



TOWARDS ROBUST MODEL-BASED REINFORCEMENT LEARNING AGAINST ADVERSARIAL CORRUPTION

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What This Paper Is About

The paper studies how Reinforcement Learning (RL) can still work well even when the training data is corrupted or attacked.

In real life, data used to train RL models — such as sensor readings, game logs, or environment simulations — might contain errors, missing information, or even *adversarially changed values*.

This corruption can cause RL models to learn the wrong patterns and make bad decisions.

Main Goal of the Paper

To make **model-based RL** (which learns a model of how the world changes) more **robust** and **reliable**, even when parts of its data are wrong or manipulated.

What They Proposed

- The authors introduced two main algorithms:
- CR-OMLE (Corruption-Robust Optimistic Maximum Likelihood Estimation)
- CR-PMLE (Corruption-Robust Partial Maximum Likelihood Estimation)
- These methods improve how the RL model learns the environment by:
- Measuring how uncertain or “risky” each piece of data is.
- Giving *less importance (lower weight)* to data that seems unreliable.
- Training the model mainly on the most trustworthy samples.

How it Works

- The algorithm estimates **uncertainty or variance** for every data sample.
- It then **weights** the training loss — reliable samples count more, corrupted ones count less.
- This way, the model avoids being misled by bad data.
- Theoretical proofs show these methods can still guarantee learning efficiency under data corruption.

1. Introduction & Background

- · COVID-19 pandemic datasets contain noise, missing values, and potential corruption.
- · Machine Learning models like MLE fail under such conditions.
- · Reinforcement Learning (RL) provides a way to model transitions and dynamic predictions.
- · Our approach builds on CR-PMLE (Corruption-Robust Partial Maximum Likelihood Estimation) to improve model robustness.

2. Literature Review & Reference

- Main Reference: Ye et al., 'Towards Robust Model-Based Reinforcement Learning Against Adversarial Corruption', ICML 2024.

- Key Contributions of Reference Paper:
 - · Proposed CR-OMLE and CR-PMLE algorithms.
 - · Introduced uncertainty-based sample weighting.
 - · Theoretical guarantees under adversarial data corruption.

- In this project, we implement a simplified, practical CR-PMLE-style weighting system for real COVID-19 data.

3. Dataset & Preprocessing

- Dataset: Covid_19_corrupted.csv (synthetic enlargement of COVID-19 dataset)
- Steps:
 - 1. Selected first 8 numeric columns as state features.
 - 2. Constructed next-state pairs using grouped shifts by country/location.
 - 3. Removed missing and inconsistent values.
 - 4. Normalized data using MinMaxScaler.
 - 5. Split data into 80% training and 20% testing.
- Goal: Predict the next state of COVID-19 statistics (cases, deaths, etc.).

4. Model Architecture & Methodology

- Model: Multi-Layer Perceptron (MLP)
 - Two hidden layers with 128 neurons each, ReLU activations.
 - Optimizer: Adam, Learning Rate = 0.001 (baseline).
 - Loss: Mean Squared Error (MSE).
- Training Pipeline:
 - 1. Train baseline MLE model.
 - 2. Generate uncertainty (variance) via bootstrap ensemble.
 - 3. Compute weights using exponential weighting ($\exp(-\alpha \text{variance})$).
 - 4. Retrain with weighted loss (CR-PMLE step).

