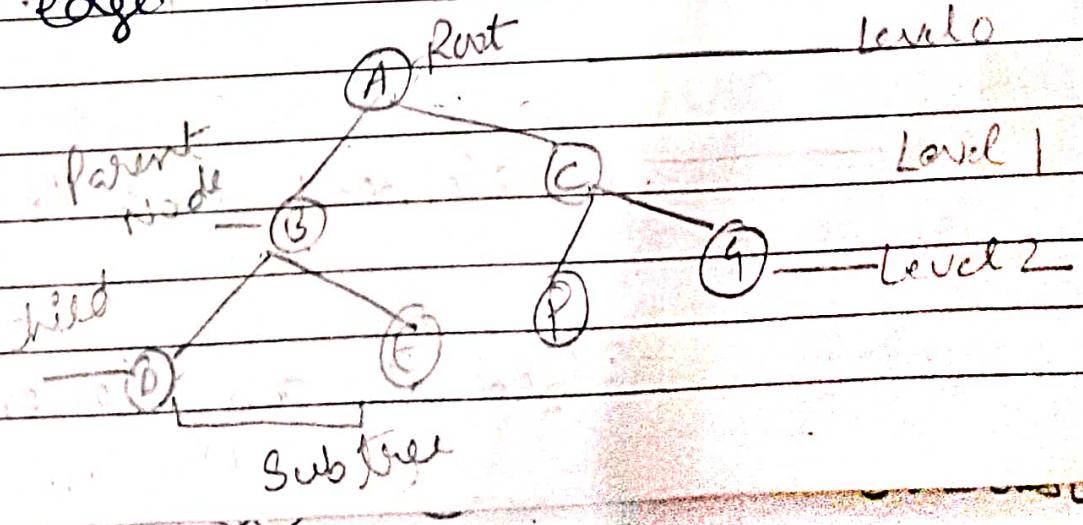


4. Tree's — A tree is a hierarchical data structure defined as a collection of nodes. Nodes represent value and nodes are connected by edges.

- The tree has one node called root. The tree originates from this & hence it does not have any parent.
- Each node has one parent only but can have multiple children.
- Each node is connected to its children via edge.



Basic Terminologies

- ① Root :- Special Node in a tree. The entire tree originate from It & it does not have any parent.
 - ② Parent Node :- It is an Immediate Predecessor of a Node.
 - ③ Child Node :- All Immediate Successors of a Node are its Children.
 - ④ Leaf :- Node which does not have any children.
 - ⑤ Edge :- It is a Connection b/w 2 Nodes or a line b/w 2 Nodes or leaf.
 - ⑥ Siblings - Node with the Same parent
 - ⑦ Subtree :- descendants of a Node represents Subtree.
 - ⑧ Path | Traversing :- No. of Successive Edges from Source node to destination Node.
- * Basic Operations :-
- ① Insert :- Insert element in a Tree / Create a tree.
 - ② Search :- Search an Element in the tree.

③ Travelling — Pass through the tree in a specific manner & contains (Pre, Post & In Order Traversing).

* Tree Node Code —

(D)

(C)

(L)

Struct Node {

int data

Struct Node *leftchild;

Struct Node *rightchild;
};

1.

Insert operation:

1st Insertion creates the tree. Afterwards

an element is to be inserted, 1st locate its proper location. Start searching from the root node, then If the data < the key value, Search for the empty location at left Side & if data is > the key value Search empty location in Right Side.

Algo: —

If root is NULL

then Create Root Node

< (100)

return

if

< (10)

If root exists then

Compare the data with Node data

While until insertion position is located

If data is greater than node.data

insertion

go to right Subtree

else

go to left Subtree

end while

(100)

LC

(Post)

RC

Post

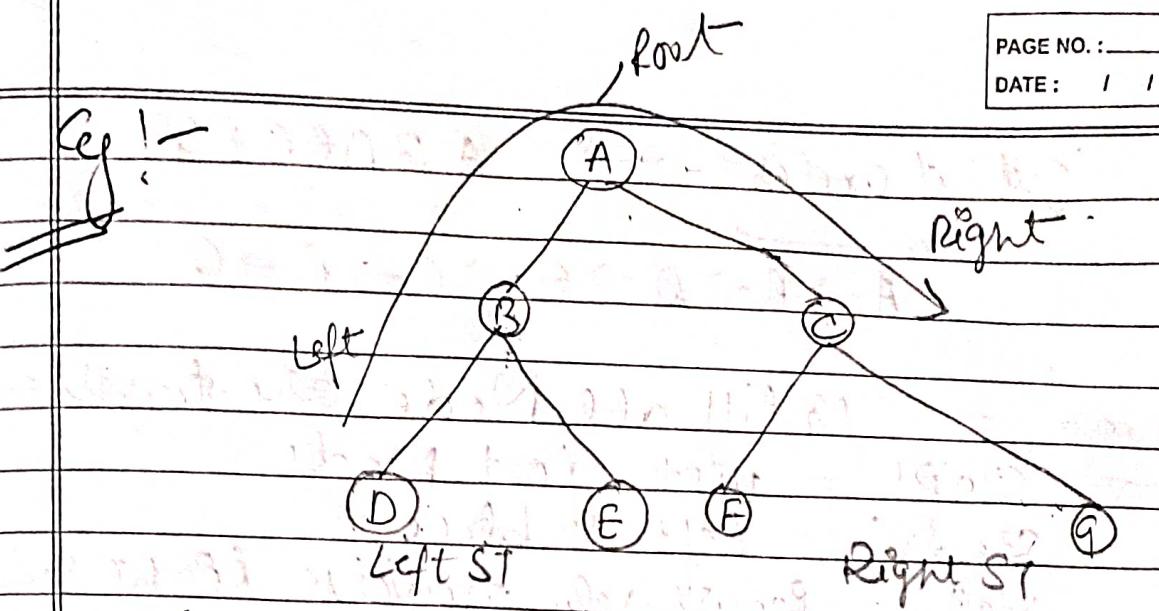
insert data
 end If

② Search operation — If Root · data = Searchdata
 return root
 else
 while data not found
 If data is greater than node · data
 go to right Subtree
 else
 go to left Subtree
 If data found
 return node
 end while
 return data not found
 end If.

4 TREE TRAVERSAL — Travelling is a process to visit all the nodes of a tree and may print their values too. All nodes are connected via edges. We always start from the Root node. We cannot randomly access a Node in a tree. There are 3 ways to Traverse a Tree.

A+B

① In-order — In this Method, the left Subtree is visited first then the Root and later the Right

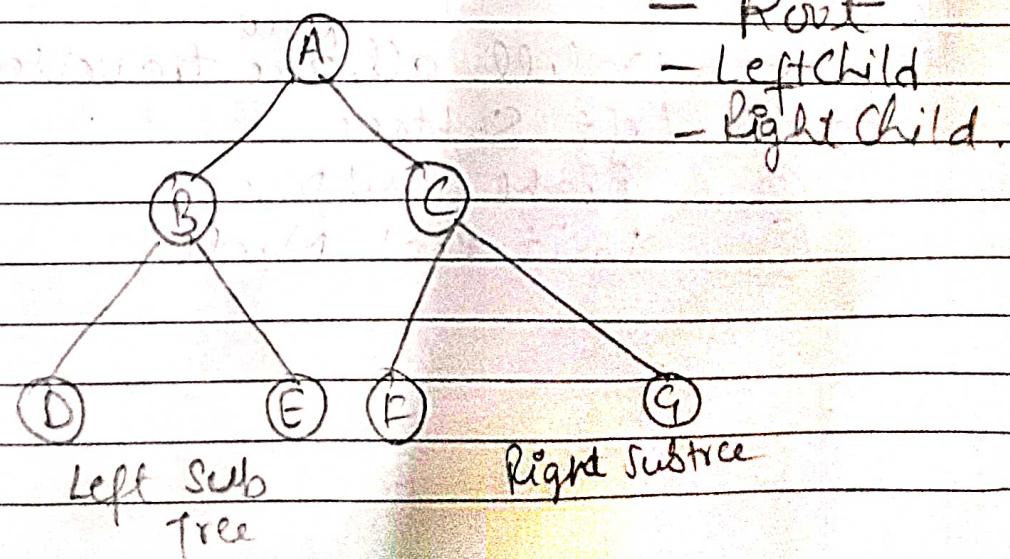


Output of Inorder Traversal is

$$D \rightarrow B \rightarrow E \rightarrow A \rightarrow F \rightarrow C \rightarrow G$$

Algorithm — Until all nodes are traversed—
 Step 1! — Recursively Traverse left Subtree
 Step 2! — Visit Root Node
 Step 3! — Recursively Traverse Right Subtree

3. Pre-Order — In this, The Root Node is visited 1st after that Left Node then Right Node.



Output Order — A B D E C F G

A → B → D → E → C → F → G

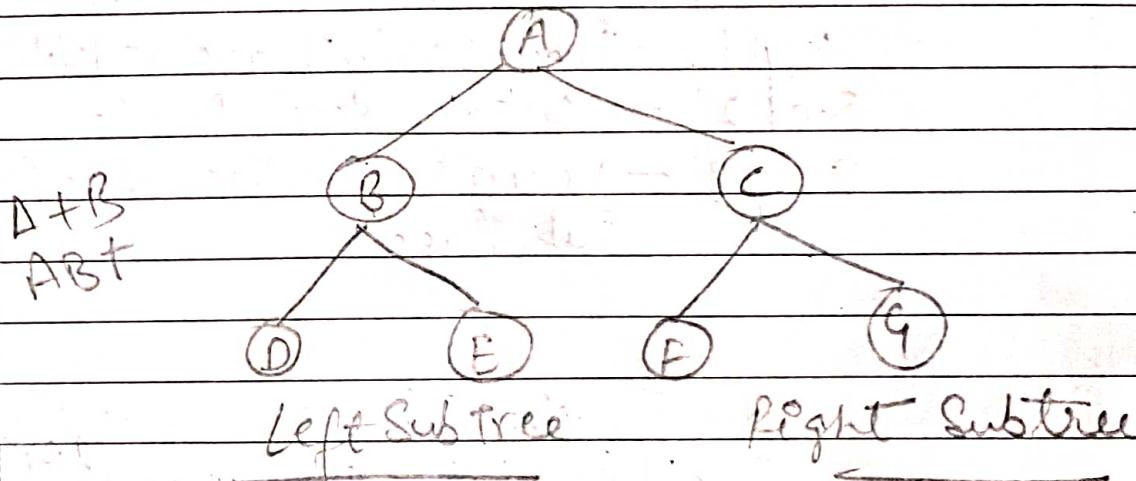
Algo :- Until all Nodes are travelled

Step 1 :- Visit Root Node

Step 2 :- Left Subtree

Step 3 :- Recursively traverse Right Subtree

3) Post order. — In this Root Node visit last, 1st Traverse left node & then right.



