfs1(0, -1);
      dfs2(0, -1, t);
   int la(int v, int k) {
      while(1) {
         int u = head[v];
         if(in[v] - k >= in[u]) return rev[in[v] - k];
         k = in[v] - in[u] + 1;
         v = par[u];
      }
   }
   int lca(int u, int v) {
      for(;; v = par[head[v]]) {
         if(in[u] > in[v]) swap(u, v);
         if(head[u] == head[v]) return u;
   }
   template<typename T, typename Q, typename F>
  T query(int u, int v, const T& e, const Q& q, const F& f,
bool edge = false) {
      Tl = e, r = e;
      for(;; v = par[head[v]]) {
         if(in[u] > in[v]) swap(u, v), swap(l, r);
         if(head[u] == head[v]) break;
         l = f(q(in[head[v]], in[v] + 1), l);
      return f(f(q(in[u] + edge, in[v] + 1), l), r);
   }
   int dist(int u, int v) { return d[u] + d[v] - 2 * d[lca(u, v)]
v)]; }
   int jump(int s, int t, int i) {
      if(!i) return s;
      int l = lca(s, t);
      int dst = d[s] + d[t] - d[l] * 2;
      if(dst < i) return -1;</pre>
      if(d[s] - d[l] >= i) return la(s, i);
      i -= d[s] - d[l];
      return la(t, d[t] - d[l] - i);
  }
};
```

flow

| bipartite-matching.hpp

```
md5: 2ffb05
```

```
struct Bimatch {
   vector<vi> g;
   vi d, mc, used, vv;
   void add(int u, int v) { g[u].eb(v); }
   void bfs() {
     d.assign(si(g), -1);
     queue<int> q;
     rep(i, si(g)) {
        if(!used[i]) {
           q.emplace(i);
           d[i] = 0;
        }
     }
     while(!q.empty()) {
        int x = q.front();
        q.pop();
        fore(e, g[x]) {
           int c = mc[e];
           if(c >= 0 \text{ and } d[c] == -1) {
              d[c] = d[x] + 1;
              q.emplace(c);
           }
     }
  }
  bool dfs(int x) {
     vv[x] = true;
     fore(e, g[x]) {
        int c = mc[e];
        if(c < 0 or (!vv[c] and d[c] == d[x] + 1 and dfs(c)))
```

```
Speed Star (The University of Tokyo)
            mc[e] = x;
            used[x] = true;
            return true;
         }
      }
      return false;
   }
   int match() {
      int ret = 0;
      while(true) {
         bfs();
         vv.assign(si(g), false);
         int f = 0;
         rep(i, si(g)) if(!used[i] and dfs(i)) f++;
         if(!f) return ret;
         ret += f;
      }
  }
flow.hpp
                                                      md5: e99393
template<typename T> struct Dinic {
   const T INF:
   struct edge {
      int to;
      T can:
      int rev;
      bool isrev:
      int idx;
   vector<vector<edge>> g;
   vector<int> c, iter;
   Dinic(int V) : INF(numeric_limits<T>::max()), g(V) {}
   void add_edge(int from, int to, T cap, int idx = -1) {
      g[from].emplace_back((edge){to, cap, si(g[to]), false,
      g[to].emplace_back((edge){from, 0, si(g[from]) - 1, true,
idx});
  }
   bool bfs(int s, int t) {
      c.assign(si(g), -1);
      queue<int> q;
      c[s] = 0;
      q.push(s);
      while(!q.empty() && c[t] == -1) {
         int x = q.front();
         q.pop();
         fore(e, g[x]) {
            if(e.cap > 0 && c[e.to] == -1) {
               c[e.to] = c[x] + 1;
               q.push(e.to);
         }
      }
      return c[t] != -1;
   T dfs(int x, int t, T flow) {
      if(x == t) return flow;
      for(int& i = iter[x]; i < si(g[x]); i++) {</pre>
         edge& e = g[x][i];
         if(e.cap > 0 \& c[x] < c[e.to]) {
            T d = dfs(e.to, t, min(flow, e.cap));
            if(d > 0) {
               e.cap -= d;
               g[e.to][e.rev].cap += d;
               return d:
         }
      }
      return 0;
```

T max_flow(int s, int t) {

while(bfs(s, t)) {

iter.assign(si(g), 0);

T flow = 0;

T f = 0;

```
Page 20 of 30
         while((f = dfs(s, t, INF)) > 0) flow += f;
      }
      return flow;
   }
   // void output() {
          for(int i = 0; i < g.size(); i++) {
   //
              for(auto &e : g[i]) {
   //
                  if(e.isrev) continue;
  //
                  auto &rev_e = g[e.to][e.rev];
                  cout << i << "->" << e.to << " (flow: " <<
  //
rev_e.cap << "/" << e.cap + rev_e.cap << ")" << endl;
   //
          }
   //
   // }
```

lower-upper-bound-flow.hpp

md5: 278a5a

```
template<tvpename T> struct lrFlow {
   Dinic<T> flow;
   vector<T> in, up;
   int X, Y, n;
   T sum:
   typename Dinic<T>::edge *p, *q;
   lrFlow(int n) : n(n), X(n), Y(n + 1), sum(0), in(n), flow(n)
+ 2) {}
   void add_edge(int from, int to, T low, T high) {
      flow.add_edge(from, to, high - low, si(up));
      in[from] -= low, in[to] += low;
      up.eb(high);
   }
   void build() {
      rep(i, n) {
         if(in[i] > 0) {
            flow.add_edge(X, i, in[i]);
            sum += in[i];
         } else if(in[i] < 0) {</pre>
            flow.add_edge(i, Y, -in[i]);
     }
   }
   bool can_flow(int s, int t) {
      flow.add_edge(t, s, flow.INF);
      p = &flow.g[t].back();
      q = &flow.g[s].back();
      return can_flow();
   bool can_flow() {
      build();
      auto ret = flow.max_flow(X, Y);
      return ret >= sum;
   }
   T max_flow(int s, int t) {
      if(can_flow(s, t)) {
         return flow.max_flow(s, t);
      } else {
         return -1;
   }
   T min_flow(int s, int t) {
      if(can flow(s, t)) {
         auto ret = flow.INF - p->cap;
         p->cap = q->cap = 0;
         return ret - flow.max_flow(t, s);
      } else {
         return -1;
      }
   }
   // void output(int M) {
          vector<flow_t> ans(M);
   //
   //
          for(int i = 0; i < flow.graph.size(); i++) {</pre>
   //
              for(auto &e : flow.graph[i]) {
   //
                  if(!e.isrev && \sime.idx) ans[e.idx] = up[e.idx]
```

