Adaptive-timesteps-v2

February 6, 2024

```
[39]: using Plots
      using LaTeXStrings
     using LinearAlgebra
      using Printf
     pyplot()
[39]: Plots.PyPlotBackend()
[40]: function rk4(f1, x, y, h)
         k1 = h*f1(x, y)
         k2 = h*f1(x+h/2, y+k1/2)
         k3 = h*f1(x+h/2, y+k2/2)
         k4 = h*f1(x+h, y+k3)
         return y + (k1+2k2+2k3+k4)/6
      end
      function caller(my_method, fn, y_ini, x0, xT, h)
         # generate x values from x0 to xT
         xs = range(x0, step=h, stop=xT);
         # calculate the number of steps
         N = length(xs);
         # initialize y
         y = y_ini;
         # initialize storage to keep y values
         ys = zeros(Float64, N, length(y_ini));
         # for each i
         for i=1:N
             x = xs[i]
                                     # get x
             ys[i,:] .= y
                                  # store y
             y = my_method(fn,x,y,h) # update y
         end
          # return y
         return ys
```

end

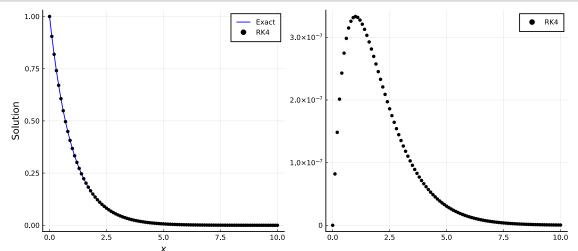
[40]: caller (generic function with 1 method)

```
[41]: \# for dy/dx = f(x,y)
      # define f(x,y)
      f(x, y) = -y;
      # Step size h
      h = 1.0e-1;
      # Time span
      x0 = 0.0;
      xT = 10.0;
      # Generate x values (for plotting and comparison)
      xs = range(x0, stop=xT, step=h);
      N = length(xs);
      # Initialize y
      y_ini = 1.0;
      # Run caller for small time (to compile)
      caller(rk4, f, y_ini, 0.0, 2h, h);
      # Final call
      @time ysrk4 = caller(rk4, f, y_ini, x0, xT, h);
```

0.000144 seconds (709 allocations: 18.250 KiB)

```
b = scatter(xs, ysrk4 .- yexact, color=:black, markersize=4, markerstrokewidth=0,label="RK4");
plot(a, b, size=(900,400))
```

[42]:



```
sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters
'vmin', 'vmax' will be ignored
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```

```
[43]: ## Cash-Karp parameters
     \#a2 = 1/5; b21 = 1/5;
     #a3 = 3/10; b31 = 3/40;
                                  b32 = 9/40;
      \#a4 = 3/5; b41 = 3/10;
                                  b42 = -9/10; b43 = 6/5;
                                                b53 = -70/27; b54 = 35/27;
      #a5 = 1; b51 = -11/54;
                                  b52 = 5/2;
      #a6 = 7/8; b61 = 1631/55296; b62 = 175/512; b63 = 575/13824; b64 = 44275/
      4110592; b65 = 253/4096;
      #
      \#c1 = 37/378; c2 = 0.0; c3 = 250/621; c4 = 125/594; c5 = 0.0; c6 = 512/1771;
      #c1s = 2825/27648; c2s = 0.0; c3s = 18575/48384; c4s = 13525/55296; c5s = 277/
      414336; c6s = 1/4;
     # Dormand-Prince in matrix form
     a = [0.2, 0.3, 0.8, 8/9, 1.0, 1.0];
     b = [
          [1/5, 0, 0, 0, 0, 0],
          [3/40, 9/40, 0, 0, 0, 0],
```