The output is = D → E → B → F → G → C → A

Algo — Until all ^{nodes} are travelled

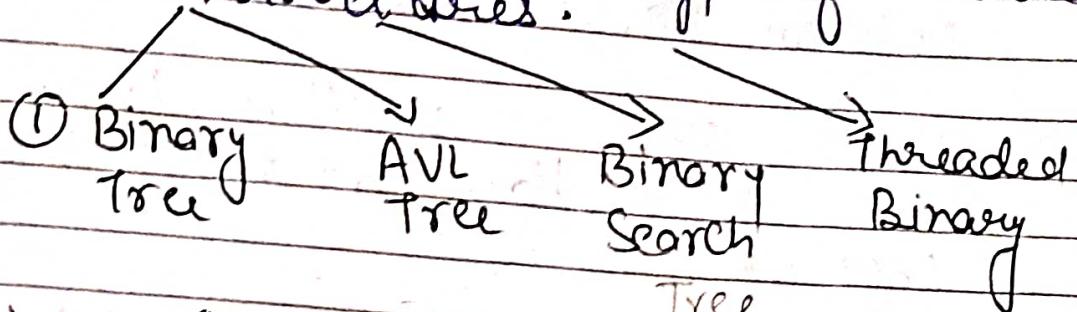
① Left Subtree

② Right Subtree

③ Visit Root Node

Types of Trees

There are mainly four types of trees used in data structures.



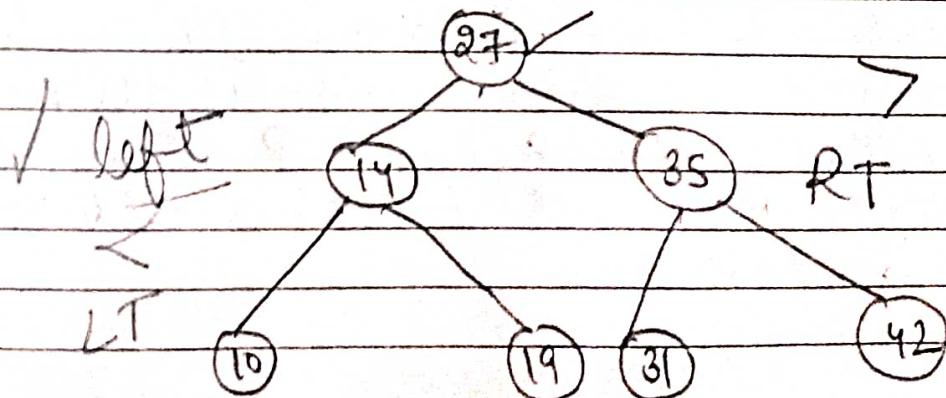
① Binary Search Tree :- In which,

- The left Subtree of a Node has a Key less or equal to (\leq) its Parent node
- The Right Subtree of a Node has a Key $>$ to its Parent Node's Key.

Thus BST, divides all its Sub-Trees into 2 Segments, the Left & Right Subtree

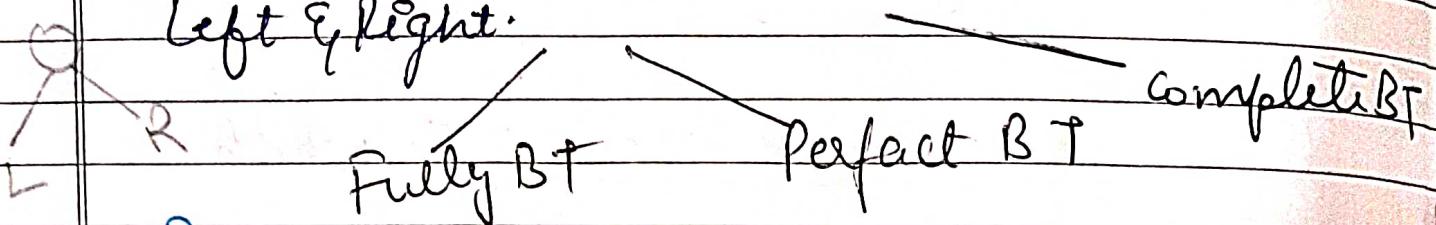
Left Subtree(Keys) \leq node(Key) \leq Right Subtree(Keys)

Representation :- Collection of nodes arranged in a way, while searching is the desired key is compared to the keys in BST & If found, the associated value is retrieved.

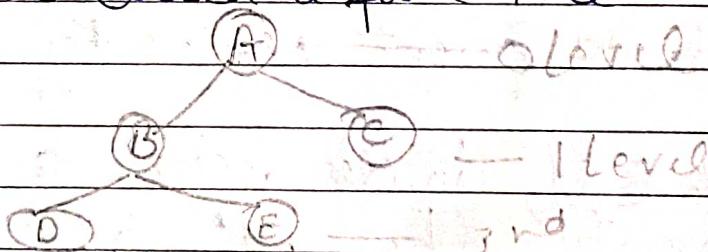


The Root Key (27) Contains all less Value Keys on Left Side & More Valued Keys on Right Side.

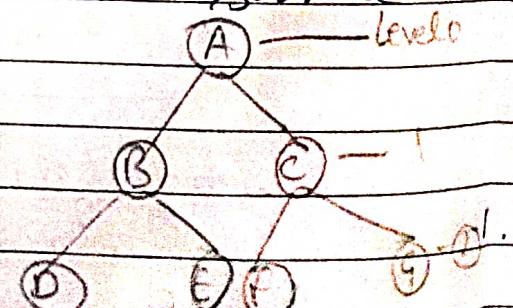
- ② Binary Tree — In This, Every node can have at most 2 Children Left & Right.



- * Fully BT — If Every Node in a tree has either 0 or 2 children then the tree is Called a full Tree.



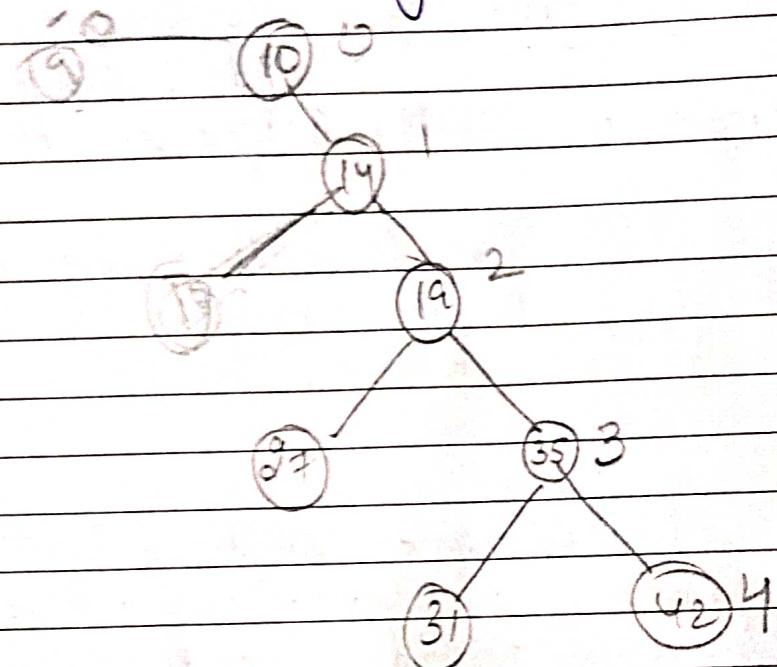
- * Perfect BT — It is a binary tree in which all Interior Nodes have 2 Children and all leaves have the same depth and same level.



- * Complete BT — A Binary tree is Complete binary tree if all levels are completely filled Except Possibly the last level and last level has all keys as left as possible.

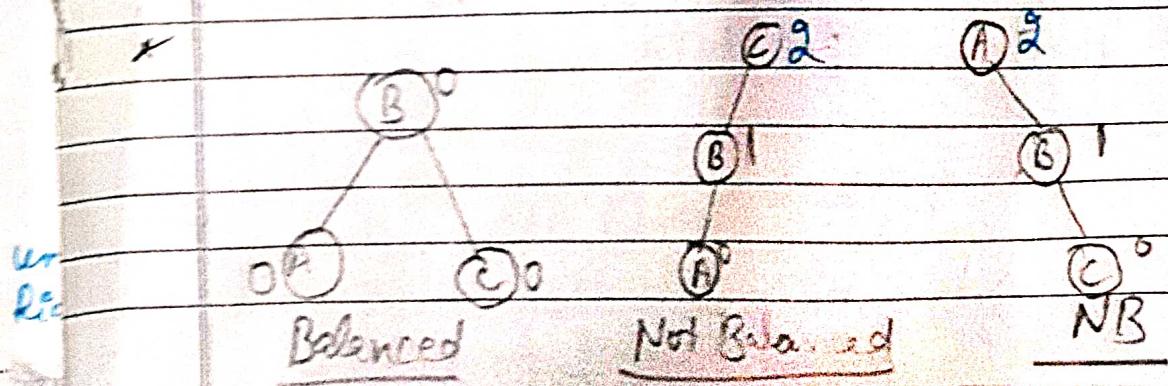
AVL Tree

- It is observed that BST, needs to arises Balance out the Existing BST.



- To Balance the BST's, AVL Trees used to Balance out.

- AVL Stands for — Adelson, Velski & Landis, AVL trees are height Balancing binary search tree - AVL checks the height of left & right Sub Trees and assures that the difference is not more than 1. This difference is called Balance factor.



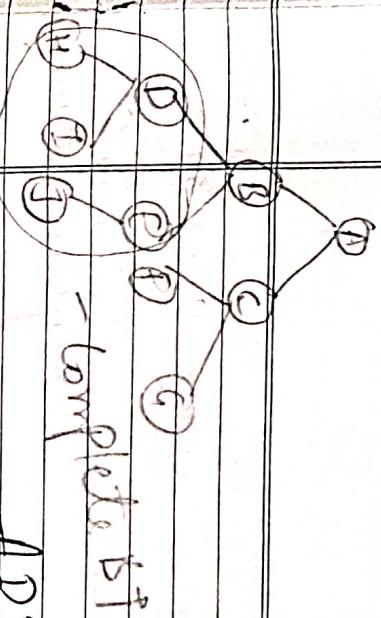
here we see the 1st tree is balanced & rest of
2 is not balanced.

