ICPC Notebook

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template

Osettings.sh

```
export CXXFLAGS='-03 -std=c++2a -D_GLIBCXX_DEBUG -
D_GLIBCXX_DEBUG_PEDANTIC -Wfatal-errors'
```

1template.hpp

md5: f368a0

```
#include <bits/stdc++.h>
using namespace std;
#define ll long long
#define pii pair<int, int>
#define pll pair<ll, ll>
#define vi vector<int>
#define vl vector<ll>
#define ov4(a, b, c, d, name, ...) name
#define rep3(i, a, b, c) for(ll i = (a); i < (b); i += (c))
#define rep2(i, a, b) rep3(i, a, b, 1)
#define rep1(i, n) rep2(i, 0, n)
#define rep0(n) rep1(aaaaa, n)
#define rep(...) ov4(__VA_ARGS__, rep3, rep2, rep1, rep0)
(__VA_ARGS__)
#define per(i, a, b) for(ll i = (a)-1; i >= (b); i--)
#define fore(e, v) for(auto&& e : v)
#define all(a) begin(a), end(a)
#define si(a) (int)(size(a))
#define lb(v, x) (lower_bound(all(v), x) - begin(v))
#define eb emplace_back
template<typename T, typename S> bool chmin(T& a, const S& b) {
return a > b ? a = b, 1 : 0; }
template<typename T, typename S> bool chmax(T& a, const S& b) {
return a < b ? a = b, 1 : 0; }
const int INF = 1e9 + 100;
const ll INFL = 3e18 + 100;
#define i128 __int128_t
  _() { cin.tie(0)->sync_with_stdio(0), cout.tie(0); }
```

hash.sh

```
# 使い方: sh hash.sh -> コピペ -> Ctrl + D
# コメント・空白・改行を削除して md5 でハッシュする
g++ -dD -E -P -fpreprocessed - | tr -d '[:space:]' | md5sum | cut -c-6
```

rnd.hpp

md5: a81b0a

```
ll rnd(ll l, ll r) { //[l, r)
   static mt19937_64
gen(chrono::steady_clock::now().time_since_epoch().count());
   return uniform_int_distribution<ll>(l, r - 1)(gen);
template<typename T> void rndshuf(vector<T>& v) { rep(i, 1,
si(v)) swap(v[i], v[rnd(0, i)]); }
template<class T> vector<T> rvi(int n, T l, T r, bool unique =
false) {
   if(unique) {
      assert(r - l >= n);
      vector<T> res;
      rep(i, n) res.eb(rnd(l, r - n + 1));
      sort(all(res));
      rep(i, n) res[i] += i;
      rndshuf(res);
      return res;
   }
   vector<T> v(n);
   fore(e, v) e = rnd(l, r);
   return v;
```

data-structure

BIT.hpp md5: 5f098b

```
struct BIT {
   vl a;
   BIT(ll n) : a(n + 1) {}
   void add(ll i, ll x) {
      while(i < si(a)) a[i] += x, i += i & -i;
   ll sum(ll r) {
      ll s = 0;
      while(r) s += a[r], r -= r & -r;
      return s;
   ll sum(ll l, ll r) { return sum(r) - sum(l); }
   // minimize i s.t. sum(i) >= w
   int lower_bound(ll w) {
      if(w <= 0) return 0;</pre>
       int x = 0, N = si(a) + 1;
      for(int k = 1 << __lg(N); k; k >>= 1) {
   if(x + k <= N - 1 && a[x + k] < w) {</pre>
             w -= a[x + k];
              x += k;
          }
      }
      return x;
   }
};
```

FastSet.hpp

md5: 9dd1e2

```
using U = uint64_t;
const U B = 64;
struct FS {
   Un;
   vector<vector<U>>> a;
   FS(U n) : n(n) {
      do a.eb(n = (n + B - 1) / B);
      while(n > 1);
   }
   bool operator[](ll i) const { return a[0][i / B] >> (i % B)
& 1; }
   void set(ll i) {
      for(auto& v : a) {
         v[i / B] |= 1ULL << (i % B);
         i /= B;
      }
   }
   void erase(ll i) {
      for(auto& v : a) {
         v[i / B] &= ~(1ULL << (i % B));
         if(v[i / B]) break;
         i /= B;
     }
  }
   ll next(ll i) {
      rep(h, si(a)) {
         i++;
         if(i / B >= si(a[h])) break;
         U d = a[h][i / B] >> (i % B);
         if(d) {
            i += countr_zero(d);
            while(h--) i = i * B + countr_zero(a[h][i]);
            return i;
         }
         i /= B;
      }
      return n;
   }
   ll prev(ll i) {
      rep(h, si(a)) {
         if(i < 0) break;</pre>
         U d = a[h][i / B] << (~i % B);
         if(d) {
            i -= countl_zero(d);
```

while(h--) $i = i * B + __lg(a[h][i]);$

```
Speed Star (The University of Tokyo)
```

```
return i;
}
i /= B;
}
return -1;
}
};
```

Skew-Heap.hpp

md5: 38dad3

```
template<typename T, bool isMin = true> struct SkewHeap {
   struct Node {
      T key, laz;
      Node *l, *r;
      int idx;
      Node() = default;
      Node(const T_k k, int i = -1): key(k), laz(0),
l(nullptr), r(nullptr), idx(i) {}
   };
   using P = Node*;
   static void propagate(P x) {
      if(x->laz == 0) return;
      if(x->l) x->l->laz += x->laz;
      if(x->r) x->r->laz += x->laz;
      x \rightarrow key += x \rightarrow laz;
      x->laz = 0;
   static P meld(P x, P y) {
      if(!x || !y) return x ? x : y;
      if(!comp(x, y)) swap(x, y);
      propagate(x);
      x->r = meld(x->r, y);
      swap(x->l, x->r);
      return x;
   static P alloc(const T& key, int idx = -1) { return new
Node(key, idx); }
   static P pop(P x) {
      propagate(x);
      return meld(x->l, x->r);
   static P push(P x, const T& key, int idx = -1) { return
meld(x, alloc(key, idx)); }
   static void apply(P x, const T& laz) {
      x->laz += laz;
      propagate(x);
   private:
   static inline bool comp(P x, P y) {
      if constexpr(isMin) {
         return x->key + x->laz < y->key + y->laz;
      } else {
         return x->key + x->laz > y->key + y->laz;
   }
```

cht.hpp

md5: a05621

```
template<bool isMin = true> struct CHT {
#define x first
#define y second
   CHT() = default;
   deque<pll> v;
   bool empty() { return v.empty(); }
   void clear() { return v.clear(); }
   inline int sgn(ll x) { return !x ? 0 : (x < 0 ? -1 : 1); }</pre>
   using D = long double;
   inline bool check(const pll& a, const pll& b, const pll& c)
      if(b.y == a.y \text{ or } c.y == b.y) \text{ return } sgn(b.x - a.x) *
sgn(c.y - b.y) >= sgn(c.x - b.x) * sgn(b.y - a.y);
      return D(b.x - a.x) * sgn(c.y - b.y) / D(abs(b.y - a.y))
\rightarrow= D(c.x - b.x) * sgn(b.y - a.y) / D(abs(c.y - b.y));
   }
   void add(ll a, ll b) {
      if(!isMin) a *= -1, b *= -1;
      pll line(a, b);
      if(empty()) v.emplace_front(line);
      else {
         if(ll c = v[0].x; c <= a) {
```

```
if(c == a) {
               if(v[0].y <= b) return;</pre>
               v.pop_front();
            while(si(v) \ge 2 and check(line, v[0], v[1]))
v.pop_front();
            v.emplace_front(line);
         } else {
            assert(a <= v.back().x);
            if(v.back().x == a) {
               if(v.back().y <= b) return;</pre>
               v.pop_back();
            while(si(v) >= 2 and check(v[si(v) - 2], v.back(),
line)) v.pop_back();
            v.emplace_back(line);
     }
   ll get_y(const pll& a, const ll& x) { return a.x * x + a.y;}
   ll query(ll x) {
      assert(!empty());
      int l = -1, r = si(v) - 1;
      while(l + 1 < r) {
         int m = (l + r) >> 1;
         if(get_y(v[m], x) \ge get_y(v[m + 1], x)) l = m;
         else r = m:
      }
      return get_y(v[r], x) * (isMin ? 1 : -1);
   ll query_monotone_inc(ll x) {
      assert(!empty());
      while(si(v) \ge 2 and get_y(v[0], x) \ge get_y(v[1], x))
v.pop front();
      return get_y(v[0], x) * (isMin ? 1 : -1);
  ll query_monotone_dec(ll x) {
      assert(!empty());
      while(si(v) \ge 2 and get_y(v.back(), x) \ge get_y(v.end()
[-2], x)) v.pop_back();
      return get_y(v.back(), x) * (isMin ? 1 : -1);
#undef x
#undef y
};
```

hash_map.hpp

md5: 1893ff

```
#include <bits/extc++.h>
struct chash {
   const uint64_t C = (ll)(4e18 * acos(0)) | 71;
   ll operator()(ll x) const { return __builtin_bswap64(x * C);
};
using namespace __gnu_pbds;
template<class T, class S> using hash_map = gp_hash_table<T, S, chash>;
```

lazy-segtree.hpp

md5: e79596

```
using U = uint64_t;
template<class S, S (*op)(S, S), S (*e)(), class F, S (*mpp)(F,
S), F (*cmpo)(F, F), F (*id)()> struct lazy_segtree {
   lazy_segtree() : lazy_segtree(0) {}
   explicit lazy_segtree(int n) : lazy_segtree(vector<S>(n,
e())) {}
   explicit lazy_segtree(const vector<$>& v) : n(si(v)) {
      s = bit_ceil(U(n));
      log = countr_zero(U(s));
      d = vector < S > (2 * s, e());
      lz = vector<F>(s, id());
      rep(i, n) d[s + i] = v[i];
      per(i, s, 1) update(i);
   void set(int p, S x) {
      p += s;
      PUSH(p):
      d[p] = x;
      rep(i, 1, log + 1) update(p >> i);
   S get(int p) {
```

```
PUSH(p);
   return d[p];
}
S prod(int l, int r) {
   if(l == r) return e();
   l += s, r += s;
   per(i, log + 1, 1) {
      if(((l >> i) << i) != l) push(l >> i);
      if(((r >> i) << i) != r) push((r - 1) >> i);
   S sml = e(), smr = e();
   while(l < r) {</pre>
      if(l \& 1) sml = op(sml, d[l++]);
      if(r \& 1) smr = op(d[--r], smr);
      l >>= 1, r >>= 1;
   }
   return op(sml, smr);
S all_prod() { return d[1]; }
void apply(int p, F f) {
   // assert(0 <= p && p < n);
   p += s;
   PUSH(p);
   d[p] = mpp(f, d[p]);
   rep(i, 1, log + 1) update(p >> i);
}
void apply(int l, int r, F f) {
   // assert(0 <= l && l <= r && r <= _n);
   if(l == r) return;
   l += s, r += s;
   per(i, log + 1, 1) {
      if(((l >> i) << i) != l) push(l >> i);
      if(((r >> i) << i) != r) push((r - 1) >> i);
   }
   int ml = l, mr = r;
   while(l < r) {</pre>
      if(l & 1) all_apply(l++, f);
      if(r & 1) all_apply(--r, f);
      l >>= 1, r >>= 1;
   }
   l = ml, r = mr;
   rep(i, 1, log + 1) {
      if(((l >> i) << i) != l) update(l >> i);
      if(((r >> i) << i) != r) update((r - 1) >> i);
}
template<class G> int max_right(int l, G g) {
   assert(g(e()));
   if(l == n) return n;
   l += s;
   PUSH(l);
   S sm = e();
   do {
      while(~l & 1) l >>= 1;
      if(!g(op(sm, d[l]))) {
         while(l < s) {</pre>
            push(l);
            l <<= 1;
            if(g(op(sm, d[l]))) {
               sm = op(sm, d[l]);
               l++;
            }
         }
         return l - s;
      }
      sm = op(sm, d[l]);
      1++:
   } while((l & -l) != l);
   return n;
}
template<class G> int min_left(int r, G g) {
   assert(g(e()));
   if(r == 0) return 0;
   r += s;
   PUSH(r - 1);
   S sm = e();
   do {
      while(r > 1 && r & 1) r >>= 1;
      if(!g(op(d[r], sm))) {
```

```
while(r < s) {</pre>
               push(r);
               r = (2 * r + 1);
               if(g(op(d[r], sm))) {
                  sm = op(d[r], sm);
                  r--;
            }
            return r + 1 - s;
         sm = op(d[r], sm);
      } while((r & -r) != r);
      return 0:
   S operator[](int k) { return get(k); }
   int len() { return n; }
   private:
   int n, s, log;
   vector<S> d;
   vector<F> lz;
   void update(int k) { d[k] = op(d[2 * k], d[2 * k + 1]); }
   void all_apply(int k, F f) {
      d[k] = mpp(f, d[k]);
      if(k < s) lz[k] = cmpo(f, lz[k]);
   void push(int k) {
      all_apply(2 * k, lz[k]);
      all_apply(2 * k + 1, lz[k]);
      lz[k] = id();
   void PUSH(int k) { per(i, log + 1, 1) push(k >> i); }
};
```

li-chao.hpp

md5: ca57d5

```
struct lctree {
   struct line {
      ll a, b;
      line(): a(0), b(INFL) {}
      line(ll a, ll b) : a(a), b(b) {}
      ll get(ll x) { return a * x + b; }
      inline bool over(line r, ll x) { return get(x) <</pre>
r.get(x); }
  };
   int n;
   vector<ll> x;
   vector<line> seg;
   lctree() {}
   lctree(const vector<ll>\& _x) : x(_x) {
      sort(all(x));
      int n2 = si(x);
      n = 1;
      while(n < n2) n <<= 1;
      x.resize(n);
      rep(i, n2, n) x[i] = x[n2 - 1];
      seg = vector<line>(n * 2);
   void upd(line L, int i, int l, int r) {
      while(true) {
         int mid = l + r >> 1;
         bool lov = L.over(seg[i], x[l]);
         bool rov = L.over(seg[i], x[r - 1]);
         if(lov == rov) {
            if(lov) swap(seg[i], L);
            return;
         bool mov = L.over(seg[i], x[mid]);
         if(mov) swap(seg[i], L);
         if(lov != mov) {
            i = (i << 1), r = mid;
         } else {
            i = (i << 1) + 1, l = mid;
     }
   }
   void upd(line L, unsigned i) {
      int ub = bit_width(i) - 1;
      int l = (n >> vb) * (i - (1 << vb));
      int r = l + (n \gg ub);
```

```
Speed Star (The University of Tokyo)
      upd(L, i, l, r);
   }
   void update(ll a, ll b) { upd(line(a, b), 1, 0, n); }
   void update_segment(ll l, ll r, ll a, ll b) {
      l = lb(x, l) + n, r = lb(x, r) + n;
      line L(a, b);
      for(; l < r; l >>= 1, r >>= 1) {
         if(l & 1) upd(L, l++);
         if(r & 1) upd(L, --r);
   ll query(ll t) {
      ll k = lb(x, t);
      k += n;
      ll res = seg[k].get(t);
      while(k > 1) {
         k >>= 1;
         chmin(res, seg[k].get(t));
      return res;
};
```

line_container.hpp

md5: b018d9

```
struct Line {
   mutable ll k, m, p;
   bool operator<(const Line& o) const { return k < o.k; }</pre>
   bool operator<(ll x) const { return p < x; }</pre>
}:
template<bool ismin = true> struct LineContainer :
multiset<Line, less<>>> {
   // (for doubles, use inf = 1/.0, div(a,b) = a/b)
   const ll inf = LLONG_MAX / 2;
   ll div(ll a, ll b) { // floored division
      return a / b - ((a ^ b) < 0 && a % b);
   bool isect(iterator x, iterator y) {
      if(y == end()) {
         x \rightarrow p = inf;
         return false;
      if(x->k == y->k) x->p = x->m > y->m ? inf : -inf;
      else x->p = div(y->m - x->m, x->k - y->k);
      return x->p >= y->p;
   void add(ll k, ll m) {
      if(ismin) k = -k, m = -m;
      auto z = insert(\{k, m, 0\}), y = z++, x = y;
      while(isect(y, z)) z = erase(z);
      if(x != begin() && isect(--x, y)) isect(x, y = erase(y));
      while((y = x) != begin() && (--x)->p >= y->p) isect(x,
erase(y));
   ll query(ll x) {
      auto l = *lower_bound(x);
      ll s = 1;
      if(ismin) s = -1;
      return s * (l.k * x + l.m);
};
```