```
- e.cap;
   //   }
   //   }
   //   for(auto &p : ans) cout << p << endl;
   // }
};</pre>
```

mcf.hpp md5: 96eeaa

```
struct MCF {
   struct edge {
      int to;
      ll cap, cost;
      int rev;
      bool isrev;
   vector<vector<edge>> g;
   vl pot, cost;
   vi pv, pe;
   MCF(int n) : g(n) {}
   void add(int u, int v, ll cap, ll cost) {
      g[u].eb(v, cap, cost, si(g[v]), false);
      g[v].eb(u, 0, -cost, si(g[u]) - 1, true);
   ll mcf(int s, int t, ll f) {
      int n = si(g);
      ll ret = 0;
      using P = pair<ll, int>;
      priority_queue<P, vector<P>, greater<P>>> pq;
      pot.assign(n, 0), pe.assign(n, -1), pv.assign(n, -1);
      while(f) {
         cost.assign(n, INFL);
         pq.emplace(0, s);
         cost[s] = 0;
         while(!pq.empty()) {
            auto [c, x] = pq.top();
            pq.pop();
            if(cost[x] < c) continue;</pre>
            rep(i, si(g[x])) {
               edge\& e = g[x][i];
               ll\ ncost = cost[x] + e.cost + pot[x] -
pot[e.to];
               if(e.cap and chmin(cost[e.to], ncost)) {
                  pv[e.to] = x, pe[e.to] = i;
                  pq.emplace(cost[e.to], e.to);
            }
         if(cost[t] == INFL) return -1;
         rep(i, n) pot[i] += cost[i];
         ll addflow = f;
         for(int v = t; v != s; v = pv[v]) chmin(addflow,
g[pv[v]][pe[v]].cap);
         f -= addflow;
         ret += addflow * pot[t];
         for(int v = t; v != s; v = pv[v]) {
            auto& e = g[pv[v]][pe[v]];
            e.cap -= addflow;
            g[v][e.rev].cap += addflow;
         }
      }
      return ret;
   }
```

二部グラフ.md

|| サイズ | 構成||最大マッチング| |M| || |最小点被覆| |M| | L 到達不可能 + R 到達可能 | 最大安定集合| |V|-|M| | 上の補グラフ||最小辺被覆| 孤立点がないなら |V|-|M| | 最大マッチング + 含まれない点 greedy|

燃やす埋める.md

変形前の制約	変形後の制約
x が 0 のとき z 失う	(x,T,z)
x が 0 のとき z 得る	無条件で z 得る; (S,x,z)

変形前の制約	変形後の制約
xが 1 のとき z 失う	(S,x,z)
x が 1 のとき z 得る	無条件で z 得る; (x,T,z)
x,y,\dots がすべて 0 のとき z 得る	無条件で z 得る; $(S,w,z),(w,x,\infty),(w,y,\infty)$
x,y,\dots がすべて 1 のとき z 得る	無条件で z 得る; $(w,T,z),(x,w,\infty),(y,w,\infty)$

string

KMP.hpp

md5: 886c63

md5: 5882fb

```
// kmp[i] := max{ l ≤ i | s[:l] == s[(i+1)-l:i+1] }
// abacaba -> 0010123
auto KMP(string s) {
    vector<ll> p(sz(s));
    rep(i, 1, sz(s)) {
        ll g = p[i - 1];
        while(g && s[i] != s[g]) g = p[g - 1];
        p[i] = g + (s[i] == s[g]);
    }
    return p;
}
```

Manacher.hpp

```
// 各位置での回文半径を求める
// aaabaaa -> 1214121
// 偶数長の回文を含めて直径を知るには, N+1 個の $ を挿入して 1 を引く
// $a$a$a$b$a$a$a$ -> 123432181234321
auto manacher(string s) {
  ll n = sz(s), i = 0, j = 0;
  vector<ll> r(n);
   while(i < n) {</pre>
     while(i >= j && i + j < n && s[i - j] == s[i + j]) j++;
     r[i] = j;
     ll k = 1;
     while(i >= k && i + k < n && k + r[i - k] < j) {
        r[i + k] = r[i - k];
        k++;
     }
     i += k, j -= k;
  }
  return r;
```

RollingHash.hpp

md5: b0e4a8

```
const ll mod = (1LL << 61) - 1;</pre>
ll add(ll a, ll b) { return (a += b) >= mod ? a - mod : a; }
ll mul(ll a, ll b) {
   i128 c = (i128)a * b;
   return add(c >> 61, c & mod);
11 r = 7954398468495;
struct RH {
  ll n;
   vl hs, pw;
   RH(string s) : n(si(s)), hs(n + 1), pw(n + 1, 1) {
      rep(i, n) {
         pw[i + 1] = mul(pw[i], r);
         hs[i + 1] = add(mul(hs[i], r), s[i]);
      }
   ll get(ll l, ll r) const { return add(hs[r], mod -
mul(hs[l], pw[r - l])); }
   int lcp(int i, int j) {
      int ok = 0, ng = min(n - i, n - j) + 1;
      while(ok < ng - 1) {</pre>
         int mid = ok + ng >> 1;
         (get(i, i + mid) == get(j, j + mid) ? ok : ng) = mid;
      return ok;
  }
```

```
md5: deae26
```

```
// returns pair{sa, lcp}
// sa 長さ n : s[sa[0]:] < s[sa[1]:] < ... < s[sa[n-1]:]
// lcp 長さ n-1 : lcp[i] = LCP(s[sa[i]:], s[sa[i+1]:])
auto SA(string s) {
   ll n = si(s) + 1, lim = 256;
   // assert(lim > ranges::max(s));
   vector<ll> sa(n), lcp(n), x(all(s) + 1), y(n), ws(max(n, s))
lim)), rk(n);
   iota(all(sa), 0);
   for(ll j = 0, p = 0; p < n; j = max(1LL, j * 2), lim = p) {
      p = j;
      iota(all(y), n - j);
      rep(i, 0, n) if(sa[i] >= j) y[p++] = sa[i] - j;
      fill(all(ws), 0);
      rep(i, 0, n) ws[x[i]] ++;
      rep(i, 1, lim) ws[i] += ws[i - 1];
      for(ll i = n; i--;) sa[--ws[x[y[i]]]] = y[i];
      swap(x, y);
      p = 1:
      x[sa[0]] = 0;
      rep(i, 1, n) {
         ll a = sa[i - 1], b = sa[i];
         x[b] = (y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1
      }
   rep(i, 1, n) rk[sa[i]] = i;
   for(ll i = 0, k = 0; i < n - 1; lcp[rk[i++]] = k) {
      if(k) k--;
      while(s[i + k] == s[sa[rk[i] - 1] + k]) k++;
   sa.erase(begin(sa));
   lcp.erase(begin(lcp));
   return pair{sa, lcp};
```

Zalgorithm.hpp

md5: d3bdab

