# Information geometry of divergences and means

## on the space of all probability measures having positive density function

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Abstract The space of all probability measures having positive density function on a measure space  $(M, \lambda)$  carries a Riemannian metric G, called the Fisher metric. By using divergences which are distance-like functions, we can define a family of torsion-free affine connections  $\{\nabla^{(\alpha)}\}_{\alpha\in\mathbb{R}}$  which satisfies that  $\nabla^{(-\alpha)}$  is the dual connection of  $\nabla^{(\alpha)}$  with respect to G and  $\nabla^{(0)}$  is the Levi-Civita connection of G. We define the normalized power mean of two probability measures and give characterizations of geodesic segments of  $\nabla^{(\alpha)}$ ,  $\alpha = -1, 0, 1$  in terms of means of its endpoints. Moreover, we show that integrations of kinetic energy of (±1)-geodesic segments are equal to the symmetrized Kullback-Leibler divergence of its endpoints. This is based on joint work [5] with Mitsuhiro Itoh.

### Fisher metric

Let  $(M, \lambda)$  be a measure space with fixed probability measure  $\lambda$  and  $\mathcal{P}^+(M)$  be the space of all probability measures on M;

$$\mathcal{P}^{+}(M) := \left\{ \mu \mid \int_{M} d\mu = 1, \ \mu \ll \lambda, \ \frac{d\mu}{d\lambda} > 0 \right\}.$$

We can regard  $\mathcal{P}^+(M)$  as an infinite dimensional manifold whose tangent space at  $\mu$  is

$$T_{\mu}\mathcal{P}^{+}(M) = \left\{\tau \; \left| \; \int_{M} d\tau = 0, \; \int_{M} \left(\frac{d\tau}{d\mu}\right)^{2} d\mu < \infty \right. \right\}.$$

**Definition 1.** The Fisher metric G on  $\mathcal{P}^+(M)$  is defined by

$$G_{\mu}(\tau_1, \tau_2) = \int_M \frac{d\tau_1}{d\mu} \cdot \frac{d\tau_2}{d\mu} d\mu, \qquad \tau_1, \tau_2 \in T_{\mu} \mathcal{P}^+(M).$$

(i) The Levi-Civita connection  $\nabla^G$  of G is given by

$$\nabla^G_{\tau_1} \tau_2 = \frac{1}{2} \left( \frac{d\tau_1}{d\mu} \cdot \frac{d\tau_2}{d\mu} - G_{\mu}(\tau_1, \tau_2) \right) \mu,$$

where  $\tau_1 \in T_n \mathcal{P}^+(M)$  and  $\tau_2$  is regarded as a constant vector field.

- (ii)  $(\mathcal{P}^+(M), G)$  is of constant sectional curvature 1/4.
- (iii) the geodesic  $\gamma(t)$  satisfying  $\gamma(0) = \mu$  and  $\dot{\gamma}(0) = \tau$  is given by

$$\gamma(t) = \left(\cos\frac{t}{2} + \sin\frac{t}{2} \cdot \frac{d\tau}{d\mu}\right)^2 \mu.$$

#### Geodesics and normalized geometric means

**Definition 3.** We define the normalized k-power mean  $\varphi^{(k)}(\mu_1, \mu_2)$  of  $\mu_1, \mu_2 \in \mathcal{P}^+(M)$  by

$$\varphi^{(k)}(\mu_1, \mu_2) = \frac{1}{C} \left\{ 1 + \left( \frac{d\mu_2}{d\mu_1} \right)^k \right\}^{1/k} \mu_1 \in \mathcal{P}^+(M),$$

where C is a normalization constant. In particular, we call  $\varphi^{(1)}$  and  $\varphi^{(0)}$ the arithmetic mean and the normalized geometric mean, respectively.

**Theorem 4** ([4, 5]). If M is connected, then for any  $\mu_1, \mu_2 \in T_\mu \mathcal{P}^+(M)$ there exists a unique geodesic segment  $\gamma:[0,\ell]\to\mathcal{P}^+(M)$  joining these two points. Here

- (i)  $\ell = \ell(\mu_1, \mu_2) := 2 \arccos\left(\int_M \sqrt{\frac{d\mu_2}{d\mu_1}} \, d\mu_1\right) \in [0, \pi)$  and  $\ell$  is the distance function of  $(\mathcal{P}^+(M), G)$
- (ii)  $\gamma$  is given by  $\gamma(t) = a_1(t) \mu_1 + a_2(t) \mu_2 + a_3(t) \varphi^{(0)}(\mu_1, \mu_2)$ , where  $\{a_i\}_{i=1,2,3}$  are functions on  $[0,\ell]$  satisfying  $\sum_i a_i(t) = 1, \ a_i(t) \ge 0$ .
- (iii)  $\dot{\gamma}(0) = \cot(\ell/2) \left( \varphi^{(0)}(\mu_1, \mu_2) \mu_1 \right)$  (see Figure, left).

