

A Mini Project Report

Course Title:Machine Learning

**Paper: Towards Robust Model-Based Reinforcement Learning
Against Adversarial Corruption**

Conference:ICML(2024)



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1. Introduction & Motivation

Real-world datasets (including COVID-19 case counts) are often noisy or adversarially corrupted. Standard maximum-likelihood or least-squares estimators may be sensitive to corrupted samples, producing models that generalize poorly. The CR-PMLE family of approaches (see Ye et al., 2024) proposes uncertainty-weighted likelihood (or weighted training) to downweight samples with high estimated uncertainty and thus limit the influence of corrupted observations. This report follows that idea, implementing a baseline MLE neural net and then applying a bootstrap/variance-based weighting and weighted training (CR-PMLE style) to produce a robust predictor for next-step COVID features.

2. Related work and reference paper

The core theoretical inspiration for the robust weighting and CR-PMLE approach comes from: *Chenlu Ye, Jiafan He, Quanquan Gu, Tong Zhang. "Towards Robust Model-Based Reinforcement Learning Against Adversarial Corruption" (ICML 2024).* That paper introduces CR-OMLE and CR-PMLE algorithms, uncertainty-weighting by total-variation (TV)-based information ratios, and shows how weighting reduces the effect of corruption on model estimation. The present practical implementation uses a bootstrap variance proxy for uncertainty (as recommended in related empirical work).

(Reference material used to prepare this report: the demo project-report layout file and the ICML 2024 paper.)

3. Dataset and preprocessing

Dataset: Covid_19_corrupted_50MB.csv (a deliberately enlarged/corrupted CSV derived from Covid_19.csv).

Key preprocessing steps:

- **Select numeric columns and keep the first 8 numeric features as the model state vector.**
- **Sort by location (if present) and build next-state pairs by shifting each numeric column within each location group.**
- **Drop rows that produce NaN in next-state columns, then fill any remaining NaNs with column means before normalization.**
- **Normalize X and Y using MinMaxScaler.**
- **Train/test split: 80% train / 20% test.**

Notes: the script checks for common date-like columns and excludes them from numeric features. If no location column exists, data are treated as a single global series.

1. Model and training procedure (code included)

```
# =====  
  
# COVID-19 RL MODEL: BASELINE + CR-PMLE VERSION  
  
# With Positive Robustness Improvements  
  
# =====
```

```
import pandas as pd  
  
import numpy as np  
  
import torch, torch.nn as nn  
  
from torch.utils.data import DataLoader, TensorDataset  
  
from sklearn.preprocessing import MinMaxScaler  
  
from sklearn.metrics import mean_squared_error  
  
from sklearn.model_selection import train_test_split  
  
from tqdm import trange  
  
# -----  
  
# LOAD DATASET  
  
# -----  
  
print("Loading dataset...")  
  
df = pd.read_csv("Covid_19_corrupted_50MB.csv") # corrupted dataset  
  
# Select numeric features safely
```

```

num_cols = df.select_dtypes(include=[np.number]).columns.tolist()

for bad_col in ["date", "Date", "DATE", "year", "month", "day"]:
    if bad_col in num_cols:
        num_cols.remove(bad_col)

if len(num_cols) == 0:
    raise ValueError("No numeric columns found in dataset. Please check your
CSV.")

state_cols = num_cols[:8] # use up to 8 numeric features
print(f"Using columns: {state_cols}")

# -----
# BUILD TRANSITIONS SAFELY
# -----

loc_col = None

for c in df.columns:
    if c.lower() in ("location", "country", "country_region", "country_name",
"region"):
        loc_col = c
        break

```

```

if loc_col is None:

    df["_location"] = "ALL"

    loc_col = "_location"


df_sorted = df.sort_values(by=[loc_col])

for c in state_cols:

    df_sorted["next_" + c] = df_sorted.groupby(loc_col)[c].shift(-1)


df_pairs = df_sorted.dropna(subset=["next_" + c for c in state_cols])

if len(df_pairs) < 10:

    raise ValueError(

        f"Not enough valid rows after creating next-state pairs ({len(df_pairs)} rows
found)."

    )


df_pairs = df_pairs.reset_index(drop=True)

print(f"Created {len(df_pairs)} transition pairs for training.")


# -----
# CLEAN NaN VALUES BEFORE NORMALIZATION
# -----

```



```

data_all = pd.concat(
    [df_pairs[state_cols], df_pairs[["next_" + c for c in state_cols]]], axis=1
)

if data_all.isnull().sum().sum() > 0:
    print(f"Found {data_all.isnull().sum().sum()} NaN values — filling with column
means.")

    data_all = data_all.fillna(data_all.mean())

X = data_all[state_cols].values.astype(np.float32)
Y = data_all[["next_" + c for c in state_cols]].values.astype(np.float32)

# -----
# NORMALIZE AND SPLIT
# -----

scaler_X = MinMaxScaler()
scaler_Y = MinMaxScaler()

X = scaler_X.fit_transform(X)
Y = scaler_Y.fit_transform(Y)

X_train, X_test, Y_train, Y_test = train_test_split(X, Y, test_size=0.2,
random_state=42)

print(f"Train: {X_train.shape}, Test: {X_test.shape}")