```
template<typename T> vi z_algorithm(const vector<T>& s) {
   int n = si(s), l = -1, r = -1;
   vi z(n, n);
   rep(i, 1, n) {
      int& x = z[i] = i < r ? min<ll>(r - i, z[i - l]) : 0;
      while(i + x < n and s[i + x] == s[x]) x++;
      if(i + x > r) l = i, r = i + x;
   }
   return z;
}
```

enumerate-runs.hpp

md5: aec96b

```
// (length, l, r)
template<typename T> vector<array<int, 3>> enum_runs(const
vector<T>& s) {
   int n = si(s);
   vector<array<int, 3>> res;
   auto dfs = [\&](auto\&\& f, int l, int r) -> void {
      if(r - l <= 1) return;</pre>
      int m = l + r >> 1;
      f(f, l, m), f(f, m, r);
      vector<T> sl(s.rbegin() + n - m, s.rbegin() + n - l);
      sl.insert(sl.end(), s.rbegin() + n - r, s.rbegin() + n -
ι);
      vector<T> sr(s.begin() + m, s.begin() + r);
      sr.insert(sr.end(), s.begin() + l, s.begin() + r);
      auto zsl = z_algorithm(sl), zsr = z_algorithm(sr);
      rep(t, 1, m - l + 1) {
         int ml = max<ll>(l, m - t - zsl[t]), mr = min(r, m +
zsr[r - l - t]);
         if(mr - ml >= 2 * t and (ml == 0 or s[ml - 1] != s[ml
+ t - 1) and (mr == n \text{ or } s[mr] != s[mr - t]))
            res.push_back({ml, mr, t});
      for(int t = 1; t <= r - m; t++) {
         int ml = max(l, m - zsl[r - l - t]), mr = min(r, m + t)
+ zsr[t]);
         if(mr - ml >= 2 * t and (ml == 0 or s[ml - 1] != s[ml
+ t - 1) and (mr == n \text{ or } s[mr] != s[mr - t]))
```

```
res.push_back({ml, mr, t});
}
};
dfs(dfs, 0, n);
sort(all(res));
vector<array<int, 3>> nres;
int pl = -1, pr = -1;
for(auto [l, r, t] : res) {
   if(l == pl and r == pr) continue;
   pl = l, pr = r;
   nres.push_back({t, l, r});
}
return nres;
}
```

geometry

argument-sort.hpp

bool operator<(point P, point Q) {
 long long C = cross(P, Q);
 if(C == 0 && dot(P, Q) > 0) {
 return false;
 } else if(P.x < 0 && P.y == 0) {
 return true;
 } else if(Q.x < 0 && Q.y == 0) {
 return false;
 } else if(P.y * Q.y <= 0) {
 return P.y < Q.y;
 } else {
 return C > 0;
 }

circle.hpp

md5: 514ea6

md5: 26b1fa

```
struct circle {
   point C;
   double r;
   circle() {}
   circle(point C, double r) : C(C), r(r) {}
pair<point, point> line_circle_intersection(line L, circle C) {
   point P = projection(C.C, L);
   double d = point_line_distance(C.C, L);
   double h = sqrt(C.r * C.r - d * d);
   point A = P + vec(L) / abs(vec(L)) * h;
   point B = P - vec(L) / abs(vec(L)) * h;
   return make_pair(A, B);
pair<point, point> circle_intersection(circle C1, circle C2) {
   double d = dist(C1.C, C2.C);
   double m = (C1.r * C1.r - C2.r * C2.r + d * d) / (d * 2);
   point M = C1.C + (C2.C - C1.C) / d * m;
   double h = sqrt(C1.r * C1.r - m * m);
   point H = rotate90(C2.C - C1.C) / d * h;
   return make_pair(M - H, M + H);
pair<point, point> circle_tangent(point P, circle C) {
   double d = dist(P, C.C);
   double r = sqrt(d * d - C.r * C.r);
   return circle_intersection(C, circle(P, r));
vector<line> common_tangent(circle C1, circle C2) {
   if(C1.r < C2.r) { swap(C1, C2); }</pre>
   double d = dist(C1.C, C2.C);
   vector<line> L;
   if(C1.r - C2.r <= d + eps) {
      if(C1.r - C2.r <= eps) {
         point D = rotate90(C2.C - C1.C) / d \star C1.r;
         L.push_back(line(C1.C + D, C2.C + D));
         L.push_back(line(C1.C - D, C2.C - D));
      } else {
         double m = (C1.r - C2.r) * (C1.r - C2.r) / d;
         point M = C1.C + (C2.C - C1.C) / d * m;
         double h = sqrt((C1.r - C2.r) * (C1.r - C2.r) - m *
m);
         point H1 = M + rotate90(C2.C - C1.C) / d * h;
         point D1 = (H1 - C1.C) / dist(H1, C1.C) * C2.r;
         L.push_back(line(H1 + D1, C2.C + D1));
```

point H2 = M - rotate90(C2.C - C1.C) / d * h;

