	EXPERIMENT NO. 6
<b>→</b>	Aim: To implement a Fuzzy Controller.  Write a program to design Fuzzy Controller.
	THEORY:  Fuzzy Logic is an approach to represent uncertainity
	Characteristics of fuzzy logic.
i)	In Fuzzy logic, exact reasoning is viewed as a limiting case of approximate reasoning.
(îi	In Fuzzy logic everything is a matter of degree.
ζííí	Any logical system can be fuzzified.
ív)	In fuzzy logic knowledge is interpreted as a collection of elastic or equivalently, fuzzy constraint on a collection of variaties.
v)	Inference is viewed as a process of propagation of elastic constraints.

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Course i/p Crusp 0/P Control Denormalization Noumalization Inference Engine Fuzzification Defuzzification Rule

Data Base

# A FUZZY INFERENCE SYSTEM (FIS)

An FKBC is a highly specialized system designed for performing a specific task during a particular phase of the life cycle of a process control system.

# → Yarions Modules:

1. NORMALIZATION

Creates a normalized universe of disetosure.

Performs a scale transformation.

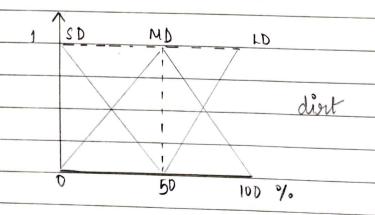
Eg: Universe of disclosure -> inCy

# 2 FUZZIFICATION

Converts ouisps values le normalized ouisp values to fuzzy set.

Eg. Very tall, medium tall, less tall etc.

Generalized way of forming a fuzzy set



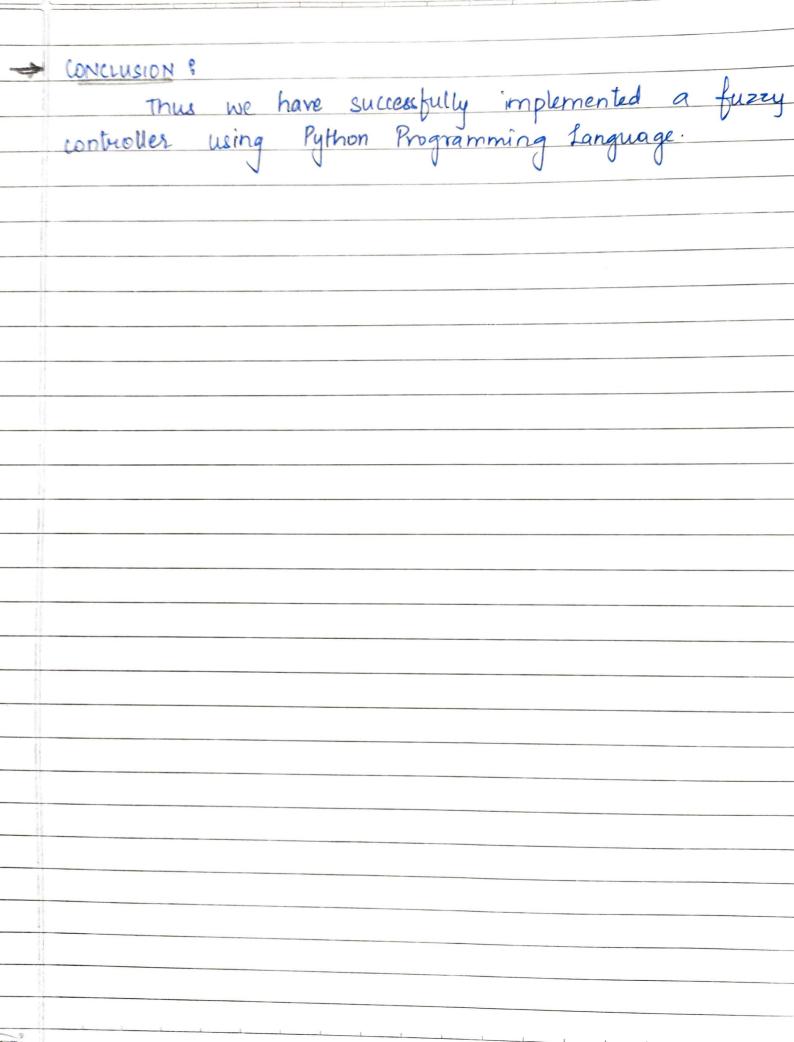
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3	Rule Base
	if then olse
	ie combination of all conditions:  if < antecedent > then < consequent >
	if < antecedent > then ( conceauget >
	V Consequent >
	VARIOUS DESIGN PARAMETERS.
	1. Choice of process state and control of praviable
	2 Choice of the content of the onle antecedent and
	relule consequent.
	3 Desiration of set of rules
4.	DATABASE
	Provides and Slores necessary information
-	Vauions design parameters are
	i) Choice of Membership function.
	Various design parameters are  i) Choice of Membership function.  ii) Choice of Scaling factor
	- U V
5	INFERENCE ENGINE :
	KB = RB + DB infers 0/P based on
	KB = RB + DB infers 0/P based on Rulebase and Database.
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6. DEPUZZIPICATION: convesting the set of fuzzy values to single point-wise value DENORMALIZATION Maps point wise to its physical domain. General Steps for Designing a fuzzy controller for vieal world problems: Step 1: Identify i/p and ofp using linguistic variable Dolaw Graphs for each Step 2: Assigning membership functions. Step 3: 3.1 Build a rule base 3.2 Rule Evaluation 3.3 Rule Decision Jable Step 4 : Defuzzification. 4.1 Min - Max Method 4.2 Rule Strength Jable 4.3 Map RDT with RST get Z value

