

AN INTRODUCTION TO PROGRAMMING THROUGH C++

with

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Lecture 18

Pointers

Venturing outside the Stack

Based on material developed by Prof. Abhiram G. Ranade

Recap

- Every variable has a unique address
 - Given by the address-of operator &
- Pointer variables can be used to store addresses
- The indirection operator * can be used to access a variable through a pointer
- So, there are two ways to access a "box" in memory: through a variable, or through an address
- Today: Creating and accessing boxes in memory which don't have any variables associated with them!

```
int a = 2;  
int* p;  
p = &a;  
(*p)++; // now a==3
```

Dynamically Allocated Memory

- Suppose we want to create a queue that can grow without limit (other than the limits set by the system policies/resources)
 - Create a queue that is as big as the maximum allowed?
 - But what if we want multiple such a priori unbounded queues?
- Ideally, the memory used for the queue should grow/shrink as the queue grows/shrinks
- More generally, we would like to create "boxes" in memory dynamically (decided at the time of program execution)

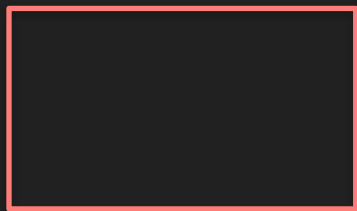
A Bit about Memory

- Each program gets its own memory space
 - Memory isolation
- Not all of the addressable space will be used by a process
 - Physical memory will not be allocated until the process needs it
 - Virtual memory
- Mapping virtual memory to physical memory is quite complex and is handled by the operating system and the hardware
 - The program only works with the virtual memory

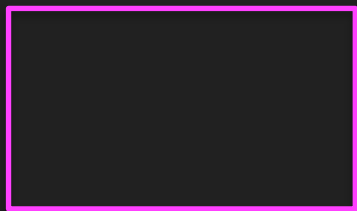
64 bit address space has
16 Exabytes (16 billion GB)

A Bit about Memory

- The virtual memory space is divided into different segments to hold various things needed by the program
- Dynamically allocated memory comes from one such segment called the heap which can grow/shrink as needed



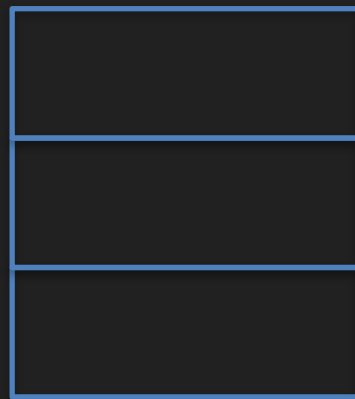
Program



Global/Static
Variables



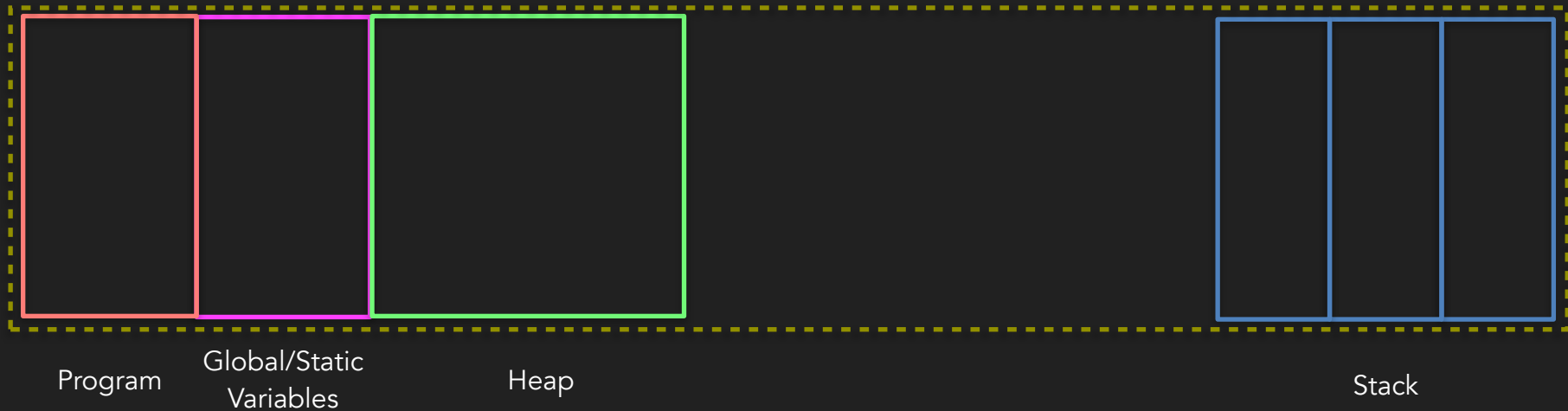
Heap



Stack

A Bit about Memory

- The virtual memory space is divided into different segments to hold various things needed by the program
- Dynamically allocated memory comes from one such segment called the heap which can grow/shrink as needed



A typical layout of virtual memory

A Box in the Heap

- A `new` expression can be used to create "boxes" in memory dynamically (decided at the time of program execution)
- But how will we access this box without a variable name?
- `new` returns a pointer to the box
 - It is the programmer's responsibility to save/use that pointer appropriately (and not lose it)

```
int* p = new int; // creates a new int "box" without a variable name!  
*p = 7;           // we can access the new box only through its address  
p = new int;      // oops! the previous box has become inaccessible now!
```

Memory Leak!