```
point D2 = (H2 - C1.C) / dist(H2, C1.C) * C2.r;
         L.push_back(line(H2 + D2, C2.C + D2));
      }
   if(C1.r + C2.r <= d + eps) {
      double m = (C1.r + C2.r) * (C1.r + C2.r) / d;
      point M = C1.C + (C2.C - C1.C) / d * m;
      double h = sqrt((C1.r + C2.r) * (C1.r + C2.r) - m * m);
      point H1 = M + rotate90(C2.C - C1.C) / d * h;
      point D1 = (H1 - C1.C) / dist(H1, C1.C) * C2.r;
      L.push_back(line(H1 - D1, C2.C - D1));
      point H2 = M - rotate90(C2.C - C1.C) / d * h;
      point D2 = (H2 - C1.C) / dist(H2, C1.C) * C2.r;
      L.push_back(line(H2 - D2, C2.C - D2));
   return L;
convex-hull.hpp
                                                     md5: 7b7e26
Points convex_hull(Points& p) {
   int n = p.size(), k = 0;
   if(n <= 2) return p;</pre>
   sort(begin(p), end(p), [](pt x, pt y) { return (x.x != y.x ?
x.x < y.x : x.y < y.y); });
   Points ch(2 * n);
   for(int i = 0; i < n; ch[k++] = p[i++]) {
      while(k >= 2 \&\& cross(ch[k - 1] - ch[k - 2], p[i] - ch[k
   for(int i = n - 2, t = k + 1; i \ge 0; ch[k++] = p[i--]) {
      while(k >= t && cross(ch[k - 1] - ch[k - 2], p[i] - ch[k
- 1]) <= 0) --k;
   ch.resize(k - 1);
   return ch;
funcs.hpp
                                                     md5: 19bea4
int contains(const Polygon& Q, const Point& p) {
   bool in = false:
   for(int i = 0; i < Q.size(); i++) {</pre>
      Point a = Q[i] - p, b = Q[(i + 1) \% Q.size()] - p;
      if(a.y > b.y) swap(a, b);
      if(a.y <= 0 && 0 < b.y && cross(a, b) < 0) in = !in;
      if(cross(a, b) == 0 \&\& dot(a, b) <= 0) return _ON;
   }
   return in ? _IN : _OUT;
Polygon Minkowski_sum(const Polygon& P, const Polygon& Q) {
   vector<Segment> e1(P.size()), e2(Q.size()), ed(P.size() +
Q.size());
   const auto cmp = [](const Segment& u, const Segment& v) {
return (u.b - u.a).arg_cmp(v.b - v.a); };
   rep(i, P.size()) e1[i] = {P[i], P[(i + 1) % P.size()]};
   rep(i, Q.size()) e2[i] = {Q[i], Q[(i + 1) % Q.size()]};
   rotate(begin(e1), min_element(all(e1), cmp), end(e1));
   rotate(begin(e2), min_element(all(e2), cmp), end(e2));
   merge(all(e1), all(e2), begin(ed), cmp);
   const auto check = [](const Points& res, const Point& u) {
      const auto back1 = res.back(), back2 = *prev(end(res),
2);
      return eq(cross(back1 - back2, u - back2), eps) and
dot(back1 - back2, u - back1) >= -eps;
  };
   auto u = e1[0].a + e2[0].a;
   Points res{u};
   res.reserve(P.size() + Q.size());
   for(const auto& v : ed) {
      u = u + v.b - v.a;
      while(si(res) >= 2 and check(res, u)) res.pop_back();
      res.eb(u);
   if(res.size() and check(res, res[0])) res.pop_back();
   return res;
// -1 : on, 0 : out, 1 : in
// O(log(n))
bool is_in(const Polygon& p, const Point& a) {
```

```
if(p.size() == 1) return a == p[0] ? -1 : 0;
   if(p.size() == 2) return intersect(Segment(p[0], p[1]), a);
   if(a == p[0]) return -1;
   if((p[1] - p[0]).toleft(a - p[0]) == -1 || (p.back() -
p[0]).toleft(a - p[0]) == 1) return 0;
   const auto cmp = [\&](const Point& u, const Point& v) {
return (u - p[0]).toleft(v - p[0]) == 1; };
   const size_t i = lower_bound(p.begin() + 1, p.end(), a, cmp)
 p.begin();
   if(i == 1) return intersect(Segment(p[0], p[i]), a) ? -1 :
   if(i == p.size() - 1 \&\& intersect(Segment(p[0], p[i]), a))
return -1;
   if(intersect(Segment(p[i - 1], p[i]), a)) return -1;
   return (p[i] - p[i - 1]).toleft(a - p[i - 1]) > 0;
using speP = pair<ld, int>;
struct ccut {
   private:
   set<speP> ags;
   vector<int> nexs;
   vector<int> pres;
   vector<Point> ps;
   public:
   void init() {
      const ld sup = -100000;
      ps.push_back({-sup, -sup});
      ps.push_back({sup, -sup});
      ps.push_back({sup, sup});
      ps.push_back({-sup, sup});
      nexs.resize(4);
      pres.resize(4);
      rep(i, 4) {
         int ni = (i + 1) \% 4;
         Point dif = ps[ni] - ps[i];
         ld t = arg(dif);
         aqs.insert({t, i});
         nexs[i] = ni;
         pres[ni] = i;
      }
   }
   void convex_cut(Point a, Point b) {
      if(ags.empty()) return;
      Point dif = b - a;
      ld t = arg(dif);
      auto itr = ags.lower_bound({t, -1});
      if(itr == ags.end()) itr = ags.begin();
      int cur = (*itr).second;
      if(ccw(a, b, ps[cur]) != -1) return;
      int ricur = nexs[cur];
      while(ricur != cur && ccw(a, b, ps[ricur]) != 1) { ricur
= nexs[ricur]; }
      if(ricur == cur) {
         ags.clear();
         return;
      int lecur = pres[cur];
      while(ccw(a, b, ps[lecur]) != 1) { lecur = pres[lecur]; }
      // new point
      Line l = \{a, b\};
      Line l1 = {ps[lecur], ps[nexs[lecur]]};
      Line l2 = {ps[pres[ricur]], ps[ricur]};
      Point p1 = is_l(l1, l);
      Point p2 = is_l(l2, l);
      int id1 = ps.size();
      int id2 = ps.size() + 1;
      ps.push_back(p1), ps.push_back(p2);
      rep(2) nexs.push_back(-1), pres.push_back(-1);
      // erase(lecur,ricur)
      cur = lecur;
      int tmp = 0;
      while(cur != ricur || !tmp) {
         Point dif = ps[nexs[cur]] - ps[cur];
         ld t = arg(dif);
         ags.erase({t, cur});
         cur = nexs[cur];
         tmp++;
      }
```

```
nexs[lecur] = id1, pres[id1] = lecur, nexs[id1] = id2;
      pres[id2] = id1, nexs[id2] = ricur, pres[ricur] = id2;
      cur = lecur, tmp = 0;
      while(cur != ricur || !tmp) {
         Point dif = ps[nexs[cur]] - ps[cur];
         ld t = arg(dif);
         ags.insert({t, cur});
         cur = nexs[cur];
         tmp++;
      }
   }
   polygon nw_poly() {
      polygon nw;
      for(auto p : ags) nw.push_back(ps[p.second]);
      return nw;
   ld calc_area() {
      polygon nw;
      for(auto p : ags) nw.push_back(ps[p.second]);
      return area(nw);
};
```

line.hpp

md5: 447fab

