

def: it is a square matoix which, when multiplied with their transpose matoix results in an identity matoix.

JA.AT=I

0 1 2x2

$$A = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 2xx \\ 0 & x & 0 \end{pmatrix}$$

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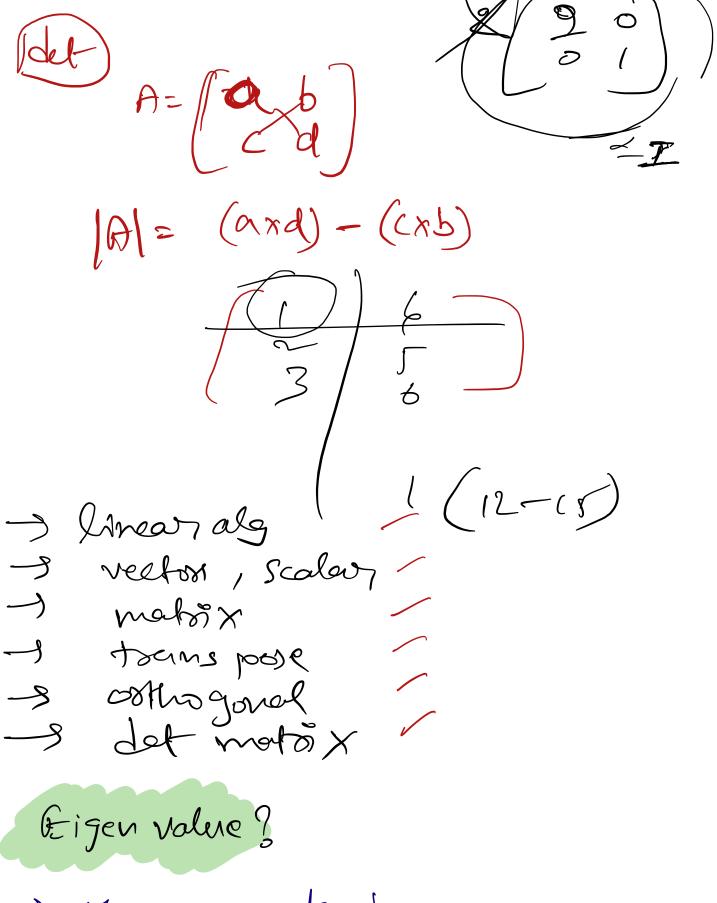
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These are also known as

charenteristic roots of scalars

associated with the system of

linear equation ...-- $A = \begin{pmatrix} 0 & -2 \\ 3 & 4 \end{pmatrix} \qquad \text{Lev}$  $\frac{1}{|A-\lambda I|=0}$   $E\cdot V$  $\begin{pmatrix} 0 & -2 \\ 3 & 4 \end{pmatrix} - \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$  $= \left| \begin{array}{cc} -\lambda & -2 \\ 0 & 4-\lambda \end{array} \right|$  $-\lambda \left(4-\lambda\right)-\left(-2\right)\left(0\right)$ ~4x=0 -4x + x = 0 2(x-6) = 0 (08) 6

for the given notion, there are

two eigen voleig D) and => how many (EV) does a lexe 601. 2 eigen values Rigen vector: vector sepresentation Il e. Volues  $A = \begin{pmatrix} 1 & 4 \\ -4 & -4 \end{pmatrix}$ (1-x) (-2-x) - 6 (-6) = 0  $/\lambda = -3/-3$ 

$$A \times = -3 \times \text{ woth}$$

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$$A - \lambda I) \times = 0$$

$$\begin{pmatrix} -4 & -4 \\ -4 & -4 \end{pmatrix} + \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$4 \times + 4y = 0 \quad (8) \times + 4y = 0$$

$$k + 4y = 0 \quad (8) \times + 4y = 0$$

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## Eigen vector for motoix A

=) what do Evaluer and Evectors tell us?

An eigen value is a number that tells us how much variance exist in the data in that direction.

E-vector is a number that tells us how spread of the data.

Transformation matrix &

If it is used to toams from one vector into another vector by the process of matrix multiplication.

S. Find the new vettor formed for the vector sit tein with the help of the transformation motor

