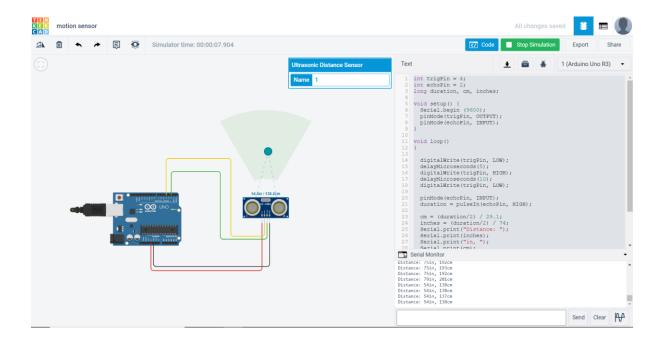
1BM18CS100 7/10/2020

LAB4

```
Q1) To demonstrate the use of ultrasonic motion sensor:
Code:
       int trigPin = 4;
int echoPin = 2;
long duration, cm, inches;
void setup() {
 Serial.begin (9600);
 pinMode(trigPin, OUTPUT);
 pinMode(echoPin, INPUT);
}
void loop()
{
 digitalWrite(trigPin, LOW);
 delayMicroseconds(5);
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 pinMode(echoPin, INPUT);
 duration = pulseIn(echoPin, HIGH);
 cm = (duration/2) / 29.1;
 inches = (duration/2) / 74;
 Serial.print("Distance: ");
 Serial.print(inches);
 Serial.print("in, ");
 Serial.print(cm);
```

```
Serial.print("cm");
Serial.println();
delay(250);
}
OUTPUT:
```



Q2) To demonstrate a fire detector using temperature sensor:

Code:

```
const int temperaturePin = 0;
int buzzer = 12;

void setup()
{
    Serial.begin (9600);
    pinMode(buzzer, OUTPUT);
    pinMode(9,OUTPUT);
}
float getVoltage(int pin)
```

```
{
 return (analogRead(pin) * 0.004882814);
}
void loop()
{
 float voltage, degreesC;
 voltage = getVoltage(temperaturePin);//gets temp in 5v
 degreesC = (voltage-0.5)*100.0;//converts the temp to celcius
 digitalWrite(9,LOW);
 if(degreesC < 37)
  Serial.print(degreesC);
       Serial.println("SAFE TEMPERATURE!");
 }
 if(degreesC > 37)
  Serial.print(degreesC);
  Serial.println(" ALERT!");
  digitalWrite(buzzer, LOW);
  digitalWrite(9,HIGH);
  tone(12, 10000,100);
  delay(100);
 }
}
OUTPUT:
```