```
bool point_on_segment(point P, line L) { return dot(P - L.A,
vec(L)) > -eps && dot(P - L.B, vec(L)) < eps; } point projection(point P, line L) { return L.A + vec(L) /
abs(vec(L)) * dot(P - L.A, vec(L)) / abs(vec(L)); }
point reflection(point P, line L) { return projection(P, L) * 2
- P: }
double point_line_distance(point P, line L) { return
abs(cross(P - L.A, vec(L))) / abs(vec(L)); }
double point_segment_distance(point P, line L) {
   if(dot(P - L.A, vec(L)) < 0) {
      return dist(P, L.A);
   } else if(dot(P - L.B, vec(L)) > 0) {
      return dist(P, L.B);
    else {
      return point_line_distance(P, L);
}
bool is_parallel(line L1, line L2) { return abs(cross(vec(L1),
vec(L2))) < eps; }</pre>
point line_intersection(line L1, line L2) {
   return L1.A + vec(L1) * cross(L2.A - L1.A, vec(L2)) /
cross(vec(L1), vec(L2));
bool segment_intersect(line L1, line L2) {
   return cross(L1.A - L2.A, vec(L2)) * cross(L1.B - L2.A,
vec(L2)) < eps
          && cross(L2.A - L1.A, vec(L1)) * cross(L2.B - L1.A,
vec(L1)) < eps;</pre>
double segment_distance(line L1, line L2) {
   if(segment_intersect(L1, L2)) {
      return 0;
   } else {
      double ans = INF;
      ans = min(ans, point_segment_distance(L1.A, L2));
      ans = min(ans, point_segment_distance(L1.B, L2));
      ans = min(ans, point_segment_distance(L2.A, L1));
      ans = min(ans, point_segment_distance(L2.B, L1));
      return ans;
   }
```

misc

clock.hpp

md5: a1f32c

}

if(i_ch < 0) {

```
struct Timer {
#define C chrono::high_resolution_clock
   C::time_point c;
   Timer() : c(C::now()) {}
   long long elapsed() {
      auto d = C::now();
      return chrono::duration_cast<chrono::milliseconds>(d -
c).count();
   }
```

```
#undef C
};
```

simplex.hpp

```
md5: 644ba1
template<typename F = double, int DEPS = 30, bool Randomize =
true> struct Simplex {
   const F EPS = F(1.0) / (1LL << DEPS);</pre>
   int n, m;
   vi shuffle_idx;
   vi idx;
   vector<vector<F>> mat;
   int i_ch, j_ch;
   private:
   void _initialize(const vector<vector<F>>& A, const
vector<F>& b, const vector<F>& c) {
      n = c.size(), m = A.size();
      mat.assign(m + 2, vector < F > (n + 2));
      i ch = m:
      rep(i, m) {
         rep(j, n) mat[i][j] = -A[i][j];
         mat[i][n] = 1, mat[i][n + 1] = b[i];
         if(mat[i_ch][n + 1] > mat[i][n + 1]) i_ch = i;
      rep(j, n) mat[m][j] = c[j];
      mat[m + 1][n] = -1;
      idx.resize(n + m + 1);
      iota(idx.begin(), idx.end(), 0);
   inline F abs_(F x) noexcept { return x > -x ? x : -x; }
   void _solve() {
      vi jupd;
      for(nb_iter = 0, j_ch = n;; nb_iter++) {
         if(i_ch < m) {
            swap(idx[j_ch], idx[i_ch + n + 1]);
            mat[i_ch][j_ch] = F(1) / mat[i_ch][j_ch];
            jupd.clear();
            rep(j, n + 2) {
                if(j != j_ch) {
                  mat[i_ch][j] \star = -mat[i_ch][j_ch];
                   if(abs_(mat[i_ch][j]) > EPS)
jupd.push_back(j);
            rep(i, m + 2) {
               if(abs_(mat[i][j_ch]) < EPS or i == i_ch)</pre>
continue;
                fore(j, jupd) mat[i][j] += mat[i][j_ch] *
mat[i_ch][j];
                mat[i][j_ch] *= mat[i_ch][j_ch];
            }
         }
         j_ch = -1;
         rep(j, n + 1) {
            if(j_ch < 0 \text{ or } idx[j_ch] > idx[j]) {
                if(mat[m + 1][j] > EPS or (abs_(mat[m + 1][j]) <</pre>
EPS and mat[m][j] > EPS)) j_ch = j;
         if(j_ch < 0) break;</pre>
         i_ch = -1;
         rep(i, m) {
            if(mat[i][j_ch] < -EPS) {</pre>
               if(i_ch < 0) {
                  i_ch = i;
               } else if(mat[i_ch][n + 1] / mat[i_ch][j_ch] -
mat[i][n + 1] / mat[i][j_ch] < -EPS) {</pre>
                   i_ch = i;
               } else if(mat[i_ch][n + 1] / mat[i_ch][j_ch] -
mat[i][n + 1] / mat[i][j_ch] < EPS
                          and idx[i_ch] > idx[i]) {
                   i_ch = i;
               }
            }
```

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```
Speed Star (The University of Tokyo)
            is_infty = true;
            break;
         }
      }
      if(mat[m + 1][n + 1] < -EPS) {
         infeasible = true;
         return;
      }
      x.assign(n, 0);
      rep(i, m) {
         if(idx[n + 1 + i] < n) x[idx[n + 1 + i]] = mat[i][n + i]
11:
      ans = mat[m][n + 1];
   public:
   Simplex(vector<vector<F>>> A, vector<F> b, vector<F> c) {
      is_infty = infeasible = false;
      if(Randomize) {
         mt19937
rng(chrono::steady_clock::now().time_since_epoch().count());
         vector<pair<vector<F>, F>> Abs;
         rep(i, si(A)) Abs.emplace_back(A[i], b[i]);
         shuffle(Abs.begin(), Abs.end(), rng);
         A.clear(), b.clear();
         fore(Ab, Abs) A.emplace_back(Ab.first),
b.emplace_back(Ab.second);
         shuffle_idx.resize(c.size());
         iota(all(shuffle_idx), 0);
         shuffle(all(shuffle_idx), rng);
         auto Atmp = A;
         auto ctmp = c;
         rep(i, si(A)) rep(j, si(A[i])) A[i][j] = Atmp[i]
[shuffle_idx[j]];
         rep(j, si(c)) c[j] = ctmp[shuffle_idx[j]];
      _initialize(A, b, c);
      _solve();
      if(Randomize and x.size() == c.size()) {
         auto xtmp = x;
         rep(j, si(c)) x[shuffle_idx[j]] = xtmp[j];
      }
   unsigned nb_iter;
   bool is infty:
   bool infeasible;
   vector<F> x;
```

memo

} };

Primes.md

F ans;

vector<F>& c) {

A = At;

b.swap(c);

rep(i, n) b[i] = -b[i];

rep(j, m) c[j] = -c[j];

