# CV Assignemnt 4 Image Segmentation with CNN

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**Scope:** Implement a CNN which takes images with a single object in them and classifies them.

The implementation is done in 2 files → cnn1.py, cnn2.py
Training and storing the model, Model evaluation is done in cnn1.py

Testing the cifar dataset i.e, its test-data batch, (predicting and printing all the class of each of the 10,000 images in the cifar dataset) is done in cnn2.py

Please note  $\rightarrow$  3 images from the internet, out of cifar dataset are also tested and classes are predicted.

Please find these images also in the above link. I.e.

https://drive.google.com/open?id=13MIUwwEp8Fz4Xbirij-jYSfegtp4T\_aD

## Implementation details:

Basic Structure of the CNN built:

Layers	<b>Layers Parameter</b>	<b>Activation Function</b>
Conv2D	32,size=(3,3)	Relu
Conv2D	32,size=(3,3)	Relu
Conv2D	32,size=(3,3)	Relu
Maxpooling2D	Size=(2,2)	
Dropout	0.25	
Conv2D	64,size=(3,3)	Relu
Conv2D	64,size=(3,3)	Relu
Conv2D	64,size=(3,3)	Relu
Maxpooling2D	Size=(2,2)	
Dropout	0.25	
Dense	512	Relu
Dropout	0.5	110
Dense	10	Softmax

<sup>\*</sup>The parameters/weights after training have been stored in a file named

**<sup>&#</sup>x27;keras\_cifar10\_trained\_model.h5'**. It is uploaded on Google Drive. Please find it in this link. <a href="https://drive.google.com/open?id=13MlUwwEp8Fz4Xbirij-jYSfegtp4T\_aD">https://drive.google.com/open?id=13MlUwwEp8Fz4Xbirij-jYSfegtp4T\_aD</a>

<sup>\*</sup>Please find other results also in the above link.

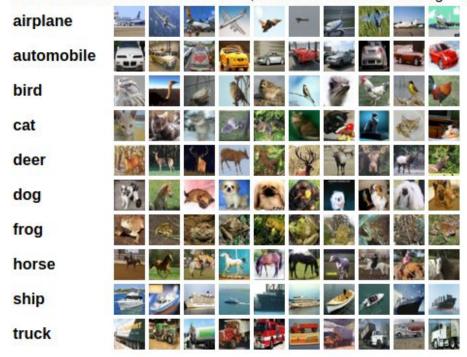
<sup>\*</sup> All the training has been done on my own laptop, using python .py and .ipynb. No GPU is used.

The DL module used: Tensor flow and Keras

Dataset: cifar-10-python

Number of classes in the dataset: 10

Here are the classes in the dataset, as well as 10 random images from each:



The CIFAR-10 dataset consists of 60000 32x32 color images in 10 classes, with 6000 images per class. There are 50000 training images and 10000 test images.

The dataset is divided into five training batches and one test batch, each with 10000 images. The test batch contains exactly 1000 randomly-selected images from each class. The training batches contain the remaining images in random order, but some training batches may contain more images from one class than another. Between them, the training batches contain exactly 5000 images from each class.

## Visualizing the dataset:

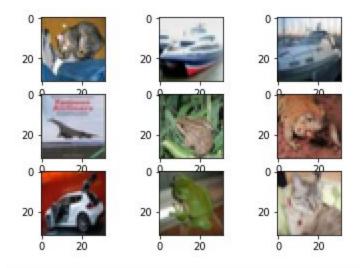
The following is the code that downloads and loads the cifar dataset in anaconda/dist-packages. It basically structures the data into TEST and TRAIN sets.

```
# load dataset
(trainX, trainy), (testX, testy) = cifar10.load_data()
```

print('Train: X=%s, y=%s' % (trainX.shape, trainy.shape))
print('Test: X=%s, y=%s' % (testX.shape, testy.shape))

```
#-----data visualisation-----
# plot first few images of the training dataset
for i in range(9):
      pyplot.subplot(330 + 1 + i)
      pyplot.imshow(trainX[i])
pyplot.show()
# plot first few images of the testing dataset
for i in range(9):
      pyplot.subplot(330 + 1 + i)
      pyplot.imshow(testX[i])
pyplot.show()
Results (Screenshots):
Train Images:
                 pyplot.imshow(testX[i])
        23 # show the figure
        24 pyplot.show()
       Train: X=(50000, 32, 32, 3), y=(50000, 1)
        Test: X=(10000, 32, 32, 3), y=(10000, 1)
                          20
          0
                          0 4
                          20
                                           20
         20
          0
                          0
                          20
         20
```

# Test Images:



1

# Parameters used and changed:

Batches = 32 to 4 varied(changed)

Optimizer used: RMSProp(changed)

Loss: categorical crossentropy(changed)

Epochs = 100 to 5 varied(changed)

**Data Augmentation:** Implemented. If data augmentation is enabled, the model will work in real-time. Instead of aiming for RCNN, RPN or multi-object classification, etc, I have tried to make the model work in real-time.

