

PROFILE

Always curious about physics... I enjoy music, coffee, and good series. I particularly like automating manual stuff. I want to be key link in between industry and automation, (Industry 4.0)

PERSONAL DETAILS

Birth date

03-11-1999

Nationality

INDIAN

Address

Bhondve Orchid, Ravet, Pune 412101.

CONTACT

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Shivam Chavan

ROS-ROBOTICS AND AUTOMATION

EXPERIENCE

INTERN

FLY MASTER, NARHE, PUNE

25th FEB 2021 - ongoing (25th MARCH 2021) Semi-automated static 1-1.5 mtr aircraft model's electonic circuit assembly, connections for servos and LEDs to custom shields and adruino. Learnt electronic connections.

INTERN

ATHIRA MOULD INDUSTRIES, MOHANNAGAR, PCMC

June 2019-july 2019

2015-2016

Studied and learnt industy standards, and basic workshop operations.

EDUCATION

Engineering Degree

BTECH INDUSTRIAL ENG. VIT PUNE, INDIA. 2018-2022

CGPA 8.12 9.17 SGPA OF CURRENT SEMISTER

12th HSC BOARD

PRATIBHA JUNIOR COLLEGE, AKURDI, PUNE, INDIA. 2017-2018

12TH HSC PERCENTAGE 73.2%

10th SSC BOARD

SPM ENGLISH MEDIUM SCHOOL, NIGDI, PUNE, INDIA

10TH SSC PERCENTAGE 85.0%

SKILLS

Python

Autonomous Navigation ROS 75%

Django Admin web framework 50%

SKILLS

Arduino IDE 50%

Machine Learning, DNN, CNN. 50%

Robotic 6-DOF arm Manipulation ROS

LAUNGUAGE

English

MAJOR ACHIEVEMENTS

Achieved 3rd rank in "Recycle RAJA" South Asia's biggest recycle competition 2014

Presented paper International Conf. on Energy and Environment on fuel measurer kit for bikes 2019

Participated in PCCOE's Spectrum for endurance bot challenge (Only team which was wireless) 2019

Achieved 5th rank in "BIZZ Hour" a National Startup idea Pitching Competition by VIIT Pune

2020

Completed successfully the responsibility as Publicity Head of SAEINDIA Team VIT 2020

Completed than 9 Udemy and 6 Coursera of various ML, Robotics, Automation, python, Linux, etc 2021

LANGUAGE

Hindi

MAJOR PROJECTS

Fuel measurer kit for bikes to check the integrity of the amount of fuel being filled 2018

Made a 2 axis CNC and was selected for BEST 2018 **EDI Group projects**

Made a SMART HELMET with Headsup display to show location and route to destination 2018

Wireless four wheel robot with differential drive using NRF 2.4 Ghz modules 2019

Autonomous navigation and pick and place of objects using perception in simulation 2021

Django Personal Portfolio Site with backend and blogging model 2021