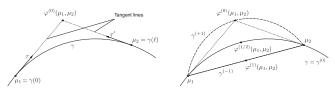


Figure: Geodesic segments and Means

### A family of affine connections induced by divergences

**Definition 5.** A divergence on  $\mathcal{P}^+(M)$  is a function  $D: \mathcal{P}^+(M) \times$  $\mathcal{P}^+(M) \to \mathbb{R}$  satisfying the following properties;

- (i)  $D[\mu:\mu_1] \geq 0$  for  $\forall \mu, \mu_1 \in \mathcal{P}^+(M)$  and equality holds iff  $\mu_1 = \mu$ .
- (ii)  $\tau_{\mu}D[\mu:\mu_1]|_{\mu_1=\mu} = \tau_{\mu}D[\mu_1:\mu]|_{\mu_1=\mu} = 0.$
- (iii)  $-\tau_{\mu}\tau_{\mu_1}D[\mu:\mu_1]|_{\mu_1=\mu}>0$  for any tangent vector  $\tau$ .

**Example 6** ([1, 2]). (i)  $D_{KL}[\mu_1 : \mu_2] := -\int_M \log\left(\frac{d\mu_2}{d\mu_1}\right) d\mu_1$  is called the Kullback-Leibler divergence.

- (ii) A convex function  $f: \mathbb{R} \to \mathbb{R}$  satisfying f(1) = 0, f''(0) = 1 gives  $D_f[\mu_1:\mu_2]:=\int_M f\left(\frac{d\mu_2}{d\mu_1}\right)\,d\mu_1$  which is called the f-divergence.
- (iii) The f-divergence given by a function

$$f^{(\alpha)}(u) = \begin{cases} u \log u & (\alpha = 1) \\ -\log u & (\alpha = -1) \\ \frac{4}{1 - \alpha^2} \left(1 - u^{\frac{1+\alpha}{2}}\right) & (\alpha \neq \pm 1) \end{cases}$$

is called the  $\alpha$ -divergence, denoted by  $D^{(\alpha)}$ .  $D^{(-1)} = D_{KL}$  (see (i)).

Remark 7 ([2]). A divergence induces a torsion-free dualistic structure, i.e., a metric g and two torsion-free affine connections  $\nabla, \nabla^*$  satisfying

$$Xg(Y,Z) = g(\nabla_X Y, Z) + g(Y, \nabla_X^* Z).$$

In particular, a dualistic structure on  $\mathcal{P}^+(M)$  induced by an f-divergence consists of the Fisher metric and the connection induced by  $\alpha$ -divergence;

$$g = G$$
,  $\nabla = \nabla^{(\alpha)}$ ,  $\nabla^* = \nabla^{(-\alpha)}$ ,  $\alpha = 2f'''(1) + 3$ 

**Theorem 8** ([5]). (i) The affine connection  $\nabla^{(\alpha)}$  at  $\mu$  is given by

$$\nabla_{\tau_1}^{(\alpha)} \tau_2(\mu) = -\frac{1+\alpha}{2} \left( \frac{d\tau_1}{d\mu} \frac{d\tau_2}{d\mu} - G_{\mu}(\tau_1, \tau_2) \right) \mu$$

where  $\tau_1 \in T_\mu \mathcal{P}^+(M)$  and  $\tau_2$  is regarded as a constant vector field.

(ii) For any  $\mu_1, \mu_2 \in T_\mu \mathcal{P}^+(M)$  there exists a unique geodesic segment  $\gamma^{(\pm 1)}:[0,1]\to \mathcal{P}^+(M)$  of  $\nabla^{(\pm 1)}$  joining these two points, given by

$$\gamma^{(1)}(t) = \left\{ \int_M \left( \frac{d\mu_2}{d\mu_1} \right)^t d\mu_1 \right\}^{-1} \left( \frac{d\mu_2}{d\mu_1} \right)^t \mu_1, \quad \gamma^{(-1)}(t) = (1-t)\mu_1 + t\mu_2$$

and their midpoints are  $\varphi^{(1)}(\mu_1, \mu_2)$  and  $\varphi^{(0)}(\mu, \mu_1)$ , respectively (see Figure, right).

(iii) 
$$\int_{0}^{1} G(\dot{\gamma}^{(1)}(t), \dot{\gamma}^{(1)}(t)) dt = \int_{0}^{1} G(\dot{\gamma}^{(-1)}(t), \dot{\gamma}^{(-1)}(t)) dt$$
$$= \frac{1}{2} \left( D_{\mathrm{KL}}[\mu_{1} : \mu_{2}] + D_{\mathrm{KL}}[\mu_{2} : \mu_{1}] \right).$$

#### References

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