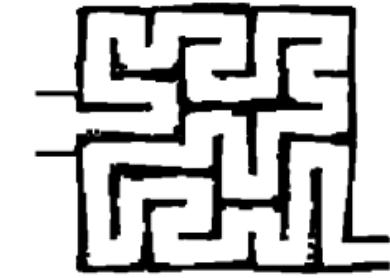
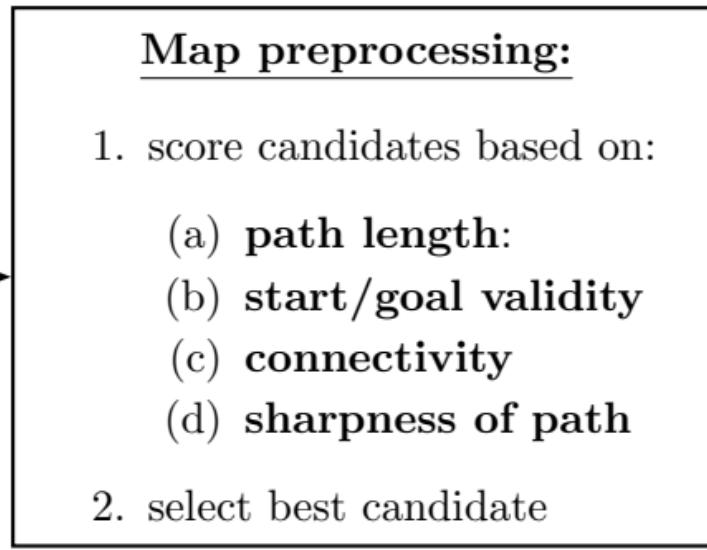


+

Start point: {....}  
Goal point: {....}  
User click set (start, goal)



Greyscale occupancy map

parameters stored:

```
{  
  "score": 0.8809628003525114,  
  "threshold_mode": "otsu",  
  "threshold": 135.0,  
  "obstacle_is_dark": true,  
  "morph_passes": 0,  
  "inflate_px": 0,  
  "cell": 4,  
  "path_found": true,  
  "start": (0,0)  
  "goal": (9.4,-5.7)  
}
```