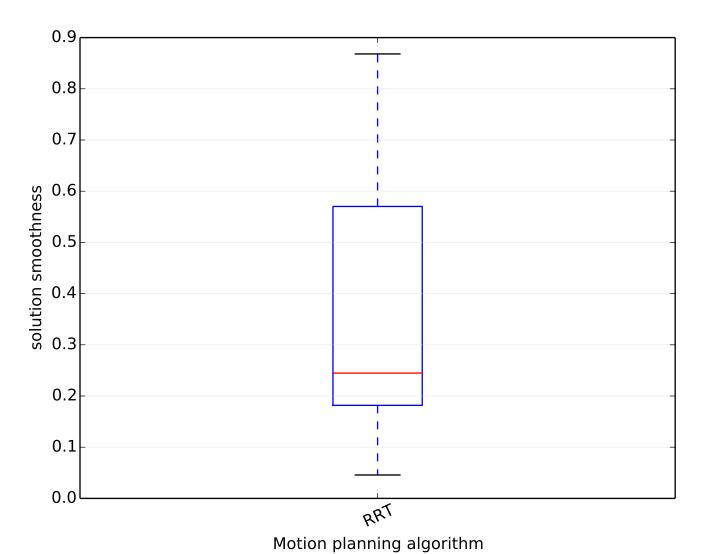
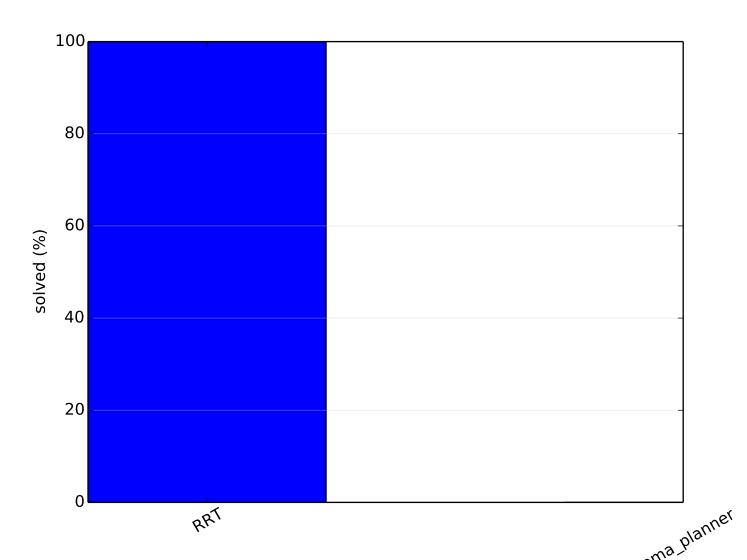
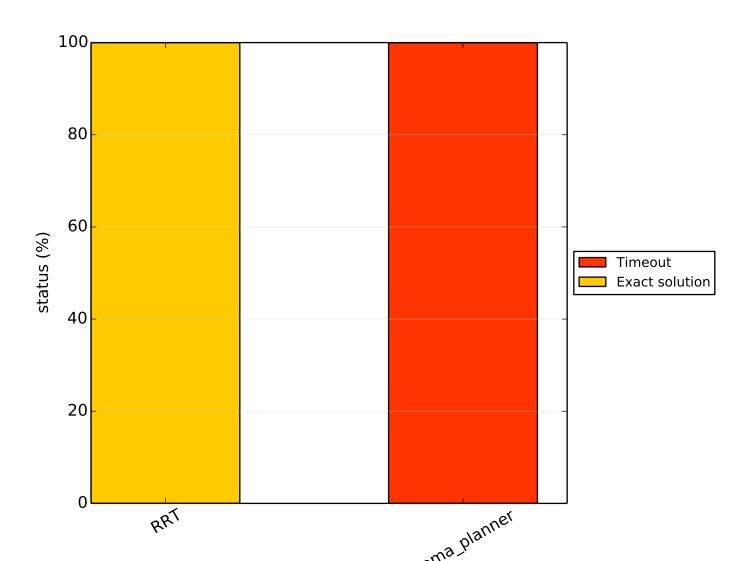
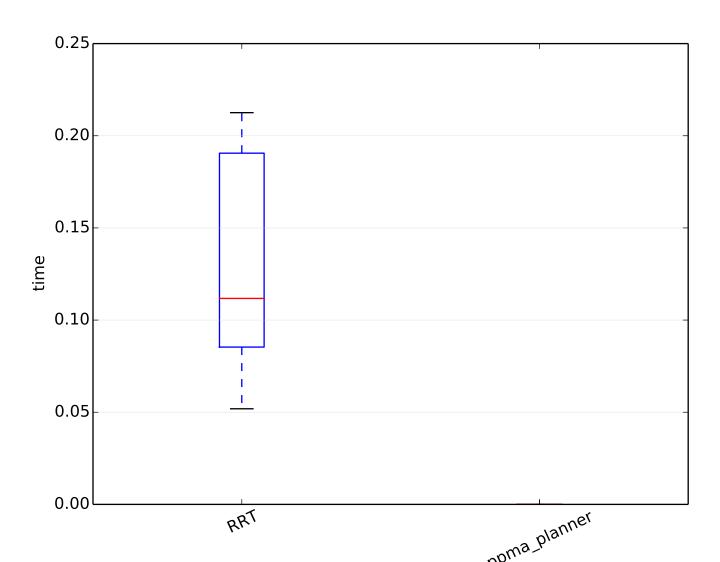


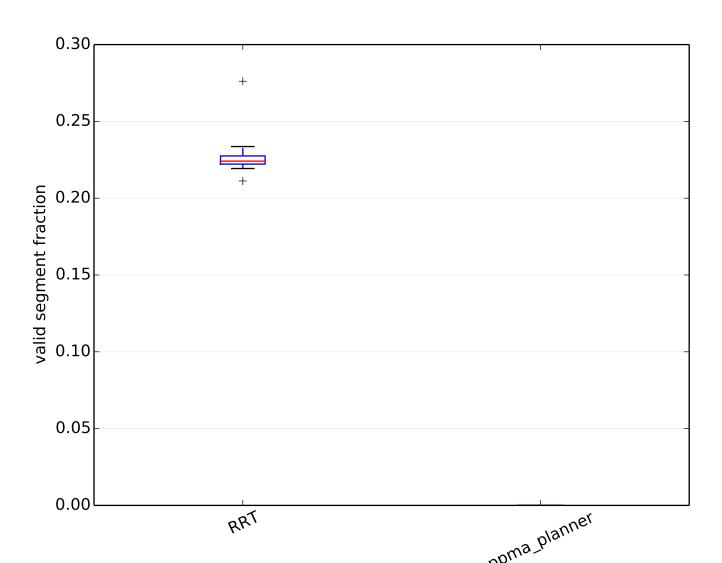
Motion planning algorithm











Experiment "Passage"

Number of averaged runs: 10

Time limit per run: 20 seconds

Memory limit per run: 10000 MB