

Lecture 13: 5 October 2020

- Lecture 12 review
- ▶ Formatting: Sampling and Quantization
- ▶ Baseband modulation
- ▶ Binary PCM waveforms
- ▶ Sources of corruption: Sampling jitter, Quantization error, Channel noise (AWGN), Channel distortion - ISI.


Lab-4

NRZ-L without delay \rightarrow WSS SP } Analytically
NRZ-L with delay \rightarrow WSS SP } derive R_x

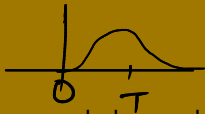
$$R_{xx}(t_1, t_2) \quad x(t) = \sum_{k=-\infty}^{\infty} V_k P(t - kT)$$

$+V$
 $-V$

$P(t)$ pulse duration T



Bandwidth efficiency



- As demonstrated, if bits are encoded as pulses, this will lead to ISI, unless the channel BW is high enough.
- How many symbols/sec can we accommodate in a given bandwidth?

B.W: W How much R_s can it support?

$$\eta_B \left[\frac{R_s}{W} \right] \rightarrow \text{Symbol/sec/Hz}$$

↳ Bandwidth efficiency

↳ $\eta_B < 1$ not good.

Binary PCM scheme with maximum η_B

- Consider a (ideal, noiseless) channel with BW f_0 Hz.
- Note the Fourier transform pair:

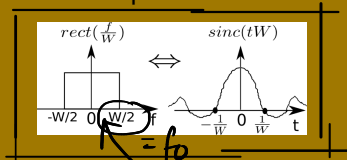
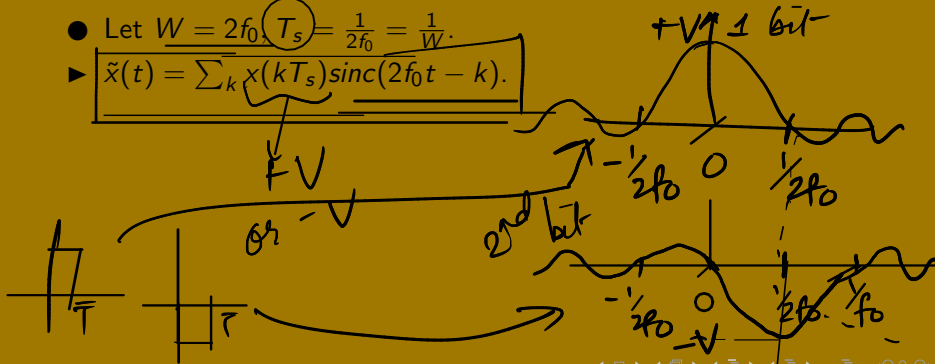


Figure: Fourier Transform pair

- Let $W = 2f_0$, $T_s = \frac{1}{2f_0} = \frac{1}{W}$.

► $\tilde{x}(t) = \sum_k x(kT_s) \text{sinc}(2f_0 t - k).$

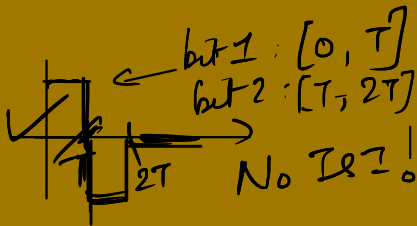




Is ISI present?
(With sinc waveforms)
 $(-\infty, \infty)$.

Yes, there is ISI!!

There is no ISI every T seconds //



➤ Note that $\text{sinc}(2f_0 n T_s - k) = 0, \forall n \neq k$.

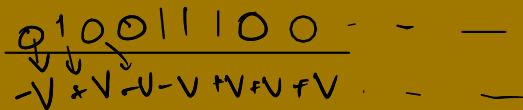
➤ Introduces ISI, but zero ISI at decision making instants
 $kT_s, k \in \mathbb{Z}$.

▶ Thus $2f_0$ symbols/sec can be transmitted over a channel with BW f_0 Hz, without distortion

(assuming no noise)

In practice generating sinc wf is not possible.