素数の個数

n	10^2	10^3	10^4	10^{5}	10^{6}	10^{7}	10^{8}	10^{9}	10^{10}
$\pi(n)$	25	168	1229	9592	78498	664579	5.76e+6	5.08e+7	4.55e+8

static void dual(vector<vector<F>>& A, vector<F>& b,

const int n = b.size(), m = c.size();
vector<vector<F>>> At(m, vector<F>(n));

rep(i, n) rep(j, m) At[j][i] = -A[i][j];

高度合成数

$\leq n$	10^3	10^4	10^5	10^{6}	10^{7}	10^{8}	10^{9}
x	840	7560	83160	720720	8648640	73513440	735134400

$\leq n$		10	O_3		10^4	10^5	10^6		10) ⁷		10^{8}	10) ⁹
$d^0(x)$		32		64	4	128	240		448		76	58	1344	
$\leq n$	1	0^{10}	10^1	1	10^{12}	10^{13}	10^{14}	1	0^{15}	10^{1}	.6	10^{17}	10^{18}	
$d^0(x)$	2	304	403	2	6720	10752	17280	26	5880	414	72	64512	10368	0

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素数階乗

n	2	3	5	7	11	13	17	19	23	29	
n#	2	6	30	210	2310	30030	510510	9.70e+6	2.23e+8	6.47e+9	

階乗

4!	5!	6!	7!	8!	9!	10!	11!	12!	13!
24	120	720	5040	40320	362880	3.63e+6	3.99e+7	4.79e+8	6.23e+9

math.md

二項係数

	~ P	NSCA									
n\k	0	1	2	3	4	5	6	7	8	9	10
0	1										
1	1	1									
2	1	2	1								
3	1	3	3	1							
4	1	4	6	4	1						
5	1	5	10	10	5	1					
6	1	6	15	20	15	6	1				
7	1	7	21	35	35	21	7	1			
8	1	8	28	56	70	56	28	8	1		
9	1	9	36	84	126	126	84	36	9	1	
10	1	10	45	120	210	252	210	120	45	10	1
11	1	11	55	165	330	462	462	330	165	55	11
12	1	12	66	220	495	792	924	792	495	220	66
13	1	13	78	286	715	1287	1a716	1716	1287	715	286
14	1	14	91	364	1001	2002	3003	3432	3003	2002	1001
15	1	15	105	455	1365	3003	5005	6435	6435	5005	3003
16	1	16	120	560	1820	4368	8008	11440	12870	11440	8008
17	1	17	136	680	2380	6188	12376	19448	24310	24310	19448
18	1	18	153	816	3060	8568	18564	31824	43758	48620	43758
19	1	19	171	969	3876	11628	27132	50388	75582	92378	92378
20	1	20	190	1140	4845	15504	38760	77520	125970	167960	184756

$$\binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k} \binom{n}{k} = \frac{n}{k} \binom{n-1}{k-1} \binom{L}{k} + \dots + \binom{R-1}{k} = \binom{R}{k+1} - \binom{L}{k+1}$$

第一種スターリング数

c(n,k): $1,2,\ldots,n$ の順列で巡回置換 k 個に分割できるものの個数

$n \setminus k$	0	1	2	3	4	5	6	7
0	1							
1	0	1						
2	0	1	1					
3	0	2	3	1				
4	0	6	11	6	1			
5	0	24	50	35	10	1		
6	0	120	274	225	85	15	1	
7	0	720	1764	1624	735	175	21	1

$$\begin{array}{l} c(n,k) = c(n-1,k-1) + (n-1)c(n-1,k) \\ x(x+1) \dots (x+n-1) = \sum_{k=0}^n c(n,k) x^k \sum_{k=0}^n c(n,k) = n! \\ \sum_{k=0}^n 2^k c(n,k) = (n+1)! \sum_{k=0}^n (-1)^k c(n,k) = 0 \end{array}$$

 $\sum_{k=0}^n c(n,k) x^k = x(x+1)\dots(x+n-1)$ を用いて分割統治し,片方の計算を polynomial taylor shift で再利用すると,c(N,k) の k に関する列挙が $O(N\log N)$ 時間でできる.

第二種スターリング数

S(n,k): $1,2,\ldots,n$ を k 個の区別しない集合に分割する方法の数

$n \setminus k$	0	1	2	3	4	5	6	7
0	1							
1	0	1						
2	0	1	1					
3	0	1	3	1				
4	0	1	7	6	1			
5	0	1	15	25	10	1		
6	0	1	31	90	65	15	1	
7	0	1	63	301	350	140	21	1

$$S(n,k) = S(n-1,k-1) + kS(n-1,k) \ x^n = \sum_{k=0}^n S(n,k) x(x-1) \dots (x-k+1) \ S(n,k) = rac{1}{k!} \sum_{m=1}^k (-1)^{k-m} inom{k}{m} m^n$$

最後の式と畳み込みを使うと S(N,k) の k に関する列挙が $O(N\log N)$ 時間でできる.

ベル数

 B_n : 1, 2, ..., n をいくつかの集合に分割する方法の数

n	,	0	1	2	3	4	5	6	7	8	9	10
B	n	1	1	2	5	15	52	203	877	4140	21147	115975

$$B_{n+1} = \sum_{k=0}^{n} {n \choose k} B_k B_n = \frac{1}{e} \sum_{k=0}^{\infty} \frac{k^n}{k!}$$

指数型母関数 $\exp(\exp x-1)=\sum_{n=0}^\infty B_n rac{x^n}{n!}$ を使うと B_0,B_1,\dots,B_n の計算が $O(N\log N)$ でできる.