link-cut.hpp

md5: e9b023

```
struct Node {
   typedef Node* NP;
   NP l, r, p;
   bool rev;
   int v, mx, lz;
   Node(): l(NULL), r(NULL), p(NULL), rev(false), v(-inf),
mx(-inf), lz(-inf) {}
   void Propagate() {
      if(rev) {
         swap(l, r);
         if(l) l->rev ^= true;
         if(r) r->rev ^= true;
         rev = false;
      if(l) chmax(l->lz, lz);
      if(r) chmax(r->lz, lz);
      chmax(v, lz);
```

```
chmax(mx, lz);
   lz = -inf;
}
int GetMax() { return max(mx, lz); }
int GetVert() { return max(v, lz); }
void Update() {
   assert(lz == -inf);
   mx = v;
   if(l) { chmax(mx, l->GetMax()); }
   if(r) { chmax(mx, r->GetMax()); }
int Pos() {
   if(p && p->l == this) return -1;
   if(p && p->r == this) return 1;
   return 0;
void Prepare() {
   if(Pos()) p->Prepare();
   Propagate();
void Rotate() {
   NP q = p, c;
   if(Pos() == 1) {
      c = 1;
      l = p;
      p->r = c;
   } else {
      c = r;
      r = p;
      p->l = c;
   if(c) c->p = p;
   p = p -> p;
   q->p = this;
   if(p && p->l == q) p->l = this;
   if(p && p->r == q) p->r = this;
   q->Update();
}
void Splay() {
   Prepare();
   while(Pos()) {
      int a = Pos(), b = p \rightarrow Pos();
      if(b && a == b) p->Rotate();
      if(b && a != b) Rotate();
      Rotate():
   }-
   Update();
}
void Expose() {
   for(NP x = this; x; x = x->p) x->Splay();
   for(NP x = this; x->p; x = x->p) {
      x \rightarrow p \rightarrow r = x;
      x->p->Update();
   }
   Splay();
}
void Evert() {
   Expose();
   if(l) {
      l->rev ^= true;
      l = NULL;
      Update();
   }
void Link(NP x) {
   Evert();
   p = x;
void Set(int q) {
   Expose();
   r = NULL;
   chmax(lz, q);
}
void Cut() {
   Expose();
   assert(l);
   l->p = NULL;
   l = NULL;
   Update();
int Get() {
   Expose();
```

```
Speed Star (The University of Tokyo)
```

```
Page 6 of 27
```

```
r = NULL;
      Update();
      return GetMax();
   }
}:
Node* LCA(Node* a, Node* b) {
   a->Expose();
   b->Expose();
   if(!a->p) { return NULL; }
   Node* d = a;
   while(a->p != b) {
      if(a->Pos() == 0) { d = a->p; }
      a = a -> p;
   }
   if(a == b->l) {
      return d;
    else {
      return b;
```

pbds.hpp

md5: a38245

```
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/priority_queue.hpp>
#include <ext/pb_ds/tag_and_trait.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace __gnu_pbds;
// using namespace __gnu_pbds;
template<typename T> using PQ = __gnu_pbds::priority_queue<T,</pre>
greater<T>, __gnu_pbds::rc_binomial_heap_tag>;
using Trie = __gnu_pbds::trie<string,</pre>
                               __gnu_pbds::null_type,
__gnu_pbds::trie_string_access_traits<>,
                               __gnu_pbds::pat_trie_tag,
__gnu_pbds::trie_prefix_search_node_update>;
// not a multiset
// find_by_order(k) -> itr of k-th(0-based) element
// order_of_key(k) -> index of lower_bound(k)
using ordered_set = tree<int, null_type, less<int>,
rb_tree_tag, tree_order_statistics_node_update>;
#include <ext/rope>
using namespace __gnu_cxx;
```

rbst.hpp

md5: b392ca

```
template<typename T, T (*f)(T, T), T (*e)()> struct RBST {
  inline int rnd() {
      static int x = 123456789;
      static int y = 362436069;
      static int z = 521288629;
      static int w = 88675123;
      int t;
      t = x ^ (x << 11);
      x = y;
      y = z;
      z = w:
      return w = (w ^ (w >> 19)) ^ (t ^ (t >> 8));
  }
  struct node {
      node *1, *r;
      int cnt;
      T x, sum;
      node() = default;
      node(T x) : x(x), sum(x), l(0), r(0) { cnt = 1; }
  RBST(int n) : pool(n) {}
  int cnt(const node* t) { return t ? t->cnt : 0; }
  T sum(const node* t) { return t ? t->sum : e(); }
  node* update(node* t) {
      t->cnt = cnt(t->l) + cnt(t->r) + 1;
      t\rightarrow sum = f(f(sum(t\rightarrow l), t\rightarrow x), sum(t\rightarrow r));
      return t;
  vector<node> pool;
  int ptr = 0;
  inline node* alloc(const T& v) {
```

```
if(si(pool) == ptr) pool.resize(si(pool) * 2);
   return &(pool[ptr++] = node(v));
}
node* merge(node* l, node* r) {
   if(!l or !r) return l ? l : r;
   if(rnd() % (cnt(l) + cnt(r)) < cnt(l)) {
      l->r = merge(l->r, r);
      return update(l);
   r->l = merge(l, r->l);
   return update(r);
}
pair<node*, node*> split(node* t, int k) {
   if(!t) return {t, t};
   if(k <= cnt(t->l)) {
      auto [l, r] = split(t->l, k);
      t->l = r:
      return {1, update(t)};
   }
   auto [l, r] = split(t->r, k - cnt(t->l) - 1);
   t->r = l;
   return {update(t), r};
}
void insert(node*& t, int k, const T& v) {
   auto [l, r] = split(t, k);
   t = merge(merge(l, alloc(v)), r);
}
```

segbeats.hpp

md5: 2fbe43

```
struct Segtree_beats {
   ll op(int type, ll x, ll y) { return type ? min(x, y) :
max(x, y); }
   bool cmp(int type, ll x, ll y) { return type ? x < y : x >
y; }
   struct alignas(32) Node {
      ll sum = 0:
      11 a1[2] = {}, a2[2] = {}-INFL, INFL}, ac[2] = {1, 1}, add
= 0;
   };
   vector<Node> v;
   ll n, log, e[3] = {-INFL, INFL, 0};
   Segtree_beats() {}
   Segtree_beats(int n) : Segtree_beats(vl(n)) {}
   Segtree_beats(const vl& a) {
      n = 1, log = 0;
      while(n < si(a)) n <<= 1, log++;</pre>
      v.resize(2 * n);
      rep(i, si(a)) { v[i + n].sum = v[i + n].a1[0] = v[i + n]
n].a1[1] = a[i]; }
      per(i, n, 1) update(i);
   }
   // 0 : add, 1 : chmin, 2 : chmax, 3 : update
   template<int cmd> void apply(int l, int r, ll x) {
      if(l == r) return;
      l += n, r += n;
      per(i, log + 1, 1) {
         if(((l >> i) << i) != l) push(l >> i);
         if(((r >> i) << i) != r) push((r - 1) >> i);
         int l2 = l, r2 = r;
         while(l < r) {</pre>
            if(l & 1) _apply<cmd>(l++, x);
            if(r & 1) _apply<cmd>(--r, x);
            l >>= 1;
            r >>= 1;
         }
         l = 12;
         r = r2;
      }
      rep(i, 1, log + 1) {
         if(((l >> i) << i) != l) update(l >> i);
         if(((r >> i) << i) != r) update((r - 1) >> i);
```

```
// 0 : max, 1 : min, 2 : sum
   template<int cmd> ll fold(int l, int r) {
      if(l == r) return e[cmd];
      l += n, r += n;
      per(i, log + 1, 1) {
         if(((l >> i) << i) != l) push(l >> i);
         if(((r >> i) << i) != r) push((r - 1) >> i);
      ll lx = e[cmd], rx = e[cmd];
      while(l < r) {</pre>
         if(l & 1) op<cmd>(lx, v[l++]);
         if(r & 1) op<cmd>(rx, v[--r]);
         l >>= 1:
         r >>= 1;
      }
      if constexpr(cmd <= 1) lx = op(cmd, lx, rx);</pre>
      if constexpr(cmd == 2) lx += rx;
      return lx;
   private:
   void update(int k) {
      Node& p = v[k];
      Node& l = v[k * 2 + 0];
      Node& r = v[k * 2 + 1];
      p.sum = l.sum + r.sum;
      rep(t, 2) {
         if(l.a1[t] == r.a1[t]) {
            p.a1[t] = l.a1[t];
            p.a2[t] = op(t, l.a2[t], r.a2[t]);
            p.ac[t] = l.ac[t] + r.ac[t];
         } else {
            bool f = cmp(t, l.a1[t], r.a1[t]);
            p.a1[t] = f ? l.a1[t] : r.a1[t];
            p.ac[t] = f ? l.ac[t] : r.ac[t];
            p.a2[t] = op(t, f? r.a1[t] : l.a1[t], f? l.a2[t]
: r.a2[t]);
      }
   void push_add(int k, ll x) {
      Node& p = v[k];
      p.sum += x \ll (\log + \_builtin\_clz(k) - 31);
      rep(t, 2) {
         p.a1[t] += x:
         if(p.a2[t] != e[t]) p.a2[t] += x;
      }
      p.add += x;
   }
   void push(int cmd, int k, ll x) {
      Node& p = v[k];
      p.sum += (x - p.a1[cmd]) * p.ac[cmd];
      if(p.a1[cmd ^ 1] == p.a1[cmd]) p.a1[cmd ^ 1] = x;
      if(p.a2[cmd ^ 1] == p.a1[cmd]) p.a2[cmd ^ 1] = x;
      p.a1[cmd] = x:
   void push(int k) {
      Node& p = v[k];
      if(p.add) {
         rep(t, 2) push_add(k * 2 + t, p.add);
         p.add = 0;
      }
      rep(t, 2) rep(s, 2) if(cmp(t, v[k * 2 + s].a1[t],
p.a1[t])) push(t, k * 2 + s, p.a1[t]);
   void subtree_ch(int cmd, int k, ll x) {
      if(!cmp(cmd, v[k].a1[cmd], x)) return;
      if(cmp(cmd, x, v[k].a2[cmd])) { return push(cmd, k, x); }
      push(k);
      rep(t, 2) subtree_ch(cmd, k * 2 + t, x);
      update(k);
   }
   template<int cmd> inline void _apply(int k, ll x) {
      rep(i, 2) if(cmd \gg i & 1) subtree_ch(i, k, x);
      if constexpr(cmd == 0) push_add(k, x);
```

```
template<int cmd> inline void op(ll& a, const Node& b) {
   if constexpr(cmd <= 1) a = op(cmd, a, b.a1[cmd]);</pre>
   if constexpr(cmd == 2) a += b.sum;
}
```

```
segtree-2d.hpp
                                                      md5: 1301f7
template<typename T, T (*op)(T, T), T (*e)()> class RangeTree {
   int n, sz;
   vector<segtree<T, op, e>> seg;
   vector<vector<pll>>> yx;
   vector<pll> sorted;
   void update_(int id, ll x, ll y, T val) {
      id += n - 1;
      int yid = lb(yx[id], pll(y, x));
      seg[id].set(yid, val);
      while(id > 0) {
         id = (id - 1) / 2;
         int yid = lb(yx[id], pll(y, x));
         seg[id].set(yid, val);
  }
   T query(int lxid, int rxid, ll ly, ll ry, int k, int l, int
r) {
      if(r <= lxid || rxid <= l) return e();</pre>
      if(lxid <= l && r <= rxid) {</pre>
         int lyid = lb(yx[k], pll(ly, -INFL));
         int ryid = lb(yx[k], pll(ry, -INFL));
         return (lyid >= ryid) ? e() : seg[k].prod(lyid, ryid);
      } else {
         return op(query(lxid, rxid, ly, ry, 2 * k + 1, l, (l +
r) / 2),
                   query(lxid, rxid, ly, ry, 2 * k + 2, (l + r)
/ 2, r));
     }
  }
   public:
   // 座標, 点の値
   RangeTree(vector<pll>& cand, vector<T>& val) : n(1),
sz(si(cand)), sorted(sz) {
      while(n < sz) n *= 2;
      rep(i, sz) sorted[i] = {cand[i].first, i};
      sort(all(sorted), [&](pll& a, pll& b) {
         return (a.first == b.first) ? (cand[a.second].second <</pre>
cand[b.second].second) : (a.first < b.first);</pre>
     });
      yx.resize(2 * n - 1), seg.resize(2 * n - 1);
      rep(i, sz) {
         yx[i + n - 1] = {{sorted[i].second, sorted[i].first}};
         vector<T> arg = {val[sorted[i].second]};
         seg[i + n - 1] = segtree < T, op, e > (arg);
         sorted[i].second = cand[sorted[i].second].second;
      per(i, n - 1, 0) {
         yx[i].resize(si(yx[2 * i + 1]) + si(yx[2 * i + 2]));
         if(yx[i].empty()) continue;
         merge(all(yx[2 * i + 1]), all(yx[2 * i + 2]),
yx[i].begin(), [&](pll& a, pll& b) {
            return (cand[a.first].second ==
cand[b.first].second) ? (a.second < b.second)</pre>
: (cand[a.first].second < cand[b.first].second);</pre>
         vector<T> arg((int)yx[i].size());
         rep(j, si(yx[i])) arg[j] = val[yx[i][j].first];
         seg[i] = segtree<T, op, e>(arg);
      rep(i, 2 * n - 1) {
         for(auto& [a, b] : yx[i]) a = cand[a].second;
   void update(ll x, ll y, T val) {
      int id = lb(sorted, pll(x, y));
      return update_(id, x, y, val);
   T query(ll lx, ll ly, ll rx, ll ry) {
      int lxid = lb(sorted, pll(lx, -INFL));
```

```
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      int rxid = lb(sorted, pll(rx, -INFL));
      return (lxid >= rxid) ? e() : query(lxid, rxid, ly, ry,
0, 0, n);
   }
segtree.hpp
                                                      md5: f8e201
template<class S, S (*op)(S, S), S (*e)()> struct segtree {
   segtree(int n) : segtree(vector<S>(n, e())) {}
   segtree(const vector < S > \& v) : n(si(v)) {
      s = bit_ceil(unsigned(n));
      log = countr_zero(unsigned(s));
      d = vector < S > (2 * s, e());
      rep(i, n) d[s + i] = v[i];
      per(i, s, 1) update(i);
   }
```

```
void set(int p, S x) {
   d[p += s] = x;
   rep(i, 1, log + 1) update(p >> i);
S prod(int l, int r) const {
   S sml = e(), smr = e();
   l += s, r += s;
   while(l < r) {</pre>
      if(l \& 1) sml = op(sml, d[l++]);
      if(r \& 1) smr = op(d[--r], smr);
      l >>= 1, r >>= 1;
   }
   return op(sml, smr);
S all_prod() const { return d[1]; }
template<typename F> int max_right(int l, F f) const {
   if(l == n) return n;
   l += s;
   S sm = e();
      while(~l & 1) l >>= 1;
      if(!f(op(sm, d[l]))) {
         while(l < s) {</pre>
            1 <<= 1:
            if(f(op(sm, d[l]))) sm = op(sm, d[l++]);
         return l - s;
      sm = op(sm, d[l++]);
   } while((l & -l) != l);
   return n;
}
template<typename F> int min_left(int r, F f) const {
   if(!r) return 0;
   r += s;
   S sm = e();
   do {
      while(r > 1 and r & 1) r >>= 1;
      if(!f(op(d[r], sm))) {
         while(r < s) {</pre>
            r = (2 * r + 1);
            if(f(op(d[r], sm))) sm = op(d[r--], sm);
         return r + 1 - s;
      }
      sm = op(d[r], sm);
   } while((r & -r) != r);
   return 0;
private:
int n, s, log;
vector<S> d:
void update(int k) { d[k] = op(d[k * 2], d[k * 2 + 1]); }
```