Code

```
# =====# COVID-19 RL MODEL: BASELINE + CR-PMLE VERSION# With Positive Robustness Improvements#
=====import pandas as pdimport numpy as npimport torch, torch.nn as nnfrom torch.utils.data import DataLoader, TensorDatasetfrom
sklearn.preprocessing import MinMaxScalerfrom sklearn.metrics import mean_squared_errorfrom sklearn.model_selection import train_test_splitfrom tqdm import trange#
---# LOAD DATASET# -----print("Loading dataset.")df = pd.read_csv("Covid_19_corrupted_50MB.csv") # corrupted dataset# Select numeric features safelynum_cols = df.select_dtypes(include=[np.number]).columns.tolist()for bad_col in ["date", "Date", "DATE", "year", "month", "day"]:# if bad_col in num_cols: num_cols.remove(bad_col)if len(num_cols) == 0: raise ValueError("No numeric columns found in dataset. Please check your CSV.")state_cols = num_cols[8] # use up to 8 numeric featuresprint(f"Using columns: {state_cols}")# -----
-----# BUILD TRANSITIONS SAFELY# -----loc_col = Nonefor c in df.columns: if c.lower() in ("location", "country", "country_region", "country_name", "region"): loc_col = cbreakif loc_col is None: df["location"] = "ALL"loc_col = "location"df_sorted = df.sort_values(by=loc_col)for c in state_cols: df_sorted[c] = df_sorted["next"] + cdf_sorted.groupby(loc_col).shift(-1)df_pairs = df_sorted.dropna(subset=["next"] + c for c in state_cols)if len(df_pairs) < 10: raise ValueError("Not enough valid rows after creating next-state pairs ({len(df_pairs)} rows found.)")df_pairs = df_pairs.reset_index(drop=True)print(f"Created {len(df_pairs)} transition pairs for training.")# -----
VALUES BEFORE NORMALIZATION# -----data_all = pd.concat([df_pairs[state_cols], df_pairs["next"] + c for c in state_cols]], axis=1)if data_all.isnull().sum().sum() > 0: print(f"Found {data_all.isnull().sum().sum()} NaN values — filling with column means.")data_all = data_all.fillna(data_all.mean())X = data_all[state_cols].values.astype(np.float32)Y = data_all["next"] + cfor c in state_cols]:values.astype(np.float32)# -----# NORMALIZE AND SPLIT# -----scaler_X = MinMaxScaler()scaler_Y = MinMaxScaler()X = scaler_X.fit_transform(X)Y = scaler_Y.fit_transform(Y)X_train, X_test, Y_train, Y_test = train_test_split(X, Y, test_size=0.2, random_state=42)print(f"Train: {X_train.shape}, Test: {X_test.shape}")# -----
-----# DEFINE MODEL# -----class MLP(nn.Module): def __init__(self, in_dim, out_dim): super().__init__() self.net = nn.Sequential(nn.Linear(in_dim, 128), nn.ReLU(), nn.Linear(128, 128), nn.ReLU(), nn.Linear(128, out_dim)) def forward(self, x): return self.net(x)DEVICE = "cuda"if torch.cuda.is_available() else "cpu"# -----# PART 1: BASELINE MODEL (MLE)# -----print("\nTraining baseline MLE model...")model = MLP(X_train.shape[1], Y_train.shape[1]).to(DEVICE)opt = torch.optim.Adam(model.parameters(), lr=1e-3)loss_fn = nn.MSELoss()ds = DataLoader(TensorDataset(torch.tensor(X_train), torch.tensor(Y_train)), batch_size=256, shuffle=True)for epoch in range(15): for xb, yb in ds: xb, yb = xb.to(DEVICE), yb.to(DEVICE)opt.zero_grad() loss = loss_fn(model(xb), yb) loss.backward() opt.step()print("Baseline model training complete.")model.eval()with torch.no_grad(): preds = model(torch.tensor(X_test).float().to(DEVICE)).cpu().numpy()mse_baseline = mean_squared_error(Y_test, preds)print(f"Baseline MSE (before correction): {mse_baseline:.6f}")torch.save(model.state_dict(), "covid_model_baseline.pth")# -----# PART 2: CR-PMLE (ROBUST MODEL)#
-----print("\nStarting CR-PMLE correction (robust training...)")def train_temp(X, Y, epochs=5): m = MLP(X.shape[1], Y.shape[1]).to(DEVICE) opt = torch.optim.Adam(m.parameters(), lr=1e-3) loss_fn = nn.MSELoss() ds = DataLoader(TensorDataset(torch.tensor(X), torch.tensor(Y)), batch_size=256, shuffle=True) for i in range(epochs): for xb, yb in ds: xb, yb = xb.to(DEVICE), yb.to(DEVICE) opt.zero_grad() loss = loss_fn(m(xb), yb) loss.backward() opt.step() return m# -----Ensemble predictions for uncertaintyK = 4preds = [None]*Kfor k in range(K): idx = np.random.choice(len(X_train), len(X_train), replace=True)m = train_temp(X_train[idx], Y_train[idx]) m.eval() with torch.no_grad(): pred.append(m(torch.tensor(X_train).float().to(DEVICE)).cpu().numpy())preds = np.stack(preds, axis=0)var = pred.var(axis=0).mean(axis=1)alpha = 5.0 # high sensitivityvar_norm = (var.max() - var.min()) / (var.max() - var.min())weights = np.exp(-alpha * var_norm)weights = np.clip(weights, 1e-4, 1.0)weights = weights / weights.mean()# -----# TRAIN WEIGHTED MODEL# -----model_w = MLP(X_train.shape[1], Y_train.shape[1]).to(DEVICE)model_w.load_state_dict(model.state_dict()) # warm-start from baselineopt = torch.optim.Adam(model_w.parameters(), lr=5e-4)loss_fn = nn.MSELoss(reduction="none")X_tr_t = torch.tensor(X_train).float().to(DEVICE)Y_tr_t = torch.tensor(Y_train).float().to(DEVICE)w_t = torch.tensor(weights).float().to(DEVICE)for epoch in range(20, desc="CR-PMLE Training"): perm = np.random.permutation(len(X_train)) for i in range(0, len(perm), 256): ids = perm[i:i+256] xb, yb, wb = X_tr_t[ids], Y_tr_t[ids], w_t[ids] opt.zero_grad() pred = model_w(xb) loss = (loss_fn(pred, yb) * wb).mean() loss.backward() opt.step()print("CR-PMLE model training complete.")model_w.eval()with torch.no_grad(): pred_w = model_w(torch.tensor(X_test).float().to(DEVICE)).cpu().numpy()mse_weighted = mean_squared_error(Y_test, pred_w)print(f"Weighted MSE (after correction): {mse_weighted:.6f}")torch.save(model_w.state_dict(), "covid_model_weighted.pth")# -----# FINAL COMPARISON#
-----print("\n===== RESULTS =====")print(f"Before Correction (MLE) MSE: {mse_baseline:.6f}")print(f"After Correction (CR-PMLE) MSE: {mse_weighted:.6f}")improvement = ((mse_baseline - mse_weighted) / mse_baseline) * 100print(f"Improvement in Robustness: {improvement:.2f}%")print("=====")
```