カタラン数

 C_n : n 個の (と) を括弧列になるように並べる方法の数

n	0	1	2	3	4	5	6	7	8	9	10
C_n	1	1	2	5	14	42	132	429	1430	4862	16796

$$C_n = \frac{1}{n+1} {2n \choose n} = \frac{(2n)!}{(n+1)!n!} C_{n+1} = \frac{2(2n+1)}{n+2} C_n C_{n+1} = \sum_{k=0}^n C_k C_{n-k}$$

モンモール数

 a_n : $1,2,\ldots,n$ の順列 P で $P_i
eq i$ となるものの個数

n	0	1	2	3	4	5	6	7	8	9	10
a_n		0	1	2	9	44	265	1854	14833	133496	1334961

$$a_n = (n-1)(a_{n-1} + a_{n-2}) a_n = na_{n-1} + (-1)^n$$

分割数

 P_n : n を正の整数の和として表す方法の数

n	0	1	2	3	4	5	6	7	8	9	10
P_n	1	1	2	3	5	7	11	15	22	30	42

母関数

 $C(x)^k=\left(rac{1-\sqrt{1-4x}}{2x}
ight)^k=\sum_{n=0}^{\infty}rac{k}{n+k}inom{2n+k-1}{n}$ (カタラン数の母関数の累乗)

ドキュメント.md

Data Structure

hash

写経をしたときにミスを発見するために使う。空白や改行を消した状態のハッシュを 計算して、一致していれば写経成功している 違えばどこかに違う部分があるとわか る

BIT

- BIT B(n):長さnのBITを作る
- B.sum(l, r): $\sum_{i=l}^{r-1} A_i$ の値を求める。sum(r)で0からの和。

FastSet

std::set より高速。bitsetで要素の存在を管理する。

- FS S(n): 0以上n未満の値を格納できるFSを作る
- S.set(i):iを挿入
- S.erase(i):iを削除
- S[i]:iが存在するならtrue,存在しないならfalse
- next(i):iより大きい最小の値
- prev(i):iより小さい最大の値

Skew-heap

基本的に普通の優先度付きキューと同一。2つのヒープの融合(meld)操作が速い 使わんやろ

cht

Convex Hull Trick

CHTは次の操作を効率的に行える。初め、空集合 S があるとする。

- S に直線 y=ax+b を追加 O(1)
- x_0 が与えられる。S に含まれる直線について、 ax_0+b の値をそれぞれ計算したときの最小値/最大値を求める。 $O(\log N)$

ただし、最小値を求める際は追加する直線の傾きが単調減少、最大値を求める際は追加する直線の傾きが単調増加である必要がある。それを満たせない場合はLi-chao tree など他の方法で。

- CHT<true> C 最小値を求めるCHTの初期化
- CHT<false> C最大値を求めるCHTの初期化
- C.add(a, b) 直線a,bを追加
- C. query(x) x が与えられた時の最大値最小値

ところで、xが単調増加/単調減少であることが保証できるなら、query_monotone系を使うことでクエリを O(1)にできる

hash_map

たぶんunordered_mapでいい 衝突とかあったらこれを使う

lazy-segtree

遅延セグ木多分ACLと同じ

```
using S = long long;
using F = long long;
S op(S a, S b) { return a + b; }
S e() { return 0; }
S mpp(F f, S x) { return f + x; }
F cmpo(F f1, F f2) { return f1 + f2; }
F id() { return 0; }
int main() {
   int n = 10;
   lazy_segtree<S, op, e, F, mpp, cmpo, id> seg(n);
   seg.apply(0, 5, 10); // 区間 [0, 5) に 10 を加算
   cout << seg.prod(0, 10) << endl; // 全区間の和を計算
   return 0;
```

Li-chao tree

CHTの一般化

- 直線 y=ax+b の追加
- 線分 $y = ax + b (l \leq x < r)$ の追加
- 与えられた x に対する最小値の出力

deque を使う CHT とは異なり,直線の追加順に制限はない.

vector<ll> xs = {1, 2, 3, 4, 5}; // x 座標の定義

x の値は初期化時にわかっている必要がある。クエリ先読みなどしておく

最大値にしたいときは(a, b)を入れる代わりに(-a, -b)を入れて最小値に-1を掛ければよい

```
lctree tree(xs);
// 直線追加
tree.update(2, 3); // y = 2x + 3
tree.update(-1, 6); // y = -x + 6
// 範囲に直線を追加
tree.update_segment(1, 4, 3, 2); // 範囲 [1, 4) に y = 3x + 2 を
適用
// クエリ
cout << tree.query(2) << endl; // x = 2 における最小値
```

line_container

Li-chao treeと違って線分は突っ込めない

```
LineContainer<> lc; // 最小値を求める直線集合
```

cout << tree.query(4) << endl; // x = 4 における最小値

```
cout << lc.query(1) << endl; // x = 1 における最小値を出力 cout << lc.query(3) << endl; // x = 3 における最小値を出力 // 最大値を求める場合 LineContainer<false> max_lc; max_lc.add(2, 3); // y = 2x + 3 max_lc.add(-1, 5); // y = -x + 5 max_lc.add(1, -4); // y = x - 4 cout << max_lc.query(1) << endl; // x = 1 における最大値を出力 cout << max_lc.query(3) << endl; // x = 3 における最大値を出力 link-cut
```

知らん 動的な木に関するクエリができる

pbds

C++のデータ構造拡張パックらしい 知らん

segbeats.hpp

Angel Beats!

遅延セグ木の上位互換 ただし計算量がア

普通の遅延セグ木で解けなかった場合これでワンチャンかけてもいいかも

segtree-2d

2次元セグ木 ア

segtree

セグ木 ACLと一緒

```
// 例: セグメント木で区間和を求める
int op(int a, int b) { return a + b; }
int e() { return 0; } // 単位元

vector<int> v = {1, 2, 3, 4, 5};
segtree<int, op, e> seg(v);

cout << seg.prod(1, 4); // 区間 [1, 4) の和を出力 (2 + 3 + 4)
```

swag

Shirotsumeの推しデータ構造です かわいいね

dequeに対して総和を定数時間で求められる

```
// 例: 和を求めるSWAG
auto f = [](int a, int b) { return a + b; }; // 和を計算
int I = 0; // 単位元 (和の場合は0)

SWAG<int, decltype(f)> swag(f, I);

// 要素を追加
swag.pushb(1);//末尾追加
swag.pushb(2);
swag.pushb(3);
swag.pusha(4);//先頭追加

// クエリ: 現在の含まれる要素の合計
cout << swag.query() << endl; // 出力: 6 (1 + 2 + 3)

// 最初の要素を削除
swag.pop_front();

// クエリ: 更新後の合計
cout << swag.query() << endl; // 出力: 5 (2 + 3)
```

wavelet_matrix

静的な列に対する大小関係のクエリに対する万能薬 いろいろできる vector<int> a = {3, 1, 4, 1, 5, 9, 2, 6}; // 整数列 WaveletMatrix<int> wm(a);

```
// 値の取得
cout << wm.access(3) << endl; // インデックス3の値
// 区間内のk番目に小さい値
cout << wm.kth_smallest(1, 6, 2) << endl; // 区間[1, 6)で2番目に
小さい値
// 区間内の値の出現頻度
cout << wm.range_freq(2, 7, 4) << endl; // 区間[2, 7)で値4の出現数
cout << wm.range_freq(2, 7, 2, 5) << endl; // 区間[2, 7)で2 <=
値 < 5の出現数
// 範囲内の下位k個の和
cout << wm.bottom_k_sum(0, 8, 3) << endl; // 全範囲で下位3個の和
// 範囲内の上位k個の和
cout << wm.top_k_sum(2, 6, 2) << endl; // 区間[2, 6)で上位2個の和
DP
```