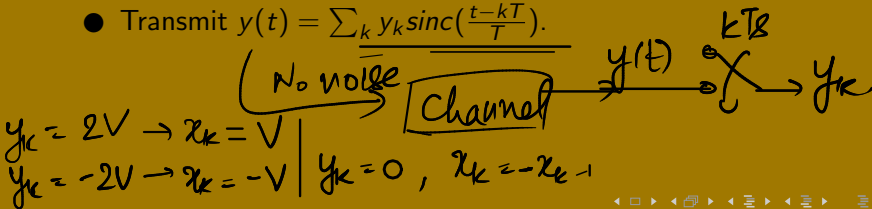
Duobinary encoding



- Let $\{x_k\}$ be a sequence of bi-polar amplitudes assigned to bits, each separated by T sec.
- Let $y_k = x_k + x_{k-1}$, with a fixed x_{-1} .

$$\underline{\underline{y_k = \begin{cases} \underline{2V}, & \text{if } x_k = x_{k-1} = V \\ 0, & \text{if } x_k = V, x_{k-1} = -V \\ \underline{-2V}, & \text{if } x_k = x_{k-1} = -V \end{cases}}}$$

- Transmit $y(t) = \sum_k y_k \text{sinc}(\frac{t-kT}{T})$.



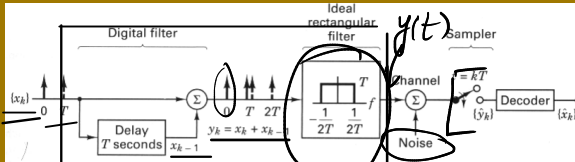


Figure: Duobinary encoding block diagram. Image Source: Sklar.

system.

SILPF

● Decoding:

$$\begin{aligned} \hat{x}_k &= V, \text{ if } y_k = 2V \\ \hat{x}_k &= -V, \text{ if } y_k = -2V \\ \hat{x}_k &= \overline{\hat{x}_{k-1}}, \text{ if } y_k = 0 \end{aligned}$$

Realizing Duobinary signaling

- $y_k = x_k + x_{k-1} \rightarrow \underline{H_1(f) = 1 + \exp(-j2\pi fT)}, \underline{h_1(t) = \delta(t) + \delta(t - T)}.$
- ▶ $y_k \rightarrow \sum_k y_k \text{sinc}(Tt - k) \Rightarrow \underline{H_2(f) = T \text{rect}(fT)}, \underline{h_2(t) = \text{sinc}(\frac{t}{T})}.$ *ILPF*
- ▶ Thus, the duobinary system is

$$\underline{H(f) = H_1(f)H_2(f) = T(1 + \exp(-j2\pi fT))\text{rect}(fT)},$$

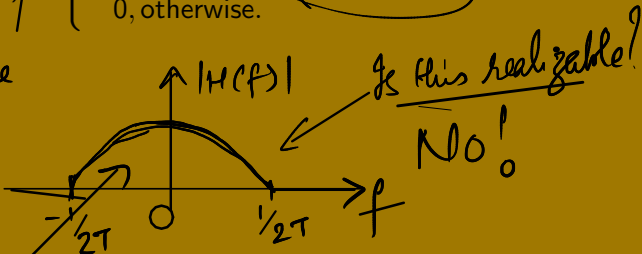
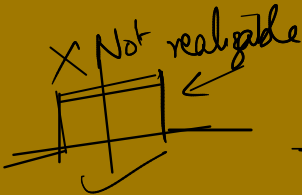
$$\underline{h(t) = \text{sinc}\left(\frac{t}{T}\right) + \text{sinc}\left(\frac{t-T}{T}\right)}$$

$$H(f) = T e^{-j\pi fT} \underbrace{(e^{j\pi fT} + e^{-j\pi fT})}_{2\cos(\pi fT)} \text{rect}(fT)$$

► Simplifying,

$$\text{rect}(t/T)$$

$$|H(f)| = \begin{cases} 2T \cos(\pi f T), & \frac{1}{2T} \leq f \leq \frac{1}{2T} \\ 0, & \text{otherwise.} \end{cases}$$



► Is this free lunch?

Better approximation is possible.