```
[44/45, -56/15, 32/9, 0, 0, 0],
    [19372/6561, -25360/2187, 64448/6561, -212/729, 0, 0],
    [9017/3168, -355/33, 46732/5247, 49/176, -5103/18656, 0],
    [35/384, 0, 500/1113, 125/192, -2187/6784, 11/84]
c = [35/384, 0, 500/1113, 125/192, -2187/6784, 11/84, 0]
# Dormand-Prince
a2 = 1/5; b21 = 1/5;
a3 = 3/10; b31 = 3/40;
                           b32 = 9/40;
a4 = 4/5; b41 = 44/45;
                                            b43 = 32/9;
                             b42 = -56/15;
a5 = 8/9; b51 = 19372/6561; b52 = -25360/2187; b53 = 64448/6561; b54 =-212/729;
a6 = 1:
          b61 = 9017/3168; b62 = -355/33; b63 = 46732/5247; b64 = 49/176;
\rightarrow b65 = -5103/18656;
a7 = 1;
         b71 = 35/384;
                           b72 = 0;
                                          b73 = 500/1113; b74 = 125/192;
\Rightarrow b75 = -2187/6784; b76 = 11/84;
c1 = 35/384; c2 = 0; c3 = 500/1113; c4 = 125/192; c5 = -2187/6784; c6 = 11/84; c7_{\square}
⇒= 0;
c1s = 5179/57600; c2s = 0; c3s = 7571/16695; c4s = 393/640; c5s = -92097/339200;
\hookrightarrow c6s = 187/2100; c7s = 1/40;
function erk54(f, x, y, h)
```

```
[44]: #Embedded Runge-Kutta formulas
         k1 = h*f(x, y)
          k2 = h*f(x + a2*h, y + b21*k1)
         k3 = h*f(x + a3*h, y + b31*k1 + b32*k2)
          k4 = h*f(x + a4*h, y + b41*k1 + b42*k2 + b43*k3)
          k5 = h*f(x + a5*h, y + b51*k1 + b52*k2 + b53*k3 + b54*k4)
          k6 = h*f(x + a6*h, y + b61*k1 + b62*k2 + b63*k3 + b64*k4 + b65*k5)
          y5 = y + c1*k1 + c2*k2 + c3*k3 + c4*k4 + c5*k5 + c6*k6
         k7 = h*f(x + a7*h, y5)
          y4 = y + c1s*k1 + c2s*k2 + c3s*k3 + c4s*k4 + c5s*k5 + c6s*k6 + c7s*k7
         return y5, y4
      end
      function caller5(my_method, fn, y_ini, x0, xT, h)
          xs = range(x0, step=h, stop=xT);
         N = length(xs);
          y = y ini;
          ys = zeros(Float64, N, length(y_ini));
          for i=1:N
             x = xs[i]
              ys[i,:] .= y
              y, y4 = my_method(fn,x,y,h)
          end
          return ys
```

```
end

function caller4(my_method, fn, y_ini, x0, xT, h)
    xs = range(x0, step=h, stop=xT);
    N = length(xs);
    y = y_ini;
    ys = zeros(Float64, N, length(y_ini));
    for i=1:N
        x = xs[i]
        ys[i,:] .= y
        y5, y = my_method(fn,x,y,h)
    end
    return ys
end
```

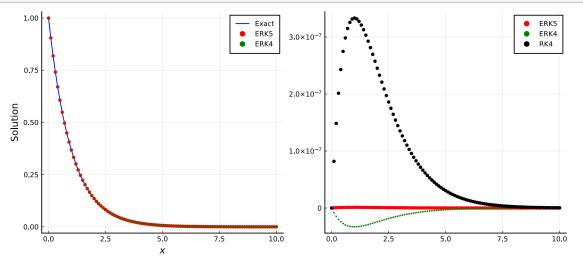
[44]: caller4 (generic function with 1 method)

```
[45]: f(x, y) = -y;
    max_iter = 500;
    abstol = 1.0e-6;
    reltol = 1.0e-6;
    y_ini = 1.0;
    x0 = 0.0;
    xT = 10.0;
    h = 0.1;
    xs = range(x0, stop=xT, step=h);
    yserk5 = caller5(erk54, f, y_ini, x0, xT, h);
    yserk4 = caller4(erk54, f, y_ini, x0, xT, h);
```