## **Code Explanation:**

The following code in the notebook is where the model is being trained **cnn1.py** 

from \_\_future\_\_ import print\_function
import keras
from keras.datasets import cifar10
from keras.preprocessing.image import ImageDataGenerator
from keras.models import Sequential
from keras.layers import Dense, Dropout, Activation, Flatten
from keras.layers import Conv2D, MaxPooling2D
import os

# Parameters - These are changed many times to get best performance

batch\_size = 4 num classes = 10

```
epochs = 14
data_augmentation = False
num_predictions = 20
save_dir = os.path.join(os.getcwd(), 'saved_models')
model_name = 'keras_cifar10_trained_model_1.h5'
# train test split
(x_train, y_train), (x_test, y_test) = cifar10.load_data()
print('x_train shape:', x_train.shape)
print(x_train.shape[0], 'train samples')
print(x_test.shape[0], 'test samples')
Make data amenable to keras library
# Convert class vectors to binary class matrices.
y_train = keras.utils.to_categorical(y_train, num_classes)
y_test = keras.utils.to_categorical(y_test, num_classes)
Design of the Neural Network
model = Sequential()
model.add(Conv2D(32, (3, 3), padding='same',
          input_shape=x_train.shape[1:]))
model.add(Activation('relu'))
model.add(Conv2D(32, (3, 3)))
model.add(Activation('relu'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))
model.add(Conv2D(64, (3, 3), padding='same'))
model.add(Activation('relu'))
model.add(Conv2D(64, (3, 3)))
model.add(Activation('relu'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(256))
model.add(Activation('relu'))
model.add(Dropout(0.5))
model.add(Dense(num_classes))
model.add(Activation('softmax'))
```

### **Optimizing**

# initiate RMSprop optimizer

```
opt = keras.optimizers.RMSprop(learning_rate=0.001, decay=1e-4)
# Let's train the model using RMSprop
Compiling the model, with the trained parameters
model.compile(loss='categorical crossentropy',
        optimizer=opt,
        metrics=['accuracy'])
x train = x train.astype('float32')
x_{test} = x_{test.astype}(float32)
x train /= 255
x_test /= 255
Normal data fitting
if not data_augmentation:
  print('Not using data augmentation.')
  history = model.fit(x_train, y_train,
        batch_size=batch_size,
        epochs=epochs,
        validation_data=(x_test, y_test),
        shuffle=True)
Else:
DataGenerator for Real time classification
  print('Using real-time data augmentation.')
  #preprocessing fro realtime data augmentation:
  datagen = ImageDataGenerator(
     featurewise center=False, samplewise center=False,
featurewise_std_normalization=False,
     samplewise_std_normalization=False, zca_whitening=False, zca_epsilon=1e-06,
     rotation range=0, width shift range=0.1, height shift range=0.1, shear range=0.,
     zoom range=0., channel shift range=0., fill mode='nearest', cval=0., horizontal flip=True,
     vertical_flip=False, rescale=None, preprocessing_function=None, data_format=None,
validation_split=0.0)
  #feature-wise normalization.
  datagen.fit(x train)
   Save the model and results to plot accuracy and loss
  # create models by datagen.flow()
  # then fit the models with the pre-trained parameters
  history = model.fit_generator(datagen.flow(x_train, y_train,
                      batch_size=batch_size),
              epochs=epochs,
              validation_data=(x_test, y_test),
```

```
workers=4)
```

```
Save the model parameters to the file 'keras_cifar10_trained_model.h5'
# Save model and weights
if not os.path.isdir(save_dir):
  os.makedirs(save dir)
model_path = os.path.join(save_dir, model_name)
model.save(model_path)
print('Saved trained model at %s ' % model path)
# Score trained model.
scores = model.evaluate(x_test, y_test, verbose=1)
print('Test accuracy in percentage: ', scores[1]*100)
print('Test loss: ', scores[0])
Plot Accuracy
plt.plot(history.history['acc'])
plt.plot(history.history['val_acc'])
plt.title('model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
Plot Loss
plt.plot(history.history['loss'])
plt.plot(history.history['val_loss'])
plt.title('model loss')
plt.ylabel('loss')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.show()
```