sparse-table-disjoint.hpp

```
template<typename T, typename F> struct sptable {
  const F f;
  vector<vector<T>> a;
  vi l;
  sptable(const vector<T>& v, F f) : f(f) {
```

```
int m = 0;
      while((1 << m) <= si(v)) ++m;</pre>
      a.resize(m, vector<T>(si(v), T()));
      rep(i, si(v)) a[0][i] = v[i];
      rep(i, 1, m) {
         int s = 1 << i;
         for(int j = 0; j < si(v); j += s * 2) {
            int t = min(j + s, si(v));
            a[i][t - 1] = v[t - 1];
            per(k, t - 1, j) a[i][k] = f(v[k], a[i][k + 1]);
            if(si(v) <= t) break;</pre>
            a[i][t] = v[t];
            int r = min(t + s, si(v));
            rep(k, t + 1, r) a[i][k] = f(a[i][k - 1], v[k]);
      }
      l.resize(1 << m);
      rep(i, 2, si(l)) l[i] = l[i >> 1] + 1;
   }
   T query(int x, int y) {
      if(x >= --y) return a[0][x];
      int p = l[x ^ y];
      return f(a[p][x], a[p][y]);
};
```

swag.hpp md5: 85c3df

```
template<typename T, typename F> struct SWAG {
   using vp = vector<pair<T, T>>;
   vp a, b;
   Ff;
   TI;
   SWAG(F f, T i) : f(f), I(i) {}
   private:
   T get(vp& v) { return empty(v) ? I : v.back().second; }
   void pusha(T x) { a.eb(x, f(x, get(a))); }
   void pushb(T x) { b.eb(x, f(get(b), x)); } // reversed!!
   void rebalance() {
      int n = si(a) + si(b);
      int s0 = n / 2 + (empty(a) ? n & 1 : 0);
      vp v{a};
      reverse(all(v));
      copy(all(b), back_inserter(v));
      a.clear(), b.clear();
      per(i, s0, 0) pusha(v[i].first);
      rep(i, s0, n) pushb(v[i].first);
   }
   public:
   T front() { return (a.empty() ? b.front() : a.back()).first;
   T back() { return (b.empty() ? a.front() : b.back()).first;
}
   void pop_front() {
      if(empty(a)) rebalance();
      a.pop_back();
   void pop back() {
      if(empty(b)) rebalance();
      b.pop_back();
   T query() { return f(get(a), get(b)); }
```

wavelet_matrix.hpp

md5: 198e80

md5: dec827

```
#define U uint32_t
#define L uint64_t
struct bit_vector {
    static constexpr U w = 64;
    vector<L> block;
    vector<U> count;
    int n, zeros;

    inline U get(U i) const { return U(block[i / w] >> (i % w))
& 1; }
    inline void set(U i) { block[i / w] |= 1LL << (i % w); }

bit_vector() {}</pre>
```

```
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   bit_vector(int n) { init(n); }
   void init(int _n) {
      n = zeros = _n;
      block.resize(n / w + 1, 0);
      count.resize(si(block), 0);
   }
   void build() {
      rep(i, 1, si(block)) count[i] = count[i - 1] +
popcount(block[i - 1]);
      zeros = rank0(n);
   }
   inline U rank0(U i) const { return i - rank1(i); }
   inline U rank1(U i) const { return count[i / w] +
popcount(block[i / w] & ((1ULL << i % w) - 1)); }</pre>
template<typename T, const int lg = 31> struct WaveletMatrix {
   int n:
   vector<T> a;
   array<bit_vector, lg> bv;
   WaveletMatrix(const vector<T>& _a) : n(_a.size()), a(_a) {
build2(); }
   void build() {
      rep(i, lg) bv[i] = bit_vector(n);
      vector<T> cur = a, nxt(n);
      per(h, lq, 0) {
         rep(i, n) if(cur[i] >> h & 1) bv[h].set(i);
         bv[h].build();
         array<decltype(begin(nxt)), 2> it{begin(nxt),
begin(nxt) + bv[h].zeros};
         rep(i, n) * it[bv[h].get(i)]++ = cur[i];
         swap(cur, nxt);
      }
      return:
   }
   inline pair<U, U> succ0(int l, int r, int h) const { return
make_pair(bv[h].rank0(l), bv[h].rank0(r)); }
   inline pair<U, U> succ1(int l, int r, int h) const {
      U l0 = bv[h].rank0(l);
      U r0 = bv[h].rank0(r);
      U zeros = bv[h].zeros;
      return make_pair(l + zeros - l0, r + zeros - r0);
   T access(U k) const {
      T ret = 0;
      per(h, lg, 0) {
         U f = bv[h].get(k);
         ret |= f ? T(1) << h : 0;
         k = f ? bv[h].rank1(k) + bv[h].zeros : bv[h].rank0(k);
      }
      return ret;
   T kth_smallest(U l, U r, U k) const {
      T res = 0;
      for(int h = lg - 1; h >= 0; --h) {
         U l0 = bv[h].rank0(l), r0 = bv[h].rank0(r);
         if(k < r0 - l0) l = l0, r = r0;
         else {
            k = r0 - 10;
            res |= (T)1 << h;
            l += bv[h].zeros - l0, r += bv[h].zeros - r0;
         }
      }
      return res;
   T kth_largest(int l, int r, int k) { return kth_smallest(l,
r, r - l - k - 1); }
   int range_freq(int l, int r, T upper) {
      if(upper >= (T(1) << lg)) return r - l;</pre>
      int ret = 0;
      per(h, lg, 0) {
         bool f = (upper >> h) & 1;
         U l0 = bv[h].rank0(l), r0 = bv[h].rank0(r);
```

if(f) {

```
Page 9 of 27
            ret += r0 - l0;
            l += bv[h].zeros - l0;
            r += bv[h].zeros - r0;
         } else {
            1 = 10;
            r = r0;
      }
      return ret;
   int range_freq(int l, int r, T lower, T upper) { return
range_freq(l, r, upper) - range_freq(l, r, lower); }
   array<vector<ll>, lg> sums;
   vector<ll> acc;
   void build2() {
      rep(i, lg) bv[i] = bit_vector(n), sums[i].assign(n + 1,
      acc.resize(si(a) + 1);
      vector<T> cur = a, nxt(n);
      per(h, lg, 0) {
         rep(i, n) if((cur[i] >> h) & 1) bv[h].set(i);
         bv[h].build();
         array<decltype(begin(nxt)), 2> it{begin(nxt),
begin(nxt) + bv[h].zeros};
         rep(i, n) * it[bv[h].get(i)]++ = cur[i];
         swap(cur, nxt);
         rep(i, n) sums[h][i + 1] = sums[h][i] + cur[i];
      rep(i, n) acc[i + 1] = acc[i] + a[i];
   }
   ll bottom_k_sum(int l, int r, int k) {
      ll res = 0;
      per(h, lg, 0) {
         U l0 = bv[h].rank0(l), r0 = bv[h].rank0(r);
         if(k < r0 - l0) {</pre>
            l = 10, r = r0;
         } else {
            res += sums[h][r0] - sums[h][l0];
            k = r0 - 10;
            l += bv[h].zeros - l0;
            r += bv[h].zeros - r0;
         }
      }
      res += sums[0][l + k] - sums[0][l];
      return res;
   }
  ll top_k_sum(int l, int r, int k) { return acc[r] - acc[l] -
bottom_k_sum(l, r, r - l - k); }
#undef U
#undef L
dp
```

d-edge-monge.hpp

md5: 4ab7ee

```
template<class C, class T = decltype(std::declval<C>().get())>
T incremental_monge_shortest_path(const int n, C init) {
   class env {
  public:
      C mid;
      C last:
      int prev;
  }:
   std::vector<env> nodes;
      int n_ = n;
      int d = 0;
      while(n_ != 0) {
         n_ /= 2;
         d += 1:
      }
      nodes.assign(d, {init, init, 0});
   }
   std::vector<T> dp(n + 1, static_cast<T>(0));
   const auto f = [&](const auto& f, const int d, const int r)
-> int {
```

```
Speed Star (The University of Tokyo)
      auto& [mid, last, prev] = nodes[d];
      const int w = 1 \ll d;
      if((r >> d) \% 2 == 1) {
         for(int i = std::max(0, r - 2 * w); i != r; i += 1) {
mid.push_back(i); }
         const int next = r + w \le n ? f(f, d + 1, r + w) : r -
         int argmin = prev;
         dp[r] = dp[argmin] + mid.get();
         for(int i = prev; i != next;) {
            mid.pop_front(i);
            i += 1;
            const T t = dp[i] + mid.get();
            if(dp[r] > t) {
               dp[r] = t;
               argmin = i;
         }
         prev = next;
         return argmin;
      } else {
         for(int i = std::max(0, r - 2 * w); i != r; i += 1) {
last.push_back(i); }
         for(int i = std::max(0, r - 3 * w); i != r - 2 * w; i
+= 1) { last.pop_front(i); }
         int argmin = prev;
         for(int i = r - 2 * w; i != r - w;) {
            last.pop_front(i);
            i += 1;
            const T t = dp[i] + last.get();
            if(dp[r] > t) {
               dp[r] = t;
               argmin = i;
         return argmin;
      }
   };
   for(int i = 1; i != n + 1; i += 1) { f(f, 0, i); }
   return dp[n];
namespace golden section search impl {
using i64 = std::int64_t;
template<class F, class T = decltype(std::declval<F>()
(std::declval<i64>())), class Compare = std::less<T>>
std::pair<i64, T> golden_section_search(F f, i64 min, i64 max,
Compare comp = Compare()) {
   assert(min <= max);</pre>
   i64 = min - 1, x, b;
      i64 s = 1, t = 2;
      while(t < max - min + 2) { std::swap(s += t, t); }</pre>
      x = a + t - s;
      b = a + t;
   T fx = f(x), fy;
   while(a + b != 2 * x) {
      const i64 y = a + b - x;
      if(max < y \mid \mid comp(fx, (fy = f(y)))) {
         b = a:
         a = y;
      } else {
         a = x;
         x = y;
```

fx = fy;

const vector<ll>* a;

} // namespace golden_section_search_impl

using golden_section_search_impl::golden_section_search;

return {x, fx};

}

struct cost {

```
Page 10 of 27

ll lambda;
ll cost;
void pop_front(int l) {}
void push_back(int r) {}
ll get() { return lambda + c } // 最小化な5 -
};

// k : 使う辺の本数
const auto f = [&](ll l) -> ll {
   auto res = incremental_monge_shortest_path(n + 1, cost{l, 0, 0}) - l * (k + 1);
   return res;
};

// L = - max(|e|) * 3, R = max(|e|) * 3
OUT(golden_section_search(f, L, R, greater<ll>()).se);
```

md5: 5737bf

mo-rollback.hpp

```
struct MoRollBack {
   using ADD = function<void(int)>;
   using REM = function<void(int)>;
   using RESET = function<void()>;
   using SNAP = function<void()>;
   using ROLLBACK = function<void()>;
   int w;
   vector<int> l, r, ord;
   MoRollBack(int n, int q) : w((int)sqrt(n)), ord(q) {
iota(all(ord), 0); }
   void add(int a, int b) { /* [l, r) */
      l.emplace_back(a);
      r.emplace_back(b);
   }
   void run(const ADD& add, const REM& rem, const RESET& reset,
const SNAP& snap, const ROLLBACK& rollback) {
      sort(begin(ord), end(ord), [\&](int a, int b) {
         int ab = l[a] / w, bb = l[b] / w;
         if(ab != bb) return ab < bb;</pre>
         return r[a] < r[b];</pre>
      });
      reset();
      for(auto idx : ord) {
         if(r[idx] - l[idx] < w) {
            rep(i, l[idx], r[idx]) add(i);
            rem(idx);
            rollback();
         }
      }
      int nr = 0, lb = -1;
      for(auto idx : ord) {
         if(r[idx] - l[idx] < w) continue;</pre>
         int b = l[idx] / w;
         if(lb != b) {
            reset();
            lb = b;
            nr = (b + 1) * w;
         while(nr < r[idx]) add(nr++);</pre>
         snap();
         per(j, (b + 1) * w, l[idx]) add(j);
         rem(idx);
         rollback():
  }
```

mo.hpp md5: 6ff6db

};

```
struct Mo {
   int n;
   vector<pii> lr;
   Mo(int n) : n(n) {}
   void add(int l, int r) { lr.eb(l, r); }
   template<typename AL, typename AR, typename EL, typename ER,
typename 0>
   void build(const AL& add_left, const AR& add_right, const
EL& erase_left, const ER& erase_right, const 0& out) {
    int q = (int)lr.size();
    int bs = n / min<int>(n, sqrt(q));
    vector<int> ord(q);
    iota(all(ord), 0);
```

md5: da6157

```
Speed Star (The University of Tokyo)
      sort(all(ord), [&](int a, int b) {
         int ab = lr[a].first / bs, bb = lr[b].first / bs;
         if(ab != bb) return ab < bb;</pre>
         return (ab & 1) ? lr[a].second > lr[b].second :
lr[a].second < lr[b].second;</pre>
      }):
      int l = 0, r = 0;
      for(auto idx : ord) {
         while(l > lr[idx].first) add_left(--l);
         while(r < lr[idx].second) add_right(r++);</pre>
         while(l < lr[idx].first) erase_left(l++);</pre>
         while(r > lr[idx].second) erase_right(--r);
         out(idx);
      }
   }
   template<typename A, typename E, typename O> void
build(const A& add, const E& erase, const O& out) {
      build(add, add, erase, erase, out);
};
```

monge-incremental-rowmin.hpp

md5: 2cff0f

```
// A[N + 1][N + 1]: Monge が i > j のみ存在しているとき、i (= 0,
..., N)行目の最小値を返す
// f(i, j, v) で、j 行目の最小値が求まっている v を用いて、A[i][j] に
template<typename T, typename F> vector<T> monge_rowmin(int n,
const F& f) {
  vector<T> mi(n + 1, numeric_limits<T>::max());
  mi[0] = 0;
  vector<int> amin(n + 1);
  auto check = [&](int i, int j) {
     if(chmin(mi[i], f(i, j, mi))) { amin[i] = j; }
  check(n, 0);
  auto solve = [&](auto&& self, int l, int r) {
     if(r - l == 1) return;
     int mid = l + r >> 1;
     rep(k, amin[l], amin[r] + 1) check(mid, k);
      self(self, l, mid);
     rep(k, l + 1, mid + 1) check(r, k);
     self(self, mid, r);
  };
  solve(solve, 0, n);
  return mi;
```

monotone-minima.hpp

md5: 187a2d

```
// monotone 行列の各行について、最小値を取る場所とその値を返す
template<typename T, typename F> vector<pair<int, T>>
monotone_minima(int h, int w, const F& f) {
    vector<pair<int, T>> dp(h, pair(-1, T()));
    auto rec = [&](auto&& rec, int u, int d, int l, int r) {
        if(u > d) return;
        int mid = u + d >> 1;
        auto& [idx, mi] = dp[mid];
        idx = l, mi = f(mid, l);
        rep(i, l + 1, r + 1) if(chmin(mi, f(mid, i))) idx = i;
        rec(rec, u, mid - 1, l, idx);
        rec(rec, mid + 1, d, idx, r);
    };
    rec(rec, 0, h - 1, 0, w - 1);
    return dp;
}
```

math

ExtGCD.hpp

md5: 88cb1c

```
// returns gcd(a, b) and assign x, y to integers
// s.t. ax + by = gcd(a, b) and |x| + |y| is minimized
ll extgcd(ll a, ll b, ll& x, ll& y) {
    // assert(a >= 0 && b >= 0);
    if(!b) return x = 1, y = 0, a;
    ll d = extgcd(b, a % b, y, x);
    y -= a / b * x;
```

```
return d;
}
ll inv_mod(ll x, ll md) {
    ll y, z;
    extgcd(x, md, y, z);
    return (y % md + md) % md;
}
```

and-or-convolution.hpp

```
// and / or convolution
template<bool isOR, typename T> void fzt(vector<T>& a, bool inv
= false) {
   int n = si(a);
   int m = __lg(n);
   rep(i, m) {
      rep(b, n) {
      if((b >> i & 1) == isOR) a[b] += a[b ^ 1 << i] * (inv
? -1 : 1);
   }
  }
}</pre>
```

binom.hpp

md5: db2821

```
constexpr int N = 1e6 + 100;
mint fact[N], ifact[N];
void pre() {
   fact[0] = 1;
   rep(i, 1, N) fact[i] = i * fact[i - 1];
   ifact[N - 1] = fact[N - 1].inv();
   per(i, N - 1, 0) ifact[i] = ifact[i + 1] * (i + 1);
}
mint C(int n, int m) { return (n < m or m < 0 ? 0 : fact[n] * ifact[m] * ifact[m] * ifact[n - m]); }</pre>
```