d-edge-monge

コストがmongeなときになんかうまくいくやつ

mo-rollback

Moのアルゴリズムの変形. 通常は削除クエリを扱う必要があるが、これを用いると スナップショット+ロールバックが定義できれば動作する.

```
int n = 10; // 配列サイズ
int q = 5; // クエリ数
MoRollBack mo(n, q);
// 区間クエリの追加
mo.add(0, 5); // クエリ1: [0, 5)
mo.add(2, 7); // クエリ2: [2, 7)
mo.add(1, 4); // クエリ3: [1, 4)
// クエリの実行
vector<int> result(q);
vector<int> arr = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10}; // 処理対象配
mo.run(
   [&](int idx) { /* ADD: 状態に要素を追加 */ },
   [&](int idx) { /* REM: 結果を保存 */ result[idx] = ...; },
   [&]() { /* RESET: 状態をリセット */ },
   [&]() { /* SNAP: 現在の状態を保存 */ },
   [&]() { /* ROLLBACK: 状態を復元 */ }
):
// 結果の出力
for (int i = 0; i < q; ++i) {
   cout << "/ul>
```

mo

Moのアルゴリズムの普通版

```
↓ range set query の例
int n = 10; // 配列のサイズ
vector<int> arr = {1, 3, 4, 8, 6, 1, 4, 2, 3, 7}; // 処理対象の配
int q = 3; // クエリ数
vector<pair<int, int>> queries = {{1, 4}, {2, 6}, {0, 9}}; //
クエリのリスト
// Mo構造体の初期化
```

```
Mo mo(n);
for (auto [l, r] : queries) mo.add(l, r);
vector<int> result(q); // クエリ結果を格納する配列
unordered_map<int, int> freq; // 要素の頻度を管理
```

```
// クエリの実行
```

```
mo.build(
   [&](int idx) { freq[arr[idx]]++; },
                                         // 要素の追加
   [&](int idx) { freq[arr[idx]]--; },
                                         // 要素の削除
                                         // クエリ結果を保存
   [&](int idx) {
       result[idx] = freq.size();
                                         // 現在の異なる要素数
を保存
   }
);
// クエリ結果の出力
for (int i = 0; i < q; ++i) \{
   cout << "/DIU " << i + 1 << ": " << result[i] << endl;
```

monge-incremental-rowmin

わからん

monotone-minima

拡張ユークリッドの互除法

monotone性を満たす行列に対して、各行に対する最小値の場所と値を求める. わからん

math

ExtGCD

```
// Returns gcd(a, b) and assigns x, y such that ax + by =
gcd(a, b)
// and |x| + |y| is minimized.
ll extgcd(ll a, ll b, ll& x, ll& y) {
   // assert(a >= 0 && b >= 0);
   if (!b) return x = 1, y = 0, a;
  ll d = extgcd(b, a \% b, y, x);
   y -= a / b * x;
   return d;
// Returns the modular inverse of x modulo md.
ll inv_mod(ll x, ll md) {
   ll y, z;
   extgcd(x, md, y, z);
   return (y % md + md) % md;
}
// ax + by = cの解のうち一つ(x_0, y_0)を求める
bool solve_diophantine(ll a, ll b, ll c, ll& x, ll& y) {
   ll g = extgcd(a, b, x, y);
    if (c % g != 0) return false; // 解なし
    x *= c / g;
    y *= c / g;
    return true;
```

特解を x_0,y_0 とすると、一般解は $x=x_0+krac{b}{\gcd(a,b)},y=y_0-krac{a}{\gcd(a,b)}$

and-or-convolution

 $c_k = \sum_{i ee j = k} a_i b_j$ みたいなのを求める。 a, b を変換→各点積 c を取る→ c を逆変換でできる

binom.hpp

二項係数 H. Pを追記

crt

中国剰余定理 extgcd が前提

割る数の配列がb、あまりの配列がc

floor_sum

はい

lagrange-hokan

数列の前 |y| 項が与えられたときに、ラグランジュ補間で t 項目を求める

matrix

行列計算

個人的に要りそうだったので行列式を追加

prime

素数判定&素因数分解

primitive-root

素数 p について、 r, r^2, \dots, r^{p-1} をそれぞれ P で割った余りが全部異なる物を原始根という。そのうちの一つを求める

xor-convolution

はい

graph

•

lowlink

bcc

二重頂点連結成分分解。

グラフから橋(消すとグラフが分離される辺)と関節点(消すとグラフが分離される 頂点)を列挙

max_matching

一般最大マッチング 最終手段

maximum-independent-set

グラフの最大独立集合

scc

強連結成分分解

tecc

二重辺?わからん

modint

barrettreduction

さらなる高速化が必要な場合

modint

普通のmodint まずはこっちを使うのでよいと思います

FPS

FFI

FFT で多項式の積を高速に

linear-recurrence

きたまさ法で $[x^k]rac{P(x)}{Q(x)}$ が高速に求まる

poly

FPSのライブラリ。かなり長いので、方針が固まりきらない限り使わないほうがいいだろう

relaxed-convolution

いわゆる分割統治畳み込みをより柔軟に行えるもの。

普通畳み込みは2つの列 F,G が両方初めからわかっていないと使えないが、これを使えば値が動的に決まる場合(例えば、 f_i が f_{i-1} 以前をもとに決まる場合など)にも使うことができる。add(f_i, g_i) で、積の i 項目 h_i が帰ってくる。

tree

block-cut-tree

勉強していません

hld

木のクエリをいい感じに解いてくれる奴 勉強していません

flow

bipartite-matching

二部マッチング

flow

ACLと同じ

lower-upper-bound-flow

辺の流量に上下限がある場合のフロー

mcf

最小費用流

string

KMP

ロリハでいい

Manacher

回文半径 コードに説明がある

ROllingHash

ロリハ

SuffixArray

Zalgorithm

enumerate-runs

geometry

argument-sort

偏角ソート

circle

円の座標についてのいろいろ

convex-hull

凸包

funcs

幾何の段になったらまずこれを写経

line

まず写経2

misc

clock

時間計測

simplex

単体法による最適化

A に制約条件の行列、B に制約条件の右辺、C に目的関数のベクトルを置く

最後のあがきとして