```
[46]: xfine = range(0.0, stop=xs[end], length=1000);
     yfine = exp.(-xfine)
     yexact = exp.(-xs);
     #yfine = xfine/2 .- sin.(2xfine)/4;
     #yexact = xs/2 .- sin.(2xs)/4;
     a = plot(xfine, yfine, seriestype=:line, linecolor=:blue, __
      -linewidth=1,label="Exact",xlabel=L"$x$", ylabel="Solution",size=(600,600));
     scatter!(xs, yserk5, color=:red, markersize=4,__
      →markerstrokewidth=0,label="ERK5");
     scatter!(xs, yserk4, color=:green, markersize=2,__
      →markerstrokewidth=0,label="ERK4");
     b = scatter(xs, yserk5 .- yexact, color=:red, markersize=4,__
      scatter!(xs, yserk4 .- yexact, color=:green, markersize=2,_
      scatter!(xs, ysrk4 .- yexact, color=:black, markersize=4,__
      →markerstrokewidth=0,label="RK4");
```

plot(a, b, size=(900,400))

[46]:



```
sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters
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```

```
[47]: # Predictor-Corrector
      # Embedded Runge-Kutta formulas
      function erk54h(f, x, y, h, k7bh)
          # Implement FSAL (first same as last)
          # The first
          \# k1 = k7bh, unless k1 is zero (initially)
          sum(k7bh)==0 ? k1 = h*f(x, y) : k1 = k7bh*h;
          # Implement rest of the Butcher table
          k2 = h*f(x + a2*h, y + b21*k1)
          k3 = h*f(x + a3*h, y + b31*k1 + b32*k2)
          k4 = h*f(x + a4*h, y + b41*k1 + b42*k2 + b43*k3)
          k5 = h*f(x + a5*h, y + b51*k1 + b52*k2 + b53*k3 + b54*k4)
          k6 = h*f(x + a6*h, y + b61*k1 + b62*k2 + b63*k3 + b64*k4 + b65*k5)
          # get y fifth-order correct
          y5 = y + c1*k1 + c2*k2 + c3*k3 + c4*k4 + c5*k5 + c6*k6 # c7 = 0
          # FSAL -> the last
          k7bh = f(x + a7*h, y5)
```

```
#@printf("%.6f %.6f %.6f %.6f\n",x, y[1], y5[1], k7bh[1]);
    # get y fourth-order correct
    y4 = y + c1s*k1 + c2s*k2 + c3s*k3 + c4s*k4 + c5s*k5 + c6s*k6 + c7s*k7bh*h
    # return y, error, k7bh
    err = 0. abs(y5 - y4);
    return y5, err, k7bh
end
function caller54(fn, y_ini, x0, xT, h0, max_iter, abstol, reltol)
    y = y_{ini}; h = h0;
    ys = zeros(Float64, max_iter, length(y_ini));
    xs = zeros(Float64, max_iter, 1);
    xs[1] = x0; ys[1,:] = y_ini;
    x = x0; i = 1; k = 1;
    k7bh = zeros(Float64, size(y_ini));
    while x<=xT && i<max_iter</pre>
        # calculate the tolerance
        if i == 1
            tol = abstol + reltol*norm(ys[i,:]);
        else
            tol = abstol + reltol*maximum([norm(ys[i,:]), norm(ys[i-1,:])]);
        end
        # get the next y and the error
        y, err, k7bh = erk54h(fn,xs[i],ys[i,:],h, k7bh);
        # get max error and the scale factor
        merr = maximum(err);
        #scale_factor = (tol/merr)^0.2;
        # for debugging
        \#Oprintf("%2d %.4f %.6f %.6f %g\n",i,xs[i],ys[i],h,merr);
        merr == 0.0 ? merr = tol/100 : nothing;
        # If the step is valid (less error than tol)
        # then we proceed
        if merr<tol</pre>
            x += h;
            i += 1;
            xs[i] = x;
            ys[i,:] .= y;
```

```
#k7 = k7t;
            #@printf("%2d %.4f %.6f %.6f\n",i,xs[i],ys[i],k7[1]);
        end
        # anyway we update h every time
        h = 0.9*h*(tol/merr)^0.2;
    end
    # if the maximum number of steps exceeded
    if i>=max_iter
        println(i," Increase max_iter.")
        return Nothing
    end
    # return the usable portion of the array
    return xs[1:i-1], ys[1:i-1,:]
end
```