crt.hpp

md5: 0e9c10

```
// (rem, mod)
pll crt(const vl& b, const vl& c) {
    int n = si(b);
    ll r = 0, m = 1;
    rep(i, n) {
        ll g, im, x;
        g = extgcd(m, c[i], im, x);
        if((b[i] - r) % g) return {0, -1};
        ll tmp = (b[i] - r) / g * im % (c[i] / g);
        r += m * tmp;
        m *= c[i] / g;
    }
    return {(r % m + m) % m, m};
}
```

floor_sum.hpp

md5: 930ca0

```
// x_i=floor((a*i+b)/c), i=0,1,..n-1
// a,c>0, b>=0
ll floor_sum(ll n, ll a, ll b, ll c) {
   if(n == 0) return 0;
   ll res = 0;
   res += n * (n - 1) / 2 * (a / c);
   a %= c;
   res += n * (b / c);
   b %= c;
   if(a == 0) return res;
   ll top = (a * (n - 1) + b) / c;
   res += top * n;
   ll h = (b + 1 + c - 1) / c;
   if(h <= top) res -= floor_sum(top - h + 1, c, c * h - (b +</pre>
1), a) + top - h + 1;
   return res;
```

lagrange-hokan.hpp

md5: 22b9e3

```
template<typename T> T lagrange_polynomial(const vector<T>& y,
ll t) {
  int n = si(y) - 1;
  if(t <= n) return y[t];
  T ret(0);
  vector<T> dp(n + 1, 1), pd(n + 1, 1);
```

matrix.hpp

md5: 270f1c

```
template<typename T> struct M {
   vector<vector<T>> a:
   int n, m;
   M(int n, int m) : n(n), m(m), a(n, vector<T>(m)) {}
   M(int n = 0) : M<T>(n, n) {}
   vector<T>& operator[](int k) { return a[k]; }
   const vector<T>& operator[](int k) const { return a[k]; }
   static M I(int n) {
      M mat(n):
      rep(i, n) mat[i][i] = 1;
      return mat;
   M& operator+=(const M& b) {
      rep(i, n) rep(j, m)(*this)[i][j] += b[i][j];
      return *this;
   M& operator-=(const M& b) {
      rep(i, n) rep(j, m)(*this)[i][j] -= b[i][j];
      return *this;
   M& operator*=(const M& b) {
      int l = b.m;
      vector c(n, vector<T>(l));
      rep(i, n) rep(j, m) rep(k, l) c[i][k] += (*this)[i][j] *
b[j][k];
      a.swap(c);
      return *this;
   M& operator^=(ll k) {
      M b = M::I(n);
      while(k) {
         if(k & 1) b *= *this;
         *this *= *this;
         k >>= 1;
      }
      a.swap(b.a);
      return *this;
   M operator+(const M& b) const { return (M(*this) += b); }
   M operator-(const M& b) const { return (M(*this) -= b); }
   M operator*(const M& b) const { return (M(*this) *= b); }
   M operator^(const M& b) const { return (M(*this) ^= b); }
};
template<typename T> pair<int, T> GaussElimination(M<T>& a,
bool LE = false) {
   int n = a.n, m = a.m;
   int rank = 0, je = LE ? m - 1 : m;
   mint det = 1;
   rep(i, ie) {
      int idx = -1;
      rep(i, rank, n) {
         if(a[i][j].x) {
            idx = i;
            break;
         }
      if(idx == -1) {
         det = 0;
         continue;
      if(rank != idx) {
         det = -det;
         swap(a[rank], a[idx]);
      det *= a[rank][j];
      if(LE && a[rank][j].x != 1) {
         mint coeff = a[rank][j].inv();
         rep(k, j, m) a[rank][k] *= coeff;
      }
      int is = LE ? 0 : rank + 1;
```

```
rep(i, is, n) {
         if(i == rank) continue;
         if(a[i][j].x) {
            mint coeff = a[i][j] / a[rank][j];
            rep(k, j, m) a[i][k] = a[rank][k] * coeff;
      }
      rank++;
   return make_pair(rank, det);
template<typename T> vector<vector<T>> LinearEquation(M<T> a,
vector<T> b) {
   int n = a.n, m = a.m;
   rep(i, n) a[i].eb(b[i]);
   a.m++;
   auto p = GaussElimination(a, true);
   int rank = p.first;
   rep(i, rank, n) {
      if(a[i][m].x != 0) return {};
   }
   vector<vector<T>> res(1, vector<T>(m));
   vi piv(m, -1);
   int j = 0;
   rep(i, rank) {
      while(a[i][j].x == 0) ++j;
      res[0][j] = a[i][m], piv[j] = i;
   rep(j, m) {
      if(piv[j] == -1) {
         vector<T> x(m);
         x[i] = 1;
         rep(k, j) {
            if(piv[k] != -1) x[k] = -a[piv[k]][j];
         res.eb(x):
     }
   }
   return res;
```

prime.hpp

md5: 94a4a8

```
template<class T, class U> T pow_mod(T x, U n, T md) {
   T r = 1 \% md;
   x \% = md;
   while(n) {
      if(n \& 1) r = (r * x) % md;
      x = (x * x) % md;
      n >>= 1;
   }-
   return r;
bool is_prime(ll n) {
   if(n <= 1) return false;</pre>
   if(n == 2) return true;
   if(n % 2 == 0) return false;
   ll d = n - 1;
   while(d % 2 == 0) d /= 2;
   for(ll a: {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37}) {
      if(n <= a) break;</pre>
      ll t = d;
      ll y = pow_mod < i128 > (a, t, n); // over
      while(t != n - 1 && y != 1 && y != n - 1) {
         y = i128(y) * y % n; // flow
         t <<= 1:
      if(y != n - 1 && t % 2 == 0) { return false; }
   return true;
ll pollard_single(ll n) {
   auto f = [\&](ll x) \{ return (i128(x) * x + R) % n; \};
   if(is_prime(n)) return n;
   if(n % 2 == 0) return 2;
   ll st = 0;
   while(true) {
      R = rnd(1, n);
      st++:
      ll x = st, y = f(x);
```

primitive-root.hpp

md5: 4088f5

```
ll primitive_root(ll p) {
    auto v = factor(p - 1);
    sort(all(v)), v.erase(unique(all(v)), end(v));
    while(true) {
        ll g = rnd(1, p);
        bool ok = true;
        for(auto d : v) {
            ll f = (p - 1) / d;
            if(pow_mod<i128>(g, f, p) == 1) {
                ok = false;
                break;
        }
        if(ok) return g;
    }
}
```

xor-convolution.hpp

md5: f5168d

```
template<typename T> void fwt(vector<T>& f, bool inv = false) {
   int n = si(f), m = __lg(n);
   rep(i, m) {
      rep(b, n) {
        if(~b >> i & 1) {
            T x = f[b], y = f[b ^ 1 << i];
            f[b] = x + y, f[b ^ 1 << i] = x - y;
        }
    }
   if(inv) {
      T iz = T(1) / T(si(f));
      fore(e, f) e *= iz;
   }
}</pre>
```

graph

bcc.hpp

md5: 3df588

```
template<typename G> struct BCC : LL<G> {
  vi used:
  vector<vector<pii>>> bc;
  vector<pii> tmp;
  using L = LL<G>;
  using L::g;
  using L::low;
  using L::ord;
  BCC(G g) : L(g) { build(); }
  void build() {
      used.assign(si(g), 0);
      rep(i, si(used)) if(!used[i]) dfs(i, -1);
  void dfs(int x, int p) {
      used[x] = true;
      fore(e, g[x]) {
         if(e == p) continue;
         if(!used[e] || ord[e] < ord[x]) tmp.eb(minmax(x, e));</pre>
         if(!used[e]) {
            dfs(e, x);
```

```
if(low[e] >= ord[x]) {
          bc.eb();
          while(true) {
                auto p = tmp.back();
                bc.back().eb(p);
                tmp.pop_back();
                if(p.first == min(x, e) and p.second ==
max(x, e)) break;
          }
        }
    }
}
```

eulerian-trail.hpp

md5: 5d421d

```
struct edge {
   int x, y, idx;
vector<edge> eulerian_path(vector<edge> es, int s, bool
directed = false) {
   if(es.empty()) return {};
   int n = 0;
   fore(e, es) chmax(n, max(e.x, e.y) + 1);
   vector<vector<pair<edge, int>>> g(n);
   for(auto& e : es) {
      int p = si(g[e.y]);
      g[e.x].emplace_back(e, p);
      if(!directed) {
         int q = si(g[e.x]) - 1;
         swap(e.x, e.y);
         g[e.x].emplace_back(e, q);
      }
   vector<edge> ord;
   stack<pair<int, edge>> st;
   st.emplace(s, edge{-1, -1, -1});
   while(st.size()) {
      int x = st.top().first;
      if(empty(g[x])) {
         ord.eb(st.top().second);
         st.pop();
      } else {
         auto e = g[x].back();
         g[x].pop_back();
         if(e.second == -1) continue;
         if(!directed) g[e.first.y][e.second].second = -1;
         st.emplace(e.first.y, e.first);
      }
   }
   ord.pop_back();
   reverse(begin(ord), end(ord));
   if(si(ord) != si(es)) return {};
   return ord;
```

lowlink.hpp

md5: e3987c

```
template<typename G> struct LL {
  int n;
  const G a:
  vi ord, low, arti;
  vector<pii> bridge;
  LL(G g) : n(si(g)), g(g), ord(si(g), -1), low(si(g), -1) {
     int k = 0;
     rep(i, n) {
         if(ord[i] == -1) k = dfs(i, k, -1);
  }
  int dfs(int x, int k, int p) {
     low[x] = (ord[x] = k++);
     int cnt = 0;
     bool is_arti = false, second = false;
      fore(e, g[x]) {
         if(ord[e] == -1) {
            k = dfs(e, k, x);
            chmin(low[x], low[e]);
            is_arti |= (p != -1) \&\& (low[e] >= ord[x]);
```

```
Page 14 of 27
```

max_matching.hpp

md5: 2ece25

```
struct Matching {
   int n;
   vector<vi> q;
   vi mt;
   vi is_ev, gr_buf;
   vector<pii> nx;
   int st:
   int group(int x) {
     if(gr_buf[x] == -1 || is_ev[gr_buf[x]] != st) return
qr_buf[x];
      return gr_buf[x] = group(gr_buf[x]);
   void match(int p, int b) {
      int d = mt[p];
      mt[p] = b;
      if(d == -1 || mt[d] != p) return;
      if(nx[p].second == -1) {
         mt[d] = nx[p].first;
         match(nx[p].first, d);
      } else {
         match(nx[p].first, nx[p].second);
         match(nx[p].second, nx[p].first);
      }
   bool arg() {
      is_ev[st] = st;
      gr_buf[st] = -1;
      nx[st] = pii(-1, -1);
      queue<int> q;
      q.push(st);
      while(q.size()) {
         int a = q.front();
         q.pop();
         for(auto b : g[a]) {
            if(b == st) continue;
            if(mt[b] == -1) {
               mt[b] = a;
               match(a, b);
               return true;
            if(is_ev[b] == st) {
               int x = group(a), y = group(b);
               if(x == y) continue;
               int z = -1;
               while(x != -1 || y != -1) {
                  if(y != -1) swap(x, y);
                  if(nx[x] == pii(a, b)) {
                     z = x;
                     break;
                  }
                  nx[x] = pii(a, b);
                  x = group(nx[mt[x]].first);
               for(int v : {group(a), group(b)}) {
                  while(v != z) {
                     q.push(v);
                     is_ev[v] = st;
                     gr_buf[v] = z;
                     v = group(nx[mt[v]].first);
                  }
               }
            } else if(is_ev[mt[b]] != st) {
               is_ev[mt[b]] = st;
               nx[b] = pii(-1, -1);
               nx[mt[b]] = pii(a, -1);
               gr_buf[mt[b]] = b;
               q.push(mt[b]);
```

```
}
}
return false;
}
Matching(const vector<vi>& _g) : n(int(_g.size())), g(_g),
mt(n, -1), is_ev(n, -1), gr_buf(n), nx(n) {
    for(st = 0; st < n; st++)
        if(mt[st] == -1) arg();
}
vector<pii> max_match() {
    vector<pii> res;
    rep(i, n) if(i < mt[i]) res.eb(i, mt[i]);
    return res;
}
};</pre>
```

maximum-independent-set.hpp

md5: ac1384

```
unsigned ll maximum_independent_set(vector<vi> g) {
   using U = unsigned long long;
   int n = si(g);
   vector<U> nbd(n);
   rep(i, n) fore(e, g[i]) nbd[i] = 1ULL << e;
   int best = 0;
   U res = 0;
   auto dfs = [&](auto&& dfs, U now, U rest) -> void {
      pii p(-1, -1);
      while(true) {
         bool upd = 0;
         rep(v, n) {
            if(rest >> v & 1) {
               int d = popcount(nbd[v] & rest);
               if(chmax(p.second, d)) p.first = v;
               if(d <= 1) rest ^= 1ULL << v, rest &= ^-nbd[v],
now |= 1ULL << v, upd = 1;
            }
         }
         if(!upd) break;
         p = \{-1, -1\};
      int a = popcount(now), b = popcount(rest);
      if(chmax(best, a)) res = now;
      if(!b or a + b <= best) return;</pre>
      int v = p.first;
      rest &= ~(1ULL << v);
      if(p.second >= 3) dfs(dfs, now, rest);
      now |= 1ULL << v;
      dfs(dfs, now, rest & ~(nbd[v]));
  };
   U now = 0, rest = (1ULL << n) - 1;
   dfs(dfs, now, rest);
   return res;
```

scc.hpp

md5: 73554b

```
template<typename G> struct SCC {
   Gg;
   vector<vi> rg;
   vi comp, ord, used;
   int num; // 連結成分の数
   SCC(G g) : g(g), rg(si(g)), comp(si(g), -1), ord(si(g)),
used(si(g)) {
      rep(i, si(g)) fore(e, g[i]) rg[e].eb(i);
     build();
   };
   int operator[](int k) { return comp[k]; }
   void dfs(int x) {
     if(used[x]) return;
     used[x] = true;
     fore(e, g[x]) if(!used[e]) dfs(e);
     ord.eb(x);
  }
   void rdfs(int x, int cnt) {
     if(comp[x] != -1) return;
      comp[x] = cnt;
     fore(e, rg[x]) if(comp[e] == -1) rdfs(e, cnt);
   void build() {
```

```
Page 15 of 27
```

md5: 3db9f2

```
Speed Star (The University of Tokyo)
    rep(i, g.size()) dfs(i);
    reverse(all(ord));
    num = 0;
    fore(i, ord) if(comp[i] == -1) { rdfs(i, num), num++; }
};
```

tecc.hpp

md5: 17c69f

```
template<typename G> struct TCC : LL<G> {
   using L = LL<G>;
  using L::bridge;
  using L::g;
  using L::low;
  using L::ord;
  vi cmp;
  vector<vi> tree, group;
  void build() {
      cmp.assign(si(g), -1);
      int k = 0:
      rep(i, si(cmp)) if(cmp[i] == -1) dfs(i, -1, k);
      qroup.resize(k);
      rep(i, si(g)) group[cmp[i]].eb(i);
      tree.resize(k);
      for(auto [a, b] : bridge) {
         tree[cmp[a]].eb(cmp[b]);
         tree[cmp[b]].eb(cmp[a]);
     }
  TCC(const G& g) : L(g) { build(); }
  void dfs(int x, int p, int& k) {
     if(p >= 0 and ord[p] >= low[x]) cmp[x] = cmp[p];
      else cmp[x] = k++;
      fore(e, g[x]) if(cmp[e] == -1) dfs(e, x, k);
```

modint

BarrettReduction.hpp

using U = uint64_t;

struct Barret {

md5: 651912

```
U m, im;
   Barret(U mod) : m(mod), im(-1ULL / m + 1) {}
   U mul(U a, U b) const {
      a *= b;
      U x = ((\__uint128_t)a * im) >> 64;
      a -= x * m;
      if((ll)a < 0) a += m;</pre>
      return a;
};
constexpr ll mod = 998244353;
static Barret b(mod);
struct mint {
   int x;
   mint(ll x_{=} = 0) : x((x_{=} % mod) + mod) {
      if(x >= mod) x -= mod;
  mint& s(uint xx) { return x = xx < mod ? xx : xx - mod,}
*this; }
   mint operator-() { return mint(-x); }
   mint& operator+=(const mint& r) { return s(x + r.x); }
   mint& operator-=(const mint& r) { return s(x + mod - r.x); }
   mint\& operator*=(const mint\& r) { return x = b.mul(x, r.x),}
*this: }
   mint& operator/=(const mint& r) { return *this *= r.inv(); }
   friend mint operator+(mint l, mint r) { return l += r; }
   friend mint operator-(mint l, mint r) { return l -= r; }
   friend mint operator*(mint l, mint r) { return l *= r; }
   friend mint operator/(mint l, mint r) { return l /= r; }
   mint inv() const { return pow(mod - 2); }
   mint pow(ll b) const {
      mint a = *this, c = 1;
      while(b) {
         if(b & 1) c *= a;
         a *= a;
         b >>= 1:
```

```
return c;
}

;

using vm = vector<mint>;
```

modint.hpp

```
constexpr int mod = 998244353;
struct mint {
   int x;
   mint(ll x_ = 0) : x(x_ \% mod) {
      if(x < 0) x += mod;
   }
   mint operator-() {
     auto res = *this;
      res.x = (x ? mod - x : 0);
      return res;
   mint& operator+=(mint r) {
      if((x += r.x) >= mod) x -= mod;
      return *this;
   mint& operator-=(mint r) {
      if((x -= r.x) < 0) x += mod;
      return *this;
   mint& operator*=(mint r) {
      x = 1LL * x * r.x % mod;
      return *this;
   mint& operator/=(mint r) { return *this *= r.inv(); }
   friend mint operator+(mint a, mint b) { return a += b; }
   friend mint operator-(mint a, mint b) { return a -= b; }
   friend mint operator*(mint a, mint b) { return a *= b; }
   friend mint operator/(mint a, mint b) { return a /= b; }
   mint inv() const { return pow(mod - 2); }
   mint pow(ll b) const {
      mint a = *this, c = 1;
      while(b) {
         if(b & 1) c *= a;
         a *= a;
         b >>= 1;
      }
      return c;
  }
};
using vm = vector<mint>;
```