PAGE NO.:
DATE: / /

\Rightarrow In Second Tree \rightarrow the left subtree of C has height 2 and the right subtree

C has height 0. So the difference is 2.

\Rightarrow In 3rd tree \rightarrow the height of A is 2 and left subtree of A has height 0. So the difference is 2.



ARRAYS

Homogeneous data

eds

Array is a container which can hold a fix no. of items & those items should be of the same type. Most of data structure make use of Arrays to implement their algo.

Element — Each item stored in array is called an Element.

Index — Each location of an element in an array has a Numerical Index, which is used to identify the Element.

Array Representation — Arrays can be declared in various ways in different languages.

int arr[10] = {35, 33, 42, 10, 14, 19, 27, 44, 16, 31};

↑ size

type

When a Node is inserted into the Right Subtree of the Right Subtree, then we perform a Single Left Rotation.

int arr[10] = {35, 33, 42, 10, 14, 19, 27, 44, 16, 31};

is

(A)

1

→

(B)

2

→

(C)

3

→

(D)

4

→

(E)

5

→

(F)

6

7

8

9

10

11

12

13

14

15

16

17

18

19

20

21

22

23

24

25

26

27

28

29

30

31

32

33

34

35

36

37

38

39

40

41

42

43

44

45

46

47

48

49

50

51

52

53

54

55

56

57

58

59

60

61

62

63

64

65

66

67

68

69

70

71

72

73

74

75

76

77

78

79

80

81

82

83

84

85

86

87

88

89

90

91

92

93

94

95

96

97

98

99

100

101

102

103

104

105

106

107

108

109

110

111

112

113

114

115

116

117

118

119

120

121

122

123

124

125

126

127

128

129

130

131

132

133

134

135

136

137

138

139

140

141

142

143

144

145

146

147

148

149

150

151

152

153

154

155

156

157

158

159

160

161

162

163

164

165

166

167

168

169

170

171

172

173

174

175

176

177

178

179

180

181

182

183

184

185

186

187

188

189

190

191

192

193

194

195

196

197

198

199

200

201

202

203

204

205

206

207

208

209

210

211

212

213

214

215

216

217

218

219

220

221

222

223

224

225

226

227

228

229

230

231

232

233

234

235

236

237

238

239

240

241

242

243

244

245

246

247

248

249

250

251

252

253

- Each element can be accessed via its index
for eg: we can fetch Index 6 as 27.

Basic Operations -

- ① Traverse - Prints all array elements one by one

- ② Insertion & Deletion - Add & delete element at the given index.

- ③ Search - Search an element using Index or by the value.

- ④ update - Updates an element at the given index.

* Array Insertions -

- ① Insertion at the beginning of an array.

$$A[2, 3, 4, 5] \rightarrow A[0, 1, 2, 3, 4]$$

- ② Insertion at the Given Index of an Array.

$$A[1, 2, 3, 4, 5] \rightarrow A[0, 1, 2, 3, 4]$$

- ③ Insertion after the given Index of an Array.

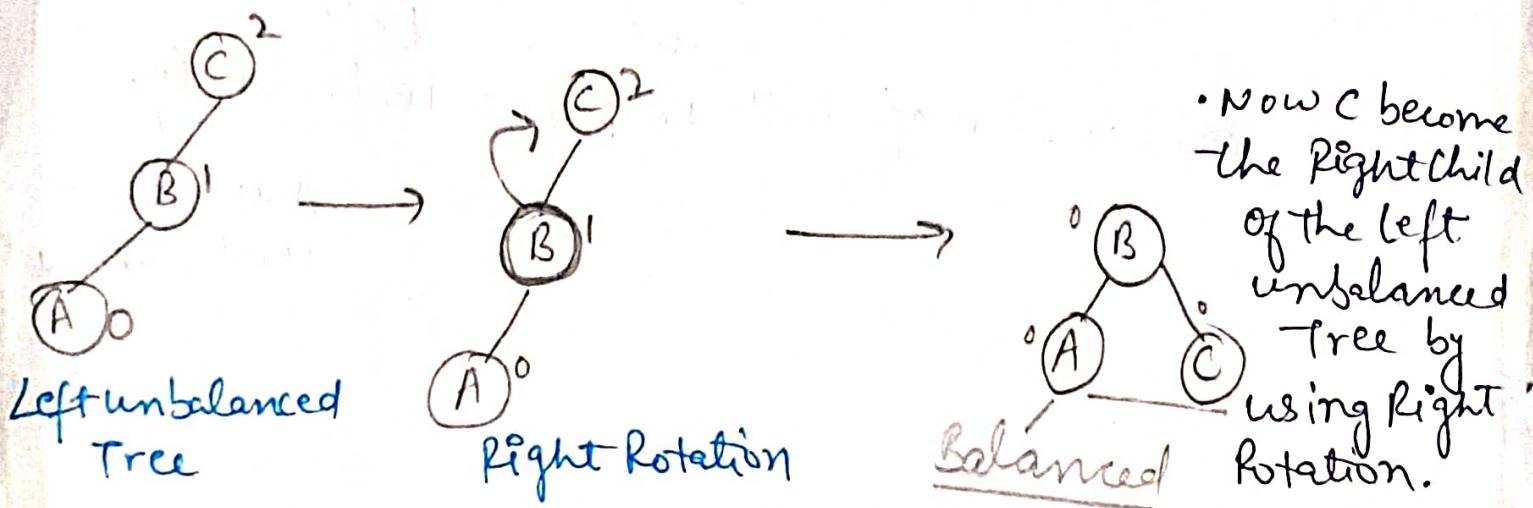
$$A[1, 2, 3, 4, 5] \rightarrow A[1, 2, 3, 4, 5]$$

- ④ Insertion before the Given Index of an Array.

$$A[1, 2, 4, 5, 3] \rightarrow A[0, 1, 2, 3, 4, 5]$$

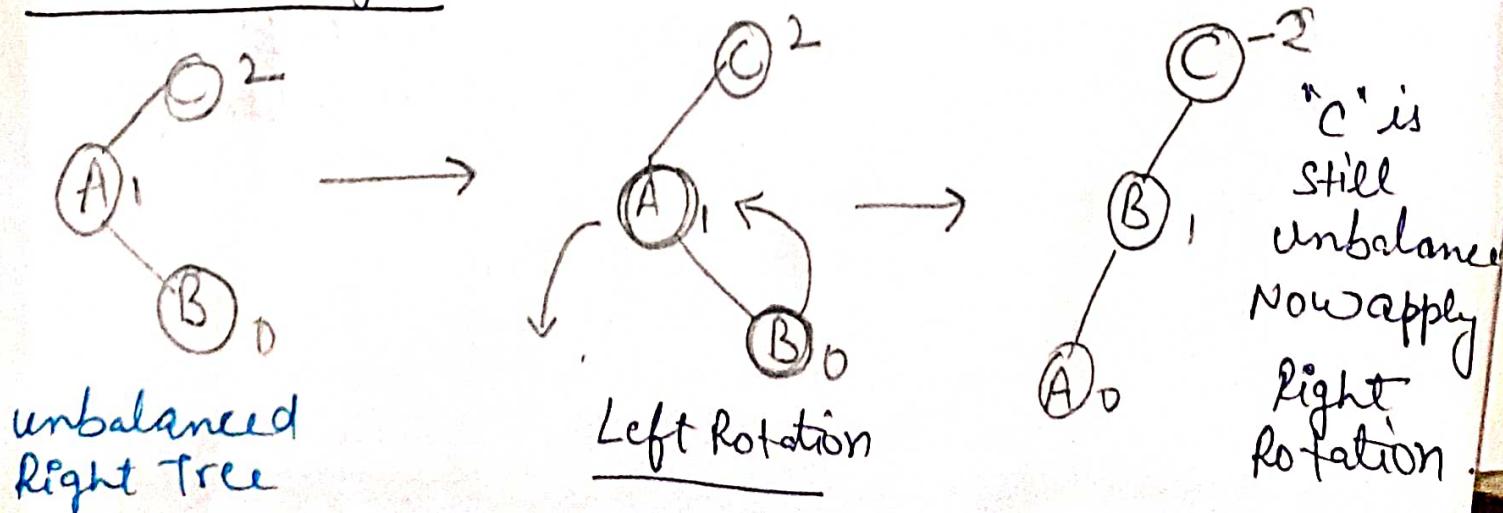
In our example, Node A has become Unbalanced as a Node is inserted in the Right Subtree of A's Right Subtree. We perform the Left Rotation by making A the left Subtree of B.

(2) Right Rotation :— AVL Tree May become unbalanced, If a Node is inserted in the left Subtree of the left subtree. The tree then needs a right rotation.

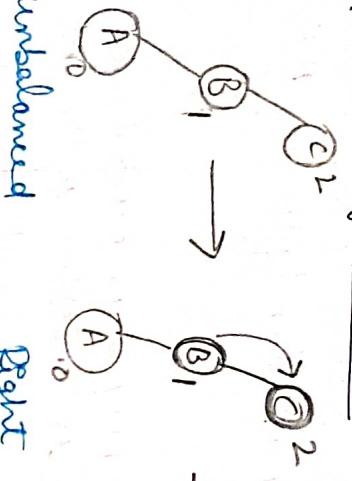


(3) Left - Right Rotation :— It is Complex Version of upper performed Rotations.

- a Left Right Rotation is combination of L-R Rotation
1st Perform — Left Rotation ✓
2nd — Right ✓



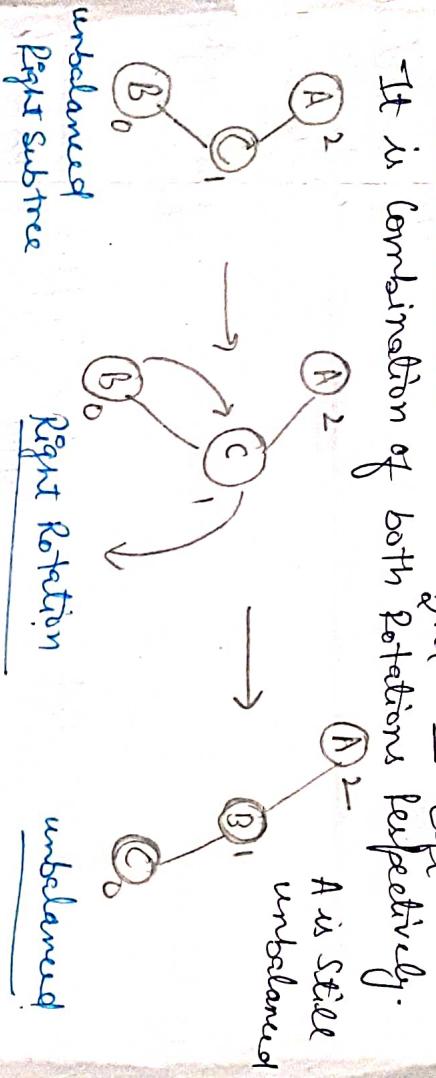
\Rightarrow Applying Right Rotation



- Now becomes
the right child
of subtree B.
of its own
left subtree.