```

```
# -----
```

```
# DEFINE MODEL
```

```
# -----
```

```
class MLP(nn.Module):
```

```
    def __init__(self, in_dim, out_dim):
```

```
        super().__init__()
```

```
        self.net = nn.Sequential(
```

```
            nn.Linear(in_dim, 128),
```

```
            nn.ReLU(),
```

```
            nn.Linear(128, 128),
```

```
            nn.ReLU(),
```

```
            nn.Linear(128, out_dim)
```

```
        )
```

```
    def forward(self, x): return self.net(x)
```

```
DEVICE = "cuda" if torch.cuda.is_available() else "cpu"
```

```
# -----
```

```
# PART 1: BASELINE MODEL (MLE)
```

```
# -----
```

```
print("\nTraining baseline MLE model...")
```

```
model = MLP(X_train.shape[1], Y_train.shape[1]).to(DEVICE)
```

```

opt = torch.optim.Adam(model.parameters(), lr=1e-3)

loss_fn = nn.MSELoss()

ds = DataLoader(TensorDataset(torch.tensor(X_train), torch.tensor(Y_train)),
batch_size=256, shuffle=True)

for epoch in range(15):

    for xb, yb in ds:

        xb, yb = xb.to(DEVICE), yb.to(DEVICE)

        opt.zero_grad()

        loss = loss_fn(model(xb), yb)

        loss.backward()

        opt.step()

print("Baseline model training complete.")

model.eval()

with torch.no_grad():

    preds = model(torch.tensor(X_test).float().to(DEVICE)).cpu().numpy()

mse_baseline = mean_squared_error(Y_test, preds)

print(f"Baseline MSE (before correction): {mse_baseline:.6f}")

torch.save(model.state_dict(), "covid_model_baseline.pth")

```

```
# -----
```

```
# PART 2: CR-PMLE (ROBUST MODEL)
```

```
# -----
```

```
print("\nStarting CR-PMLE correction (robust training)...")
```

```
def train_temp(X, Y, epochs=5):
```

```
    m = MLP(X.shape[1], Y.shape[1]).to(DEVICE)
```

```
    opt = torch.optim.Adam(m.parameters(), lr=1e-3)
```

```
    loss_fn = nn.MSELoss()
```

```
    ds = DataLoader(TensorDataset(torch.tensor(X), torch.tensor(Y)),
```

```
batch_size=256, shuffle=True)
```

```
    for _ in range(epochs):
```

```
        for xb, yb in ds:
```

```
            xb, yb = xb.to(DEVICE), yb.to(DEVICE)
```

```
            opt.zero_grad()
```

```
            loss = loss_fn(m(xb), yb)
```

```
            loss.backward()
```

```
            opt.step()
```

```
    return m
```

```
# Ensemble predictions for uncertainty
```

```
K = 4
```

```

preds = []

for k in range(K):

    idx = np.random.choice(len(X_train), len(X_train), replace=True)

    m = train_temp(X_train[idx], Y_train[idx])

    m.eval()

    with torch.no_grad():

        preds.append(m(torch.tensor(X_train).float().to(DEVICE)).cpu().numpy())

preds = np.stack(preds, axis=0)

var = preds.var(axis=0).mean(axis=1)

# -----

# STRONGER CR-PMLE WEIGHTING (positive robustness)

# -----

alpha = 5.0 # high sensitivity

var_norm = (var - var.min()) / (var.max() - var.min() + 1e-8)

weights = np.exp(-alpha * var_norm)

weights = np.clip(weights, 1e-4, 1.0)

weights = weights / weights.mean()

# -----

# TRAIN WEIGHTED MODEL

# -----

```

```

model_w = MLP(X_train.shape[1], Y_train.shape[1]).to(DEVICE)
model_w.load_state_dict(model.state_dict()) # warm-start from baseline
opt = torch.optim.Adam(model_w.parameters(), lr=5e-4)
loss_fn = nn.MSELoss(reduction='none')

Xtr_t = torch.tensor(X_train).float().to(DEVICE)
Ytr_t = torch.tensor(Y_train).float().to(DEVICE)
w_t = torch.tensor(weights).float().to(DEVICE)

for epoch in trange(20, desc="CR-PMLE Training"):
    perm = np.random.permutation(len(X_train))
    for i in range(0, len(perm), 256):
        ids = perm[i:i+256]
        xb, yb, wb = Xtr_t[ids], Ytr_t[ids], w_t[ids]
        opt.zero_grad()
        pred = model_w(xb)
        loss = (loss_fn(pred, yb).mean(1) * wb).mean()
        loss.backward()
        opt.step()

print("CR-PMLE model training complete.")

```

```

model_w.eval()

with torch.no_grad():
    preds_w = model_w(torch.tensor(X_test).float().to(DEVICE)).cpu().numpy()

mse_weighted = mean_squared_error(Y_test, preds_w)

print(f"Weighted MSE (after correction): {mse_weighted:.6f}")


torch.save(model_w.state_dict(), "covid_model_weighted.pth")


# -----
# FINAL COMPARISON
# -----

print("\n===== RESULTS =====")

print(f"Before Correction (MLE) MSE: {mse_baseline:.6f}")

print(f"After Correction (CR-PMLE) MSE: {mse_weighted:.6f}")

improvement = ((mse_baseline - mse_weighted) / mse_baseline) * 100

print(f"Improvement in Robustness: {improvement:.2f}%")

print("=====")

```


Future work:

- **Apply Bayesian neural networks or dropout-based variance estimation for more principled uncertainty measures.**
- **Extend CR-PMLE to full model-based reinforcement learning pipelines with planning and policy optimization.**
- **Evaluate the approach on additional public health and finance datasets to validate scalability and robustness.**

References

1. **Ye, C., He, J., Gu, Q., & Zhang, T. (2024). *Towards Robust Model-Based Reinforcement Learning Against Adversarial Corruption*. Proceedings of the 41st International Conference on Machine Learning (ICML 2024).**
2. **Project layout adapted from the provided demo report template and design.**
3. **COVID-19 dataset derived from the public COVID-19 dataset and synthetically enlarged to for robustness testing.**