FPS

FFT.hpp md5: f769b5

```
mint g = 3; // 原始根
void fft(vm& a, bool inv = false) {
   int n = si(a), s = __lg(n);
   static vm z, iz;
   while(si(z) <= s) {</pre>
      z.eb(g.pow(mint(-1).x / (1 << si(z))));
      iz.eb(z.back().inv());
   }
   vm b(n);
   rep(i, 1, s + 1) {
      int w = 1 << s - i;</pre>
      mint base = inv ? iz[i] : z[i], now = 1;
      for(int y = 0; y < n / 2; y += w) {
         rep(x, w) {
            auto l = a[y << 1 | x], r = now * a[y << 1 | x |
w1;
            b[y \mid x] = l + r, b[y \mid x \mid n >> 1] = l - r;
         }
         now *= base;
      }
      swap(a, b);
   }
}
vm mul(vm a, vm b) {
   int n = si(a), m = si(b);
   if(!n or !m) return {};
   if(min(n, m) \le 30) {
```

linear-recurrence.hpp

md5: 7ef16a

```
// [x ^ k] p / q
mint LinearRecurrence(ll k, fps q, fps p) {
   q.shrink();
   mint ret = 0;
   if(si(p) >= si(q)) {
      auto r = p / q;
      p -= r * q;
      p.shrink();
      if(k < r.size()) ret += r[k];
   if(p.size() == 0) return ret;
   p.resize(q.size() - 1);
   while(k) {
      auto q2 = q;
      for(int i = 1; i < q2.size(); i += 2) q2[i] = -q2[i];
      auto s = p * q2, t = q * q2;
      for(int i = (k \& 1); i < s.size(); i += 2) p[i >> 1] =
s[i]:
      for(int i = 0; i < t.size(); i += 2) q[i >> 1] = t[i];
      k >>= 1;
   }
   return ret + p[0];
// a * q = 0
mint kitamasa(ll n, fps q, fps a) {
   if(n < si(a)) return a[n];</pre>
   auto p = a.pre(si(q) - 1) * q;
   p.resize(si(q) - 1);
   return LinearRecurrence(n, q, p);
```

poly.hpp

md5: 8da6ee

```
struct fns {
  fps(const vm& v = {}) : v(v) {}
  fps(int n) : v(n) {}
  void shrink() {
      while(v.size() && !v.back().x) v.pop_back();
  void resize(int n) { v.resize(n); }
  int size() const { return int(v.size()); }
  mint freq(int p) const { return (p < size()) ? v[p] : 0; }</pre>
  mint& operator[](int k) { return v[k]; }
  void emplace_back(mint x) { v.eb(x); }
  fps pre(int le) const { return {{v.begin(), v.begin() +
min(size(), le)}}; }
  fps operator-() const {
      vm res{v};
      fore(e, res) e = -e;
      return res;
  fps operator+(const fps& r) const {
      auto n = max(size(), r.size());
      vm res(n);
      rep(i, n) res[i] = freq(i) + r.freq(i);
      return res;
  fps operator-(const fps& r) const { return (*this) + (-r); }
  fps operator*(const fps& r) const { return {mul(v, r.v)}; }
   fps operator*(const mint& r) const {
      int n = size();
      vm res(n);
      for(int i = 0; i < n; i++) res[i] = v[i] * r;
```

```
return res;
   }
   fps operator/(const mint& r) const { return *this * r.inv();
   fps operator/(const fps& r) const {
      if(size() < r.size()) return {{}};</pre>
      int n = size() - r.size() + 1;
      return (rev().pre(n) * r.rev().inv(n)).pre(n).rev();
   fps operator%(const fps& r) const { return *this - *this / r
* r; }
  fps operator<<(int s) const {</pre>
      vm res(size() + s);
      rep(i, size()) res[i + s] = v[i];
      return res;
   fps operator>>(int s) const {
      if(size() <= s) return fps();</pre>
      vm res(size() - s);
      rep(i, size() - s) res[i] = v[i + s];
      return res;
   }
   fps& operator+=(const fps& r) { return *this = *this + r; }
   fps& operator-=(const fps& r) { return *this = *this - r; }
   fps& operator*=(const fps& r) { return *this = *this * r; }
   fps& operator*=(const mint& r) { return *this = *this * r; }
   fps& operator/=(const fps& r) { return *this = *this / r; }
   fps& operator/=(const mint& r) { return *this = *this / r; }
   fps& operator%=(const fps& r) { return *this = *this % r; }
   fps& operator<<=(int n) { return *this = *this << n; }</pre>
   fps& operator>>=(int n) { return *this = *this >> n; }
   fps rev(int n = -1) const {
      vm res = v;
      if(n != -1) res.resize(n);
      reverse(res.begin(), res.end());
      return res;
   fps diff() const {
      vm res(max(0, size() - 1));
      rep(i, 1, size()) res[i - 1] = freq(i) * i;
      return res;
   fps inteq() const {
      vm res(size() + 1);
      rep(i, size()) res[i + 1] = freq(i) / (i + 1);
      return res;
   // f * f.inv() = 1 + g(x)x^m
   fps inv(int m) const {
      fps res = fps(vm{mint(1) / freq(0)});
      for(int i = 1; i < m; i *= 2) { res = (res * mint(2) -</pre>
res * res * pre(2 * i)).pre(2 * i); }
      return res.pre(m);
   fps exp(int n) const {
      assert(freq(0).x == 0);
      fps g = fps(vm{1});
      for(int i = 1; i < n; i *= 2) { g = (g * (pre(i * 2) + i * 2)) }
fps(vm{1}) - g.log(i * 2))).pre(i * 2); }
      return g.pre(n);
   }
   fps log(int n) const {
      assert(freq(0).x == 1);
      auto f = pre(n);
      return (f.diff() * f.inv(n - 1)).pre(n - 1).integ();
   fps sqrt(int n) const {
      assert(freq(0).x == 1);
      fps f = pre(n + 1);
      fps g({1});
      for(int i = 1; i < n; i *= 2) { g = (g + f.pre(2 * i) *
g.inv(2 * i)) * mint((mod + 1) / 2); }
      return g.pre(n + 1);
   fps pow(ll k, ll n) {
      if(k == 0) {
         fps res(n);
         res[0] = 1;
         return res;
      rep(i, size()) {
         if((*this)[i].x) {
```

```
Speed Star (The University of Tokyo)
            mint rev = mint(1) / (*this)[i];
            fps ret = (((*this * rev) >> i).log(n) *
                                                                      1 + i];
mint(k)).exp(n);
                                                                            }
            ret *= (*this)[i].pow(k);
            ret = (ret << (i * k)).pre(n);
            if(ret.size() < n) ret.resize(n);</pre>
                                                                            return h[n - 1];
            return ret:
                                                                         }
                                                                      };
         if(i128(i + 1) * k >= n) return fps(n);
      }-
                                                                      tree
      return fps(n);
   fps pow_mod(ll n, const fps& mod) {
      fps x = *this, r = {\{1\}};
      while(n) {
                                                                         int N, cnt;
         if(n \& 1) r = r * x % mod;
         x = x * x % mod;
         n >>= 1;
                                                                            N = E.size();
      return r;
};
relaxed-convolution.hpp
                                                      md5: f1c765
                                                                                  d[i] = 0;
struct relaxed_multiplication {
   vector<mint> f, g, h;
                                                                            }
                                                                            cnt = 0;
   // fg_prefix_ntts[d] = (NTTs of first 2^d terms of f and g)
                                                                            G.resize(N + 1);
   vector<pair<vector<mint>, vector<mint>>> fg_prefix_ntts;
   const auto& get_fg_prefix_ntt(int d) {
      while(int(fg_prefix_ntts.size()) <= d) {</pre>
         int fftlen = 1 << fg_prefix_ntts.size();</pre>
         vector<mint> vf(f.begin(), f.begin() + fftlen);
         vector<mint> vg(g.begin(), g.begin() + fftlen);
                                                                                  cnt++;
         ntt(vf, false), ntt(vg, false);
         fg_prefix_ntts.emplace_back(vf, vg);
                                                                               }
      }
                                                                            }
      return fg_prefix_ntts[d];
                                                                            G.pop_back();
   relaxed_multiplication() {}
   mint add(const mint& f_i, const mint& g_i) {
      f.push_back(f_i), g.push_back(g_i);
      const int n = f.size(), d = __builtin_ctz(n), D = 1 << d;</pre>
                                                                                  next[v] = w;
      if(int gsz = n - 1 + D; h.size() < gsz) h.resize(gsz);</pre>
      if(n == D) {
                                                                                  imos[v]++;
         // Convolve f[0, D) * g[0, D) -> h[D - 1, D * 2 - 1)
         const auto& [nttf, nttg] = get_fg_prefix_ntt(d);
                                                                            }
         vector<mint> tmp(nttf.size());
         for(int i = 0; i < nttf.size(); ++i) tmp[i] = nttf[i]</pre>
* nttg[i];
```

ntt(tmp, true);

h[n - 1] += tmp[n - 1];

 $f[i] * g[k - i] + f[k - i] * g[i]; }$

tmpf[i] * nttg[i] + tmpg[i] * nttf[i]; } ntt(tmpf, true);

h[i]; // 回り込みを削除

} else {

}

} else {

tmpg{g.end() - D, g.end()};

1 + D)

1);

for(int i = 0; i < n - 1; ++i) h[n + i] += tmp[i] -

// Convolve f[0, 2 * D) * g[n - D, n) -> h[n - 1, n -

for(int i = n - D; i < n; ++i) {
 for(int k = n - 1; k < n - 1 + D; ++k) { h[k] +=</pre>

if(d <= 4) { // Bruteforce threshold</pre>

vector<mint> tmpf{f.end() - D, f.end()},

tmpf.resize(D * 2), tmpg.resize(D * 2);

const auto& [nttf, nttg] = get_fg_prefix_ntt(d +

for(int i = 0; i < tmpf.size(); ++i) { tmpf[i] =</pre>

ntt(tmpf, false), ntt(tmpg, false);

```
for(int i = 0; i < D; ++i) h[n - 1 + i] += tmpf[D -
```

```
block-cut-tree.hpp
```

md5: bf0113

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```
struct extended block cut tree {
   vector<vector<int>> G;
   extended_block_cut_tree(vector<vector<int>>& E) {
      vector<int> next(N, -1);
      vector<int> d(N, -1);
      vector<int> imos(N, 0);
      for(int i = 0; i < N; i++) {
         if(d[i] == -1) {
            dfs1(E, next, d, imos, i);
      vector<bool> used(N, false);
      for(int i = 0; i < N; i++) {
         if(d[i] == 0) { dfs2(E, d, imos, used, cnt, i); }
         if(E[i].empty()) {
            G[i].push_back(N + cnt);
            G[N + cnt].push_back(i);
            G.push_back({});
   void dfs1(vector<vector<int>>& E, vector<int>& next,
vector<int>& d, vector<int>& imos, int v) {
      for(int w : E[v]) {
         if(d[w] == -1) {
            d[w] = d[v] + 1;
            dfs1(E, next, d, imos, w);
            imos[v] += imos[w];
         } else if(d[w] < d[v] - 1) {</pre>
            imos[next[w]]--;
   void dfs2(vector<vector<int>>& E, vector<int>& d,
vector<int>& imos, vector<bool>& used, int b, int v) {
      used[v] = true;
      bool ok = false;
      for(int w : E[v]) {
         if(d[w] == d[v] + 1 \&\& !used[w]) {
            if(imos[w] > 0) {
               if(!ok) {
                  ok = true;
                  G[v].push_back(N + b);
                  G[N + b].push_back(v);
               }
               dfs2(E, d, imos, used, b, w);
            } else {
               G[v].push_back(N + cnt);
               G[N + cnt].push_back(v);
               G.push_back({});
               dfs2(E, d, imos, used, cnt - 1, w);
            }
         }
      }
      if(!ok \&\& d[v] > 0) {
         G[v].push_back(N + b);
         G[N + b].push_back(v);
```

template<typename G> struct HLD {

```
hld.hpp
```

G& g;

md5: fa40a1

```
vector<int> sub, in, out, head, rev, par, d;
   HLD(G\& g) : n(si(g)), g(g), sub(n), in(n), out(n), head(n),
rev(n), par(n), d(n) {}
   void dfs1(int x, int p) {
      par[x] = p;
      sub[x] = 1;
      if(g[x].size() and g[x][0] == p) swap(g[x][0],
q[x].back());
      fore(e, g[x]) {
         if(e == p) continue;
         d[e] = d[x] + 1;
         dfs1(e, x);
         sub[x] += sub[e];
         if(sub[g[x][0]] < sub[e]) swap(g[x][0], e);
   void dfs2(int x, int p, int& t) {
      in[x] = t++:
      rev[in[x]] = x;
      fore(e, g[x]) {
         if(e == p) continue;
         head[e] = (g[x][0] == e ? head[x] : e);
         dfs2(e, x, t);
      }
      out[x] = t;
   }
   void build() {
      int t = 0;
      head[0] = 0;
      dfs1(0, -1);
      dfs2(0, -1, t);
   int la(int v, int k) {
      while(1) {
         int u = head[v];
         if(in[v] - k >= in[u]) return rev[in[v] - k];
         k = in[v] - in[u] + 1;
         v = par[u];
      }
   int lca(int u, int v) {
      for(;; v = par[head[v]]) {
         if(in[u] > in[v]) swap(u, v);
         if(head[v] == head[v]) return u;
      }
   }
   template<typename T, typename Q, typename F>
   T query(int u, int v, const T& e, const Q& q, const F& f,
bool edge = false) {
      Tl = e, r = e;
      for(;; v = par[head[v]]) {
         if(in[u] > in[v]) swap(u, v), swap(l, r);
         if(head[u] == head[v]) break;
         l = f(q(in[head[v]], in[v] + 1), l);
      return f(f(q(in[u] + edge, in[v] + 1), l), r);
   int dist(int u, int v) { return d[u] + d[v] - 2 * d[lca(u, v)]
v)1: }
   int jump(int s, int t, int i) {
      if(!i) return s;
      int l = lca(s, t);
      int dst = d[s] + d[t] - d[l] * 2;
      if(dst < i) return -1;</pre>
      if(d[s] - d[l] >= i) return la(s, i);
      i -= d[s] - d[l];
      return la(t, d[t] - d[l] - i);
  }
```

flow

bipartite-matching.hpp

