1BM18CS100 30/09/2020

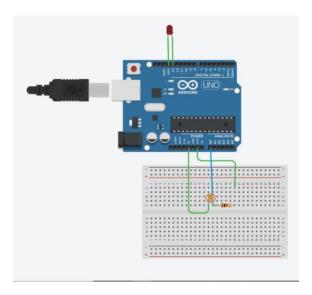
## LAB2

## LDR (Light Dependent Resistor)

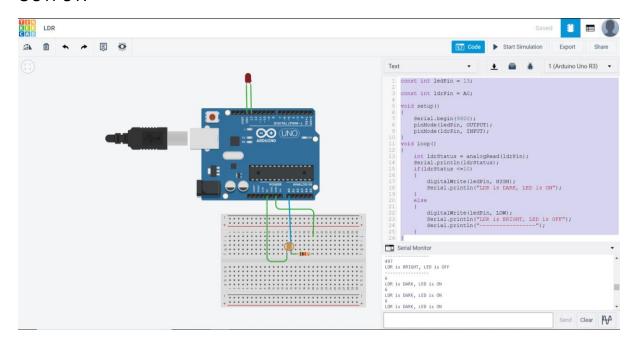
```
CODE:
```

```
const int ledPin = 13;
const int ldrPin = A0;
void setup()
{
        Serial.begin(9600);
         pinMode(ledPin, OUTPUT);
         pinMode(ldrPin, INPUT);
}
void loop()
{
        int IdrStatus = analogRead(IdrPin);
        Serial.println(ldrStatus);
        if(ldrStatus <=10)
        {
                 digitalWrite(ledPin, HIGH);
                 Serial.println("LDR is DARK, LED is ON");
        }
        else
        {
                 digitalWrite(ledPin, LOW);
    Serial.println("LDR is BRIGHT, LED is OFF");
                 Serial.println("----");
        }
```

#### **CIRCUIT:**



#### **OUTPUT:**

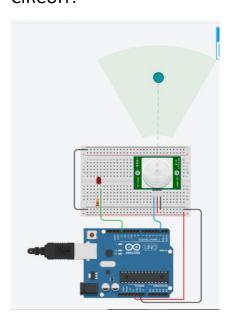


# PIR(Passive InfraRed sensor)

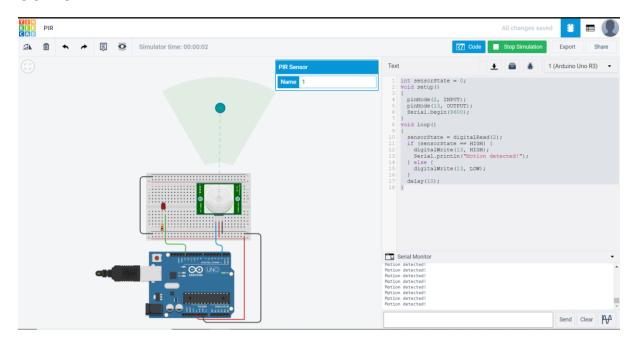
### CODE:

```
int sensorState = 0;
void setup()
{
 pinMode(2, INPUT);
 pinMode(13, OUTPUT);
 Serial.begin(9600);
}
void loop()
{
 sensorState = digitalRead(2);
 if (sensorState == HIGH) {
  digitalWrite(13, HIGH);
  Serial.println("Motion detected!");
 } else {
  digitalWrite(13, LOW);
 }
 delay(10);
}
```

### **CIRCUIT:**



### **OUTPUT:**



### Temperature sensor:

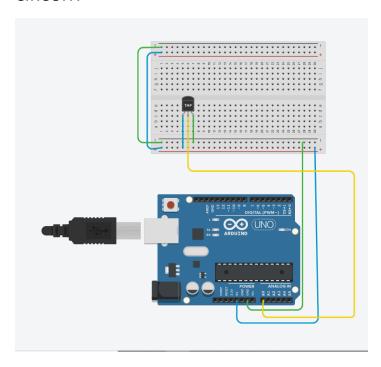
#### CODE:

```
int outputpin=0;
void setup()
{
    Serial.begin(9600);
}

void loop()
{
    int rawvoltage=analogRead(outputpin);
    float millivolts=(rawvoltage/1024.0)*5000;
    int tempc=millivolts/10;
    int tempf=((tempc*9)/5 + 32);
    Serial.println("Temperature:");
    Serial.println(tempc);
    Serial.println(tempc);
    Serial.print("Fahrenheit:");
```

```
Serial.println(tempf);
delay(3000);
}
```

#### **CIRCUIT:**



#### **OUTPUT:**