FOR EDUCATIONAL USE

(Jundaram)



## **Soft Computing**

Title: Program to Solve the Tipping problem

```
Program:
```

```
x = int(input('Enter the Rating for Food Quality [0-10] :'))
```

y = int(input('Enter the Rating for Service [0-10]:'))

...

### Input Descriptors:

1) Food Quality [0-10]:

i) VP: Very Poor

ii)P: Poor

iii)G: Good

iv)E: Excellent

2) Service[0-10]:

i) VP: Very Poor

ii)P: Poor

iii)G: Good

iv)E: Excellent

### **Ouput Descriptor:**

1) Tip [0-25%]:

i) VL: Very Less

ii) L: Less

iii) N: Normal

iv) H: High

v) VH: Very High

...

### **#Food Quality Membership Function**

$$fq_vp = 0$$

$$fq_vp = (5 - x) / 5$$

$$fq_p = 0$$

$$fq_p = x / 50$$

$$fq_p = (8 - x) / 3$$

$$fq_g = 0$$

$$fq_g = (x - 5) / 3$$

$$fq_g = (10-x) / 2$$

$$fq_e = (x - 8) / 2$$

**#Service Membership Function** 

$$s_vp = (5 - y) / 5$$

$$s_p = y / 50$$

$$s_p = (8 - y) / 3$$

$$s_g = (y - 5) / 3$$

$$s_g = (10-y) / 2$$

```
s_e = (y - 8) / 2
```

```
r1 = min(fq_vp, s_vp)
r2 = min(fq_vp, s_p)
r3 = min(fq_vp, s_g)
r4 = min(fq_vp, s_e)
r5 = min(fq_p, s_vp)
r6 = min(fq_p, s_p)
r7 = min(fq_p, s_g)
r8 = min(fq_p, s_e)
r9 = min(fq_g, s_vp)
r10 = min(fq_g, s_p)
r11 = min(fq_g, s_g)
r12 = min(fq_g, s_e)
r13 = min(fq_e, s_vp)
r14 = min(fq_e, s_p)
r15 = min(fq_e, s_g)
r16 = min(fq_e, s_e)
out = max(r1, r2, r3, r4, r5, r6, r7, r8, r9, r10, r11, r12, r13, r14, r15, r16)
if r1 == out or r2 == out or r5 == out:
  vl = out
  z = 5 - 5 * vl
if r3 == out or r4 == out or r6 == out or r7 == out or r9 == out or r13 == out :
  l = out
  z1 = 5 * l
  z2 = 10 - 5 * l
  z = (z1 + z2) / 2
if r8 == out or r10 == out or r14 == out:
  n = out
  z1 = 5 * n + 5
  z2 = 20 - 10 * n
  z = (z1 + z2) / 2
if r11 == out or r12 == out :
```

```
h = out

z1 = 10 * h + 10

z2 = 25 - 5 * h

z = (z1 + z2) / 2

if r15 == out or r16 == out:

vh = out

z = 20 + 5 *vh

print('The calculated Tip is : {0} %'.format(z))

Output:

Enter the Rating for Food Quality [0-10]8

Enter the Rating for Service [0-10]8

The calculated Tip is : 20.0 %
```

C:/Users/asus/Desktop/sc.py

>>>

\_\_\_\_\_

Enter the Rating for Food Quality [0-10]:3

Enter the Rating for Service [0-10]:10

The calculated Tip is : 5.0 %