```
md5: 2ffb05
```

```
struct Bimatch {
   vector<vi> g;
   vi d, mc, used, vv;
   Bimatch(int n, int m) : g(n), mc(m, -1), used(n) {}
   void add(int u, int v) { g[u].eb(v); }
   void bfs() {
      d.assign(si(g), -1);
      queue<int> q;
      rep(i, si(g)) {
         if(!used[i]) {
            q.emplace(i);
            d[i] = 0;
      }
      while(!q.empty()) {
         int x = q.front();
         q.pop();
         fore(e, g[x]) {
            int c = mc[e];
            if(c >= 0 \text{ and } d[c] == -1) {
               d[c] = d[x] + 1;
               q.emplace(c);
            }-
         }
      }
   }
   bool dfs(int x) {
      vv[x] = true;
      fore(e, g[x]) {
         int c = mc[e];
         if(c < 0 or (!vv[c] and d[c] == d[x] + 1 and dfs(c)))
            mc[e] = x;
            used[x] = true;
            return true;
      }
      return false;
   }
   int match() {
      int ret = 0;
      while(true) {
         bfs();
         vv.assign(si(g), false);
         int f = 0:
         rep(i, si(g)) if(!used[i] and dfs(i)) f++;
         if(!f) return ret;
         ret += f;
      }
   }
};
```

flow.hpp md5: e99393

```
template<typename T> struct Dinic {
   const T INF;
   struct edge {
     int to;
      T cap;
      int rev:
      bool isrev;
      int idx;
   vector<vector<edge>> g;
   vector<int> c, iter;
   Dinic(int V) : INF(numeric_limits<T>::max()), g(V) {}
   void add_edge(int from, int to, T cap, int idx = -1) {
      g[from].emplace_back((edge){to, cap, si(g[to]), false,
idx}):
      g[to].emplace_back((edge){from, 0, si(g[from]) - 1, true,
idx});
   }
```

```
bool bfs(int s, int t) {
      c.assign(si(g), -1);
      queue<int> q;
      c[s] = 0;
      q.push(s);
      while(!q.empty() && c[t] == -1) {
         int x = q.front();
         q.pop();
         fore(e, g[x]) {
             if(e.cap > 0 && c[e.to] == -1) {
                c[e.to] = c[x] + 1;
                q.push(e.to);
         }
      }
      return c[t] != -1;
   T dfs(int x, int t, T flow) {
      if(x == t) return flow;
      for(int& i = iter[x]; i < si(g[x]); i++) {</pre>
         edge\& e = g[x][i];
          if(e.cap > 0 \&\& c[x] < c[e.to]) {
             T d = dfs(e.to, t, min(flow, e.cap));
             if(d > 0) {
                e.cap -= d;
                g[e.to][e.rev].cap += d;
                return d;
         }
      }
      return 0;
   T max_flow(int s, int t) {
      T flow = 0;
      while(bfs(s, t)) {
         iter.assign(si(g), 0);
         T f = 0:
         while((f = dfs(s, t, INF)) > 0) flow += f;
      }
      return flow;
   }
   // void output() {
          for(int i = 0; i < g.size(); i++) {
               for(auto &e : g[i]) {
   //
   //
                   if(e.isrev) continue;
                   auto &rev_e = g[e.to][e.rev];
cout << i << "->" << e.to << " (flow: " <<</pre>
   //
   //
rev_e.cap << "/" << e.cap + rev_e.cap << ")" << endl;
   //
               }
   //
          }
   // }
```

lower-upper-bound-flow.hpp

md5: 278a5a

```
template<typename T> struct lrFlow {
   Dinic<T> flow:
   vector<T> in, up;
   int X, Y, n;
   T sum;
   typename Dinic<T>::edge *p, *q;
   lrFlow(int n) : n(n), X(n), Y(n + 1), sum(0), in(n), flow(n)
+ 2) {}
   void add_edge(int from, int to, T low, T high) {
      flow.add_edge(from, to, high - low, si(up));
      in[from] -= low, in[to] += low;
      up.eb(high);
   }
   void build() {
      rep(i, n) {
         if(in[i] > 0) {
            flow.add_edge(X, i, in[i]);
            sum += in[i];
         } else if(in[i] < 0) {</pre>
            flow.add_edge(i, Y, -in[i]);
```

```
}
   bool can_flow(int s, int t) {
      flow.add_edge(t, s, flow.INF);
      p = &flow.g[t].back();
      q = &flow.g[s].back();
      return can_flow();
   bool can_flow() {
      build();
      auto ret = flow.max_flow(X, Y);
      return ret >= sum;
   T max_flow(int s, int t) {
      if(can_flow(s, t)) {
         return flow.max_flow(s, t);
      } else {
         return -1;
      }
   T min_flow(int s, int t) {
      if(can_flow(s, t)) {
         auto ret = flow.INF - p->cap;
         p->cap = q->cap = 0;
         return ret - flow.max_flow(t, s);
      } else {
         return -1;
      }
   }
   // void output(int M) {
   //
          vector<flow_t> ans(M);
   //
          for(int i = 0; i < flow.graph.size(); i++) {</pre>
   //
              for(auto &e : flow.graph[i]) {
   //
                  if(!e.isrev && ~e.idx) ans[e.idx] = up[e.idx]
- e.cap;
   //
   //
   //
          for(auto &p : ans) cout << p << endl;</pre>
   // }
};
```

mcf.hpp md5: 96eeaa

```
struct MCF {
   struct edge {
      int to;
      ll cap, cost;
      int rev;
      bool isrev;
   };
   vector<vector<edge>> g;
   vl pot, cost;
   vi pv, pe;
   MCF(int n) : g(n) {}
   void add(int u, int v, ll cap, ll cost) {
      g[u].eb(v, cap, cost, si(g[v]), false);
      g[v].eb(u, 0, -cost, si(g[u]) - 1, true);
   ll mcf(int s, int t, ll f) {
      int n = si(g);
      ll ret = 0;
      using P = pair<ll, int>;
      priority_queue<P, vector<P>, greater<P>> pq;
      pot.assign(n, 0), pe.assign(n, -1), pv.assign(n, -1);
      while(f) {
         cost.assign(n, INFL);
         pq.emplace(0, s);
         cost[s] = 0;
         while(!pq.empty()) {
            auto [c, x] = pq.top();
            pq.pop();
            if(cost[x] < c) continue;</pre>
            rep(i, si(g[x])) {
               edge\& e = g[x][i];
               ll ncost = cost[x] + e.cost + pot[x] -
pot[e.to];
```

```
if(e.cap and chmin(cost[e.to], ncost)) {
                  pv[e.to] = x, pe[e.to] = i;
                  pq.emplace(cost[e.to], e.to);
         }
         if(cost[t] == INFL) return -1;
         rep(i, n) pot[i] += cost[i];
         ll addflow = f;
         for(int v = t; v != s; v = pv[v]) chmin(addflow,
g[pv[v]][pe[v]].cap);
         f -= addflow;
         ret += addflow * pot[t];
         for(int v = t; v != s; v = pv[v]) {
            auto& e = g[pv[v]][pe[v]];
            e.cap -= addflow;
            g[v][e.rev].cap += addflow;
      return ret;
```

二部グラフ.md

|| サイズ | 構成||最大マッチング| |M| || |最小点被覆| |M| | L 到達不可能 + R 到達可能||最大安定集合||V| — |M| | 上の補グラフ||最小辺被覆|孤立点がないなら|V| — |M| |最大マッチング + 含まれない点 greedy|

燃やす埋める.md

変形前の制約	変形後の制約
xが 0 のとき z 失う	(x,T,z)
x が 0 のとき z 得る	無条件で z 得る; (S,x,z)
xが 1 のとき z 失う	(S,x,z)
xが 1 のとき z 得る	無条件で z 得る; (x,T,z)
x,y,\dots がすべて 0 のとき z 得る	無条件で z 得る; $(S,w,z),(w,x,\infty),(w,y,\infty)$
x,y,\dots がすべて 1 のとき z 得る	無条件で z 得る; $(w,T,z),(x,w,\infty),(y,w,\infty)$

string

KMP.hpp

md5: 886c63

```
// kmp[i] := max{ l ≤ i | s[:l] == s[(i+1)-l:i+1] }
// abacaba -> 0010123
auto KMP(string s) {
    vector<ll> p(sz(s));
    rep(i, 1, sz(s)) {
        ll g = p[i - 1];
        while(g && s[i] != s[g]) g = p[g - 1];
        p[i] = g + (s[i] == s[g]);
    }
    return p;
}
```

Manacher.hpp

md5: 5882fb

```
// 各位置での回文半径を求める
// aaabaaa -> 1214121
// 偶数長の回文を含めて直径を知るには, N+1 個の $ を挿入して 1 を引く
// $a$a$a$b$a$a$a$ -> 123432181234321
auto manacher(string s) {
    ll n = sz(s), i = 0, j = 0;
    vector<ll> r(n);
    while(i < n) {
        while(i >= j && i + j < n && s[i - j] == s[i + j]) j++;
        r[i] = j;
        ll k = 1;
        while(i >= k && i + k < n && k + r[i - k] < j) {
            r[i + k] = r[i - k];
```

```
k++;
}
i += k, j -= k;
}
return r;
```

RollingHash.hpp

md5: b0e4a8

```
const ll mod = (1LL << 61) - 1;</pre>
ll add(ll a, ll b) { return (a += b) >= mod ? a - mod : a; }
ll mul(ll a, ll b) {
   i128 c = (i128)a * b;
   return add(c >> 61, c & mod);
ll r = 7954398468495;
struct RH {
  ll n;
   vl hs, pw;
   RH(string s) : n(si(s)), hs(n + 1), pw(n + 1, 1) {
      rep(i, n) {
         pw[i + 1] = mul(pw[i], r);
         hs[i + 1] = add(mul(hs[i], r), s[i]);
      }
   ll get(ll l, ll r) const { return add(hs[r], mod -
mul(hs[l], pw[r - l])); }
   int lcp(int i, int j) {
      int ok = 0, ng = min(n - i, n - j) + 1;
      while(ok < ng - 1) {</pre>
         int mid = ok + ng >> 1;
         (get(i, i + mid) == get(j, j + mid) ? ok : ng) = mid;
      return ok;
};
```

SuffixArray.hpp

md5: deae26

```
// returns pair{sa, lcp}
// sa 長さ n : s[sa[0]:] < s[sa[1]:] < … < s[sa[n-1]:]
// lcp 長さ n-1 : lcp[i] = LCP(s[sa[i]:], s[sa[i+1]:])
auto SA(string s) {
  ll n = si(s) + 1, lim = 256;
   // assert(lim > ranges::max(s));
   vector<ll> sa(n), lcp(n), x(all(s) + 1), y(n), ws(max(n, s))
lim)), rk(n);
   iota(all(sa), 0);
   for(ll j = 0, p = 0; p < n; j = max(1LL, j * 2), lim = p) {
      p = j;
      iota(all(y), n - j);
      rep(i, 0, n) if(sa[i] >= j) y[p++] = sa[i] - j;
      fill(all(ws), 0);
      rep(i, 0, n) ws[x[i]] ++;
      rep(i, 1, lim) ws[i] += ws[i - 1];
      for(ll i = n; i--;) sa[--ws[x[y[i]]]] = y[i];
      swap(x, y);
      p = 1;
      x[sa[0]] = 0;
      rep(i, 1, n) {
         ll a = sa[i - 1], b = sa[i];
         x[b] = (y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1
: p++;
   }
   rep(i, 1, n) rk[sa[i]] = i;
   for(ll i = 0, k = 0; i < n - 1; lcp[rk[i++]] = k) {
      if(k) k--:
      while(s[i + k] == s[sa[rk[i] - 1] + k]) k++;
   sa.erase(begin(sa));
   lcp.erase(begin(lcp));
   return pair{sa, lcp};
```

Zalgorithm.hpp

md5: d3bdab

```
template<typename T> vi z_algorithm(const vector<T>& s) {
  int n = si(s), l = -1, r = -1;
  vi z(n, n);
  rep(i, 1, n) {
```

```
int& x = z[i] = i < r ? min<ll>(r - i, z[i - l]) : 0;
  while(i + x < n and s[i + x] == s[x]) x++;
  if(i + x > r) l = i, r = i + x;
}
return z;
}
```

enumerate-runs.hpp

md5: aec96b

```
// (length, l, r)
template<typename T> vector<array<int, 3>> enum_runs(const
vector<T>& s) {
   int n = si(s):
   vector<array<int, 3>> res;
   auto dfs = [&](auto&& f, int l, int r) -> void {
      if(r - l <= 1) return;</pre>
      int m = l + r >> 1;
      f(f, l, m), f(f, m, r);
      vector<T> sl(s.rbegin() + n - m, s.rbegin() + n - l);
      sl.insert(sl.end(), s.rbegin() + n - r, s.rbegin() + n -
ι);
      vector<T> sr(s.begin() + m, s.begin() + r);
      sr.insert(sr.end(), s.begin() + l, s.begin() + r);
      auto zsl = z_algorithm(sl), zsr = z_algorithm(sr);
      rep(t, 1, m - l + 1) {
         int ml = max<ll>(l, m - t - zsl[t]), mr = min(r, m +
zsr[r - l - t]);
         if(mr - ml >= 2 * t and (ml == 0 \text{ or } s[ml - 1] != s[ml
+ t - 1) and (mr == n \text{ or } s[mr] != s[mr - t]))
            res.push_back({ml, mr, t});
      for(int t = 1; t <= r - m; t++) {
         int ml = max(l, m - zsl[r - l - t]), mr = min(r, m + t)
+ zsr[t]);
         if(mr - ml >= 2 * t and (ml == 0 \text{ or } s[ml - 1] != s[ml]
 t - 1) and (mr == n \text{ or } s[mr] != s[mr - t]))
            res.push_back({ml, mr, t});
   };
   dfs(dfs, 0, n);
   sort(all(res));
   vector<array<int, 3>> nres;
   int pl = -1, pr = -1;
   for(auto [l, r, t] : res) {
      if(l == pl and r == pr) continue;
      pl = 1, pr = r;
      nres.push_back({t, l, r});
   return nres;
```

geometry

argument-sort.hpp

md5: 26b1fa

```
bool operator<(point P, point Q) {
   long long C = cross(P, Q);
   if(C == 0 && dot(P, Q) > 0) {
      return false;
   } else if(P.x < 0 && P.y == 0) {
      return true;
   } else if(Q.x < 0 && Q.y == 0) {
      return false;
   } else if(P.y * Q.y <= 0) {
      return P.y < Q.y;
   } else {
      return C > 0;
   }
}
```

circle.hpp

md5: 514ea6

```
struct circle {
  point C;
  double r;
  circle() {}
  circle(point C, double r) : C(C), r(r) {}
};
pair<point, point> line_circle_intersection(line L, circle C) {
  point P = projection(C.C, L);
```