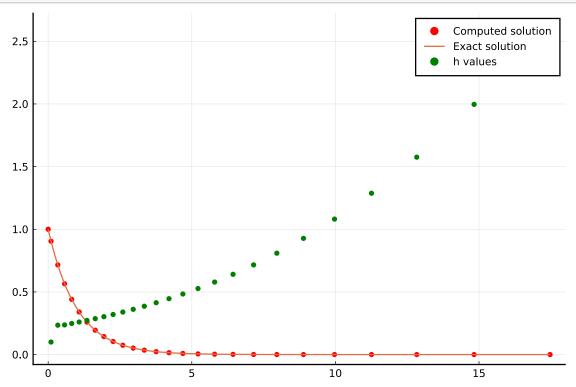
[47]: caller54 (generic function with 1 method)

```
[48]: # Choose dy/dx = -y
      f(x, y) = -y;
      # Initialize parameters
      \max iter = 2000;
      abstol = 1.0e-6;
     reltol = 1.0e-8;
      y_ini = 1.0;
     x0 = 0.0;
      xT = 20.0;
     h0 = 0.1;
      # Call it with small delta to compile
      caller54(f, y_ini, x0, 2h0, h0, max_iter, abstol, reltol)
      # Final call
      @time xs54, yserk54 = caller54(f, y_ini, x0, xT, h0, max_iter, abstol, reltol);
```

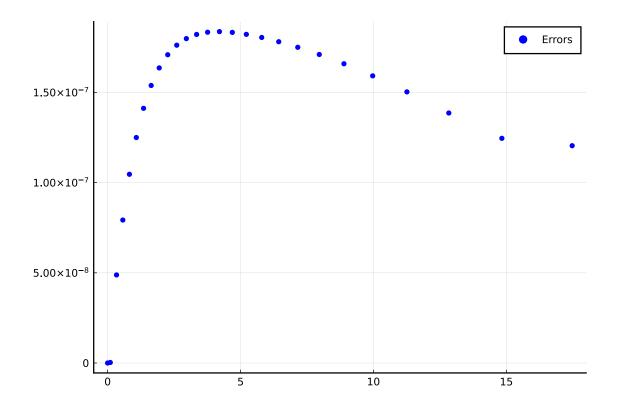
0.001310 seconds (4.38 k allocations: 205.125 KiB)

```
[49]: # Plot solution
      scatter(xs54, yserk54, markercolor=:red, markerstrokewidth=0, label="Computed_
       ⇔solution")
      # Generate and plot exact solution
      xfine = range(xs54[1], stop=xs54[end], length=1000);
      yfine = exp.(-xfine)
      yexact = exp.(-xs54);
```

[49]:



9



```
sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters
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sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters
'vmin', 'vmax' will be ignored
```

```
[51]: # d2y/dx2 = -y
f(x, y) = [y[2], -y[1]];

# intialize parameters
max_iter = 2000;
abstol = 1.0e-6;
reltol = 1.0e-8;
y_ini = [1.0, 0.0];
x0 = 0.0;
xT = 20.0;
h0 = 0.1;

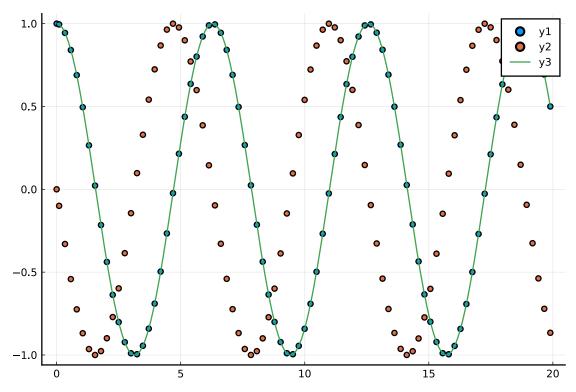
# compile
caller54(f, y_ini, x0, 2h0, h0, max_iter, abstol, reltol)
```

```
@time xs54, yserk54 = caller54(f, y_ini, x0, xT, h0, max_iter, abstol, reltol);
# plot the computed solution
scatter(xs54, yserk54)

# plot the exact solution
xfine = range(xs54[1], stop=xs54[end], length=1000);
yfine = @. [cos(xfine) -sin(xfine)];
plot!(xfine, yfine[:,1])
```