(4) Right Left Rotation :- 1st rotation - Right
2nd - Left

It is combination of both rotations respectively.

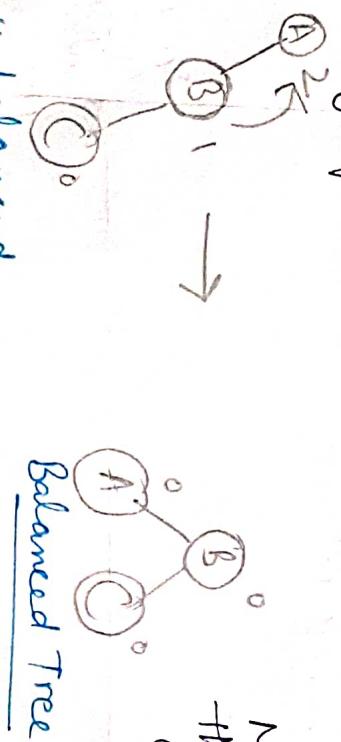


Right Rotation

unbalanced

unbalanced
Right subtree

\rightarrow Apply left Rotation :-

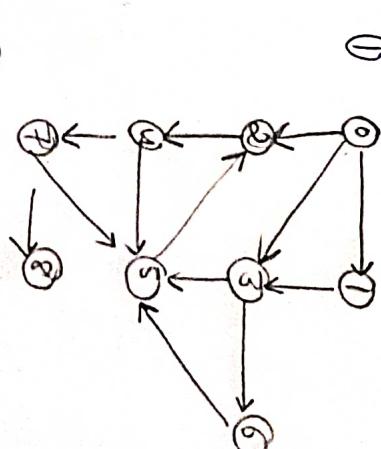
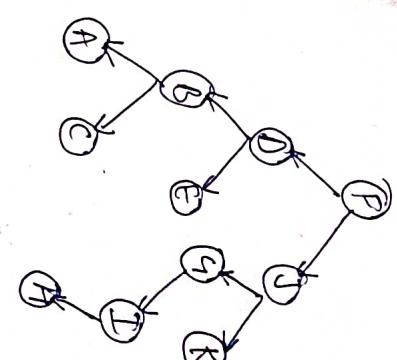
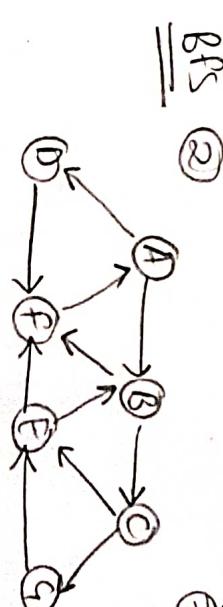


Balanced Tree

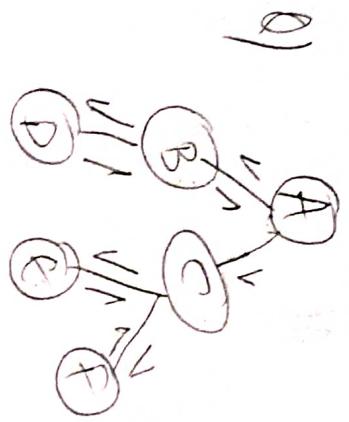
Now A becomes
the left child
of subtree B.

unbalanced

BFS :-



Q)



DFS

Ex:

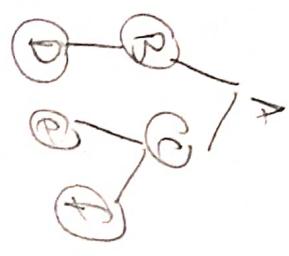
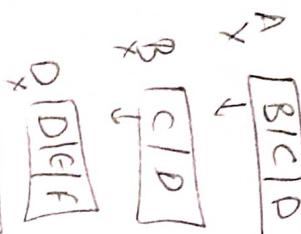
LIFO

- All left child Pointers that would normally be Null point to the inorder predecessor of the Node.
- * Thread — The Pointers Reference the Next Node in an Inorder Traversal Called Threads.

①

A | B | C |

A \nwarrow
C



Q) Why do we Need Threaded Binary Tree?

✓ Binary tree have a lot of wasted space. the leaf node each have 2 Null Pointers. we can use these pointers to help us Inorder Traversals.

* Threaded binary tree makes the tree traverse faster.

* Types of TBT

Double \rightarrow R & L

Single \rightarrow Right
either Left

① Single TBT

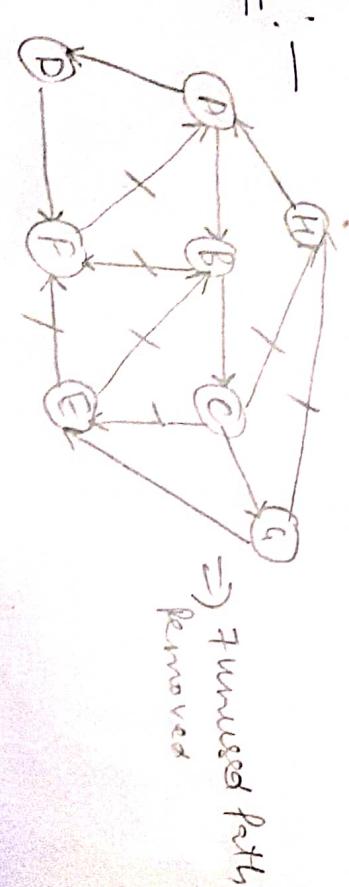
— Each Node is threaded towards either the inorder predecessor or successor

(left or right)

Single Threaded

Right side

1, 3, 5, 6, 7, 8, 9, 11, 13



DTS :-

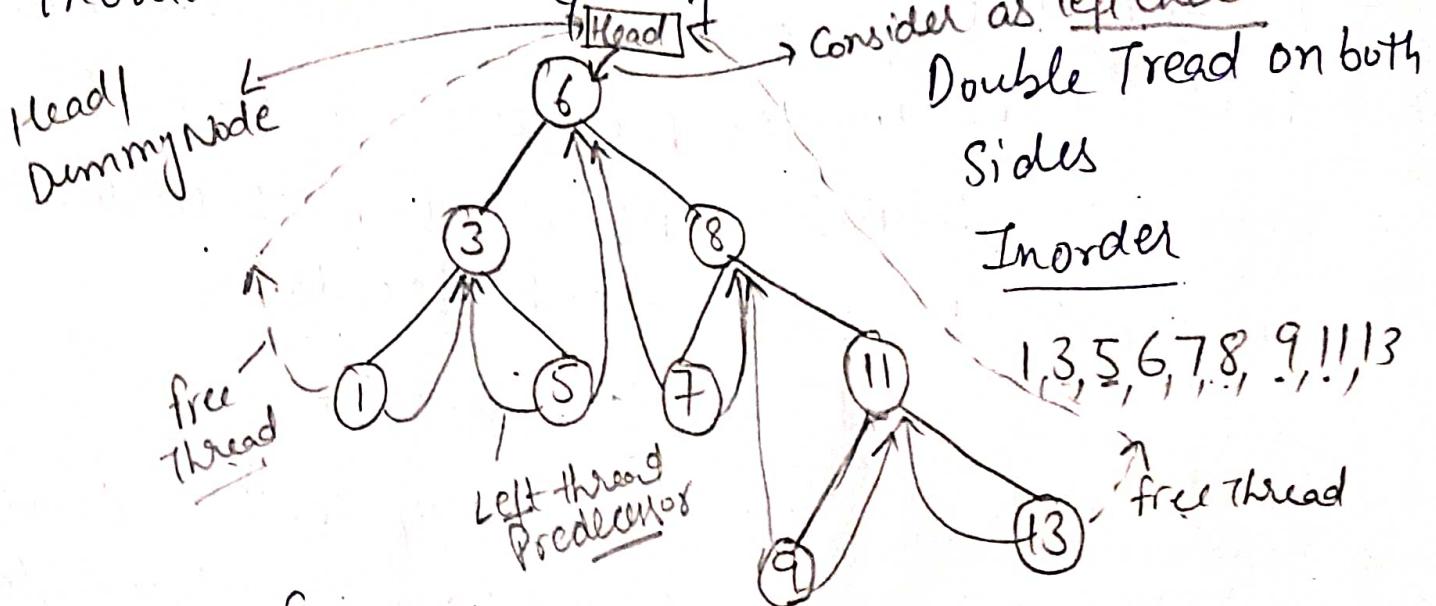
Ex: F X

\Rightarrow Traversed path
removed

② Inorder Successor

② Double TBT :— Each Node is threaded Towards both inorder predecessor & successor

(left & right). all Right pointers will point to inorder Successor & leftside → predecessor.

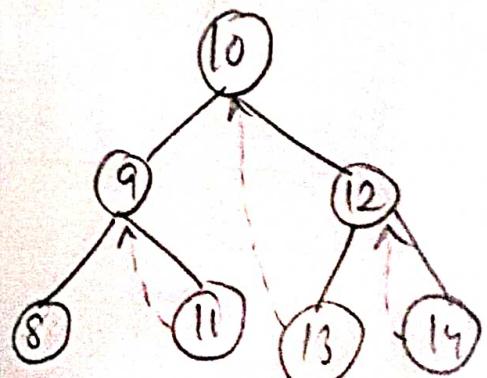
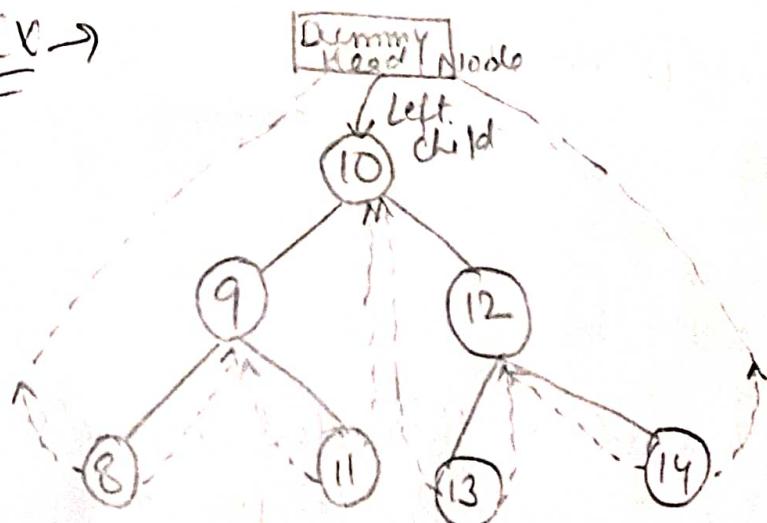


Inorder

1, 3, 5, 6, 7, 8, 9, 11, 13

+ Free Threads are called "Dangling Pointers"

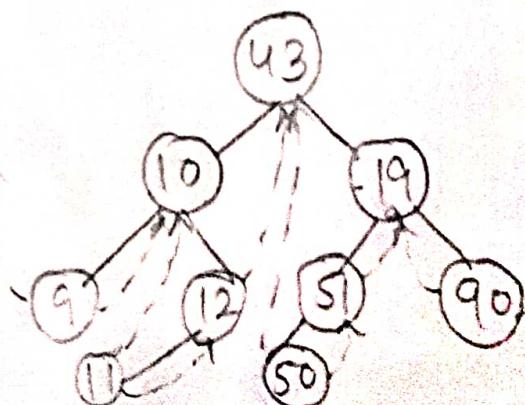
Ex →



Single Thread

Left Thread

Inorder → 8, 9, 11, 10, 13, 12, 14

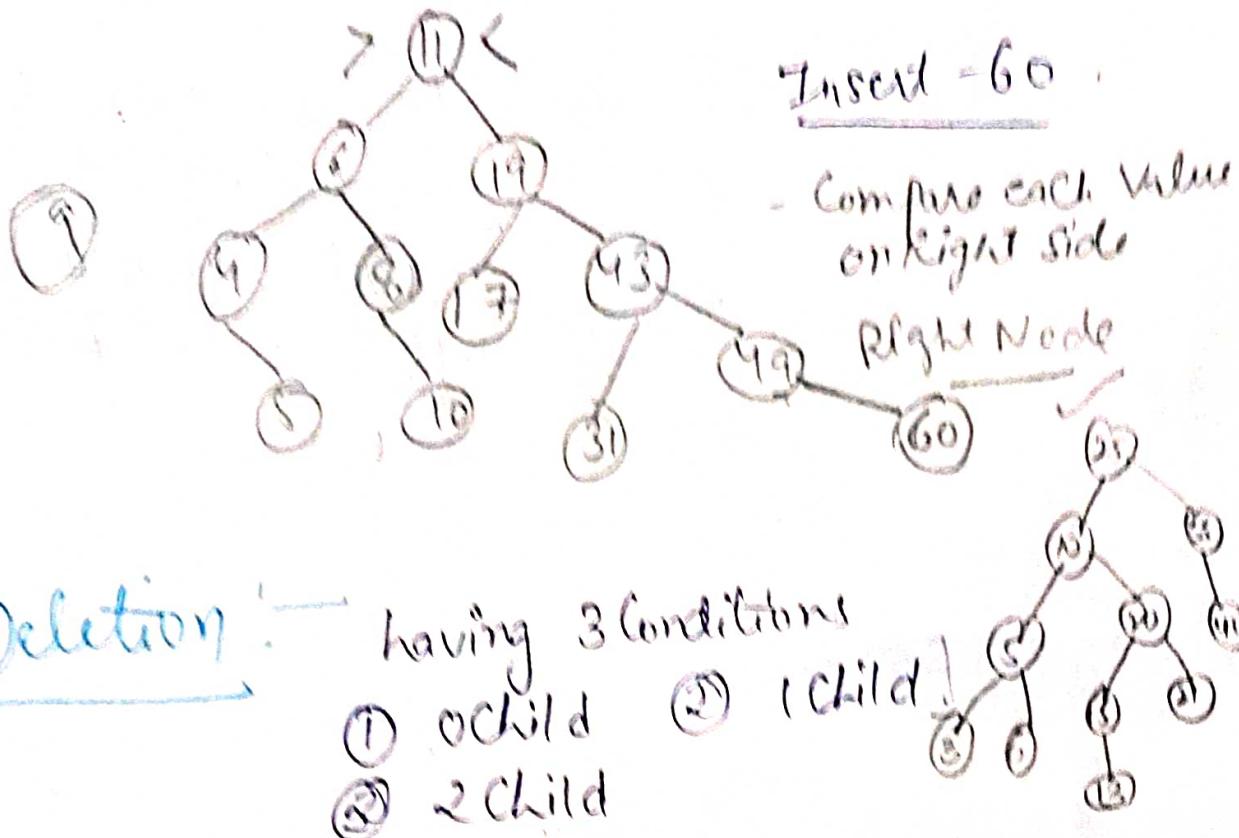


→ 9, 10, 11, 12, 43, 50, 51, 90

Operations on Binary Search Tree

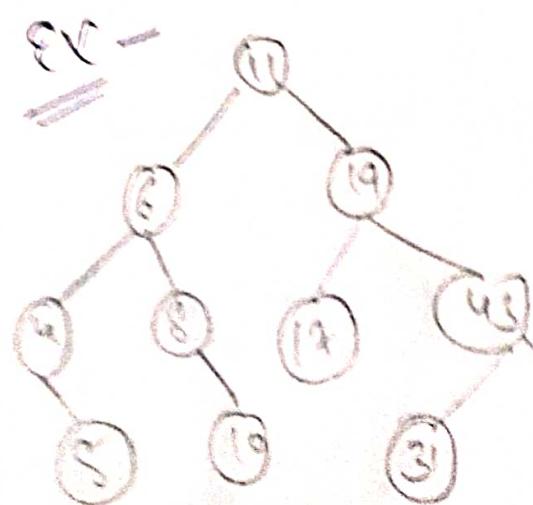
Insertion Deletion

① Insertion : — 11, 6, 8, 19, 4, 10, 5, 17, 43, 49, 31



② Deletion : — having 3 conditions

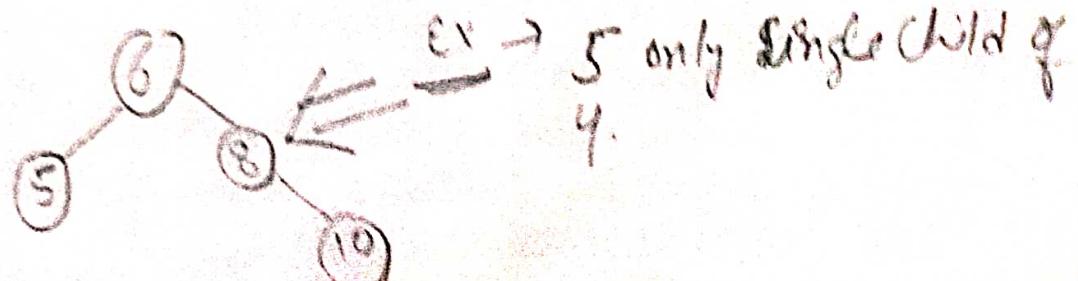
- ① 0 child
- ② 1 child
- ③ 2 child



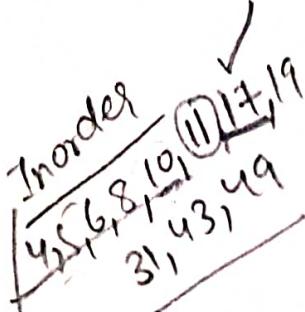
① 0 child : — delete the node having 0 child.

Ex — delete 31 because no child is there

② 1 child : — delete 1 child value.



③ 2 Child :- delete Node having 2 children but Having 2 Cases



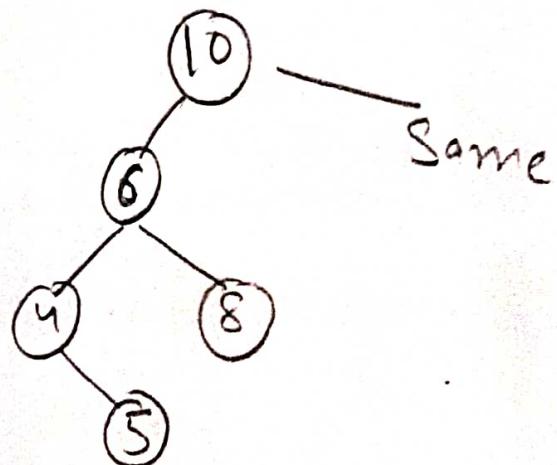
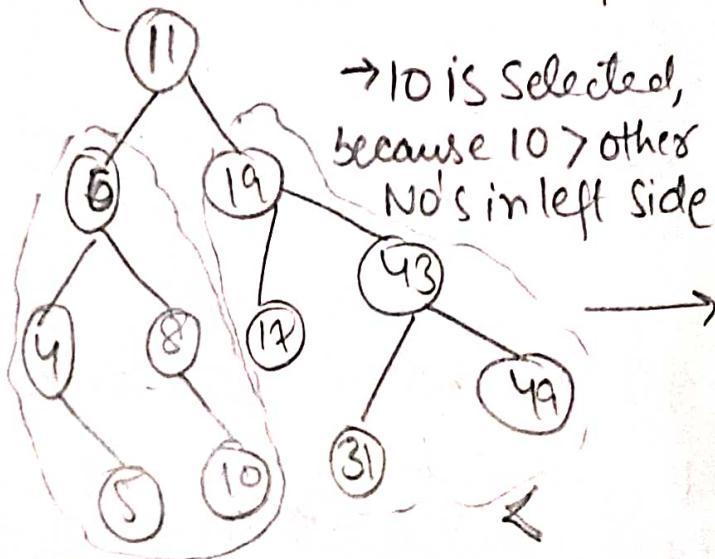
① Inorder Predecessor

② Inorder Successor

Inorder Predecessor :- for eg remove 11 having 2 children.