```
double d = point_line_distance(C.C, L);
   double h = sqrt(C.r * C.r - d * d);
   point A = P + vec(L) / abs(vec(L)) * h;
   point B = P - \text{vec}(L) / \text{abs}(\text{vec}(L)) * h;
   return make_pair(A, B);
}
pair<point, point> circle_intersection(circle C1, circle C2) {
   double d = dist(C1.C, C2.C);
   double m = (C1.r * C1.r - C2.r * C2.r + d * d) / (d * 2);
   point M = C1.C + (C2.C - C1.C) / d * m;
   double h = sqrt(C1.r * C1.r - m * m);
   point H = rotate90(C2.C - C1.C) / d * h;
   return make_pair(M - H, M + H);
pair<point, point> circle_tangent(point P, circle C) {
   double d = dist(P, C.C);
   double r = sqrt(d * d - C.r * C.r);
   return circle_intersection(C, circle(P, r));
vector<line> common_tangent(circle C1, circle C2) {
   if(C1.r < C2.r) { swap(C1, C2); }</pre>
   double d = dist(C1.C, C2.C);
   vector<line> L;
   if(C1.r - C2.r <= d + eps) {
      if(C1.r - C2.r <= eps) {
         point D = rotate90(C2.C - C1.C) / d * C1.r;
         L.push_back(line(C1.C + D, C2.C + D));
         L.push_back(line(C1.C - D, C2.C - D));
      } else {
         double m = (C1.r - C2.r) * (C1.r - C2.r) / d;
         point M = C1.C + (C2.C - C1.C) / d * m;
         double h = sqrt((C1.r - C2.r) * (C1.r - C2.r) - m *
m);
         point H1 = M + rotate90(C2.C - C1.C) / d * h;
         point D1 = (H1 - C1.C) / dist(H1, C1.C) * C2.r;
         L.push_back(line(H1 + D1, C2.C + D1));
         point H2 = M - rotate90(C2.C - C1.C) / d * h;
         point D2 = (H2 - C1.C) / dist(H2, C1.C) * C2.r;
         L.push_back(line(H2 + D2, C2.C + D2));
     }
   if(C1.r + C2.r <= d + eps) {
      double m = (C1.r + C2.r) * (C1.r + C2.r) / d;
      point M = C1.C + (C2.C - C1.C) / d * m;
      double h = sqrt((C1.r + C2.r) * (C1.r + C2.r) - m * m);
      point H1 = M + rotate90(C2.C - C1.C) / d * h;
      point D1 = (H1 - C1.C) / dist(H1, C1.C) * C2.r;
      L.push_back(line(H1 - D1, C2.C - D1));
      point H2 = M - rotate90(C2.C - C1.C) / d * h;
      point D2 = (H2 - C1.C) / dist(H2, C1.C) * C2.r;
      L.push_back(line(H2 - D2, C2.C - D2));
   }
   return L;
```

convex-hull.hpp

md5: 7b7e26

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```
Points convex_hull(Points& p) {
    int n = p.size(), k = 0;
    if(n <= 2) return p;
    sort(begin(p), end(p), [](pt x, pt y) { return (x.x != y.x ?
    x.x < y.x : x.y < y.y); });
    Points ch(2 * n);
    for(int i = 0; i < n; ch[k++] = p[i++]) {
        while(k >= 2 && cross(ch[k - 1] - ch[k - 2], p[i] - ch[k
        - 1]) <= 0) --k;
    }
    for(int i = n - 2, t = k + 1; i >= 0; ch[k++] = p[i--]) {
        while(k >= t && cross(ch[k - 1] - ch[k - 2], p[i] - ch[k
        - 1]) <= 0) --k;
    }
    ch.resize(k - 1);
    return ch;
}</pre>
```

funcs.hpp

md5: 19bea4

```
int contains(const Polygon& Q, const Point& p) {
  bool in = false;
  for(int i = 0; i < Q.size(); i++) {
    Point a = Q[i] - p, b = Q[(i + 1) % Q.size()] - p;
    if(a.y > b.y) swap(a, b);
```

```
Speed Star (The University of Tokyo)
      if(a.y <= 0 \& 0 < b.y \& cross(a, b) < 0) in = !in;
      if(cross(a, b) == 0 \&\& dot(a, b) <= 0) return _ON;
   }
   return in ? _IN : _OUT;
Polygon Minkowski_sum(const Polygon& P, const Polygon& Q) {
   vector<Segment> e1(P.size()), e2(Q.size()), ed(P.size() +
   const auto cmp = [](const Segment& u, const Segment& v) {
return (u.b - u.a).arg_cmp(v.b - v.a); };
   rep(i, P.size()) e1[i] = {P[i], P[(i + 1) % P.size()]};
   rep(i, Q.size()) e2[i] = {Q[i], Q[(i + 1) % Q.size()]};
   rotate(begin(e1), min_element(all(e1), cmp), end(e1));
   rotate(begin(e2), min_element(all(e2), cmp), end(e2));
   merge(all(e1), all(e2), begin(ed), cmp);
   const auto check = [](const Points& res, const Point& u) {
      const auto back1 = res.back(), back2 = *prev(end(res),
      return eq(cross(back1 - back2, u - back2), eps) and
dot(back1 - back2, u - back1) >= -eps;
  };
   auto u = e1[0].a + e2[0].a;
   Points res{u};
   res.reserve(P.size() + Q.size());
   for(const auto& v : ed) {
      u = u + v.b - v.a;
      while(si(res) >= 2 and check(res, u)) res.pop_back();
      res.eb(u):
   if(res.size() and check(res, res[0])) res.pop_back();
   return res;
// -1 : on, 0 : out, 1 : in
// O(log(n))
bool is_in(const Polygon& p, const Point& a) {
   if(p.size() == 1) return a == p[0] ? -1 : 0;
   if(p.size() == 2) return intersect(Segment(p[0], p[1]), a);
   if(a == p[0]) return -1;
   if((p[1] - p[0]).toleft(a - p[0]) == -1 || (p.back() -
p[0]).toleft(a - p[0]) == 1) return 0;
   const auto cmp = [&](const Point& u, const Point& v) {
return (u - p[0]).toleft(v - p[0]) == 1; };
   const size_t i = lower_bound(p.begin() + 1, p.end(), a, cmp)
 p.begin();
  if(i == 1) return intersect(Segment(p[0], p[i]), a) ? -1 :
   if(i == p.size() - 1 \&\& intersect(Segment(p[0], p[i]), a))
   if(intersect(Segment(p[i - 1], p[i]), a)) return -1;
   return (p[i] - p[i - 1]).toleft(a - p[i - 1]) > 0;
using speP = pair<ld, int>;
struct ccut {
   private:
   set<speP> ags;
   vector<int> nexs:
   vector<int> pres;
   vector<Point> ps;
   public:
   void init() {
      const ld sup = -100000;
      ps.push_back({-sup, -sup});
      ps.push_back({sup, -sup});
      ps.push_back({sup, sup});
      ps.push_back({-sup, sup});
      nexs.resize(4);
      pres.resize(4);
      rep(i, 4) {
         int ni = (i + 1) \% 4;
         Point dif = ps[ni] - ps[i];
         ld t = arg(dif);
         ags.insert({t, i});
         nexs[i] = ni;
         pres[ni] = i;
      }
```

void convex_cut(Point a, Point b) {

if(ags.empty()) return;

```
Point dif = b - a;
      ld t = arg(dif);
      auto itr = ags.lower_bound({t, -1});
      if(itr == ags.end()) itr = ags.begin();
      int cur = (*itr).second;
      if(ccw(a, b, ps[cur]) != -1) return;
      int ricur = nexs[cur];
      while(ricur != cur && ccw(a, b, ps[ricur]) != 1) { ricur
= nexs[ricur]; }
      if(ricur == cur) {
         ags.clear();
         return;
      int lecur = pres[cur];
      while(ccw(a, b, ps[lecur]) != 1) { lecur = pres[lecur]; }
      // new point
      Line l = \{a, b\};
      Line l1 = {ps[lecur], ps[nexs[lecur]]};
      Line l2 = {ps[pres[ricur]], ps[ricur]};
      Point p1 = is_ll(l1, l);
      Point p2 = is_ll(l2, l);
      int id1 = ps.size();
      int id2 = ps.size() + 1;
      ps.push_back(p1), ps.push_back(p2);
      rep(2) nexs.push_back(-1), pres.push_back(-1);
      // erase(lecur,ricur)
      cur = lecur;
      int tmp = 0;
      while(cur != ricur || !tmp) {
         Point dif = ps[nexs[cur]] - ps[cur];
         ld t = arg(dif);
         ags.erase({t, cur});
         cur = nexs[cur];
         tmp++;
      }
      nexs[lecur] = id1, pres[id1] = lecur, nexs[id1] = id2;
      pres[id2] = id1, nexs[id2] = ricur, pres[ricur] = id2;
      cur = lecur, tmp = 0;
      while(cur != ricur || !tmp) {
         Point dif = ps[nexs[cur]] - ps[cur];
         ld t = arg(dif);
         ags.insert({t, cur});
         cur = nexs[cur];
         tmp++;
      }
   polygon nw_poly() {
      polygon nw;
      for(auto p : ags) nw.push_back(ps[p.second]);
      return nw;
   }
   ld calc_area() {
      polygon nw;
      for(auto p : ags) nw.push_back(ps[p.second]);
      return area(nw);
};
```

line.hpp

md5: 447fab

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```
bool point_on_segment(point P, line L) { return dot(P - L.A,
vec(L)) > -eps && dot(P - L.B, vec(L)) < eps; }
point projection(point P, line L) { return L.A + vec(L) /
abs(vec(L)) * dot(P - L.A, vec(L)) / abs(vec(L)); }
point reflection(point P, line L) { return projection(P, L) * 2
double point_line_distance(point P, line L) { return
abs(cross(P - L.A, vec(L))) / abs(vec(L)); }
double point_segment_distance(point P, line L) {
   if(dot(P - L.A, vec(L)) < 0) {
     return dist(P, L.A);
   else\ if(dot(P - L.B, vec(L)) > 0) {
      return dist(P, L.B);
   } else {
      return point_line_distance(P, L);
bool is_parallel(line L1, line L2) { return abs(cross(vec(L1),
vec(L2))) < eps; }</pre>
point line_intersection(line L1, line L2) {
```

```
return L1.A + vec(L1) * cross(L2.A - L1.A, vec(L2)) /
cross(vec(L1), vec(L2));
bool segment_intersect(line L1, line L2) {
   return cross(L1.A - L2.A, vec(L2)) * cross(L1.B - L2.A,
vec(L2)) < eps
          && cross(L2.A - L1.A, vec(L1)) * cross(L2.B - L1.A,
vec(L1)) < eps;</pre>
double segment_distance(line L1, line L2) {
   if(segment_intersect(L1, L2)) {
      return 0;
   } else {
      double ans = INF;
      ans = min(ans, point_segment_distance(L1.A, L2));
      ans = min(ans, point_segment_distance(L1.B, L2));
      ans = min(ans, point_segment_distance(L2.A, L1));
      ans = min(ans, point_segment_distance(L2.B, L1));
      return ans;
  }
```

misc

clock.hpp

md5: a1f32c

```
struct Timer {
#define C chrono::high_resolution_clock
   C::time_point c;
   Timer() : c(C::now()) {}
   long long elapsed() {
      auto d = C::now();
      return chrono::duration_cast<chrono::milliseconds>(d -
c).count();
  }
#undef C
};
```

simplex.hpp

md5: 644ba1

```
template<typename F = double, int DEPS = 30, bool Randomize =
true> struct Simplex {
   const F EPS = F(1.0) / (1LL << DEPS);</pre>
   int n, m;
   vi shuffle_idx;
   vi idx;
   vector<vector<F>> mat;
   int i_ch, j_ch;
   private:
   void _initialize(const vector<vector<F>>& A, const
vector<F>& b, const vector<F>& c) {
      n = c.size(), m = A.size();
      mat.assign(m + 2, vector < F > (n + 2));
      i_ch = m;
      rep(i, m) {
         rep(j, n) mat[i][j] = -A[i][j];
         mat[i][n] = 1, mat[i][n + 1] = b[i];
         if(mat[i_ch][n + 1] > mat[i][n + 1]) i_ch = i;
      }
      rep(j, n) mat[m][j] = c[j];
      mat[m + 1][n] = -1;
      idx.resize(n + m + 1);
      iota(idx.begin(), idx.end(), 0);
   inline F abs_(F x) noexcept { return x > -x ? x : -x; }
   void _solve() {
      vi jupd;
      for(nb_iter = 0, j_ch = n;; nb_iter++) {
         if(i_ch < m) {
            swap(idx[j_ch], idx[i_ch + n + 1]);
            mat[i_ch][j_ch] = F(1) / mat[i_ch][j_ch];
            jupd.clear();
            rep(j, n + 2) {
               if(j != j_ch) {
                  mat[i_ch][j] *= -mat[i_ch][j_ch];
                  if(abs_(mat[i_ch][j]) > EPS)
jupd.push_back(j);
```

```
}
            rep(i, m + 2) {
               if(abs_(mat[i][j_ch]) < EPS or i == i_ch)</pre>
continue;
               fore(j, jupd) mat[i][j] += mat[i][j_ch] *
mat[i_ch][j];
               mat[i][j_ch] *= mat[i_ch][j_ch];
         }
         j_ch = -1;
         rep(j, n + 1) {
            if(j_ch < 0 \text{ or } idx[j_ch] > idx[j]) {
               if(mat[m + 1][j] > EPS or (abs_(mat[m + 1][j]) <</pre>
EPS and mat[m][j] > EPS)) j_ch = j;
         if(j_ch < 0) break;</pre>
         i_ch = -1;
         rep(i, m) {
            if(mat[i][j_ch] < -EPS) {
               if(i_ch < 0) {
                   i_ch = i;
               } else if(mat[i_ch][n + 1] / mat[i_ch][j_ch] -
mat[i][n + 1] / mat[i][j_ch] < -EPS) {
                  i_ch = i;
               } else if(mat[i_ch][n + 1] / mat[i_ch][j_ch] -
mat[i][n + 1] / mat[i][j_ch] < EPS
                          and idx[i_ch] > idx[i]) {
                  i_ch = i;
               }
            }
         if(i_ch < 0) {
            is_infty = true;
            break;
      }
      if(mat[m + 1][n + 1] < -EPS) {
         infeasible = true;
         return:
      }
      x.assign(n, 0);
      rep(i, m) {
         if(idx[n + 1 + i] < n) x[idx[n + 1 + i]] = mat[i][n +
1];
      ans = mat[m][n + 1];
  }
   public:
   Simplex(vector<vector<F>> A, vector<F> b, vector<F> c) {
      is_infty = infeasible = false;
      if(Randomize) {
         mt19937
rng(chrono::steady_clock::now().time_since_epoch().count());
         vector<pair<vector<F>, F>> Abs;
         rep(i, si(A)) Abs.emplace_back(A[i], b[i]);
         shuffle(Abs.begin(), Abs.end(), rng);
         A.clear(), b.clear();
         fore(Ab, Abs) A.emplace_back(Ab.first),
b.emplace_back(Ab.second);
         shuffle_idx.resize(c.size());
         iota(all(shuffle_idx), 0);
         shuffle(all(shuffle_idx), rng);
         auto Atmp = A;
         auto ctmp = c;
         rep(i, si(A)) rep(j, si(A[i])) A[i][j] = Atmp[i]
[shuffle_idx[j]];
         rep(j, si(c)) c[j] = ctmp[shuffle_idx[j]];
      _initialize(A, b, c);
      _solve();
      if(Randomize and x.size() == c.size()) {
         auto xtmp = x;
```

```
rep(j, si(c)) x[shuffle_idx[j]] = xtmp[j];
}
unsigned nb_iter;
bool is_infty;
bool infeasible;
vector<F> x;
F ans;