0.003650 seconds (13.62 k allocations: 655.734 KiB)

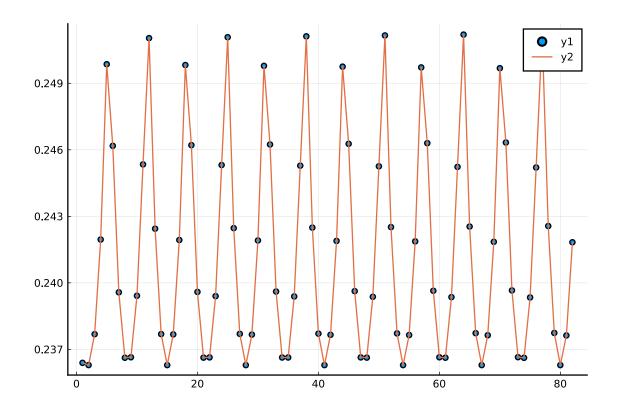
[51]:



```
sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters
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sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters
'vmin', 'vmax' will be ignored

[52]: scatter(diff(xs54)[2:end])
plot!(diff(xs54)[2:end])
```

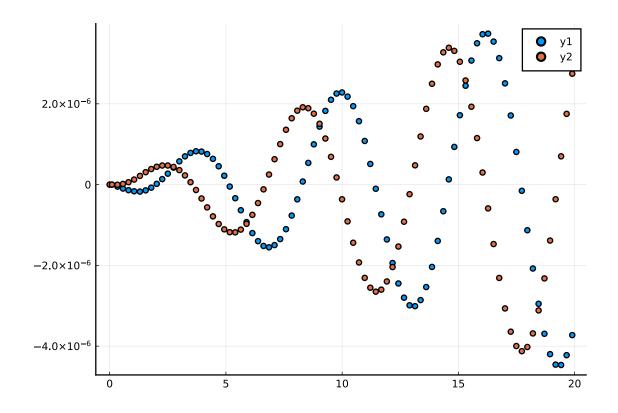
[52]:



```
sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters 'vmin', 'vmax' will be ignored sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters 'vmin', 'vmax' will be ignored sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters 'vmin', 'vmax' will be ignored sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters 'vmin', 'vmax' will be ignored
```

[56]: scatter(xs54, @. yserk54 - [cos(xs54) -sin(xs54)])

[56]:



```
sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters
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'vmin', 'vmax' will be ignored
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'vmin', 'vmax' will be ignored
sys:1: UserWarning: No data for colormapping provided via 'c'. Parameters
'vmin', 'vmax' will be ignored
```

[54]: yserk54

[54]: 84×2 Matrix{Float64}:

1.0 0.0 0.995004 -0.0998334 0.943952 -0.330084 0.84045 -0.541889 0.689231 -0.724541 0.495555 -0.868576 0.265395 -0.964139 0.0224333 -0.999748 -0.215436 -0.976518 -0.438349 -0.898804 -0.636849 -0.770988 -0.801513 -0.597976

```
-0.922753
            -0.385391
-0.026787
             0.999637
0.211264
             0.977425
0.434529
             0.900654
0.63355
             0.773697
0.798905
             0.601451
0.921012
             0.389524
0.988934
             0.148332
0.995611
            -0.0935435
            -0.325386
0.945577
0.84313
            -0.537702
0.692864
            -0.721063
0.500022
            -0.866008
```

[]: