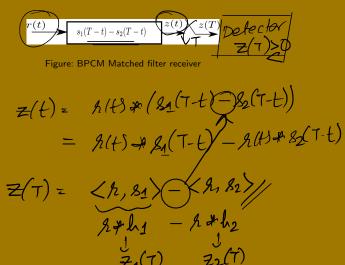
#### CT303 Lecture 17: 19 October 2020

- Lecture 16 review:
- ▶ Binary PCM Matched filter to minimize  $P_B$  is  $h(t) \neq s_1(T-t) s_2(T-t)$ .

  ▶ With this,  $P_B = Q\left(\frac{1}{2}\sqrt{SNR}\right) = Q\left(\sqrt{\frac{E_d}{2N_0}}\right)$ , where  $E_d$  is the energy of the difference between the two symbol waveforms:  $s_1 - s_2$ .

#### Equivalent receiver for Binary PCM



Equivalent receiver for Binary PCM How well a matches (correlates) with Sa thes with &2

• Simplifying the energy of difference between signals:

$$E_{d} = \int_{0}^{T} (s_{1}(t) - s_{2}(t))^{2} dt$$

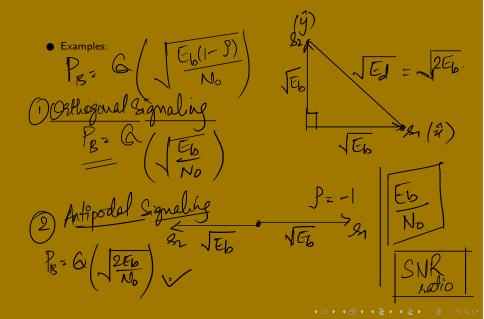
$$= \int_{0}^{T} s_{1}^{2}(t) dt + \int_{0}^{T} s_{2}^{2}(t) dt - 2 \int_{0}^{T} s_{1}(t)s_{2}(t) dt$$

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$$\text{Let } \rho = \frac{\int_{0}^{T} s_{1}(t)s_{2}(t) dt}{\sqrt{E_{s_{1}}E_{s_{2}}}} = \frac{(|s_{1}||s_{2}|| - |s_{2}||s_{2}||}{(|s_{1}||s_{2}||s_{2}|| - |s_{2}||s_{2}||} = \cos(\theta_{s_{1},s_{2}})$$

$$E_{d} = ||s_{1}||^{2} + ||s_{2}||^{2} - 2\rho||s_{1}|| + ||s_{2}|| - 2\rho||s_{1}|| + ||s_{2}||s_{2}||$$

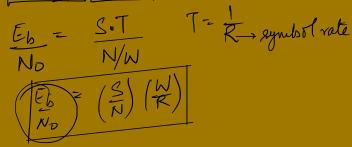
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# $\frac{E_b}{N_0}$ - Bit energy to Noise PSD ratio

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 - Bit energy to Noise PSD ratio

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- ▶ Then,  $E_b = S \cdot T$ , and  $N = N_0 \cdot W$ .
- $ightharpoonup rac{E_b}{N_0} = rac{S \cdot T}{N/W} = \left(rac{S}{N}
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- $ightharpoonup |E_b/N_0|$  is a more suitable parameter for DCS.

O All eymbod wif used for DC are energy signals

2 8-ary PCM signalling > 21, ... (38) 3 bits

per symbol

Pa the same

H the same

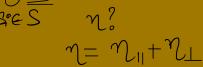
Eb To Value 8 ary signaling Eb = Es To Eb = Es To

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- Receiver architecture: Use M matched filters  $\{\underline{h_1,\ldots,h_M}\}$  defined as  $\underline{h_i(t)} = s_i(T-t)$ . Denote the sampled output of each matched filter by  $\overline{z_i}, i=1,\ldots,M$ .

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Assume that MES.

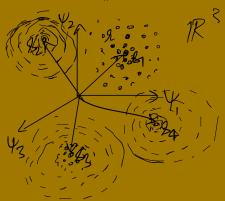
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- ▶ Since matched filters can be seen as projectors to  $\{s_1, \ldots, s_M\}$ , the perpendicular component  $\eta_{\perp}$  will be filtered out by the matched filters.
- $\blacktriangleright$  Hence the received signal r can be assumed to belong to S.

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- Let  $P = \{v_1, \dots, v_N\}$  denote an error of P. Thus  $S_i = \sum_{k=1}^N \eta_k \Psi_k$ .

  Let  $P = \sum_{i=1}^N \bar{r}_i \Psi_i, \bar{r} = [\bar{r}_1, \dots, \bar{r}_N]^T$ , and  $\eta_{||} = \sum_{k=1}^N \eta_k \Psi_k$ .  $\eta_{||} \sim \mathcal{N}(0, \sigma I)$ .

  Likelihood  $p(r|s_i) = \mathcal{N}(\widehat{a_i})$ ,  $i = 1, \dots, M$ , i.e.,

$$\begin{array}{l} \blacktriangleright \ \, \eta_{||} \sim \mathcal{N}(0,\sigma I). \\ \blacktriangleright \ \, \text{Likelihood} \, \, p(r|s_i) = \underbrace{\mathcal{N}(\widehat{a_i}|\sigma I)}_{}, i = 1,\ldots,M, \text{ i.e.,} \end{array}$$

$$p(r|s_i) = \frac{1}{(2\pi)^{\frac{N}{2}}\sigma} \exp\left(-\frac{1}{2}(\bar{r} - a_i)^T \Sigma^{-1}(\bar{r} - a_i)\right)$$

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$$\frac{\left(\ln(p(r|s_{i})p(s_{i}))\right) \propto 2\sigma^{2}\ln p(s_{i}) - ||\bar{r} - a_{i}||^{2}}{\propto 2\sigma^{2}\ln p(s_{i}) - (||\bar{r}||^{2} + ||a_{i}||^{2} - 2\bar{r}^{T}a_{i})} \times 2\sigma^{2}\ln p(s_{i}) - (||\bar{r}||^{2} + ||a_{i}||^{2} - 2\bar{r}^{T}a_{i})}{\sim 2\sigma^{2}\ln p(s_{i}) - ||a_{i}||^{2} + 2\bar{r}^{T}a_{i}}$$

$$\frac{\langle x_{i}^{2} + x_{i}^{2} - x_{i}^{2} \rangle}{\langle x_{i}^{2} + x_{i}^{2} - x_{i}^{2} \rangle} \times x_{i}^{2} + \bar{r}^{T}a_{i}$$

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$$\begin{split} \rho(r|s_i) = & \frac{1}{(2\pi)^{\frac{N}{2}}\sigma} \exp\left(-\frac{1}{2}(\bar{r} - a_i)^T \Sigma^{-1}(\bar{r} - a_i)\right) \\ = & \frac{1}{(2\pi)^{\frac{N}{2}}\sigma} \exp\left(-\frac{1}{2}\frac{||\bar{r} - a_1||^2}{\sigma^2}\right) \end{split}$$

► In 
$$p(r|s_i) = k - \frac{||\bar{r} - a_i||^2}{2\sigma^2}$$

► MAP:

$$\begin{aligned} & ln(p(r|s_{i})p(s_{i})) \propto & 2\sigma^{2} ln \ p(s_{i}) - ||\bar{r} - a_{i}||^{2} \\ & \propto & 2\sigma^{2} \ ln \ p(s_{i}) - (||\bar{r}||^{2} + ||a_{i}||^{2} - 2\bar{r}^{T} a_{i}) \\ & \propto & 2\sigma^{2} \ ln \ p(s_{i}) - ||a_{i}||^{2} + 2\bar{r}^{T} a_{i} \\ & \propto & k_{i} + 2\bar{r}^{T} a_{i} \simeq k_{i} + \bar{r}^{T} a_{i} \end{aligned}$$

▶ Decision:  $s_k$  was transmitted if  $k_k + \bar{r}^T a_k > k_i + \bar{r}^T a_i, \forall i \neq k$ .

#### MAP estimation

lacktriangledown M matched filters with impulse responses  $\{s_1(T-t),\ldots,s_M(T-t)\}$ 



#### MAP estimation

- M matched filters with impulse responses  $\{s_1(T-t), \ldots, s_M(T-t)\}$
- ▶ The output of the matched filter  $h_i(t) = s_i(T t)$  is

Ris Arch using M matched filters for M-ary PCM.