Dynamic Queue

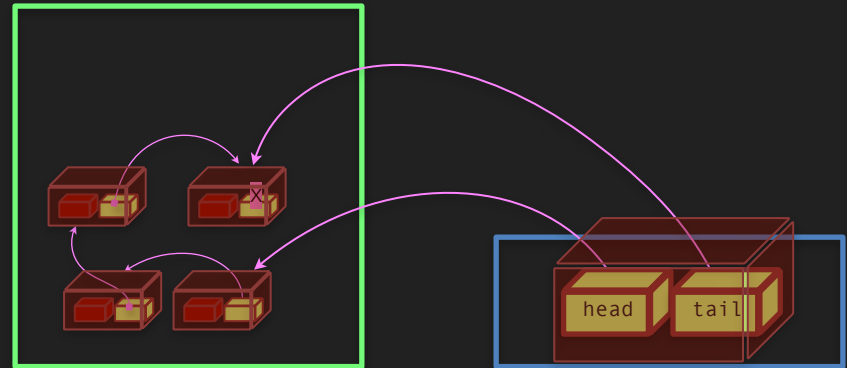
- Today's example: A queue that grows without limit (other than the limits set by the system policies/resources)
- Idea: Each queue element will be dynamically allocated in the heap
 - We will need to access the head and the tail of the queue (for dequeuing and enqueueing): two pointers
 - In fact, the address of every element in the queue should be saved (so that it doesn't become inaccessible)
 - So for n elements in the queue, we'll need n pointers too. But where will we keep them?

Dynamic Queue

```
struct node {  
    int val;  
    node* next = nullptr;  
};
```

- Solution: Use a struct which contains a pointer to another such struct, as well as a queue element (say an int)
- For convenience, we will define another struct for the whole queue

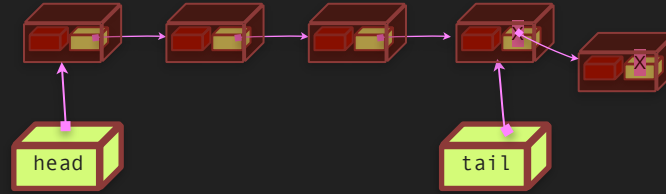
```
struct queue {  
    node* head = nullptr;  
    node* tail = nullptr;  
    void enqueue(int v);  
    bool dequeue(int& v);  
};
```



Enqueuing

```
struct node {  
    int val;  
    node* next = nullptr;  
};
```

```
struct queue {  
    node* head = nullptr;  
    node* tail = nullptr;  
    void enqueue(int v);  
    bool dequeue(int& v);  
};
```



new gives next initialised to nullptr as specified in the definition of the struct

- Enqueuing affects only the tail
- But **beware of corner cases!**
- If queue empty, head, tail are nullptr

```
if(!tail)  
    tail = head = new node;  
else {  
    tail->next = new node;  
    tail = tail->next;  
}  
tail->val = v;
```

Dynamic Queue

```
struct node {  
    int val;  
    node* next = nullptr;  
};
```

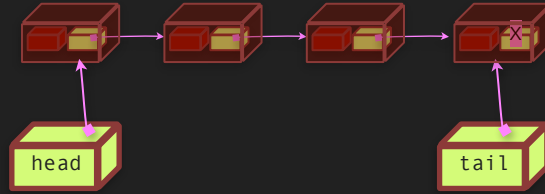
```
struct queue {  
    node* head = nullptr;  
    node* tail = nullptr;  
    void enqueue(int v);  
    bool dequeue(int& v);  
};
```

```
void queue::enqueue(int v) {  
    tail = (tail? tail->next : head) = new node;  
    tail->val = v;  
}
```

Dequeuing

```
struct node {  
    int val;  
    node* next = nullptr;  
};
```

```
struct queue {  
    node* head = nullptr;  
    node* tail = nullptr;  
    void enqueue(int v);  
    bool dequeue(int& v);  
};
```



- If the queue is empty, return false
- **Corner case:** Queue becomes empty after dequeuing

```
if(!head)  
    return false;  
v = head->val;  
head = head->next;  
if(!head) tail=nullptr;  
return true;
```

Memory Leak!