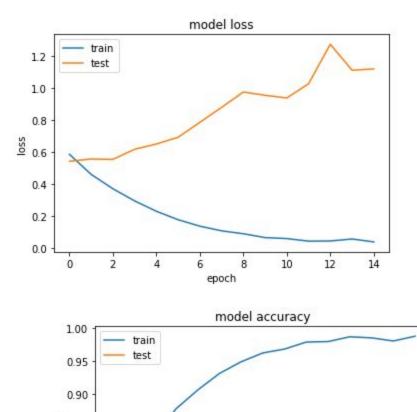
The following code in the notebook is where the model is being tested cnn2.py

import math
from matplotlib import pyplot
from keras.datasets import cifar10
from keras.models import load\_model
from keras.preprocessing import image
import numpy as np
import matplotlib.pyplot as plt
from numpy import linalg as LA

```
# load dataset
(trainX, trainy), (testX, testy) = cifar10.load_data()
print('Train: X=%s, y=%s' % (trainX.shape, trainy.shape))
print('Test: X=%s, y=%s' % (testX.shape, testy.shape))
#-----data visualisation-----
# plot first few images of the training dataset
for i in range(9):
       pyplot.subplot(330 + 1 + i)
       pyplot.imshow(trainX[i])
pyplot.show()
# plot first few images of the testing dataset
for i in range(9):
       pyplot.subplot(330 + 1 + i)
       pyplot.imshow(testX[i])
pyplot.show()
#load the test data batch of cifar10
def unpickle(file):
  import pickle
  with open(file, 'rb') as fo:
     dict = pickle.load(fo, encoding='bytes')
  return dict
file1 = file1 = '/home/shivani/cifar-10-batches-py/test batch'
batch1 = unpickle(file1)
data = ∏
labels = ∏
data.append(batch1[b'data'])
labels.append(batch1[b'labels'])
data = np.array(data)
labels = np.array(labels)
#rgb_data = np.concatenate(data)
#batch_labels = np.concatenate(labels)
# dimensions of our images
img_width, img_height = 32, 32
# load the model that is pretrained i.e, 'keras_cifar10_trained_model_1.h5'
model = load_model('/home/shivani/saved_models/keras_cifar10_trained_model_1.h5')
```

```
model.compile(loss='binary_crossentropy',
        optimizer='rmsprop',
        metrics=['accuracy'])
#----random test images other than those in cifar10, (from internet))
s = ['/home/shivani/Downloads/car1.jpg', '/home/shivani/Downloads/bird1.jpg',
'/home/shivani/Downloads/ship1.jpg']
# predicting images
images = []
for i in range(3):
       img = image.load_img(s[i], target_size = (img_width, img_height))
       x = image.img_to_array(img)
       x = np.expand\_dims(x, axis=0)
       images = np.vstack([x])
       #images = np.concatenate(images,x, axis = 1)
       classes = model.predict_classes(images, batch_size=10)
       #print(images.shape)
       #print (classes[0])
data = data[0]
classes_test = []
for i in range(10000):
       d = data[i,:].reshape((1,32,32,3))
       classes_test.append(model.predict_classes(d, batch_size=10))
       #print(len(d))
       #print("\n")
       #print(d)
print(len(classes_test))
print(classes_test)
#print (classes)
#print (classes[0])
#print (classes[0][0])
```

Plots for Model Accuracy and Model Loss for epoch = 14



0.85 - 0.80 - 0.75 - 0.70 - 0.

The time for training, with respect to different parameters:

Epoch 14 -- 2 hrs, epoch 5 -- 30 min

Change (Improvement) of accuracy with epoch: Best accuracy is got with epoch around 14.

## For the optimizer, the experimented parameters are:

learning\_rate=0.001, decay=1e-4

Observation: Lower learning rate  $\rightarrow$  convergence is slow. Takes too many epochs to converge Higher Learning rate  $\rightarrow$  Converge is fast but should be taken care that oscillation won't happen

## Results:

Training(epoch = 5). Therefore, the accuracy is very low. Around 30% Training(epoch = 14). Therefore, the accuracy is very good. Around 70%

```
nivani@shivani-HP-Notebook: ~
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2.0835

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- 385s_8ms/step - loss: 1.6392 - accuracy: 0.4216 - val_loss: 1.3898 - val_accuracy:
        50000/50000
       0.3224
        0.3224
Epoch 4/5
13988/50000 [=====>>.....] - ETA: 4:21 - loss: 1.8484 - accuracy: 0.3795
```

#### Results of classification:

