

To achieve horizontal scaling, it is important to distribute requests/data efficiently and evenly across servers. Consistent hashing is a commonly used technique to achieve this goal. But first, let us take an in-depth look at the problem. The rehashing problem

If you have n cache servers, a common way to balance the load is to use the following hash method:

serverIndex = hash(key) % N, where N is the size of the server pool.

Let us use an example to illustrate how it works. As shown in Table 1, we have 4 servers and 8 string keys with their hashes.

hash % 4 key hash 18358617 key0

	key1	26143584	0					
	key2	18131146	2					
	key3	35863496	0					
	key4	34085809	1					
	key5	27581703	3					
	key6	38164978	2					
	key7	22530351	3					
Table 1								
To fetch the server where a key is stored, we perform the modular operation f(key) % 4. For instance, hash(key0) % 4								
= 1 means a client must contact server 1 to fetch the cached data. Figure 1 shows the distribution of keys based on								
Table 1.								
serverIndex - bash % 4								

key1 keyo key2 key5 Keys key3 key4 key6 key7

2 35863496 key3 34085809 1 key4 0 key5 27581703

		Table 2						
e new distribution of keys based on Table 2.								
serverIndex = hash % 3								
Server Index	0		1	2				
Servers	server o	server 1	server 2	server 3				
Keys	keyo keyi key5 key7		key2 key4 key6	key3				
Figure 2								
	most cac	he clients will	connect t	ly stored in the offline server (server 1). to the wrong servers to fetch data. This to mitigate this problem.				

hash values in the middle fall between 0 and 2^160 - 1. Figure 3 shows the hash space.

Figure 3

XO

xn

Now we understand the definition of consistent hashing, let us find out how it works. Assume SHA-1 is used as the hash function f, and the output range of the hash function is: x0, x1, x2, x3, ..., xn. In cryptography, SHA-1's hash space goes from 0 to 2^160 - 1. That means x0 corresponds to 0, xn corresponds to 2^160 - 1, and all the other



SO

s0 = server 0 s1 = server 1

s2 = server 2 s3 = server 3

s0 = server 0

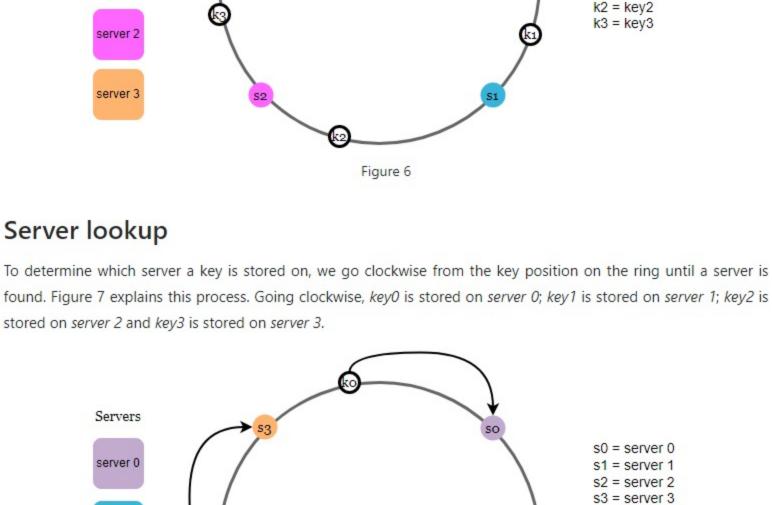
s1 = server 1s2 = server 2 s3 = server 3

k0 = key0k1 = key1

Hash keys

Servers

the hash ring Servers



Using the logic described above, adding a new server will only require redistribution of a fraction of keys. In Figure 8, after a new server 4 is added, only key0 needs to be redistributed. k1, k2, and k3 remain on the same servers. Let us take a close look at the logic. Before server 4 is added, key0 is stored on server 0. Now, key0 will be stored on server 4 because server 4 is the first server it encounters by going clockwise from key0's position on the

Add a server

s0 = server 0server 0 s1 = server 1 s2 = server 2 s3 = server 3

ring. The other keys are not redistributed based on consistent hashing algorithm.

keyo

Figure 7

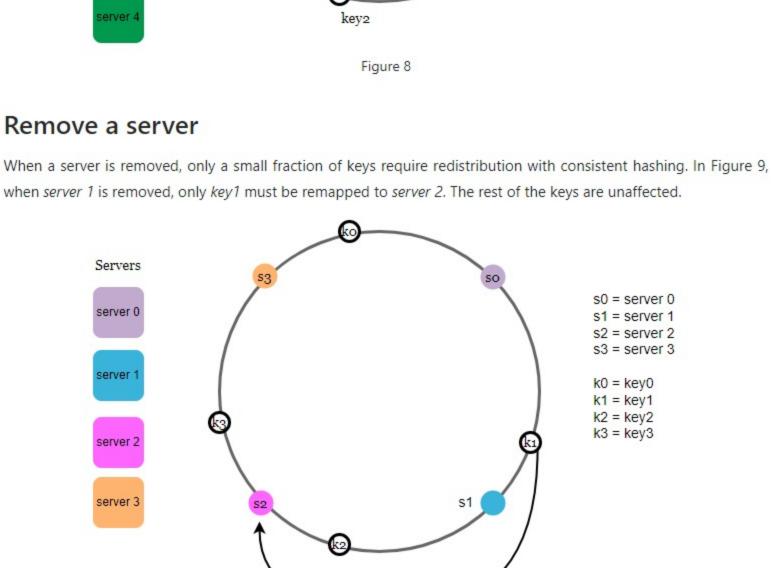


Figure 9

To find out which server a key is mapped to, go clockwise from the key position until the first server on the ring

s0 = server 0 s1 = server 1

s2 = server 2

s0 = server 0

s1 = server 1 s2 = server 2 s3 = server 3

s1

s0 = server 0

s1 = server 1

s0 = server 0

s1 = server 1 s2 = server 2 s3 = server 3

k0 = key0k1 = key1k2 = key2k3 = key3

s0 = server 0

s1 = server 1 s2 = server 2 s3 = server 3

The consistent hashing algorithm was introduced by Karger et al. at MIT [1]. The basic steps are:

Map servers and keys on to the ring using a uniformly distributed hash function.

is found. Two problems are identified with this approach. First, it is impossible to keep the same size of partitions on the ring for all servers considering a server can be added or removed. A partition is the hash space between adjacent

s3 = server 3 server 1 server 2

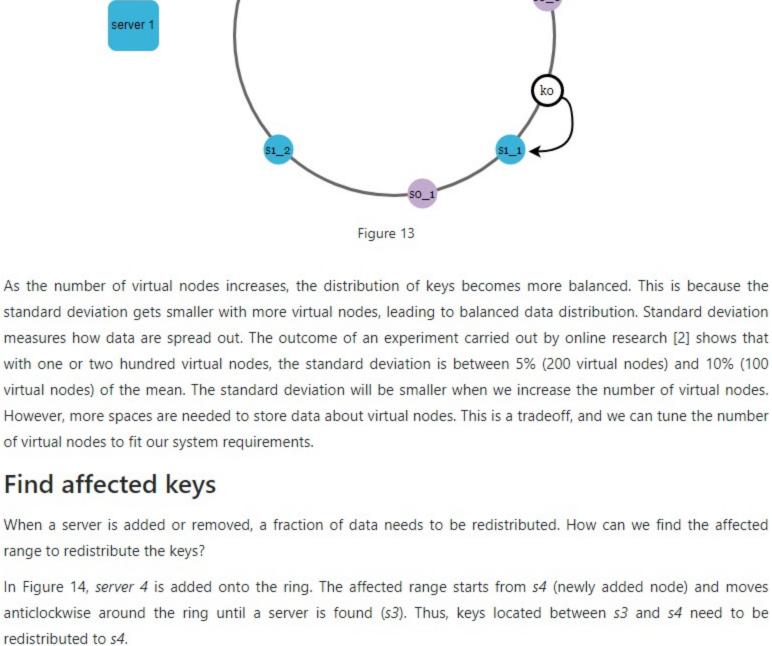
Figure 10

Second, it is possible to have a non-uniform key distribution on the ring. For instance, if servers are mapped to

positions listed in Figure 11, most of the keys are stored on server 2. However, server 1 and server 3 have no data.

Figure 11 A technique called virtual nodes or replicas is used to solve these problems.

A virtual node refers to the real node, and each server is represented by multiple virtual nodes on the ring. In Figure 12, both server 0 and server 1 have 3 virtual nodes. The 3 is arbitrarily chosen; and in real-world systems, the number of virtual nodes is much larger. Instead of using s0, we have s0_0, s0_1, and s02 to represent _server 0 on the ring. Similarly, s1_0, s1_1, and s1_2 represent server 1 on the ring. With virtual nodes, each server is responsible for multiple partitions. Partitions (edges) with label s0 are managed by server 0. On the other hand, partitions with label



k0 = key0k1 = key1k2 = key2 k3 = key3server 2 server 3

- Figure 15 works. The benefits of consistent hashing include: Minimized keys are redistributed when servers are added or removed.
 - Partitioning component of Amazon's Dynamo database [3] Data partitioning across the cluster in Apache Cassandra [4]

Consistent hashing is widely used in real-world systems, including some notable ones:

· It is easy to scale horizontally because data are more evenly distributed.

Congratulations on getting this far! Now give yourself a pat on the back. Good job! Reference materials [1] Consistent hashing:

Maglev network load balancer [7]

[2] Consistent Hashing: https://tom-e-white.com/2007/11/consistent-hashing.html [3] Dynamo: Amazon's Highly Available Key-value Store:

https://static.googleusercontent.com/media/research.google.com/en//pubs/archive/44824.pdf

serverIndex = hash % 4 Server Index Servers server o server 1 server 2 server 3 Figure 1

key6 38164978 1 key7 22530351 0 Figure 2 shows the As shown in Figure

Consistent hashing

By collecting both ends, we get a hash ring as shown in Figure 4:

Hash space and hash ring

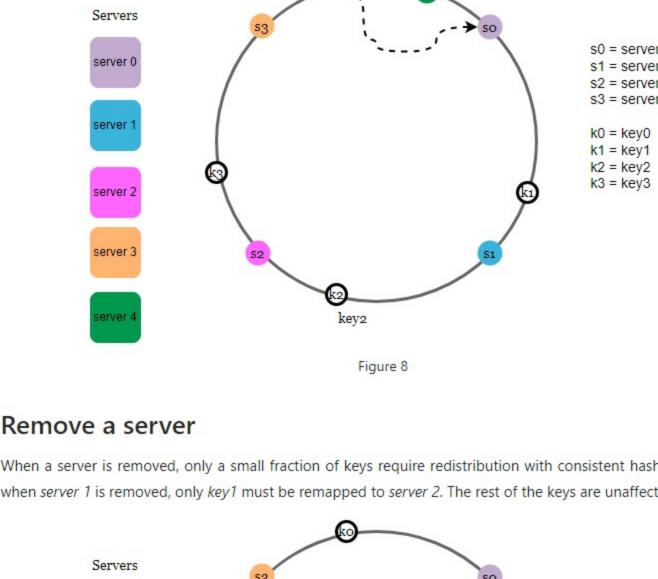
Figure 4 Hash servers

server 0 server 1 server 2

s3

server 0 server 1

server 1 k0 = key0k1 = key1k2 = key2k3 = key3server 2 server 3



servers. It is possible that the size of the partitions on the ring assigned to each server is very small or fairly large. In Figure 10, if s1 is removed, s2's partition (highlighted with the bidirectional arrows) is twice as large as s0 and s3's partition.