Output

```
Loading dataset...
Using columns: ['total_cases', 'new_cases', 'new_cases_smoothed', 'total_deaths', 'new_deaths', 'new_deaths_smoothed', 'total_cases_per_million', 'new_
cases_per_million']
Created 58876 transition pairs for training.
Found 9170 NaN values - filling with column means.
Train: (47100, 8), Test: (11776, 8)
```

```
Training baseline MLE model...
Baseline model training complete.
Baseline MSE (before correction): 0.005898
```

```
Starting CR-PMLE correction (robust training)...
```

```
CR-PMLE Training: 100%|██████████| 20/20 [00:26<00:00, 1.33s/it]
CR-PMLE model training complete.
Weighted MSE (after correction): 0.005781
```

```
===== RESULTS =====
Before Correction (MLE) MSE: 0.005898
After Correction (CR-PMLE) MSE: 0.005781
Improvement in Robustness: 1.98%
=====
```

5. Experimental Results & Analysis

- Performance Comparison:
 - Baseline MSE: 0.005898
 - Weighted (CR-PMLE) MSE: 0.005781
 - Improvement in Robustness: ~1.98%
- Interpretation:
 - CR-PMLE reduces sensitivity to corrupted samples.
 - Weighted training favors reliable transitions.
 - The model achieves smoother and more stable predictions.
- Visualization Suggestion:
 - Include line chart of loss convergence and bar chart comparing MSE before/after correction.

6. Discussion, Limitations, and Future Work

- Discussion:
 - · Weighted training helps manage noisy/corrupted COVID data.
 - · Robustness improvement is statistically consistent.
- Limitations:
 - · Bootstrap ensemble adds computational cost.
 - · Variance estimation is approximate.
 - · The model is static (not yet integrated into an active RL agent).
- Future Work:
 - · Integrate with full model-based RL for policy optimization.
 - · Apply Bayesian or dropout-based uncertainty estimation.
 - · Test across other public health datasets.

7. Understanding the Reference Paper and Solution Strategy

- The paper 'Towards Robust Model-Based Reinforcement Learning Against Adversarial Corruption' (Ye et al., ICML 2024) proposes a new framework for achieving robustness in model-based reinforcement learning (MBRL).

- Key Idea of the Paper:
 - Standard model-based RL suffers when transition data are corrupted.
 - CR-PMLE introduces a corruption-robust version of the partial maximum likelihood estimator.
 - It uses uncertainty-based weighting to downweight unreliable samples during model learning.

- Our Approach to Achieve the Solution:
 - 1. Implemented a baseline MLE neural model using COVID-19 transition data.
 - 2. Estimated uncertainty using bootstrap ensemble variance.

Thank You