Freeing a Box in the Heap

- `new` allocates a box in the heap and returns a pointer to it
- If we no longer need that box, before letting go of the pointer to it, we should "release" the memory allocated for the box
- Using operator `delete`

Especially important for programs that run for a long time, and/or allocate large amounts of memory

```
int* p = new int; // creates a new int "box" without a variable name!  
...             // use *p to work with the box  
delete p;       // box's use over. release the memory used for it.  
p = nullptr;    // now we can overwrite the address
```

Dynamic Queue

```
struct node {  
    int val;  
    node* next = nullptr;  
};
```

```
struct queue {  
    node* head = nullptr;  
    node* tail = nullptr;  
    void enqueue(int v);  
    bool dequeue(int& v);  
};
```

```
void queue::enqueue(int v) {  
    tail = (tail? tail->next : head) = new node;  
    tail->val = v;  
}
```

```
bool queue::dequeue(int &v) {  
    if(!head) return false;  
    v = head->val;  
    node* old_head = head;  
    head = head->next;  
    delete old_head;  
    if(!head) tail=nullptr;  
    return true;  
}
```

Dynamic Queue

Demo

```
void queue_demo() {  
    queue Q;  
    for(int i=0; i < 100000000; i++) // 10 Million times  
        Q.enqueue(1);  
}
```

Memory Leak! When Q goes out of scope, its "contents" allocated using new are not deleted!

```
int main() {  
    for(int i=0; i < 100; i++)  
        queue_demo();  
}
```

Dynamic Queue

```
void queue_demo() {  
    queue Q;  
    for(int i=0; i < 10000000; i++) // 10 Million times  
        Q.enqueue(1);  
    Q.clear();  
}
```

Later: Calling such a "clean up"
function when an object goes out of
scope can be automated

```
int main() {  
    for(int i=0; i < 100; i++)  
        queue_demo();  
}
```

```
struct queue {  
    node* head = nullptr;  
    node* tail = nullptr;  
    void enqueue(int v);  
    bool dequeue(int& v);  
    void clear(){  
        int v;  
        while(dequeue(v)) {}  
    }  
};
```


Variable Length Arrays

- Can create variable length arrays in the heap
- `new type[n]` expression returns a pointer to the first element in an array of n elements of the requested type
- Should free it using the operator `delete[]` (not using `delete` which will result in undefined behaviour)

```
unsigned n; cin >> n;
int* p = new int[n]; // p[0], ..., p[n-1] are allocated now
...                // use the array
delete[] p;         // release the memory for the entire array
p = nullptr;        // now we can overwrite the address
```

Example: Reading Inputs of Given Length

```
int* sort(int p[], int n); // returns an array allocated on the heap

int main() {
    int n; cin >> n;
    int* p = new int[n]; // instead of relying on VLA support: int p[n];
    for(int i=0; i<n; i++) cin >> p[i];
    int* q = sort(p,n);
    for(int i=0; i<n; i++) cout << q[i] << " ";
    cout << endl;
    delete[] p;           // release the memory allocated
    delete[] q;           // was allocated within sort as an array
}
```

Example: Reading Inputs of Given Length

```
void sort(int in[], int out[], int n); // cleans up all new memory

int main() {
    int n; cin >> n;
    int* p = new int[n]; int* q = new int[n]; // two arrays created here
    for(int i=0; i<n; i++) cin >> p[i];
    sort(p,q,n);
    for(int i=0; i<n; i++) cout << q[i] << " ";
    cout << endl;
    delete[] p;           // and two arrays deleted here
    delete[] q;           // easier to prevent memory leaks
}
```

Some Tips

- Whenever you use `new` or `new []` in your program, make sure there is a matching `delete` or `delete []`
 - Even if it may look like it doesn't matter (small program, will anyway exit right after this,...), before exiting, **a good C++ program should delete all the heap memory allocated via new**
 - Because `new` may do more than allocate memory and `delete` may do more than free it.
 - Tools which analyse a program for bugs may detect such errors "that don't matter", and the real bugs will remain hard to find

Some Tips

- Whenever you use `new` or `new []` in your program, make sure there is a matching `delete` or `delete []`
 - May be hidden inside other functions (e.g., `enqueue`, and `dequeue` or `clear`)
- Accessing a deleted pointer is an error (undefined behaviour)
- Deleting an already deleted pointer is an error (crashes, typically)
 - Beware when multiple pointers may hold the same address
- C++ has several mechanisms to help with correctly using memory
 - Constructor and destructor functions (Coming up)
 - Pre-implemented data structures in the standard library (Later)
 - Smart Pointers (not covered)

Note that `delete p` doesn't change the address stored in `p`.