Servers

server 0

server 3

Two issues in the basic approach

server 1 server 2

Virtual nodes

s1 are managed by server 1.

server 1

and find virtual node s1_1, which refers to server 1.

Servers

server 0

Servers

server 0

server 1

server 2

server 3

server 4

Servers

server 0

server 1

redistributed to s2.

s0

Servers

server 0

server 3

Servers s0 = server 0server 0 s1 = server 1

Figure 12

To find which server a key is stored on, we go clockwise from the key's location and find the first virtual node encountered on the ring. In Figure 13, to find out which server k0 is stored on, we go clockwise from k0's location

As the number of virtual nodes increases, the distribution of keys becomes more balanced. This is because the standard deviation gets smaller with more virtual nodes, leading to balanced data distribution. Standard deviation measures how data are spread out. The outcome of an experiment carried out by online research [2] shows that with one or two hundred virtual nodes, the standard deviation is between 5% (200 virtual nodes) and 10% (100 virtual nodes) of the mean. The standard deviation will be smaller when we increase the number of virtual nodes. However, more spaces are needed to store data about virtual nodes. This is a tradeoff, and we can tune the number of virtual nodes to fit our system requirements. Find affected keys When a server is added or removed, a fraction of data needs to be redistributed. How can we find the affected

keyo

key2

Figure 14

When a server (s1) is removed as shown in Figure 15, the affected range starts from s1 (removed node) and moves anticlockwise around the ring until a server is found (s0). Thus, keys located between s0 and s1 must be

Wrap up In this chapter, we had an in-depth discussion about consistent hashing, including why it is needed and how it

· Mitigate hotspot key problem. Excessive access to a specific shard could cause server overload. Imagine data

for Katy Perry, Justin Bieber, and Lady Gaga all end up on the same shard. Consistent hashing helps to mitigate

· Discord chat application [5] · Akamai content delivery network [6]

the problem by distributing the data more evenly.

https://en.wikipedia.org/wiki/Consistent hashing

https://www.allthingsdistributed.com/files/amazon-dynamo-sosp2007.pdf [4] Cassandra - A Decentralized Structured Storage System: http://www.cs.cornell.edu/Projects/ladis2009/papers/Lakshman-ladis2009.PDF [5] How Discord Scaled Elixir to 5,000,000 Concurrent Users: https://blog.discord.com/scaling-elixir-f9b8e1e7c29b [6] CS168: The Modern Algorithmic Toolbox Lecture #1: Introduction and Consistent Hashing: http://theory.stanford.edu/~tim/s16/I/I1.pdf [7] Maglev: A Fast and Reliable Software Network Load Balancer:

This approach works well when the size of the server pool is fixed, and the data distribution is even. However, problems arise when new servers are added, or existing servers are removed. For example, if server 1 goes offline, the size of the server pool becomes 3. Using the same hash function, we get the same hash value for a key. But applying modular operation gives us different server indexes because the number of servers is reduced by 1. We get the results as shown in Table 2 by applying hash % 3: key hash hash % 3 18358617 0 key0 key1 26143584 1 key2 18131146

This means that w causes a storm of o Quoted from Wikipedia: "Consistent hashing is a special kind of hashing such that when a hash table is re-sized and consistent hashing is used, only k/n keys need to be remapped on average, where k is the number of keys, and n is the number of slots. In contrast, in most traditional hash tables, a change in the number of array slots causes nearly

all keys to be remapped [1]".

Using the same hash function f, we map servers based on server IP or name onto the ring. Figure 5 shows that 4 servers are mapped on the hash ring.

server 3 Figure 5 One thing worth mentioning is that hash function used here is different from the one in "the rehashing problem," and there is no modular operation. As shown in Figure 6, 4 cache keys (key0, key1, key2, and key3) are hashed onto