(left)

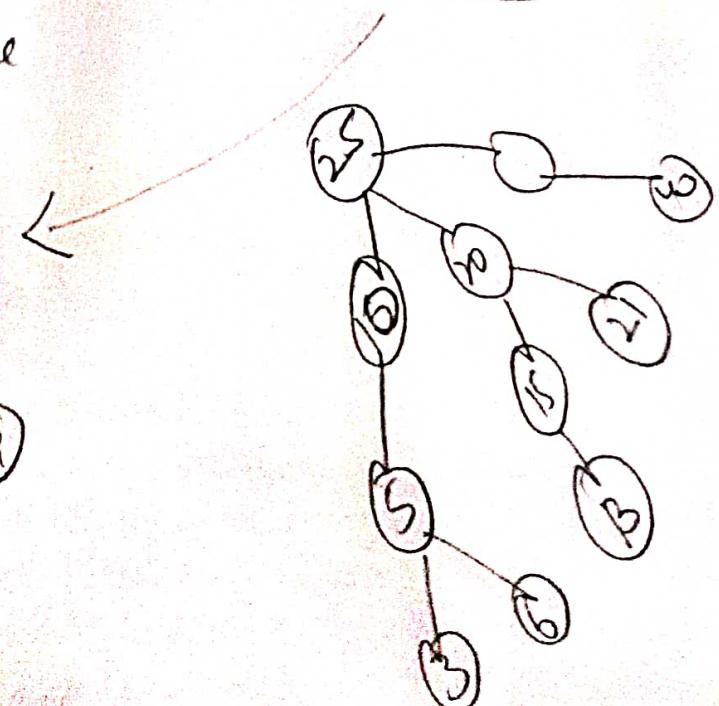
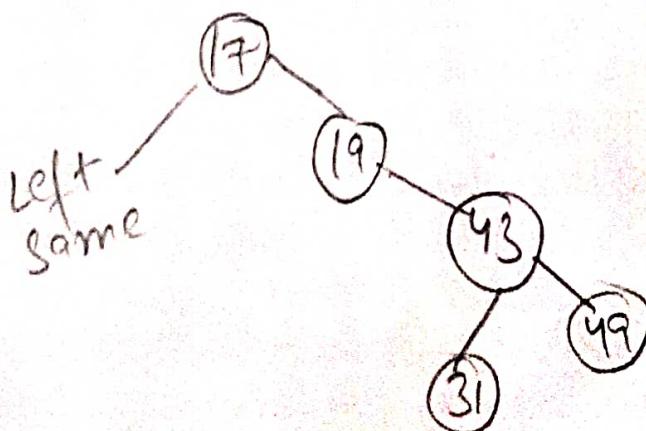
- So, Select one No. from left side to replace 11.



7

Inorder Successor (right)

- Select Min or L No. for Inorder Successor from Right Side



B-TREES

DATA STRUCTURE

order = 6 ORDER

- B-tree is a generalised ~~m~~^m way tree that can be widely used for sorted data. A B-tree of order 'm' can have at most $m-1$ keys & m children. One of the main reason of using B-tree is its capability to store large no. of keys in a single Node.

- ① Every Node in a B-tree contains at most m children

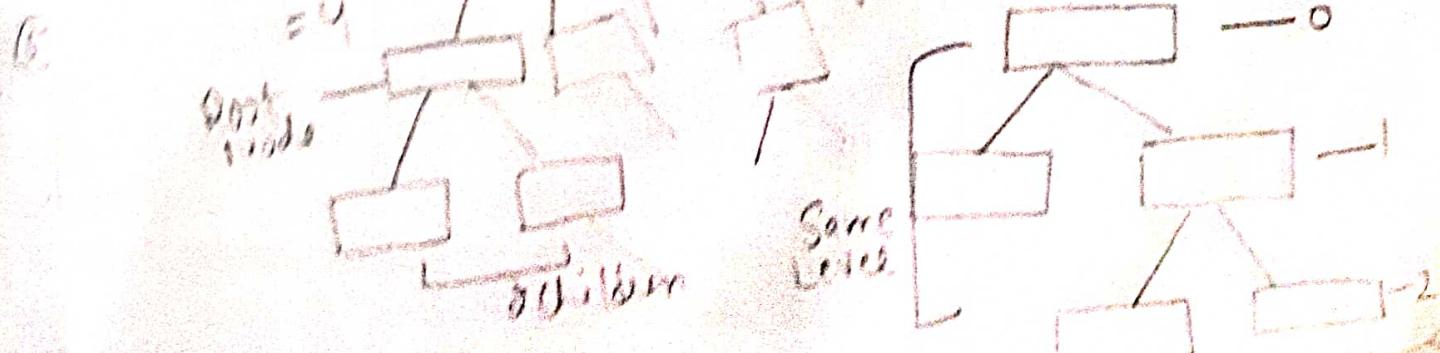
$$[m=5]$$

- ② Every node in a B-tree except the root node is a leaf node contains at least $m/2$ children.
 - ③ The last nodes must have at least 2 nodes.
 - ④ All leaf nodes must be at the same level.
- Note - It is not necessary that all nodes contains the same no. of children but, each node must have $m/2$ no. of nodes.

$$m = 5$$

$$\frac{m}{2} = \frac{5}{2} = 2.5$$

$\lceil m/2 \rceil = \lceil 2.5 \rceil = 3$ Keys ceiling value.



~~Keys~~ - $m-1$
~~s-1 = 4~~ ✓

Min Keys - Root Node - 1

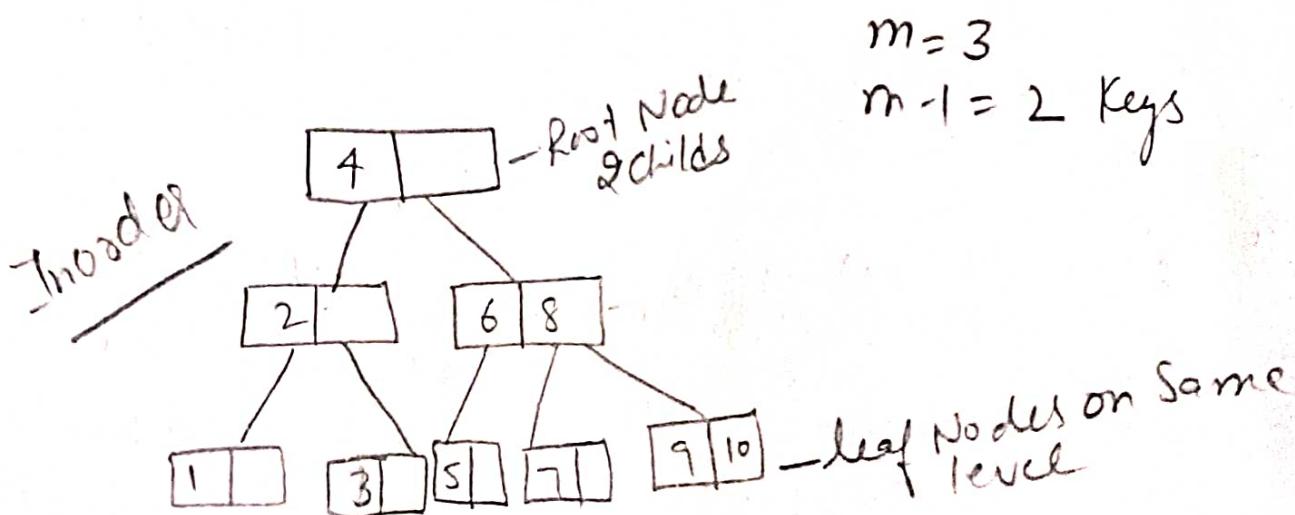
- all other Nodes = $\left[\frac{m}{2}\right] - 1$

$$\frac{5}{2} \text{ } \cancel{\text{= 2.5}} \text{ } \cancel{\text{3}}$$

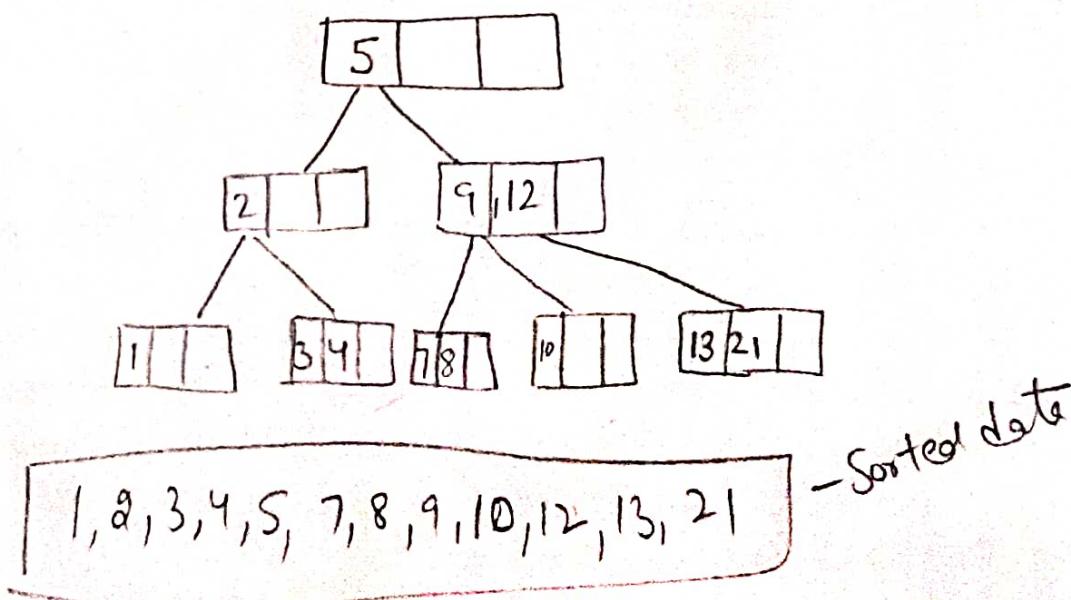
$$3-1 = 2$$

Ex → Order = 3

insert values from 1-10.