static void dual(vector<vector<F>& A, vector<F>& b,
vector<F>& c) {
    const int n = b.size(), m = c.size();
    vector<vector<F>> At(m, vector<F>(n));
    rep(i, n) rep(j, m) At[j][i] = -A[i][j];
    A = At;
    rep(i, n) b[i] = -b[i];
    rep(j, m) c[j] = -c[j];
    b.swap(c);
}
};
```

memo

Primes.md

素数の個数

n	10^2	10^3	10^4	10^5	10^{6}	10^{7}	10^{8}	10^{9}	10^{10}
$\pi(n)$	25	168	1229	9592	78498	664579	5.76e+6	5.08e+7	4.55e+8

高度合成数

$\leq n$	10^3	10^4	10^5	10^6	107	,	10^{8}	10^{9}	
\boldsymbol{x}	840	7560	83160	720720	86486	40 7	3513440	735134	400
$d^0(x)$	32	64	128	240	448	7	68	1344	
$\leq n$	10^{10}	10^{11}	10^{12}	10^{13}	10^{14}	10^{15}	10^{16}	10^{17}	10^{18}
$d^0(x)$	2304	4032	6720	10752	17280	2688	0 41472	64512	103680

素数階乗

n	2	3	5	7	11	13	17	19	23	29
n#	2	6	30	210	2310	30030	510510	9.70e+6	2.23e+8	6.47e+9

階乗

4!	5!	6!	7!	8!	9!	10!	11!	12!	13!
24	120	720	5040	40320	362880	3.63e+6	3.99e+7	4.79e+8	6.23e+9

math.md

二項係数

n\k	0	1	2	3	4	5	6	7	8	9	10
0	1										
1	1	1									
2	1	2	1								
3	1	3	3	1							
4	1	4	6	4	1						
5	1	5	10	10	5	1					
6	1	6	15	20	15	6	1				
7	1	7	21	35	35	21	7	1			
8	1	8	28	56	70	56	28	8	1		
9	1	9	36	84	126	126	84	36	9	1	
10	1	10	45	120	210	252	210	120	45	10	1
11	1	11	55	165	330	462	462	330	165	55	11
12	1	12	66	220	495	792	924	792	495	220	66
13	1	13	78	286	715	1287	1a716	1716	1287	715	286
14	1	14	91	364	1001	2002	3003	3432	3003	2002	1001

n\k	0	1	2	3	4	5	6	7	8	9	10
15	1	15	105	455	1365	3003	5005	6435	6435	5005	3003
16	1	16	120	560	1820	4368	8008	11440	12870	11440	8008
17	1	17	136	680	2380	6188	12376	19448	24310	24310	19448
18	1	18	153	816	3060	8568	18564	31824	43758	48620	43758
19	1	19	171	969	3876	11628	27132	50388	75582	92378	92378
20	1	20	190	1140	4845	15504	38760	77520	125970	167960	184756

$$\binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k} \, \binom{n}{k} = \frac{n}{k} \, \binom{n-1}{k-1} \, \binom{L}{k} + \dots + \binom{R-1}{k} = \binom{R}{k+1} - \binom{L}{k+1}$$

第一種スターリング数

c(n,k): $1,2,\ldots,n$ の順列で巡回置換 k 個に分割できるものの個数

$n \setminus k$	0	1	2	3	4	5	6	7
0	1							
1	0	1						
2	0	1	1					
3	0	2	3	1				
4	0	6	11	6	1			
5	0	24	50	35	10	1		
6	0	120	274	225	85	15	1	
7	0	720	1764	1624	735	175	21	1

$$\begin{array}{l} c(n,k) = c(n-1,k-1) + (n-1)c(n-1,k) \\ x(x+1) \dots (x+n-1) = \sum_{k=0}^n c(n,k) x^k \sum_{k=0}^n c(n,k) = n! \\ \sum_{k=0}^n 2^k c(n,k) = (n+1)! \sum_{k=0}^n (-1)^k c(n,k) = 0 \end{array}$$

 $\sum_{k=0}^n c(n,k) x^k = x(x+1)\dots(x+n-1)$ を用いて分割統治し,片方の計算を polynomial taylor shift で再利用すると,c(N,k) の k に関する列挙が $O(N\log N)$ 時間でできる.

第二種スターリング数

S(n,k): $1,2,\ldots,n$ を k 個の区別しない集合に分割する方法の数

$n \setminus k$	0	1	2	3	4	5	6	7
0	1							
1	0	1						
2	0	1	1					
3	0	1	3	1				
4	0	1	7	6	1			
5	0	1	15	25	10	1		
6	0	1	31	90	65	15	1	
7	0	1	63	301	350	140	21	1

S(n,k) = S(n-1,k-1) + kS(n-1,k) $x^n = \sum_{k=0}^n S(n,k)x(x-1)\dots(x-k+1)$ $S(n,k) = \frac{1}{k!} \sum_{m=1}^k (-1)^{k-m} {k \choose m} m^n$

最後の式と畳み込みを使うと S(N,k) の k に関する列挙が $O(N\log N)$ 時間でできる.

ベル数

 B_n : $1,2,\ldots,n$ をいくつかの集合に分割する方法の数

n	0	1	2	3	4	5	6	7	8	9	10
B_n	1	1	2	5	15	52	203	877	4140	21147	115975

 $B_{n+1} = \sum_{k=0}^{n} \binom{n}{k} B_k B_n = \frac{1}{e} \sum_{k=0}^{\infty} \frac{k^n}{k!}$

指数型母関数 $\exp(\exp x-1)=\sum_{n=0}^\infty B_n rac{x^n}{n!}$ を使うと B_0,B_1,\dots,B_n の計算が $O(N\log N)$ でできる.

カタラン数

 C_n : n 個の (と)を括弧列になるように並べる方法の数

n	0	1	2	3	4	5	6	7	8	9	10
C_n	1	1	2	5	14	42	132	429	1430	4862	16796

$$C_n = \frac{1}{n+1} \binom{2n}{n} = \frac{(2n)!}{(n+1)!n!} \; C_{n+1} = \frac{2(2n+1)}{n+2} C_n \; C_{n+1} = \sum_{k=0}^n C_k C_{n-k}$$

モンモール数

 a_n : $1,2,\ldots,n$ の順列 P で $P_i
eq i$ となるものの個数

n	0	1	2	3	4	5	6	7	8	9	10
a_n		0	1	2	9	44	265	1854	14833	133496	1334961

$$a_n = (n-1)(a_{n-1} + a_{n-2}) a_n = na_{n-1} + (-1)^n$$

分割数

 P_n : n を正の整数の和として表す方法の数

n	0	1	2	3	4	5	6	7	8	9	10
P_n	1	1	2	3	5	7	11	15	22	30	42

母関数は $\prod_{n=1}^\infty \frac{1}{1-x^n} = \sum_{n=0}^\infty P_n x^n$ である.五角数定理より $\prod_{n=1}^\infty (1-x^n) = \sum_{n=-\infty}^\infty (-1)^n x^{n(3n+1)/2}$ なので, P_0,P_1,\ldots,P_N を $O(N\log N)$ 時間で列挙できる.

母関数

$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + x^4 + \dots = \sum_{n=0}^{\infty} x^n$$

$$\frac{1}{(1-x)^2} = 1 + 2x + 3x^2 + 4x^3 + 5x^4 + \dots = \sum_{n=0}^{\infty} (n+1)x^n$$

$$rac{1}{(1-x)^3} = 1 + 3x + 6x^2 + 10x^3 + 15x^4 + \dots = \sum_{n=0}^{\infty} rac{1}{2}(n+1)(n+2)x^n$$

$$rac{1}{(1-x)^d} = \sum_{n=0}^{\infty} inom{n+d-1}{n} x^n$$

$$\sqrt{1-x}=1-rac{1}{2}x-rac{1}{8}x^2-rac{1}{16}x^3-rac{5}{128}x^4-\cdots=1-\sum_{n=1}^{\infty}rac{(2n-2)!}{2^{2n-1}n!(n-1)!}x^n$$

$$\frac{1}{\sqrt{1-x}} = 1 + \frac{1}{2}x + \frac{3}{8}x^2 + \frac{5}{16}x^3 + \frac{35}{128}x^4 - \dots = \sum_{n=0}^{\infty} \frac{(2n)!}{4^n n!} x^n$$

$$rac{1-\sqrt{1-4x}}{2x}=1+x+2x^2+5x^3+14x^4+\cdots=\sum_{n=0}^{\infty}C_nx^n=\sum_{n=0}^{\infty}rac{(2n)!}{(n+1)!n!}x^n$$
 (カタラン数)

$$rac{1}{\sqrt{1-4x}} = \sum_{n=0}^{\infty} inom{2n}{n} x^n$$

$$rac{1}{1-x-x^2}=1+x+2x^2+3x^3+5x^4+\cdots=\sum_{n=0}^{\infty}F_nx^n$$
 (フィボナッチ数)

$$\log(1-x) = -x - \frac{1}{2}x^2 - \frac{1}{3}x^3 - \frac{1}{4}x^4 - \dots = \sum_{n=1}^{\infty} \frac{1}{n}x^n$$

$$\exp(\exp x - 1) = \sum_{n=0}^{\infty} B_n \frac{x^n}{n}$$
 (ベル数)

$$\frac{1}{k}(\exp x-1)^k=\sum_{n=0}^\infty S(n,k)rac{x^n}{n!}$$
 (第二種スターリング数)

$$\frac{\exp(-x)}{1-x} = 1 + \frac{1}{2}x^2 + \frac{1}{3}x^3 + \frac{3}{8}x^4 + \dots = \sum_{n=0}^{\infty} a_n \frac{x^n}{n!}$$
 (モンモール数)

$$C(x)^k = \left(\frac{1-\sqrt{1-4x}}{2x}\right)^k = \sum_{n=0}^{\infty} \frac{k}{n+k} {2n+k-1 \choose n}$$
 (カタラン数の母関数の累乗)

ドキュメント.md

Data Structure

hash

写経をしたときにミスを発見するために使う。空白や改行を消した状態のハッシュを 計算して、一致していれば写経成功している 違えばどこかに違う部分があるとわか る

BIT

- BIT B(n):長さnのBITを作る
- B.sum(l, r) : $\sum_{i=l}^{r-1} A_i$ の値を求める。 $\operatorname{sum}(r)$ で0からの和。

FastSet

std::setより高速。bitsetで要素の存在を管理する。

- FS S(n): 0以上n未満の値を格納できるFSを作る
- S.set(i):iを挿入
- S.erase(i):iを削除
- S[i]:iが存在するならtrue,存在しないならfalse
- next(i):iより大きい最小の値
- prev(i):iより小さい最大の値

Skew-heap

基本的に普通の優先度付きキューと同一。2つのヒープの融合(meld)操作が速い使わんやろ

cht

Convex Hull Trick

 CHT は次の操作を効率的に行える。初め、空集合 S があるとする。

- S に直線 y=ax+b を追加 O(1)
- x_0 が与えられる。S に含まれる直線について、 ax_0+b の値をそれぞれ計算したときの最小値/最大値を求める。 $O(\log N)$

ただし、最小値を求める際は追加する直線の傾きが単調減少、最大値を求める際は追加する直線の傾きが単調増加である必要がある。それを満たせない場合はLi-chao tree など他の方法で。

- CHT<true> C 最小値を求める CHT の初期化
- CHT<false> C 最大値を求める CHT の初期化
- C.add(a, b) 直線a,bを追加
- C.query(x) xが与えられた時の最大値最小値

ところで、xが単調増加/単調減少であることが保証できるなら、 $query_monotone$ 系を使うことでクエリを O(1)にできる

hash_map

たぶん unordered_map でいい 衝突とかあったらこれを使う

lazy-segtree

遅延セグ木多分ACLと同じ

```
using S = long long;
using F = long long;

S op(S a, S b) { return a + b; }
S e() { return 0; }
S mpp(F f, S x) { return f + x; }
F cmpo(F f1, F f2) { return f1 + f2; }
F id() { return 0; }
int main() {
   int n = 10;
   lazy_segtree<S, op, e, F, mpp, cmpo, id> seg(n);
   seg.apply(0, 5, 10); // 区間 [0, 5) に 10 を加算
```

```
cout << seg.prod(0, 10) << endl; // 全区間の和を計算
return 0:
```

Li-chao tree

```
CHTの一般化
```

- ・直線 y=ax+b の追加
- •線分 $y = ax + b(l \le x < r)$ の追加
- 与えられた x に対する最小値の出力

dequeを使うCHTとは異なり、直線の追加順に制限はない.

x の値は初期化時にわかっている必要がある。クエリ先読みなどしておく

最大値にしたいときは(a, b)を入れる代わりに(-a, -b)を入れて最小値に-1を掛ければよ

```
vector<ll> xs = {1, 2, 3, 4, 5}; // x 座標の定義
lctree tree(xs);
```

```
// 直線追加
tree.update(2, 3); // y = 2x + 3
tree.update(-1, 6); // y = -x + 6
```

// 範囲に直線を追加 tree.update_segment(1, 4, 3, 2); // 範囲 [1, 4) に y = 3x + 2 を 適用

```
cout << tree.query(2) << endl; // x = 2 における最小値
cout << tree.query(4) << endl; // x = 4 における最小値
```

// クエリ

line_container

Li-chao treeと違って線分は突っ込めない

LineContainer<> lc; // 最小値を求める直線集合

```
// 直線を追加
lc.add(2, 3);
                    // y = 2x + 3
lc.add(-1, 5);
                    // y = -x + 5
lc.add(1, -4);
                    // y = x - 4
```

// クエリ cout << lc.query(1) << endl; // x = 1 における最小値を出力 cout << lc.query(3) << endl; // x = 3 における最小値を出力

// 最大値を求める場合

```
LineContainer<false> max_lc;
max_lc.add(2, 3);
                     // y = 2x + 3
                       // y = -x + 5
max_lc.add(-1, 5);
\max_{lc.add(1, -4);}
                       // y = x - 4
```

cout << max_lc.query(1) << endl; // x = 1 における最大値を出力 cout << max_lc.query(3) << endl; // x = 3 における最大値を出力

link-cut

知らん 動的な木に関するクエリができる

pbds

C++のデータ構造拡張パックらしい 知らん

segbeats.hpp

Angel Beats!

遅延セグ木の上位互換 ただし計算量がア

普通の遅延セグ木で解けなかった場合これでワンチャンかけてもいいかも

segtree-2d

2次元セグ木 ア

segtree

```
セグ木 ACLと一緒
```

```
// 例: セグメント木で区間和を求める
int op(int a, int b) { return a + b; }
int e() { return 0; } // 単位元
vector<int> v = \{1, 2, 3, 4, 5\};
segtree<int, op, e> seg(v);
cout << seg.prod(1, 4); // 区間 [1, 4) の和を出力 (2 + 3 + 4)
```

swag

Shirotsumeの推しデータ構造です かわいいね

dequeに対して総和を定数時間で求められる

```
// 例: 和を求めるSWAG
auto f = [](int a, int b) { return a + b; }; // 和を計算
int I = 0; // 単位元 (和の場合は0)
```

```
SWAG<int, decltype(f)> swag(f, I);
```

```
// 要素を追加
```

swag.pushb(1);//末尾追加

swag.pushb(2); swaq.pushb(3);

swag.pusha(4);//先頭追加

// クエリ: 現在の含まれる要素の合計

cout << swag.query() << endl; // 出力: 6 (1 + 2 + 3)</pre>

```
// 最初の要素を削除
swaq.pop_front();
```

```
// クエリ: 更新後の合計
cout << swag.query() << endl; // 出力: 5 (2 + 3)
```

wavelet_matrix

静的な列に対する大小関係のクエリに対する万能薬 いろいろできる

```
vector<int> a = {3, 1, 4, 1, 5, 9, 2, 6}; // 整数列
WaveletMatrix<int> wm(a);
```

// 値の取得

cout << wm.access(3) << endl; // インデックス3の値

// 区間内のk番目に小さい値

cout << wm.kth_smallest(1, 6, 2) << endl; // 区間[1, 6)で2番目に 小さい値

// 区間内の値の出現頻度

cout << wm.range_freq(2, 7, 4) << endl; // 区間[2, 7)で値4の出現数 cout << wm.range_freq(2, 7, 2, 5) << endl; // 区間[2, 7)で2 <= 値 < 5の出現数

// 範囲内の下位k個の和

cout << wm.bottom_k_sum(0, 8, 3) << endl; // 全範囲で下位3個の和

// 範囲内の上位k個の和

cout << wm.top_k_sum(2, 6, 2) << endl; // 区間[2, 6)で上位2個の和

DP

d-edge-monge

コストが monge なときになんかうまくいくやつ

mo-rollback

Moのアルゴリズムの変形. 通常は削除クエリを扱う必要があるが、これを用いると スナップショット+ロールバックが定義できれば動作する.

```
int n = 10; // 配列サイズ
int q = 5; // クエリ数
```

```
MoRollBack mo(n, q);
// 区間クエリの追加
mo.add(0, 5); // クエリ1: [0, 5)
mo.add(2, 7); // クエリ2: [2, 7)
mo.add(1, 4); // クエリ3: [1, 4)
// クエリの実行
vector<int> result(q);
vector<int> arr = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10}; // 処理対象配
mo.run(
   [&](int idx) { /* ADD: 状態に要素を追加 */ },
   [&](int idx) { /* REM: 結果を保存 */ result[idx] = ...; },
   [&]() { /* RESET: 状態をリセット */ },
   [&]() { /* SNAP: 現在の状態を保存 */ },
   [&]() { /* ROLLBACK: 状態を復元 */ }
);
// 結果の出力
for (int i = 0; i < q; ++i) {
   cout << "/ul>
}
mo
Moのアルゴリズムの普通版
```

```
int n = 10; // 配列のサイズ vector<int> arr = \{1, 3, 4, 8, 6, 1, 4, 2, 3, 7\}; // 処理対象の配列 int q = 3; // クエリ数
```

↓ range set query の例

```
vector<pair<int, int>> queries = {{1, 4}, {2, 6}, {0, 9}}; //
クエリのリスト
// Mo構造体の初期化
Mo mo(n);
for (auto [l, r] : queries) mo.add(l, r);
vector<int> result(q); // クエリ結果を格納する配列
unordered_map<int, int> freq; // 要素の頻度を管理
// クエリの実行
mo.build(
   [&](int idx) { freq[arr[idx]]++; },
                                    // 要素の追加
   [&](int idx) { freq[arr[idx]]--; },
                                    // 要素の削除
   [&](int idx) {
                                    // クエリ結果を保存
      result[idx] = freq.size();
                                    // 現在の異なる要素数
を保存
   }
);
// クエリ結果の出力
for (int i = 0; i < q; ++i) {
```

monge-incremental-rowmin

わからん

monotone-minima

monotone性を満たす行列に対して、各行に対する最小値の場所と値を求める.