Ex → B tree for order = 4 ($m=4$)
 5, 3, 21, 9, 1, 13, 2, 7, 10, 12, 4, 8

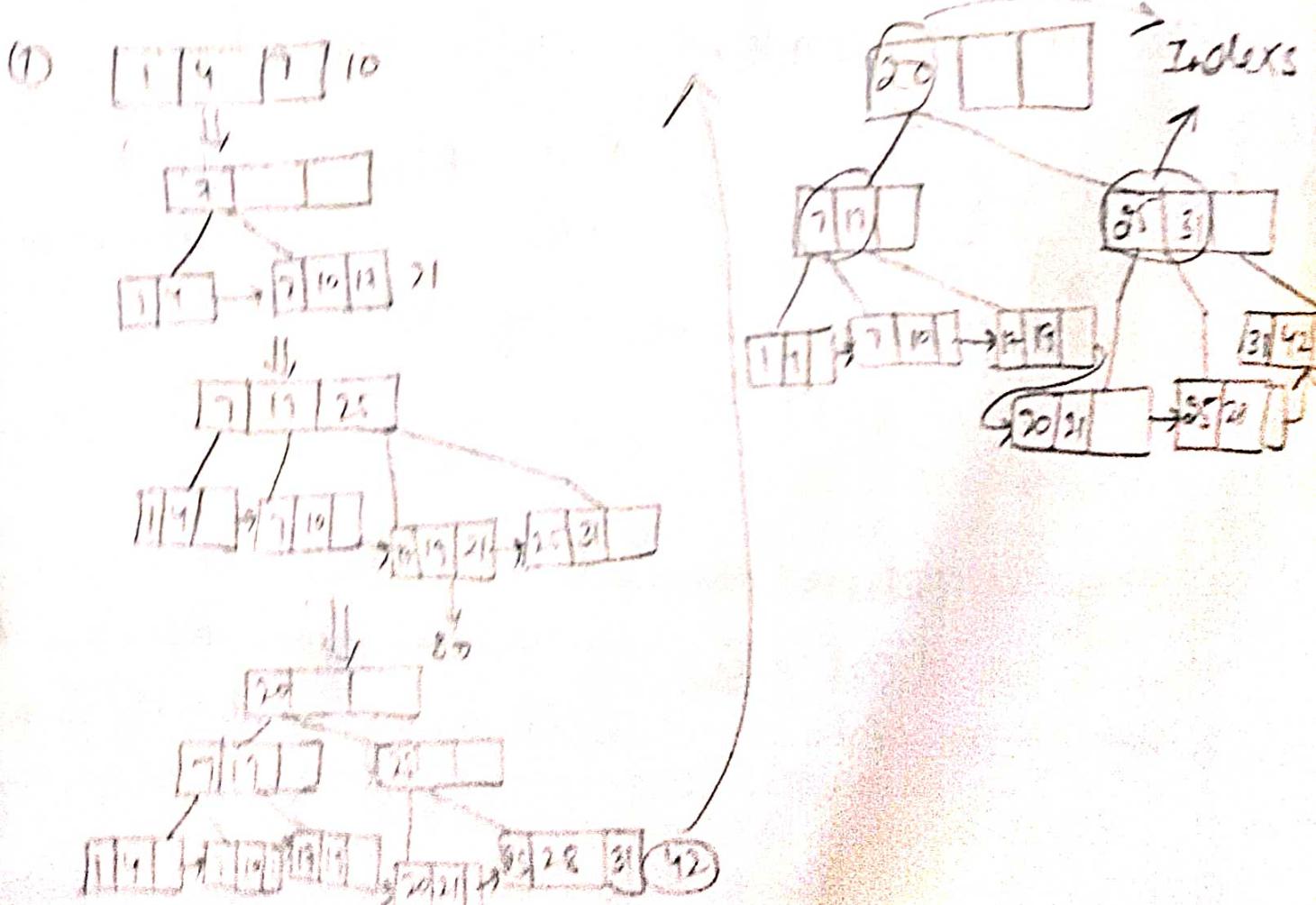


B+ Trees

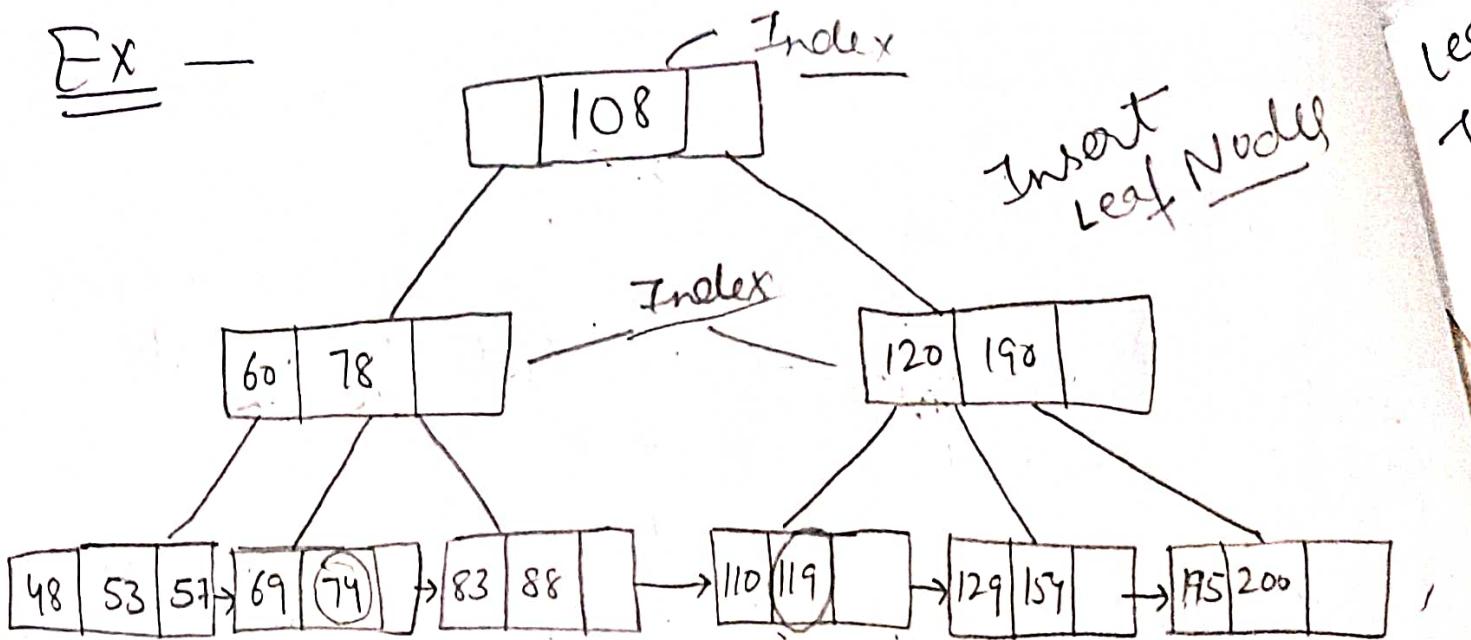
- It is an extension of B Tree.
- The leaf nodes of a B+ Tree are linked together in the form of single linked lists to make the search queries more efficient.
- It stores large amount of data.
- The internal nodes of B+ Trees are often called Index Nodes. It stores data only in leaf Nodes not in Root Node.

Ex - Order = 4 Keys = ①
 max. child = 4 = ③ Min Keys = ①
 min child = $\frac{m}{2} = 2$

1, 4, 7, 10, 13, 21, 31, 35, 19, 20, 28, 42 [Index does not repeat]



Ex -



Q) Difference b/w B & B+Trees

B Tree

- * Search Keys Can not be Repeatedly stored.
- * Data Can be stored in leaf Nodes as well as internal Nodes.
- * Searching for some data is a slower process since data can be found on internal Nodes as well as on the leaf Nodes.
- * Deletion of Internal Nodes are so Complicated & Time Consuming.

B+ Trees

- * Redundant Search Keys can be stored.
- * Data can only be stored on the leaf Nodes.
- * Searching is faster bcz data can only be found in leaf Nodes.
- * Deletion will never be a complexed process bcz element will always be deleted from the leaf Nodes.

Leaves can not be linked together

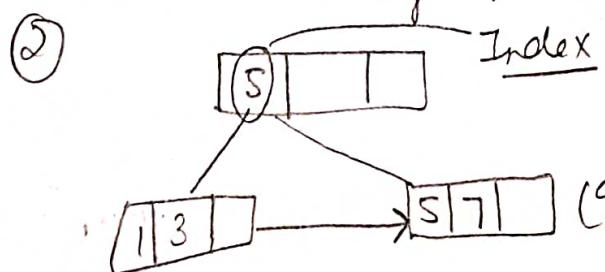
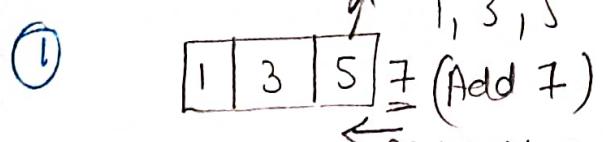
connected keys are the search operations more efficient ✓

B+ TREE - Insert

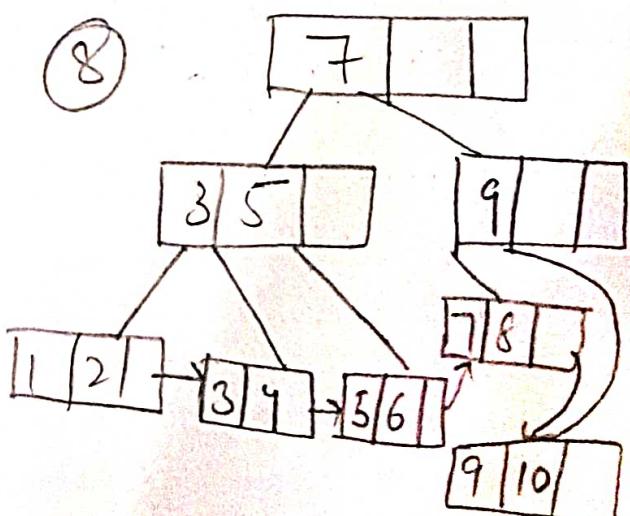
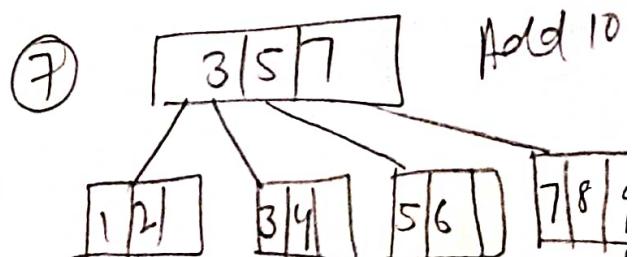
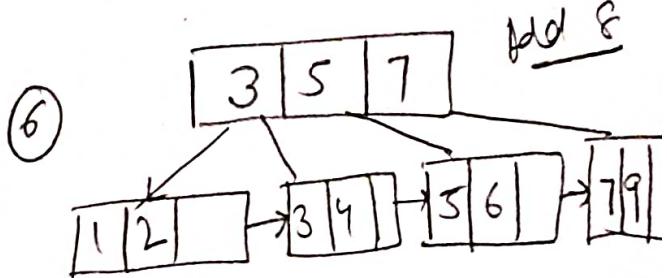
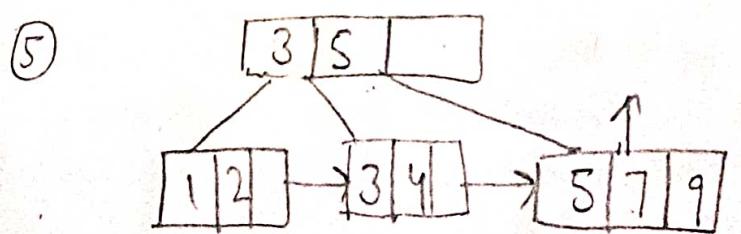
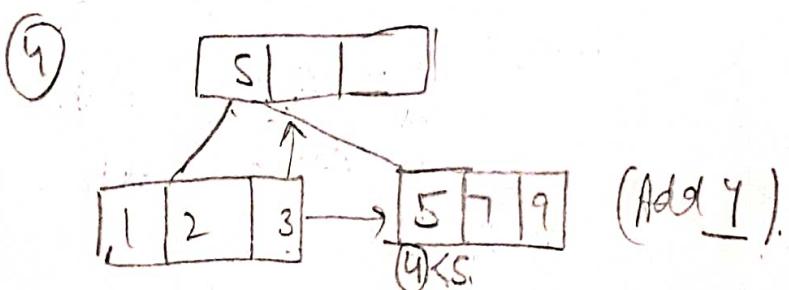
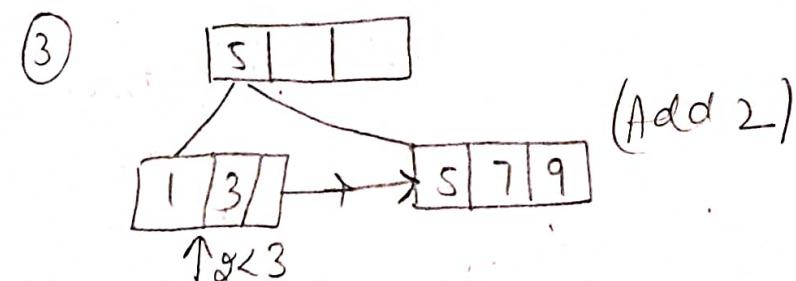
1, 3, 5, 7, 9, 2, 4, 6, 8, 10

order = 4

Keys = 3



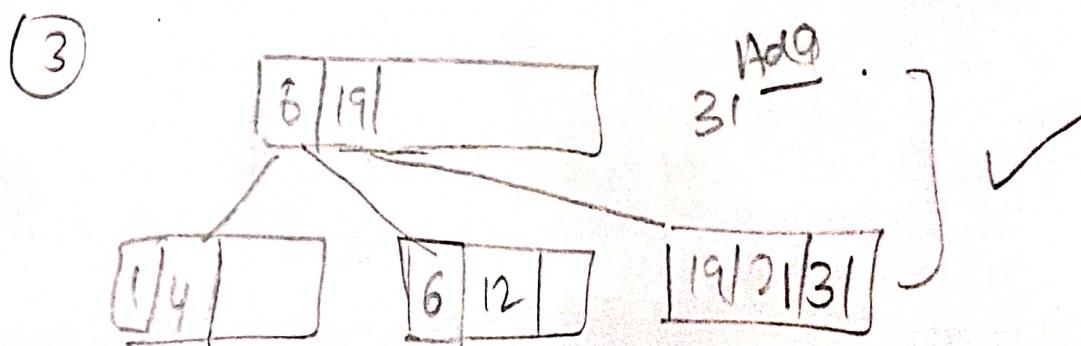
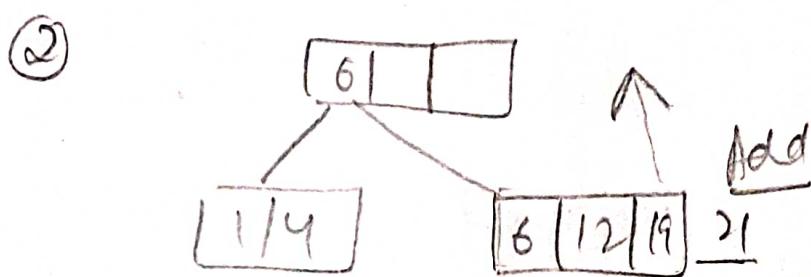
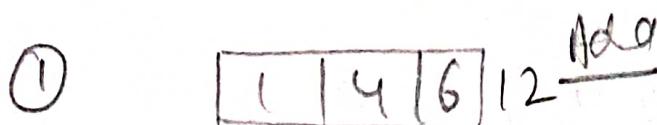
Add (9)



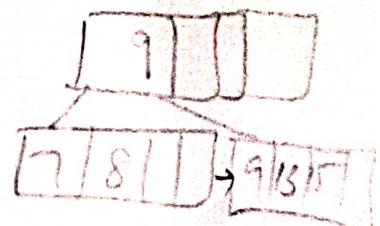
Add 6

Q. 1, 4, 6, 12, 19, 21, 31 \rightarrow B+Tree
 (m) Order - 4

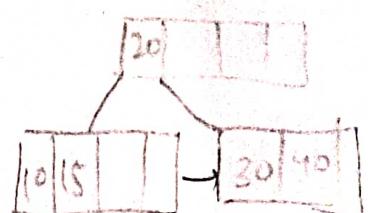
$$\text{Keys} = m - 1 = \textcircled{3}$$



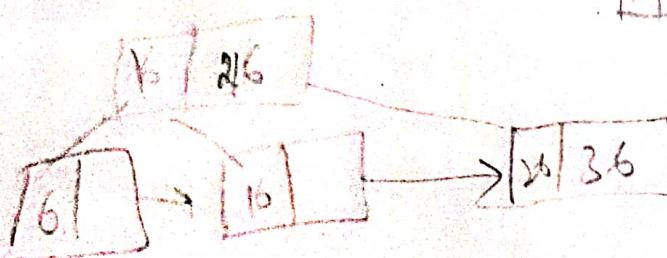
Q ① 7, 9, 13, 15, 8 order = 5



② 10, 20, 30, 40, 15 \rightarrow order = 5



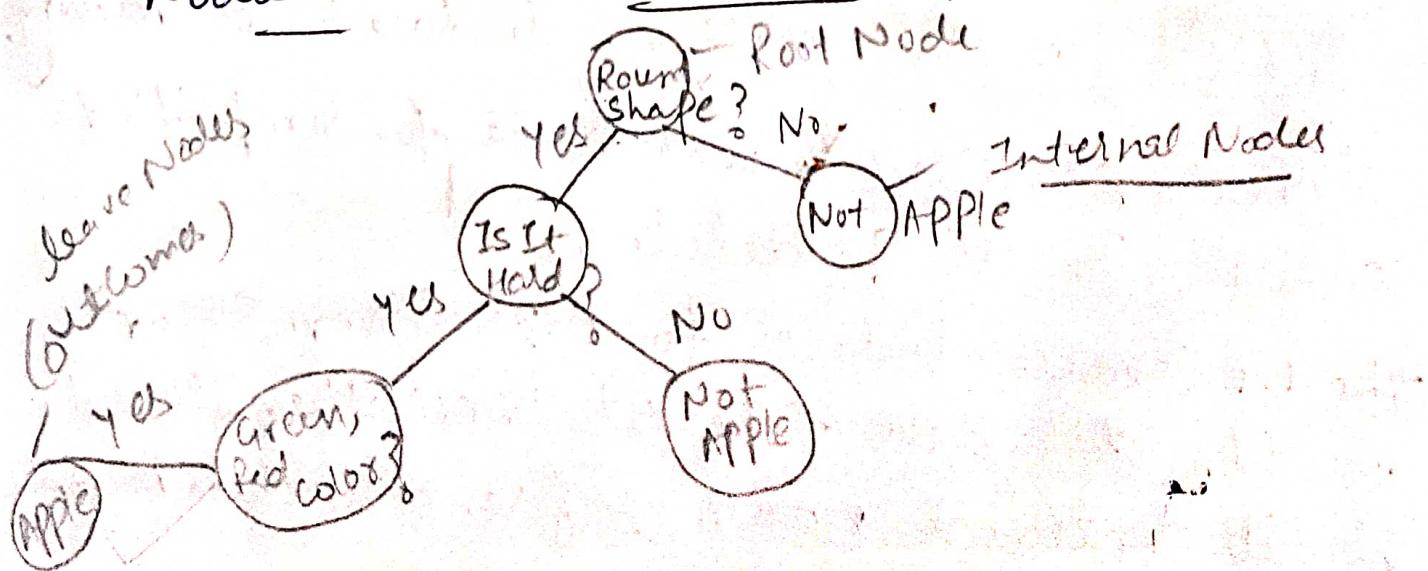
③ 6, 16, 26, 36, 46 order = 3



→ Applications Of Binary Trees:— Binary Trees are mainly used for searching & sorting as they provide a means to store data hierarchy! Some common operations that can be conducted on Binary Trees include insertion, deletion & traversal.

① Routing Tables:— The tree data structure will store the location of routers based on their IP addresses. Routers with similar addresses are grouped under a single subtree.

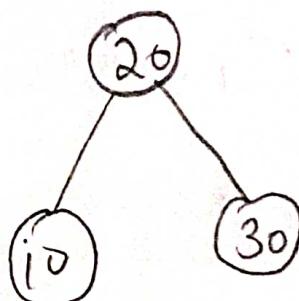
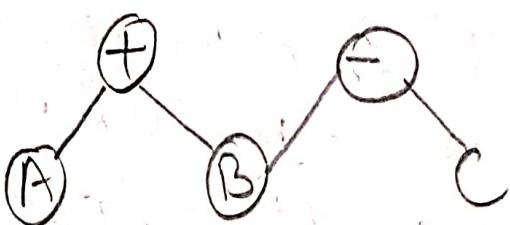
② Decision Trees:— It is used for classification purposes. The binary tree data structure is used here to emulate the decision making process. A decision tree usually begins with a Root Node. The internal Nodes are conditions or data set features. Branches are decision rules while the leaf Nodes are the outcomes of the decision.



③ Expression Evaluation :— Used in Mathematicsⁱⁿ
Expressions are statements with operators and this
Operands that evaluate a value. The leaves
of the BT are the Operands while the internal
Nodes are the operators.

$$A + B - C$$

Ex:-



Binary Search Tree

④ Sorting :— A BT is simply an ordered or sorted binary tree such that the value in the left child is $<$ than the value of root node and right child is $>$ than the root node.

To complete a sorting procedure, the items to be sorted are first inserted into a binary search tree.

⑤ Indices for database :— In databases indexing,

B⁺ Trees are used to sort data for simplified search, insert & delete.

The DB creates indices for each given record in the database. The B⁺ Trees then stored in its internal nodes, reference to data records

With the Actual data records in its leaf nodes.
This provide Sequential Access to data in the DB's.

- ⑥ Data Compression :- In data Compression, it is used to Compress data by using fewer bits. Or all about encoding the data.
- Encoding is related to occurrence of the characters, frequently occurring characters will have a shorter path as compared to less occurring characters. This is done to reduce the No. of bits for frequent characters & ensure max. data compression.